Ali Marjaninejad

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Education

Ph.D., Biomedical Engineering

GPA: 3.95/4.0

M.Sc., Electrical Engineering (Data science)

GPA: 3.88/4.0

M.Sc., Biomedical Engineering (Bioelectrics)

GPA: 4.0/4.0

B.Sc., Electrical Engineering (Bioelectrics)

GPA: 3.83/4.0 (Junior/Senior: 3.96/4.0)

University of Southern California (USC)

Fall 2021

University of Southern California (USC)

Fall 2017

Amirkabir University of Technology (AUT)

Spring 2015

Sahand University of Technology (SUT)

Spring 2012

Honors & Awards

- Being featured on the cover of the march 2019 issue of the *nature machine intelligence* and one of the only two research articles being featured on its *one* year anniversary special collection
- Appeared on more than 80 news outlets including the Wired magazine, PCMage, and VoAe for research contributions
- USC Stevens center for innovation's "Best Commercial Potential" award for the work done on bio-inspired autonomous robots (2019)
- USC Provost's fellowship; the most prestigious fellowship at USC (2015 2019)
- USC Grad. School's Research Advancement fellowship recipient; The most competitive project award at USC (2018 2019)
- Society for Brain Mapping & Therapeutics (SBMT) and Brain Mapping Foundation Student Outstanding Leadership and Service Award (2019)
- USC Viterbi BME Best Research Assistant award (2021)
- USC Viterbi BME Jenny Wang Excellence in Teaching Awards (2021)
- USC Grad. Student Government's International Student Recognition Award (2018)
- Finalist in Maseeh Entrepreneurship Prize Competition, USC Stevens Innovation Awards, and the Creating Reality Hackathon (Won the Sponsor award)
- Featured on USC news for instructing MATLAB classes for students in the SHINE program (2016)
- Honor student privilege package award (Iran ministry of science and technology 2012)
- Awarded the Certificate of Appreciation from the Deputy Minister of Science for my active role in the "Bioelectric" journal (awarded as the best national student journal of the year – Iran, 2009)

Publications

Refereed full-length Articles

- "insideOut: A Bio-Inspired Machine Learning Approach to Estimating Posture in Robots Driven by Compliant Tendons" | Daniel A Hagen, Ali Marjaninejad, Gerald Eli Loeb, Francisco J Valero-Cuevas | Frontiers in Neurorobotics, 2021
- 2. "Data-Efficient Causal Decoding of Spiking Neural Activity Using Weighted Voting" | Ali Marjaninejad, Christian Klaes, Francisco Valero-Cuevas | 43th Annual International Conference of the IEEE Engineering in Medicine and Biology Society (IEEE EMBC), 2021
- 3. "Estimating Center of Pressure of a Bipedal Mechanism Using a Proprioceptive Artificial Skin around its Ankles" | Darío Urbina-Meléndez, Jiaoran Wang, Daniel Wang, Ali Marjaninejad, Francisco Valero-Cuevas | 43th Annual International Conference of the IEEE Engineering in Medicine and Biology Society (IEEE EMBC), 2021
- 4. "Autonomous functional movements in a tendon-driven limb via limited experience" | A. Marjaninejad, D. Urbina-Meléndez, B. A. Cohn, and F. J. Valero-Cuevas | *Nature Machine Intelligence*, vol. 1, no. 3, pp. 144–154, 2019.
- 5. "A Bio-Inspired Framework for Joint Angle Estimation from Non-Collocated Sensors in Tendon-driven Systems" | Hagen DA, Marjaninejad A, Valero-Cuevas FJ / IEEE International Conference on Intelligent Robots and Systems (IEEE IROS), 2020
- **6.** "Autonomous Control of a Tendon-driven Robotic Limb with Elastic Elements Reveals that Added Elasticity can Enhance Learning" | Marjaninejad A, Tan J, Valero-Cuevas FJ | 42th Annual International Conference of the IEEE Engineering in Medicine and Biology Society (IEEE EMBC), 2020
- 7. "Simple Kinematic Feedback Enhances Autonomous Learning in Bio-Inspired Tendon-Driven Systems" | Marjaninejad A, Urbina-Meléndez D, Valero-Cuevas FJ | 42th Annual International Conference of the IEEE Engineering in Medicine and Biology Society (IEEE EMBC), 2020
- 8. "Blood Glucose Regulation Using Adaptive Fuzzy Sliding Mode Control in Type I Diabetic Patients" | M Khazaei, A Geramipour, S Sadat-Hosseini, A Marjaninejad | International Journal of Mechatronics, Electrical and Computer Technology (IJMEC), 2018
- 9. "Model-Free Control of Movement in a Tendon-Driven Limb via a Modified Genetic Algorithm" | A Marjaninejad, R Annigeri, FJ Valero-Cuevas | Proceedings of the Annual International Conference of the IEEE Engineering in Medicine and Biology Society, (IEEE EMBC), 2018
- 10. "An Analytical Approach to Posture-Dependent Muscle Force and Muscle Activation Patterns" | A Marjaninejad, J Berry, FJ Valero-Cuevas | Proceedings of the Annual International Conference of the IEEE Engineering in Medicine and Biology Society, (IEEE EMBC), 2018
- 11. "Finger movements are mainly represented by a linear transformation of energy in band-specific ECoG signals" | A Marjaninejad, B Taherian, FJ Valero-Cuevas | Proceedings of the Annual International Conference of the IEEE Engineering in Medicine and Biology Society, (IEEE EMBC), 2017.

