







# Don't forget, there is more than forgetting: new metrics for Continual Learning

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#### **Outline**

- Continual Learning
- Motivation
- Continual Learning Framework
- New Metrics for Continual Learning
- Experiments
- Future Work (WIP)

Continual Learning (CL)

#### **Continual Learning Algorithms:**

- learn from a stream of data/tasks
- continuously and adaptively thought time
- enable the incremental development of ever more complex knowledge and skills.



#### **Motivation:**

- The lack of consensus in evaluating CL algorithms
- Almost exclusive focus on catastrophic forgetting<sup>1</sup>

We propose: Comprehensive, implementation independent metrics accounting for factors we believe have practical implications worth considering w.r.t.:

- "Non-static" ML settings
- Deployment of real AI systems that learn continually

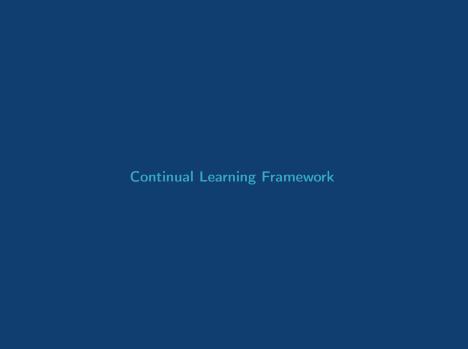
<sup>&</sup>lt;sup>1</sup>[McCloskey and Cohen, 1989, French, 1999]

# Catastrophic forgetting<sup>3</sup>

- The well-known phenomenon of a neural network experiencing a rapid overriding of previously learned knowledge when trained sequentially on new data.
- An important objective quantified for assessing the quality of CL approaches<sup>2</sup>.

<sup>&</sup>lt;sup>2</sup>[Serrà et al., 2018, Lopez-Paz and Ranzato, 2017, Hayes et al., 2018, Farquhar and Gal, 2018]

<sup>&</sup>lt;sup>3</sup>[McCloskey and Cohen, 1989, French, 1999]



#### **Continual Learning Framework**

In Continual Learning,

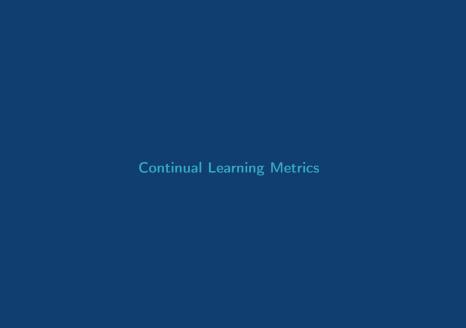
- $\mathcal{D} = \{D_1, \dots, D_N\}$ : a potentially infinite sequence of unknown distributions over  $X \times Y$  encountered over time
- X and Y input and output r.v.
- h\*: general target function (i.e. our ideal prediction model)
- Task T: defined by a unique task label t and its target function  $g_{\hat{t}}^*(x) \equiv h^*(x, t = \hat{t})$  (i.e., the objective of its learning).

A CL algorithm  $A^{CL}$  has the signature:

$$\forall D_i \in \mathcal{D}, \qquad A_i^{CL}: \langle h_{i-1}, Tr_i, M_{i-1}, t \rangle \rightarrow \langle h_i, M_i \rangle \tag{1}$$

#### where

- hi: the model
- Tr<sub>i</sub>: training set of examples drawn from distribution D<sub>i</sub>
- M<sub>i</sub>: external memory (can store previous training examples)
- N: nr of tasks (one per  $Tr_i$ ).



# Accuracy (A)<sup>5</sup>

Originally assessed the model performance at the end of the last  $task^4$ ; we extend A to account for performance at every timestep in time:

$$A = \frac{\sum_{i \ge j}^{N} R_{i,j}}{\frac{N(N+1)}{2}} \tag{2}$$

where  $R_{i,j}$  in Accuracy matrix  $R \in \mathbb{R}^{N \times N}$  is test classification accuracy on task  $t_j$  after observing the last sample from task  $t_i$ .

R	$Te_1$	Te <sub>2</sub>	Te <sub>3</sub>
Tr <sub>1</sub>	R*	R <sub>ij</sub>	$R_{ij}$
$Tr_2$	$R_{ij}$	$R^*$	$R_{ij}$
Tr <sub>3</sub>	$R_{ij}$	$R_{ij}$	$R^*$

<sup>&</sup>lt;sup>4</sup>[Lopez-Paz and Ranzato, 2017]

<sup>&</sup>lt;sup>5</sup>Accuracy matrix R: elements accounted to compute A (white & cyan), BWT (cyan), and FWT (gray).  $R^*=R_{ii}$ ,  $Tr_i=$  training,  $Te_i=$  test tasks.

