

# AI – Machine Learning

## Artificial Intelligence Research Group



# Posterior Distribution

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- Markov Chain Monte Carlo (MCMC)
- Variational Inference

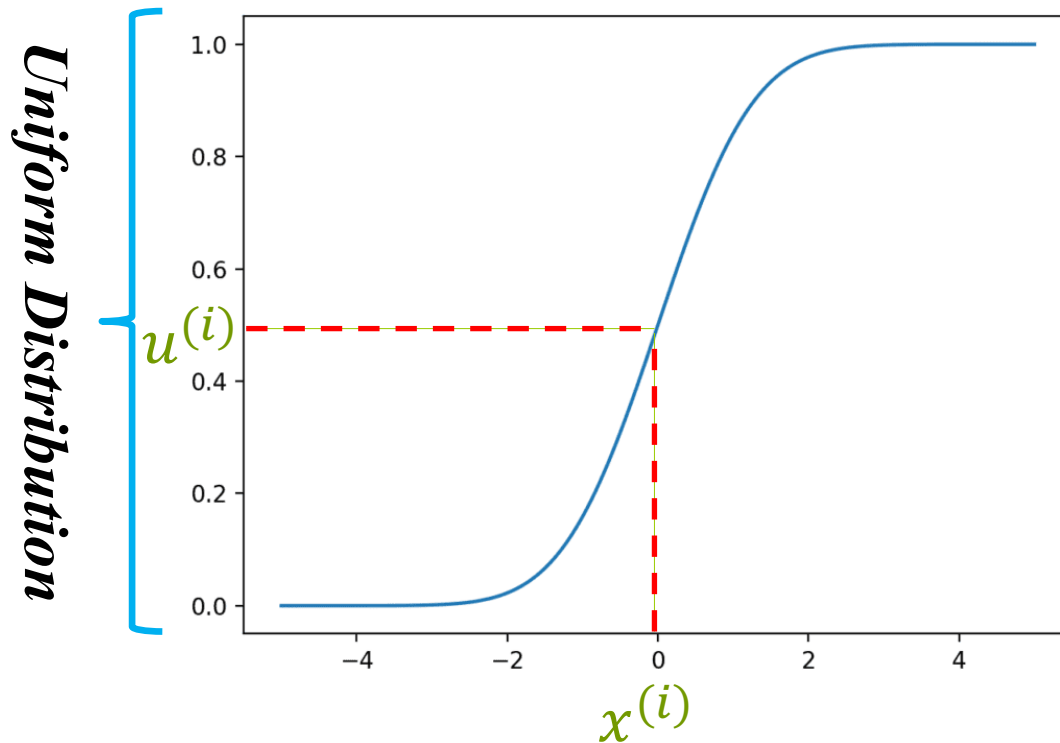
$$p(\theta|x) \propto \underbrace{p(x|\theta)p(\theta)}$$

$$\mathcal{N}(\mu|\hat{\mu}_0, \hat{\sigma}_0^2) \propto \mathcal{N}(x|\mu, \sigma^2) \mathcal{N}(\mu|\mu_0, \sigma_0^2)$$