- 12. "A Radial Basis Function Neural Network approximator with fast terminal sliding mode-based learning algorithm and its application in control systems" | M Khazaei, H Sadat-Hosseini, A Marjaninejad, S Daneshvar | Iranian Conference on Electrical Engineering (IEEE ICEE), 2017
- 13. "A model-based exploration of the role of pattern generating circuits during locomotor adaptation" | A. Marjaninejad and J. M. Finley | Proceedings of the Annual International Conference of the IEEE Engineering in Medicine and Biology Society, (IEEE EMBC), 2016.
- 14. "Online signal to noise ratio improvement of ECG signal based on EEMD of synchronized ECG beats" | A Marjaninejad, F Almasganj, AJ Sheikhzadeh | Iranian Conference on Biomedical Engineering (IEEE ICBME), 2014
- 15. "A low-cost real-time wheelchair navigation system using electrooculography" | A Marjaninejad, S Daneshvar | Iranian Conference on Electrical Engineering (IEEE ICEE), 2014
- 16. "Design of FPGA-based Digital PID controller using Xilinx SysGen® for regulating blood glucose level of type-i diabetic patients" | A Geramipour, M Khazaei, A Marjaninejad, M Khazaei | International Journal of Mechatronics, Electrical and Computer Technology (IJMEC), 3 (7), 56-69, 2013

Refereed Book Chapters

1. "Should Anthropomorphic Systems be 'Redundant,'?" | A Marjaninejad, FJ Valero-Cuevas | Biomechanics of Anthropomorphic Systems, Springer Tracts in Advanced Robotics (STAR) series, Springer, 2019

Under-review (full-length papers)

1. Biological Underpinnings for Lifelong LearningMachines | Dhireesha Kudithipudi et. al. | Nature Machine Intelligence, 2021

Non-refereed full-length publications

- "Quantifying and attenuating pathologic tremor in virtual reality." | Cohn, Brian A., Dilan D. Shah, Ali Marjaninejad, Martin Shapiro, Serhan Ulkumen, Christopher M. Laine, Francisco J. Valero-Cuevas, Kenneth H. Hayashida, and Sarah Ingersoll | ArXiv preprint ID arXiv:1809.05970 (2018)
- 2. "The utility of tactile force to autonomous learning of in-hand manipulation is task-dependent" | Mir, Romina, A Marjaninejad, FJ Valero-Cuevas | ArXiv Preprint ID arXiv:2002.02418, 2020

Refereed Conference/Workshop abstracts

- 1. The ability of musculotendons to undergo eccentric contractions is a critical enabler of learning for the control of movement | Ali Marjaninejad, D Urbina-Meléndez, BA Cohn, FJ Valero-Cuevas | The Society for the Neural Control of Movement (NCM) conference 2021
- 2. Active sensing in a bioinspired hand as an enabler of implicit curriculum learning for manipulation | R Mir, P Ojaghi, A Marjaninejad, M Wehner, F J Valero-Cuevas | International Symposium on Adaptive Motion of Animals and Machines 2021
- 3. Autonomous Functional Movements in a tendon-driven leg via limited experience | Ali Marjaninejad, Urbina-Meléndez D, Cohn BA, Valero-Cuevas FJ | *Dynamical Walking, Canmore, Canada, 2019.*
- **4.** "Autonomous Functional Locomotor Movements in a Tendon-Driven Limb via Limited Experience" | Marjaninejad A, Urbina-Meléndez D, Cohn BA, Valero-Cuevas FJ | The 9th International Symposium on Adaptive Motion of Animals and Machines EPFL, Lausanne, 2019.
- 5. Few-shot learning of autonomous behavior in a bio-plausible hardware-software setting | Ali Marjaninejad | 15th Annual World Congress of Society for Brain Mapping and therapeutics (SBMT), Los Angeles, CA, 2019.
- **6.** "Simple and Two-Element Hill-Type Muscle Models Cannot Replicate Realistic Muscle Stiffness" | Ali Marjaninejad, Babak Taherian, Kian Jalaleddini, and Francisco J Valero-Cuevas | *The 41st American Society of Biomechanics (ASB) Conference, Boulder, CO, 2017.*

