Denotational Semantics of PCF

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1 Denotation of Types

The Denotational Semantics maps the types of PCF to a domain representing that type. We define a function:

$$\llbracket - \rrbracket : Type \rightarrow Domain$$

that maps a type to a Domain. We have two possible ways to define a type, so there are two domains we use:

1. The type of Natural numbers is the ground type, so they are modelled by a single domain. We use the flat domain of Natural numbers, where \bot represents a term that loops forever.

$$[Nat] = \mathbb{N}_{\perp}$$

2. Function types are formed of other types. We model them using the domain of continuous functions.

$$[\![A \to B]\!] = [\![A]\!] \to [\![B]\!]$$

2 Denotation of Typing Contexts

The Denotational Semantics maps the terms of PCF to a domain. We define a function:

$$[-]_{Ctx}: Context \rightarrow Domain$$

that maps a typing context to a domain. The domain will be a nested tuple, the size of which depends on the number of variables in Γ . We prove separately that products of domains are also domains.

The empty context is given by

$$[\cdot]_{Ctx} = 1$$

the single element set. We also prove separately that this is a domain.

Adding a variable to a context Γ gives us the following:

$$\llbracket \Gamma, x : A \rrbracket_{Ctx} = \llbracket \Gamma \rrbracket \times \llbracket A \rrbracket$$

The products of the domains give all combinations of all possible values of each variable. If we want a specific valuation of the variables, we can refer to $\gamma \in [\Gamma]_{Ctx}$.

3 Denotation of well typed terms

Given a well typed term $\Gamma \vdash e : A$ we have

$$\llbracket \Gamma \vdash e : A \rrbracket \in \llbracket \Gamma \rrbracket_{Ctx} \to \llbracket A \rrbracket$$

So $\llbracket \Gamma \vdash e : A \rrbracket \gamma$ gives us an element of $\llbracket A \rrbracket$. We can define this on each possible value of e individually:

Variables Given a context $\Gamma = x_0 : A_0, \ldots, x_n : A_n, \llbracket \Gamma \rrbracket_{Ctx}$ maps a tuple γ in $\llbracket A_0 \rrbracket \times \cdots \times \llbracket A_n \rrbracket$ to a value in $\llbracket A_i \rrbracket$:

$$\llbracket \Gamma \vdash x_i : A_i \rrbracket = \lambda \gamma \in \llbracket \Gamma \rrbracket . \pi_i(\gamma)$$

We use the *i*th projection function to get the value of the *i*th variable in the context.

Zero z is an element of Nat, the domain of which we have defined to be \bot . As z is a constant, we always map it to the same value, which is 0, no matter what γ is:

$$\llbracket \Gamma \vdash z : Nat \rrbracket \gamma = 0$$

Successor When $\Gamma \vdash s(e) : Nat$ is a well typed term, then so is $\Gamma \vdash e : Nat$, so we can use $\llbracket \Gamma \vdash e : Nat \rrbracket$ in the definition of the denotational semantics for successor. As the domain of e is \mathbb{N}_{\perp} , we must consider the case where e maps to \perp , for which we would also have to map s(e) to \perp :

$$[\![\Gamma \vdash s(e) : Nat]\!] \gamma = \text{Let } v = [\![\Gamma \vdash e : Nat]\!] \gamma \text{ in}$$

$$\begin{cases} v+1 & \text{if } v \neq \bot \\ \bot & \text{if } v = \bot \end{cases}$$

Case When $\Gamma \vdash case\ (e, z \mapsto e_0, s(y) \mapsto e_S)$: C is a well typed term, then so is $\Gamma \vdash e : Nat$, so we can use $\llbracket \Gamma \vdash e : Nat \rrbracket$ in the definition of the denotational semantics for case:

Application In this rule we already have a denotation for the function and for the element we are applying it to. The bottom element of our domain of functions is the function that loops on all inputs, $\lambda x \in X.\bot_Y$. Therefore the value of f will always be a function. Functions on domains can be applied to bottom elements, so we can still have f(v) when $v = \bot$. Therefore there is only one case for function application:

$$[\![\Gamma \vdash e\ e':B]\!]\gamma = \text{Let}\ f = [\![\Gamma \vdash e:A \to B]\!]\gamma$$
 in
$$\text{Let}\ v = [\![\Gamma \vdash e':A]\!]\gamma$$
 in $f(v)$