## Backward Transfer (BWT)<sup>7</sup>

BWT measures the influence that learning a task has on the performance on previous tasks $^6$ .

$$BWT = \frac{\sum_{i=2}^{N} \sum_{j=1}^{i-1} (R_{i,j} - R_{j,j})}{\frac{N(N-1)}{2}}$$
(3)

R	$Te_1$	Te <sub>2</sub>	Te <sub>3</sub>
Tr <sub>1</sub>	R*	Rij	R <sub>ij</sub>
$Tr_2$	$R_{ij}$	$R^*$	$R_{ij}$
Tr <sub>3</sub>	$R_{ij}$	$R_{ij}$	$R^*$

<sup>&</sup>lt;sup>6</sup>[Lopez-Paz and Ranzato, 2017]

 $<sup>^7</sup>$ Accuracy matrix R: elements accounted to compute A (white & cyan), BWT (cyan), and FWT (gray).  $R^*=R_{ii}$ ,  $Tr_i=$  training,  $Te_i=$  test tasks.

## Backward Transfer ( $BWT^+$ ) and Remembering (REM)

BWT is broken into two different clipped terms: (originally negative BWT, forgetting), **Remembering**:

$$REM = 1 - |min(BWT, 0)| \tag{4}$$

and (originally positive BWT) improvement over time: **Positive Backward Transfer** ( $BWT^+$ ):

$$BWT^{+} = \max(BWT, 0) \tag{5}$$

### Forward Transfer (FWT)<sup>9</sup>

Measures the influence that learning a task has on the performance of future tasks<sup>8</sup>:

$$FWT = \frac{\sum_{i < j}^{N} R_{i,j}}{\frac{N(N-1)}{2}}$$
 (6)

R	Te <sub>1</sub>	$Te_2$	Te <sub>3</sub>
$Tr_1$	R*	$R_{ij}$	$R_{ij}$
$Tr_2$	$R_{ij}$	$R^*$	$R_{ij}$
$Tr_3$	$R_{ij}$	$R_{ij}$	$R^*$

FWT can occur when the model is able to perform zero-shot learning.

<sup>&</sup>lt;sup>8</sup>[Lopez-Paz and Ranzato, 2017]

<sup>&</sup>lt;sup>9</sup>Accuracy matrix R: elements accounted to compute A (white & cyan), BWT (cyan), and FWT (gray).  $R^*=R_{ii}$ ,  $Tr_i=$  training,  $Te_i=$  test tasks.

### Model Size (MS) efficiency

The memory size of model  $h_i$ , quantified in terms of parameters  $\theta$  at each task i,  $Mem(\theta_i)$ , should not grow too rapidly w.r.t. the size of the model that learned the first task,  $Mem(\theta_1)$ :

$$MS = min(1, \frac{\sum_{i=1}^{N} \frac{Mem(\theta_1)}{Mem(\theta_i)}}{N})$$
 (7)

#### Samples Storage Size (SSS) efficiency

The memory occupation in bits by the samples storage memory M, Mem(M), should be bounded by the occupation of the total nr of examples encountered at the end of last task:

$$SSS = 1 - min(1, \frac{\sum_{i=1}^{N} \frac{Mem(M_i)}{Mem(D)}}{N})$$
 (8)

where D is the lifetime dataset associated to all distributions  $\mathcal{D}$ .

## Computational Efficiency (CE)

CE is bounded by the nr of operations for training set Tr<sub>i</sub>:

$$CE = min(1, \frac{\sum_{i=1}^{N} \frac{Ops\uparrow\downarrow(Tr_i)\cdot\varepsilon}{1+Ops(Tr_i)}}{N})$$
 (9)

where

- Ops(Tr<sub>i</sub>): nr (mul-adds) operations needed to learn Tr<sub>i</sub>
- $Ops \uparrow \downarrow (Tr_i)$ : operations required to do one forward and one backward (backprop) pass on  $Tr_i$
- $\varepsilon$ : a scaling factor<sup>10</sup>

<sup>&</sup>lt;sup>10</sup>Associated to the nr of epochs needed to learn  $T_{f_i}$ : when  $Ops \uparrow \downarrow (T_{f_i})$  is negligible w.r.t.  $Ops(T_{f_i})$ , a  $\varepsilon > 1$  makes CE more interpretable (here  $\varepsilon = 10$ ).

#### CL<sub>score</sub>

We fuse<sup>11</sup> these metrics into a single score:

$$CL_{score} = \sum_{i=1}^{\#C} w_i c_i \tag{10}$$

where

- $c_i \in [0,1]$ : avg. of r runs of  $c_i$ , assigned a weight  $w_i \in [0,1]$  s.t.  $\sum_{i=1}^{C} w_i = 1$
- As each  $c_i$ , the final  $CL_{score}$ :
  - $\bullet \ \in [0,1]$
  - is to be maximized
  - can rank CL strategies

 $<sup>^{11}</sup>$ Drawing inspiration from the standard Multi-Attribute Value Theory (MAVT)[Ishizaka and Nemery, 2013, Keeney and Raiffa, 1993]

The avg. of the std. deviations from all previous criteria  $c_i$ :

$$CL_{stability} = 1 - \sum_{i=1}^{\#C} w_i \sigma_{c_i}$$
 (11)