Non-refereed Conference/Workshop abstracts

- "Bioinspired few-shot learning in robotic systems" | Ali Marjaninejad, Urbina-Meléndez D, Cohn BA, Valero-Cuevas FJ | Society for Neuroscience (SfN) Conference, Chicago, IL, 2019.
- 2. "New generation of bio-inspired robots that learn and adapt using limited experience" | Ali Marjaninejad | 23th Grodins Research Symposium, Los Angeles, CA, 2019.
- "Autonomous Functional Movements in a Tendon-Driven Limb via Limited Experience" | Ali Marjaninejad | USC Biomedical Graduate Talk Series, Los Angeles, CA, 2019.
- "Using Genetic Algorithm to Control a Tendon-Driven limb" | Ali Marjaninejad, F.J. Valero-Cuevas / 22th Grodins Research Symposium, Los Angeles, CA, 2018.
- 5. "Using genetic algorithm to control tendon-driven systems with unknown structure" | Ali Marjaninejad, R. Annigeri, F.J. Valero-Cuevas | Society for Neuroscience (SfN) Conference, San Diego, CA, 2018.
- 6. Evaluating the learnability-dimensionality relationship in a tendon- driven finger" | Brian A. Cohn, A. Marjaninejad, F. J. Valero-Cuevas | Society for Neuroscience (SfN) Conference, San Diego, CA, 2018.
- 7. "A NeuRoBotic experimental system to study muscle function" | D. Urbina-Meléndez, A. Marjaninejad, B.A. Cohn, J.A. Berry, H. Zhao, F.J. Valero-Cuevas | Society for Neuroscience (SfN) Conference, San Diego, CA, 2018.
- 8. Simple and Two-Element Hill-Type Muscle Models Cannot Replicate Realistic Muscle Stiffness / Ali Marjaninejad and Francisco J Valero-Cuevas | 21th Grodins Research Symposium, Los Angeles, CA, 2017.
- 9. "A Model-based Exploration of the Role of Pattern Generating Circuits during Locomotor Adaptation." | Ali Marjaninejad, James M. Finley | Society for Neuroscience (SfN) Conference, San Diego, CA, 2016.

 "An Exploration of the Role of Pattern Generating Oscillators during Locomotor Adaptation" | Ali Marjaninejad, James M. Finley | The 20th Grodins Research Symposium, Los Angeles, CA, 2016.

Technical Articles

- "Toward A New Generation of Robots: A Bio-Inspired Tendon-Driven Robot That Teaches Itself How To Walk" ♥ | Ali Marjaninejad | wevolver com 2020
- 3. "Toward A New Generation of Robots: A Bio-Inspired Tendon-Driven Robot That Teaches Itself How to Walk" / wevolver.com, 2020

Invited Talks

- 1. On the New Generation of Bio-inspired Robots MATLAB EXPO 2019, San Jose, Ca. 2019
- 2. Bio-plausible Mechanics, Learning, and Control for Robots Google Brain / Robotics, Mountain View, Ca. 2019
- 3. Learning without forgetting in real-time with limited experience: A bio-inspired approach. | Ali Marjaninejad, S.C. Raja, F.J. Valero-Cuevas | DARPA Electronics Resurgence Initiative (ERI) Summit. Detroit, MI, July 15-17, 2019.
- 4. Learning and Control in Bio-inspired Robots Kanso Bioinspired Motion Lab, University of Southern California, Los Angeles, Ca. 2019
- 5. Experience-driven, Autonomous Learning for Robots ICAROS Lab, University of Southern California, Los Angeles, Ca. 2019.
- 6. Principles and the future of Biomedical Signal Processing (BSP) Amirkabir University of Technology, 2014.