 λ abstraction For λ abstraction, by its typing rule, we already have a denotation for $[\![\Gamma,x:A\vdash e:B]\!]\gamma$. This is a function of type $[\![\Gamma]\!]\times[\![A]\!]\to[\![B]\!]$. The function we want to obtain is of type $[\![\Gamma]\!]\to([\![A\to B]\!])$, so we must return a continuous function. We use currying, with our denotation of $\Gamma,x:A\vdash e:B$. As this is in a different context, we need our function to be in a context where

the value of x is our $a \in \llbracket A \rrbracket$ that is the argument to our function, which is $(\gamma, a/x)$:

$$\llbracket\Gamma \vdash \lambda x : A.e : A \to B \rrbracket \gamma = \lambda a \in \llbracket A \rrbracket. \llbracket\Gamma, x : A \vdash e : A \rrbracket (\gamma, a/x)$$

Fixpoint For fixpoint, by its typing rule we already have a denotation for $\llbracket \Gamma, x : A \vdash e : A \rrbracket \gamma$ This is a function of type $\llbracket \Gamma \rrbracket \times \llbracket A \rrbracket \to \llbracket A \rrbracket$. The function we want to obtain is of type $\llbracket \Gamma \rrbracket \to \llbracket A \rrbracket$ To get an element of $\llbracket A \rrbracket$, we use the fixpoint function, $fix_{\llbracket A \rrbracket}$, which is a continuous function of type $(\llbracket A \rrbracket \to \llbracket A \rrbracket) \to \llbracket A \rrbracket$. the function we give to the fixpoint is the one that maps any given $a \in \llbracket A \rrbracket$ to the denotation of $\Gamma, x : A \vdash e : A$ in a context where a is the value of x:

$$\llbracket \Gamma \vdash fix \ x : A.e : A \rrbracket \gamma = fix_{\llbracket A \rrbracket} (\lambda a \in \llbracket A \rrbracket. \llbracket \Gamma, x : A \vdash e : A \rrbracket (\gamma, a/x))$$

4 Theorems

4.1 Substitution Theorem

The following theorem says that given a well typed expression e and another expression e', which is well typed in the context with x:A added, then the denotation of e' with e substituted for x is the same as the denotation of the original expression in the context with x:A added and valuation with the denotation of e as the value of x:

Theorem 1. If
$$\Gamma \vdash e : A$$
 and $\Gamma, x : A \vdash e' : C$ and $\gamma \in \llbracket \Gamma \rrbracket$, then $\llbracket \Gamma \vdash [e/x]e' : C \rrbracket \gamma = \llbracket \Gamma, x : A \vdash e' : C \rrbracket (\gamma, \llbracket \Gamma \vdash e : A \rrbracket \gamma / x)$

Proof. We prove this by induction on the value of e':

Variables There are two cases for variables:

- 1. For a variable x:C,C must be equal to A, so we get $\llbracket\Gamma\vdash [e/x]x:A\rrbracket\gamma=\llbracket\Gamma\vdash e:A\rrbracket\gamma$, from the substitution rule.
 - On the right hand side, $[\![\Gamma, x : A \vdash x : A]\!](\gamma, [\![\Gamma \vdash e : A]\!]\gamma/x) = \pi_i(\gamma, [\![\Gamma \vdash e : A]\!]\gamma/x)$. The value of this is the value of x, which is $[\![\Gamma \vdash e : A]\!]\gamma$.
 - Therefore $[\![\Gamma\vdash[e/x]x:A]\!]\gamma=[\![\Gamma,x:A\vdash x:A]\!](\gamma,[\![\Gamma\vdash e:A]\!]\gamma/x)=[\![\Gamma\vdash e:A]\!]\gamma$
- 2. For a variable y: C, we have $\llbracket \Gamma \vdash [e/x]y: C \rrbracket \gamma = \llbracket \Gamma \vdash y: C \rrbracket \gamma$, by the substitution rule for variables. This is equal to $\pi_i(\gamma)$, where y: C is the *i*th element of Γ . If we extend the context Γ with x: A and the valuation γ with $\llbracket \Gamma \vdash e: A \rrbracket \gamma/x$, then this does not affect $\pi_i(\gamma)$, as each variable is

independent. Therefore $\llbracket\Gamma \vdash [e/x]y : C\rrbracket\gamma = \llbracket\Gamma, x : A \vdash y : C\rrbracket(\gamma, \llbracket\Gamma \vdash e : A\rrbracket\gamma/x)$.