*Conjugate distribution*

$$\hat{\theta} = \frac{1}{N} \sum_{i=1}^N \theta^{(i)}$$

# Cumulative Distribution Function

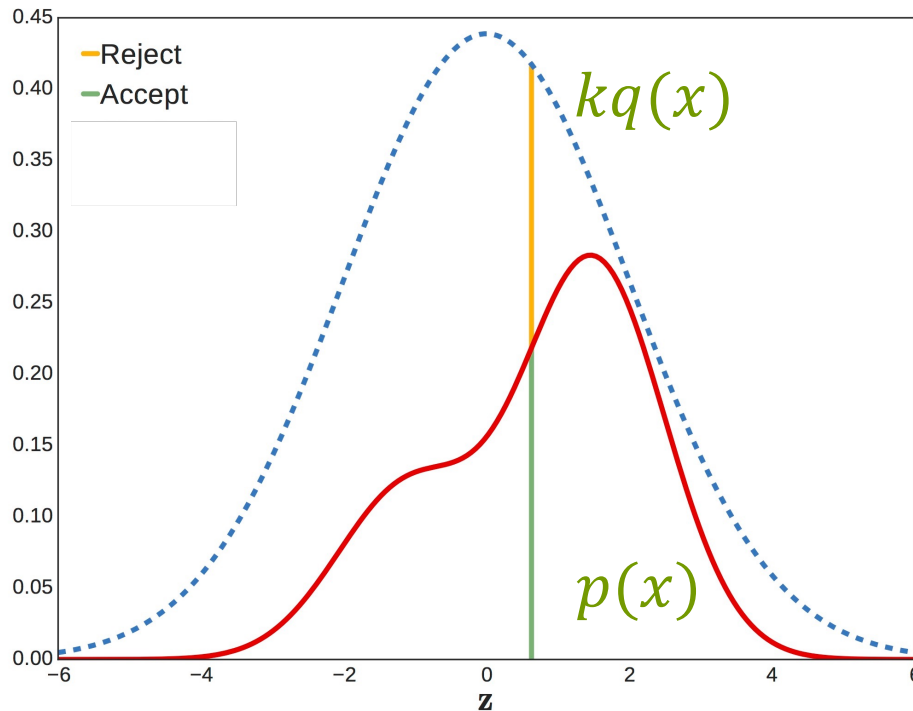


$$\text{cdf}(x) = \int_{-\infty}^t p(t) dt$$

$$u \sim \mathcal{U}(0,1)$$

$$x \sim \text{cdf}^{-1}(u)$$

# Rejection Sampling



**While**  $i \neq N$

$x^{(i)} \sim q(x)$  and  $u \sim \mathcal{U}(0,1)$

**if**  $u < \frac{p(x^{(i)})}{kq(x^{(i)})}$  **then**

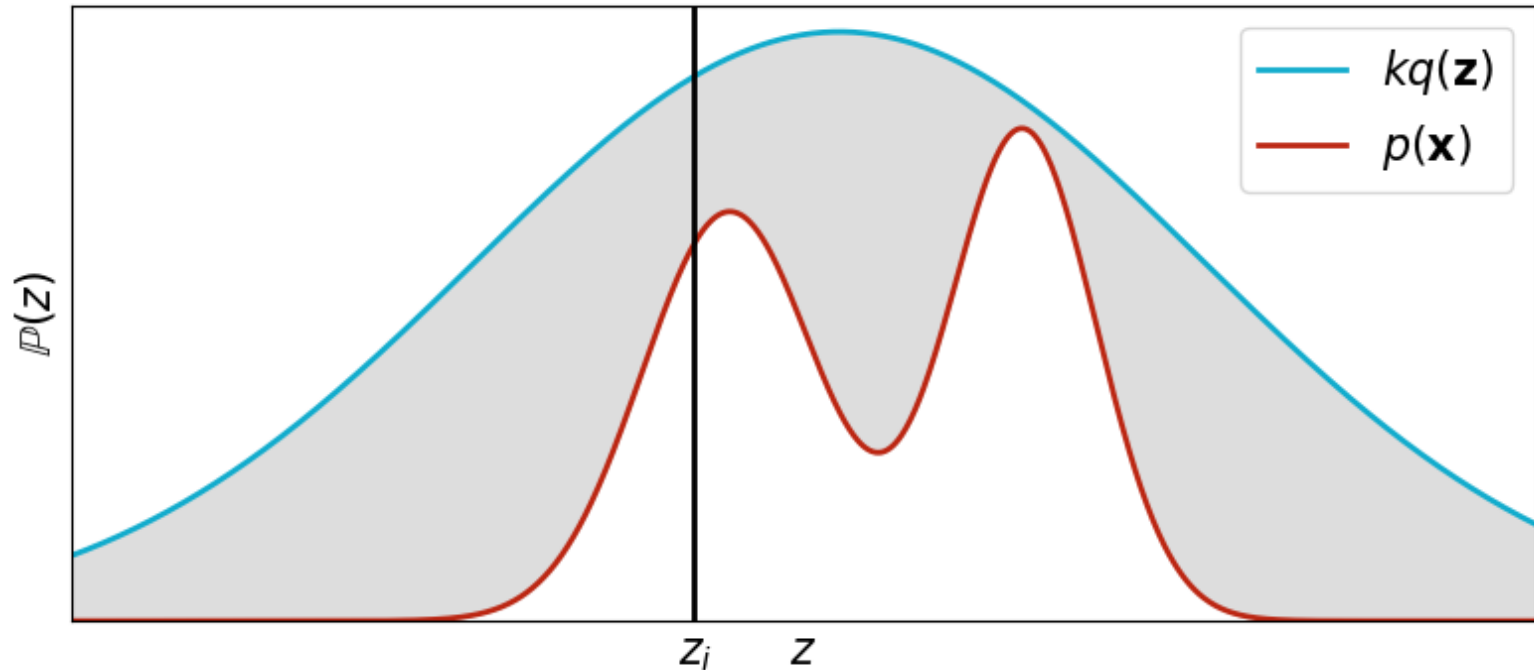