- $c_i \in [0,1]$ : avg. of r runs assigned a weight  $w_i \in [0,1]$  s.t.  $\sum_i^{\mathcal{C}} w_i = 1$
- $\sigma_{c_i}$ : std. deviation of criterion  $c_i$



#### **Experiments: Dataset and Baselines**

Dataset: iCIFAR-100: each of the 10 tasks: a training batch of 10 disjoint classes

#### Baselines:

- Naïve strategy (Lower bound): starts at Tr<sub>1</sub> and learns continuously the coming training sets Tr<sub>2</sub>,..., Tr<sub>N</sub> simply tuning the model across batches<sup>12</sup>.
- Cumulative strategy (Upper bound): starts from scratch every time, learning from the accumulation of  $Tr_1, ..., Tr_{i-1}, Tr_i$  retrained with the patterns from the current batch and all previous batches<sup>13</sup>.

#### CL strategies<sup>14</sup>:

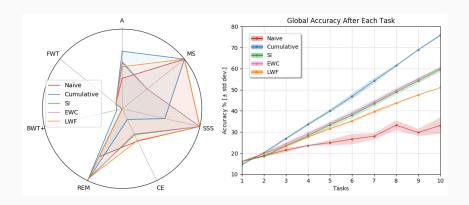
- Elastic Weight Consolidation (EWC)
- Synaptic Intelligence (SI)
- Learning without Forgetting (LwF)

<sup>&</sup>lt;sup>12</sup>Without any specific mechanism to control forgetting, except early stopping.

<sup>&</sup>lt;sup>13</sup>Only in this approach we assume all previous data can be stored and reused.

<sup>&</sup>lt;sup>14</sup>EWC [Kirkpatrick et al., 2016], SI [Zenke et al., 2017], LwF [Li and Hoiem, 2016].

#### Experiments: Accuracy per CL strategy computed over the fixed test set



- The larger the area under the CL algorithm curve,
  - $\rightarrow$  the highest (more optimal)  $\mathit{CL}_{\mathit{score}}$  is.
- The farther away from the cumulative (blue) surface,
  - ightarrow the larger room for improvement

## Experiments<sup>15</sup>

Strategy/CL Metric	$CL_{score}$			$CL_{stability}$			
	$W_1$	$W_2$	$W_3$	$W_1$	$W_2$	$W_3$	
Naïve	0.5140	0.5529	0.5312	0.9986	0.9969	0.9973	
Cumulative	0.5128	0.6223	0.5373	0.9979	0.9976	0.9964	
EWC	0.4894	0.6449	0.5816	0.9972	0.9976	0.9940	
LWF	0.5768	0.6554	0.6030	0.9986	0.9990	0.9972	
SI	0.4861	0.6372	0.5772	0.9970	0.9945	0.9927	

Three weight configurations  $W = [w_A, w_{MS}, w_{SSS}, w_{CE}, w_{BWT^+}, w_{REM}, w_{FWT}]$ :

- $W_1$ :  $w_i = \frac{1}{\#\mathcal{C}}$
- $W_2 = [0.4, 0.1, 0.1, 0.1, 0.2, 0.05, 0.05]$
- $W_3 = [0.4, 0.05, 0.2, 0.2, 0.05, 0.05, 0.05]$

 $<sup>^{15}</sup>$ Same CNN model as in [Zenke et al., 2017, Maltoni and Lomonaco, 2018] (4 conv. + 2 FC layers)

## Experiments<sup>16</sup>

CL metrics for each CL strategy (higher is better)

Str.	Α	REM	$BWT^+$	FWT	MS	SSS	CE	CL <sub>score</sub>	$CL_{stability}$
Naï	0.3825	0.6664	0.0000	0.1000	1.0000	1.0000	0.4492	0.5140	0.9986
Cum	0.7225	1.0000	0.0673	0.1000	1.0000	0.5500	0.1496	0.5128	0.9979
EWC	0.5940	0.9821	0.0000	0.1000	0.4000	1.0000	0.3495	0.4894	0.9972
LWF	0.5278	0.9667	0.0000	0.1000	1.0000	1.0000	0.4429	0.5768	0.9986
SI	0.5795	0.9620	0.0000	0.1000	0.4000	1.0000	0.3613	0.4861	0.9970

 $<sup>\</sup>overline{^{\mathbf{16}}\mathsf{U}}\mathsf{sing}\ W_{\mathbf{1}}: w_i = \frac{\mathbf{1}}{\#\mathcal{C}}$ 

#### **Future Work**

- Provide more insights to assess:
  - importance of different metric schemes
  - their entanglement
- How to use metrics wisely to assist choosing among algorithms?
- Evolve & extend metrics beyond classification
- More datasets<sup>17</sup>, tasks, ...
- Adoption (!)



CORe50 CL Dataset https://vlomonaco.github.io/core50/ [Lomonaco and Maltoni, 2017]

#### Thank you!

Join! https://www.continualai.org/
Slack channel: https://continualai.herokuapp.com/





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