Zero By the substitution rule for zero, $\llbracket\Gamma \vdash [e/x]z : Nat \rrbracket\gamma = \llbracket\Gamma \vdash z : Nat \rrbracket\gamma$. As z is a constant, its denotation will be the same for any Γ and γ , so we always get 0. Therefore $\llbracket\Gamma \vdash [e/x]z : Nat \rrbracket\gamma = \llbracket\Gamma, x : A \vdash z : Nat \rrbracket(\gamma, \llbracket\Gamma, \vdash e : A \rrbracket\gamma/x) = 0$.

Successor Using the substitution rule, $\llbracket \Gamma \vdash [e/x]s(e') : Nat \rrbracket \gamma = \llbracket \Gamma \vdash s([e/x]e') : Nat \rrbracket \gamma$. The induction hypothesis is $\llbracket \Gamma \vdash [e/x]e' : C \rrbracket \gamma = \llbracket \Gamma, x : A \vdash e' : C \rrbracket (\gamma, \llbracket \Gamma \vdash e : A \rrbracket \gamma/x)$, so we can use this to rewrite $\llbracket \Gamma \vdash s([e/x]e') : Nat \rrbracket \gamma$ as the following function:

Let $v = [\![\Gamma, x : A \vdash e' : C]\!] (\gamma, [\![\Gamma \vdash e : A]\!] \gamma/x)$ in

$$\begin{cases} v+1 & \text{if } v \neq \bot \\ \bot & \text{if } v = \bot \end{cases}$$

This function is also the definition of $[\![\Gamma, x : A \vdash s(e') : C]\!] (\gamma, [\![\Gamma \vdash e : A]\!] \gamma/x)$.

Therefore $\llbracket \Gamma \vdash [e/x]s(e') : Nat \rrbracket \gamma = \llbracket \Gamma, x : A \vdash s(e') : C \rrbracket (\gamma, \llbracket \Gamma \vdash e : A \rrbracket \gamma/x)$

Case Using the substitution rule for case, $[\Gamma \vdash [e/x](case\ (e', z \mapsto e_0, s(y) \mapsto e_S) : C]]\gamma = [\Gamma \vdash (case\ ([e/x]e', z \mapsto [e/x]e_0, s(y) \mapsto [e/x]e_S) : C]]\gamma$. We can use induction on all the expressions with substitutions to get the following definition of $[\Gamma \vdash (case\ ([e/x]e', z \mapsto [e/x]e_0, s(y) \mapsto [e/x]e_S) : C]]\gamma$:

Let $v = \llbracket \Gamma, x : A \vdash e' : Nat \rrbracket (\gamma, \llbracket \Gamma \vdash e : A \rrbracket \gamma / x)$ in

$$\begin{cases} \llbracket \Gamma, x : A \vdash e_0 : C \rrbracket (\gamma, \llbracket \Gamma \vdash e : A \rrbracket \gamma / x) & \text{if } v = 0 \\ \llbracket \Gamma, y : Nat, x : A \vdash e_S : C \rrbracket (\gamma, n/y, \llbracket \Gamma \vdash e : A \rrbracket \gamma / x) & \text{if } v = n+1 \\ \bot & \text{if } v = \bot \end{cases}$$

This function is also the definition of $\llbracket \Gamma, x : A \vdash [e/x](case\ (e', z \mapsto e_0, s(v) \mapsto e_S)) : C \rrbracket (\gamma, \llbracket \Gamma \vdash e : A \rrbracket \gamma/x)$

Therefore $\llbracket \Gamma \vdash [e/x](case\ (e',z\mapsto e_0,s(v)\mapsto e_S):C\rrbracket\gamma=\llbracket \Gamma,x:A\vdash case\ (e',z\mapsto e_0,s(v)\mapsto e_S):C\rrbracket(\gamma,\llbracket \Gamma\vdash e:A\rrbracket\gamma/x)$