**accept**  $x^{(i)}$

$i = i + 1$

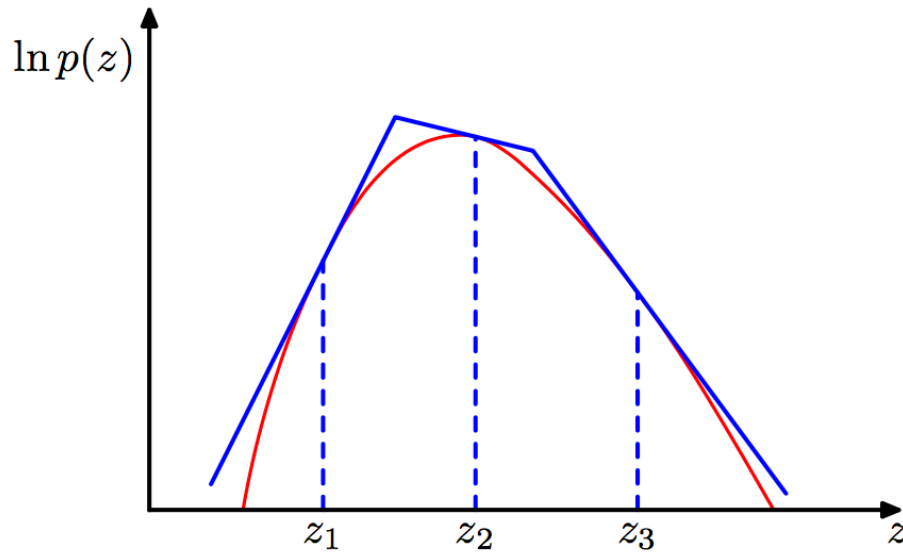
**else**

**reject**  $x^{(i)}$

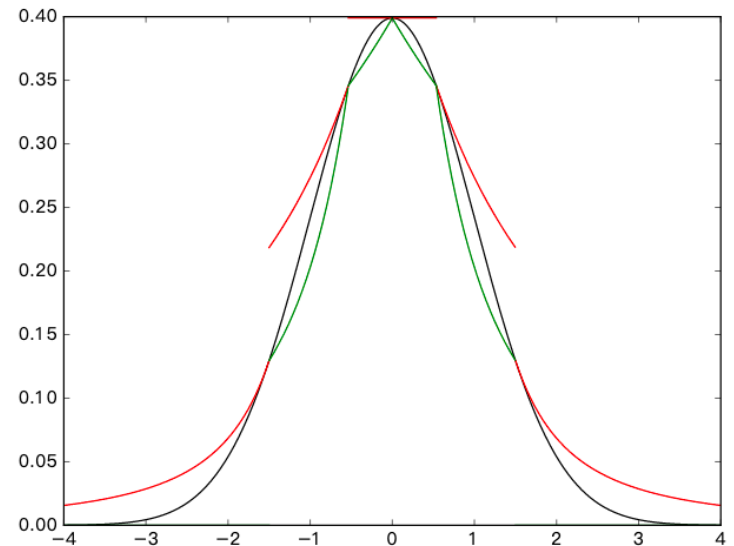
# Efficiency of sampling



# Piece-wise Exponential Distribution



The distribution  $p(x)$  is  
log-concave function



# Importance Sampling

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$$E_{p(x)}[f(x)] = \int_x f(x)p(x)dx \quad x \sim p(x)$$