Professional Experiences

- Postdoctoral Research Fellow at University of Southern California (2021 Current)
 - o Developing Autonomous Robotic Systems and Embodied Intelligence
- Research Assistant at Brain-Body Dynamics Lab: Exploring the neuromechanics of the hand and its representation in human cortex (2016 present)
 - o Finding sensory motor representations on human brain in EEG, ECoG, and Single Unit Activity (SUA) signals
 - Showed that a linear mapping can efficiently describe the relationship between finger positions (joint angles) and signal power in different frequency bands of ECoG recordings
 - Used Genetic Algorithm (GA) to find optimal tendon excursion values in a tendon-driven robotic limb (with unknown parameters) to follow a desired trajectory and ML to control the over- and under-determined robotic systems
 - Addressed the long-standing problem of redundancy in the anthropomorphic neuromechanics using optimization and dimensional reduction approaches
 - $\circ \ \ Developed \ the \ Neuromechanics \ toolbox \ in \ MATALB \ environment \ as \ a \ complementary \ toolbox \ for \ the \ book: Fundamentals \ of \ Neuromechanics$
 - Led two groups of interns in hardware and software development projects; resulted in peer-reviewed publications and raising research grant funding
- A.I. Residency offer from Google X (2019)
- Internship as a Data Scientist at Neural Analytics (Summer 2018)
 - i. Worked on algorithms to improve the search speed and efficiency of the robotic brain scanner
 - ii. Designed machine learning protocols to enable robotic system to make data driven clinical decisions
- Trained in Computational Sensory Motor Neuroscience (CoSMo) and Health Data Exploration (HDE) summer schools (2017, 2018)
 - o Received competitive, merit-based fellowships to attend each program
 - \circ Trained to work with bigdata, neural data, and health related data by the most famous leaders of the field
- Research Assistant at Intelligent Signal and Data Processing Lab: Biological and Array Signal Processing (2012 2015)
 - Used SVM and Neural Network regressors to predict the direction of arrival of a sound wave to a microphone array system
 - Collected a database of microphone array recordings using Persian vocabulary and implemented a MATLAB toolbox that increased speech recognition ratio using beamforming; the project was later integrated successfully in industry
- Internship at the MRI section of the exclusive service provider for the General Electric Healthcare in Iran (Pishrafteh Co., 2011)
 - o Contributed to both hardware and software Installation, repair, and maintenance
 - o Mastered the general principles of physics of imaging modalities especially the MRI

Teaching Experiences

- Course Instructor
 - Electronics I Laboratory (at AUT)
 - o Electrical Circuits Laboratory (at AUT)
 - Microprocessors Laboratory (at AUT)
- Teaching Assistantships
 - o BME/BKN 504 Neuromuscular Systems (at USC) | Supervisor: Dr. Francisco J. Valero-Cuevas

- BME 423 Statistical Methods in Biomedical Engineering (at USC) / Supervisors: Dr. David Z. D'Argenio and Dr. Brittany P. Kay
 BME 404 Orthopedic Biomechanics (at USC) / Supervisor: Dr. Edward Ebramzadeh
 Digital Signal Processing (at AUT) / Supervisor: Dr. Farshad Almasganj
 Microprocessors (at AUT) / Supervisor: Dr. Farshad Almasganj
- Workshop Instructor

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- o Introduction to MATLAB (at SUT, AUT, and USC)
- Pspice Electronic Circuit Optimization & Simulation Software (SUT)

Signals and Systems (at SUT) | Supervisor: Dr. Mousa Shamsi

Biostatistics (at AUT) | Supervisor: Dr. Mousa Shamsi

- Advanced MATLAB Courses (at SUT and AUT):
 - Neural Networks Fuzzy Inference Systems Genetic Algorithm
 - Digital Signal Processing
 Digital Image Processing
 Adaptive Neuro-fuzzy Inference Systems
- How to prepare an academic publication using Endnote and MS-Word (at AUT)

Professional Skills

- Programming Languages
 - MATLAB
 Python
 C
 C++
 VHDL
 Assembly
- Other Engineering software packages
 - ROS
 ModelSim
 CodeVision (AVR)
 Pspice
 Chart (ADinstruments)
 Protel
 Xilinx ISE (FPGA)
 Proteus
- General software packages
 - Microsoft Office (Word, Excel, PowerPoint)
 Latex
 Mendeley

Professional Certificates

- Graduate Certificate in Health, Technology and Engineering from the Health, Technology, and Engineering Program (HTE*) at USC, May 2019
- Data Scientist with Python accomplishment certificate, DataCamp[®], August 2020
- ISO 13485 Internal audit training certificate, Oxfordcert[₱]. Registration Number: TIA1331509010

Services and Memberships

- Assistant editor of Paladyn, Journal of Behavioral Robotics De Gruyter
- · Review Editor in Frontiers of Robotics and AI
- President of the student branch of the Society for Brain Mapping & Therapeutics (SBMT) at USC (2018-2019)
- Chairing the "Biorobotics and Biomechanics & Computational Systems & Synthetic Biology; Multiscale modeling" session at IEEE EMBC (2018)
- Vice president of the organizing committee for the Grodins conference (2018)
- Vice president of the Iranian Graduate Student Association (IGSA)[®] at USC (2016)
- Editor of the Student Journal of Biomedical Engineering at Amirkabir University of Technology (2014)
- IEEE Student member
- · Society for Neuroscience (SfN) student member
- American Society of Biomechanics (ASB) student member

Languages

English (Fluent)
 Persian (Native)
 Turkish (Native)