Application Using the substitution rule for application, $\llbracket \Gamma \vdash [e/x](e_0 \ e_1) : B \rrbracket \gamma = \llbracket \Gamma \vdash [e/x]e_0([e/x]e_1) : B \rrbracket \gamma$. We can use induction on $\llbracket \Gamma \vdash [e/x]e_0 : A \to B \rrbracket$ and $\llbracket \Gamma \vdash [e/x]e_1 : A \rrbracket$ to rewrite the denotation as the following:

Let
$$f = \llbracket \Gamma, x : A \vdash e_0 : A \to B \rrbracket (\gamma, \llbracket \Gamma \vdash e : A \rrbracket \gamma/x)$$
 in Let $v = \llbracket \Gamma, x : A \vdash e_1 : A \rrbracket (\gamma \llbracket \Gamma \vdash e : A \rrbracket \gamma/x)$ in $f(v)$

This function is also the definition of $\llbracket \Gamma, x : A \vdash e_0 \ e_1 : B \rrbracket (\gamma \llbracket \Gamma \vdash e : A \rrbracket \gamma / x)$. Therefore, $\llbracket \Gamma \vdash [e/x](e_0 \ e_1) : B \rrbracket \gamma = \llbracket \Gamma, x : A \vdash e_0 \ e_1 : B \rrbracket (\gamma, \llbracket \Gamma \vdash e : A \rrbracket \gamma / x)$

 λ abstraction Using the substitution rule we have $\llbracket \Gamma \vdash [e/x](\lambda y : A.e') : A \rightarrow B \rrbracket \gamma = \llbracket \Gamma \vdash \lambda y : A.([e/x]e') : A \rightarrow B \rrbracket \gamma$. We can use induction with $\llbracket \Gamma \vdash \lambda [e/x]e' : B$, to rewrite the denotation as the following:

$$\lambda a \in \llbracket A \rrbracket. \llbracket \Gamma, y : A, x : A \vdash e : B \rrbracket (\gamma, a/y, \llbracket \Gamma \vdash e : A \rrbracket \gamma/x)$$

This is also the definition of $\llbracket \Gamma, x : A \vdash \lambda y : A.\ e' : A \to B \rrbracket (\gamma, \llbracket \Gamma \vdash e : A \rrbracket \gamma/x)$ Therefore $\llbracket \Gamma \vdash [e/x](\lambda y : A.e') : A \to B \rrbracket \gamma = \llbracket \Gamma, x : A \vdash \lambda y : A.\ e' : A \to B \rrbracket (\gamma, \llbracket \Gamma \vdash e : A \rrbracket \gamma/x)$

Fixpoint Using the substitution rule for fixpoint, $\llbracket \Gamma \vdash [e/x](fix \ y : C.e' : C) \rrbracket \gamma = \llbracket \Gamma \vdash fix \ y : C.[e/x]e' : C \rrbracket \gamma$. We can use induction on $\llbracket \Gamma, y : C \vdash [e/x]e' : C \rrbracket$ to rewrite the denotation as the following:

$$fix_{\llbracket C \rrbracket}(\lambda c \in \llbracket C \rrbracket. \llbracket \Gamma, y : C, x : A \vdash e' : C \rrbracket (\gamma, c/y, \llbracket \Gamma \vdash e : A \rrbracket \gamma/x)$$

This is also the definition of $\llbracket \Gamma, x : A \vdash (fix \ y : A.e' : A) \rrbracket (\gamma, \llbracket \Gamma \vdash e : A \rrbracket \gamma / x)$. Therefore $\llbracket \Gamma \vdash [e/x] (fix \ y : C.e' : C) \rrbracket \gamma = \llbracket \Gamma, x : A \vdash (fix \ y : C.e' : C) \rrbracket (\gamma, \llbracket \Gamma \vdash e : A \rrbracket \gamma / x)$.

Now we have proved the theorem for every case of e'.