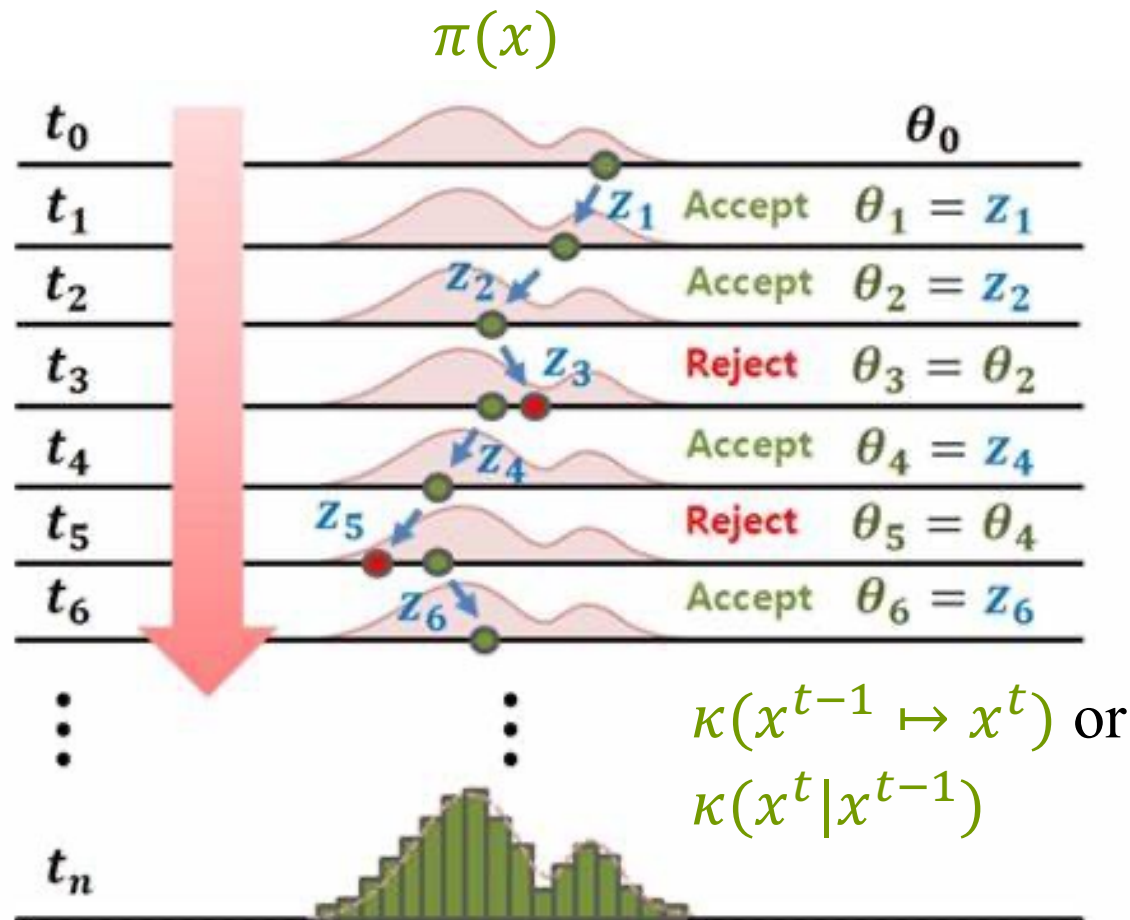
$$\hat{E}_{p(x)}[f(x)] = \frac{1}{N} \sum_{i=1}^N f(x^{(i)})$$

$$E[f(x)] = \int_x \frac{f(x)p(x)}{q(x)} q(x)dx \quad x \sim q(x)$$

$$\hat{E}_{q(x)}[f(x)] = \frac{1}{N} \sum_{i=1}^N f(x^{(i)}) \underbrace{\frac{p(x^{(i)})}{q(x^{(i)})}}_{\text{Weight}}$$

*Weight*

# Markov Chain Monte Carlo







# Chapman-Kolmogorov Equation

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$$\pi_t(x^*) = \int_x \pi_{t-1}(x) \kappa(x^*|x) dx$$

$$p(y) = \int_x \underbrace{p(x)p(y|x)}_{p(x,y)} dx$$

$$\pi(x^*) = \int_x \pi(x) \kappa(x^*|x) dx \quad \text{since } \pi_t(x^*) = \pi_{t-1}(x)$$

*not necessarily*   *imply*

$$\pi(x) \kappa(x^*|x) = \pi(x^*) \kappa(x|x^*) \quad \text{\textit{The detailed balance}}$$

$$\begin{aligned} \int_x \pi(x) \kappa(x^*|x) dx &= \int_x \pi(x^*) \kappa(x|x^*) dx = \pi(x^*) \underbrace{\int_x \kappa(x|x^*) dx}_{=1} \\ &= \pi(x^*) \end{aligned}$$