4.2 Correctness

The following theorem says that for a well typed expression e, if it maps to another expression e', then its denotation will be equal to that of the new expression in the same context:

Theorem 2. If $\Gamma \vdash e : A$ and $e \mapsto e'$ and $\gamma \in \llbracket \Gamma \rrbracket$, then $\llbracket \Gamma \vdash e : A \rrbracket \gamma = \llbracket \Gamma \vdash e' : A \rrbracket \gamma$

Proof. By induction on $e \mapsto e'$, so there is a case for each evaluation rule:

Variables have no rules, so there are no cases here.

Zero is a value, so it has no evaluation rules. Therefore there are no cases for zero.

Successor We use a congruence rule for successor, so when $s(e) \mapsto s(e')$ we also know that $e \mapsto e'$. From $\Gamma \vdash s(e) : Nat$, we know that $\Gamma \vdash e : Nat$. Therefore we can use induction on this to get $\Gamma \vdash e : A = \Gamma \vdash e' : A$.

We can use this to rewrite $[\Gamma \vdash s(e) : Nat]\gamma$ as:

Let $v = \llbracket \Gamma \vdash e' : Nat \rrbracket \gamma$ in

$$\begin{cases} v+1 & \text{if } v \neq \bot \\ \bot & \text{if } v = \bot \end{cases}$$

Which is the same as $\llbracket \Gamma \vdash s(e') : Nat \rrbracket \gamma$

Case There are three cases for case:

1. When e is an expression that can be reduced, we use a congruence rule for case, so when $case\ (e,z\mapsto e_0,s(y)\mapsto e_S)\mapsto case\ (e',z\mapsto e_0,s(y)\mapsto e_S)$ we also know that $e\mapsto e'$. From $\Gamma\vdash case\ (e,z\mapsto e_0,s(y)\mapsto e_S):C$, we know that $\Gamma\vdash e:Nat$. Therefore we can use induction to get $\llbracket\Gamma\vdash e:Nat\rrbracket\gamma=\llbracket\Gamma\vdash e':Nat\rrbracket\gamma$.

We can use this to rewrite $\llbracket \Gamma \vdash case\ (e, z \mapsto e_0, s(y) \mapsto e_S) : C \rrbracket \gamma$ as:

Let $v = \llbracket \Gamma \vdash e' : Nat \rrbracket \gamma$ in

$$\begin{cases} \llbracket \Gamma \vdash e_0 : C \rrbracket \gamma & \text{if } v = 0 \\ \llbracket \Gamma, y : Nat \vdash e_S : C \rrbracket (\gamma, n/y) & \text{if } v = n+1 \\ \bot & \text{if } v = \bot \end{cases}$$

Which is the same as $\llbracket \Gamma \vdash case\ (e', z \mapsto e_0, s(y) \mapsto e_S) : C \rrbracket \gamma$.

2. When e = z, we have $\llbracket \Gamma \vdash case(z, z \mapsto e_0, s(y) \mapsto e_S) : C \rrbracket \gamma$ which is:

Let
$$v = \llbracket \Gamma \vdash z : Nat \rrbracket \gamma$$
 in

$$\begin{cases} \llbracket \Gamma \vdash e_0 : C \rrbracket \gamma & \text{if } v = 0 \\ \llbracket \Gamma, y : Nat \vdash e_S : C \rrbracket (\gamma, n/y) & \text{if } v = n+1 \\ \bot & \text{if } v = \bot \end{cases}$$

As $\llbracket \Gamma' \vdash z : Nat \rrbracket \gamma$ is always 0, this can be simplified to $\llbracket \Gamma \vdash e_0 : C \rrbracket \gamma$, which is the result of the evaluation rule

3. When e = s(v), we have $\llbracket \Gamma \vdash case(s(v), z \mapsto e_0, s(y) \mapsto e_S) : C \rrbracket \gamma$ which is:

Let
$$v' = \llbracket \Gamma \vdash s(v) : Nat \rrbracket \gamma$$
 in

$$\begin{cases} \llbracket \Gamma \vdash e_0 : C \rrbracket \gamma & \text{if } v' = 0 \\ \llbracket \Gamma, y : Nat \vdash e_S : C \rrbracket (\gamma, n/y) & \text{if } v' = v + 1 \\ \bot & \text{if } v' = \bot \end{cases}$$

where $n = \llbracket \Gamma \vdash v : Nat \rrbracket \gamma$.

There are two possibilities for the value of v'.

- (a) If $v' = \bot$ then the function will return \bot
- (b) Otherwise v'=n+1, where $n=[\![\Gamma\vdash v:Nat]\!]\gamma$. With this we can simplify the definition of the expression to $[\![\Gamma,y:Nat\vdash e_S:C]\!](\gamma,n/y)$

This is the same as:

$$\llbracket \Gamma, y : Nat \vdash e_S : C \rrbracket (\gamma, \llbracket \Gamma \vdash v : Nat \rrbracket \gamma/y)$$

Using substitution, we get $[\Gamma \vdash [v/y]e_S]\gamma$.

Application There are two cases for application:

1. We use a congruence rule for function application, so when $e_0 \ e_1 \mapsto e_0' \ e_1$ we also know that $e \mapsto e'$. From $\Gamma \vdash e_0 \ e_1 : B$, we know that $\Gamma \vdash e_0 : A \to B$. Therefore we can use induction on this to get $\llbracket \Gamma \vdash e_0 \ e_1 : A \rrbracket \gamma = \llbracket \Gamma' \vdash e_0' \ e_1 : A \rrbracket \gamma$.

We can use this to rewrite $\llbracket \Gamma \vdash e_0 \ e_1 : B \rrbracket \gamma$ as:

Let
$$f = \llbracket \Gamma \vdash e_0' : A \to B \rrbracket \gamma$$
 in

Let
$$v = \llbracket \Gamma \vdash e_1 : A \rrbracket \gamma$$

in $f(v)$

which is the same as $\llbracket \Gamma \vdash e_0' \ e_1 : B \rrbracket \gamma$

2. When $e=\lambda x:A.e,$ it is a value, so cannot be reduced further by the congruence rule. We use the semantic rule:

$$\overline{(\lambda x : A. \ e) \ e' \mapsto [e'/x]e}$$

so we need a denotation $\llbracket\Gamma \vdash [e'/x]e\rrbracket\gamma$.

As we have the denotation of $\llbracket \Gamma \vdash (\lambda x : A.e) \ e' : B \rrbracket \gamma$, we have $f = \llbracket \Gamma \vdash \lambda x : A.e : A \rightarrow B \rrbracket \gamma$ and $v = \llbracket \Gamma \vdash e' : A \rrbracket \gamma$.

$$f=\lambda a\in [\![A]\!].[\![\Gamma,x:A\vdash e:A]\!](\gamma,a/x)$$
 , so f v is $[\![\Gamma,x:A\vdash e:A]\!](\gamma,[\![\Gamma\vdash e':A]\!]\gamma/x)$

By substitution, this is the same as $\llbracket \Gamma \vdash [e'/x]e \rrbracket \gamma$

 λ abstraction $\,$ is a value, so has no evaluation rules. Therefore there are no cases.

Fixpoint As $\llbracket \Gamma \vdash fix \ x : A.e : A \rrbracket \gamma$ is a fixpoint operator, we know that f(fix(f)) = fix(f), so we can rewrite it as:

$$(\lambda a \in \llbracket A \rrbracket. \llbracket \Gamma, x : A \vdash e : A \rrbracket (\gamma, a/x)) [fix_{\llbracket A \rrbracket} (\lambda a \in \llbracket A \rrbracket. \llbracket \Gamma, x : A \vdash e : A \rrbracket (\gamma, a/x))]$$

which is equal to:

$$[\![\Gamma,x:A\vdash e:A]\!](\gamma,fix_{\llbracket A\rrbracket}(\lambda a\in [\![A]\!].[\![\Gamma,x:A\vdash e:A]\!](\gamma,a/x))/x)$$

which is equal to:

$$\llbracket \Gamma, x : A \vdash e : A \rrbracket (\gamma, \llbracket \Gamma \vdash fix \ x : A.e : A \rrbracket \gamma/x)$$

Using the substitution lemma, this is the same as

$$\llbracket\Gamma \vdash [fix\ x:A.e/x]e:A\rrbracket\gamma$$

The evaluation rule is

$$\overline{fix \ x: A.e \mapsto [fix \ x: A.e/x]e}$$

so this is the denotation we need.