# Metropolis-Hastings Sampling

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**Initialize**  $x^{(0)}$

**For**  $i = 0$  **to**  $N - 1$

$x^* \sim q(x^* | x^{(i)})$  and  $u \sim \mathcal{U}(0,1)$

**if**  $u < \alpha(x^*) = \min \left( 1, \frac{\pi(x^*)q(x|x^*)}{\pi(x)q(x^*|x)} \right)$  **then**

$x^{(i+1)} = x^*$

**else**

$x^{(i+1)} = x^{(i)}$

# Metropolis-Hastings Sampling

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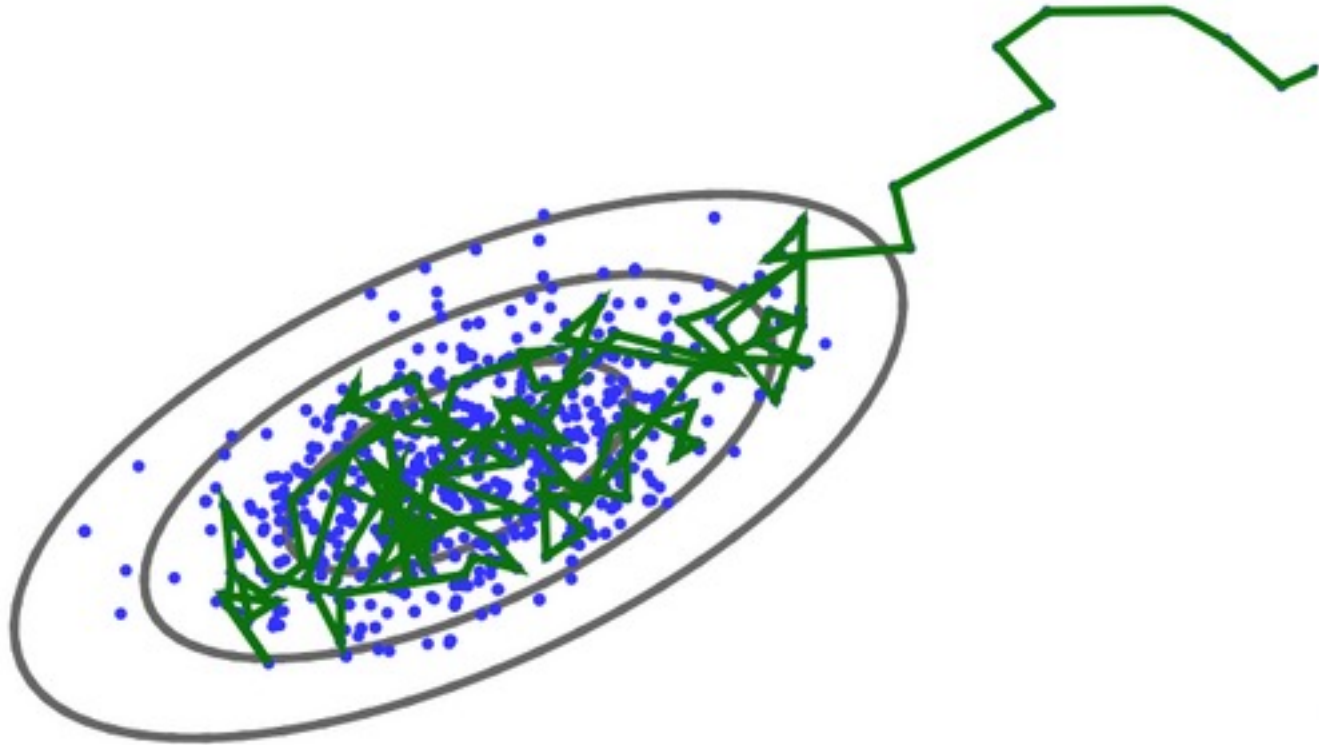
$$\pi(x) \kappa(x^*|x) = \pi(x^*) \kappa(x|x^*) \quad \textit{The detailed balance}$$

$$\begin{aligned} & \underbrace{\pi(x) \kappa(x^*|x)}_{\pi(x) q(x^*|x)} \cdot \min \left( 1, \frac{\pi(x^*) q(x|x^*)}{\pi(x) q(x^*|x)} \right) \\ &= \min(\pi(x) q(x^*|x), \pi(x^*) q(x|x^*)) \\ &= \pi(x^*) q(x|x^*) \min \left( \frac{\pi(x) q(x^*|x)}{\pi(x^*) q(x|x^*)}, 1 \right) \\ &= \pi(x^*) \kappa(x|x^*) \end{aligned}$$

A good choice of  $q(x^*|x)$ :  $\frac{\partial \log p(x)}{\partial x} = \frac{p'(x)}{p(x)}$

# An Example of MH Sampling

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# Gibbs Sampling

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$$f(x, y, z)$$

$$X^{(1)} = (x^{(1)}, y^{(1)}, z^{(1)})$$

$$x^{(2)} = p(x|y^{(1)}, z^{(1)})$$

$$y^{(2)} = p(y|x^{(2)}, z^{(1)})$$

$$z^{(2)} = p(z|x^{(2)}, y^{(2)})$$

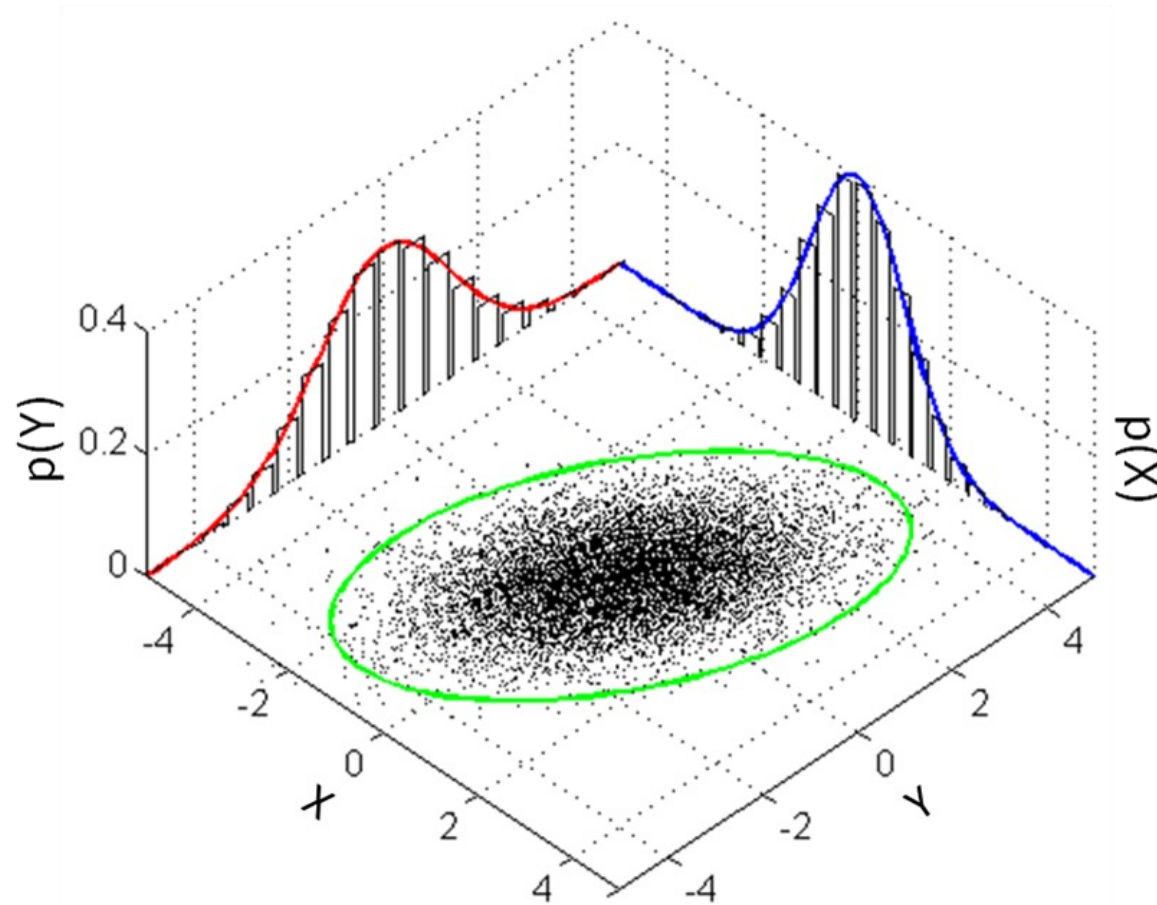
$$f(x, y, z, u)$$

$$u \sim p(u|x, y, z)$$

$$p(x, y, z|u)$$

$$= p(x|u)p(y|u)p(z|u)$$

# An Example of Gibbs Sampling



# Any question?



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