
Anaconda Tutorial

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2024年9月9日星期一

Outline

- Introduction: What is Anaconda?
- Install in your computer

What is Anaconda?

Anaconda is a distribution that provides easy access to and management of packages, and unified management of environments.

Anaconda includes over 180 scientific packages and their dependencies, including conda, Python, and more.



ANACONDA®

Install Anaconda in your computer

Anaconda介绍、安装及使用教程

(<https://zhuanlan.zhihu.com/p/32925500>)



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PyTorch Tutorial

Outline

- Background: Prerequisites & What is Pytorch?
- Training & Testing Neural Networks in Pytorch
- Dataset & Dataloader
- Tensors
- torch.nn: Models, Loss Functions
- torch.optim: Optimization
- Save/load models

Prerequisites

- We assume you are already familiar with...

1. Python3

- if-else, loop, function, file IO, class, ...
- refs: [link1](#), [link2](#), [link3](#)

2. Deep Learning Basics

- ref: [link1](#), [link2](#)



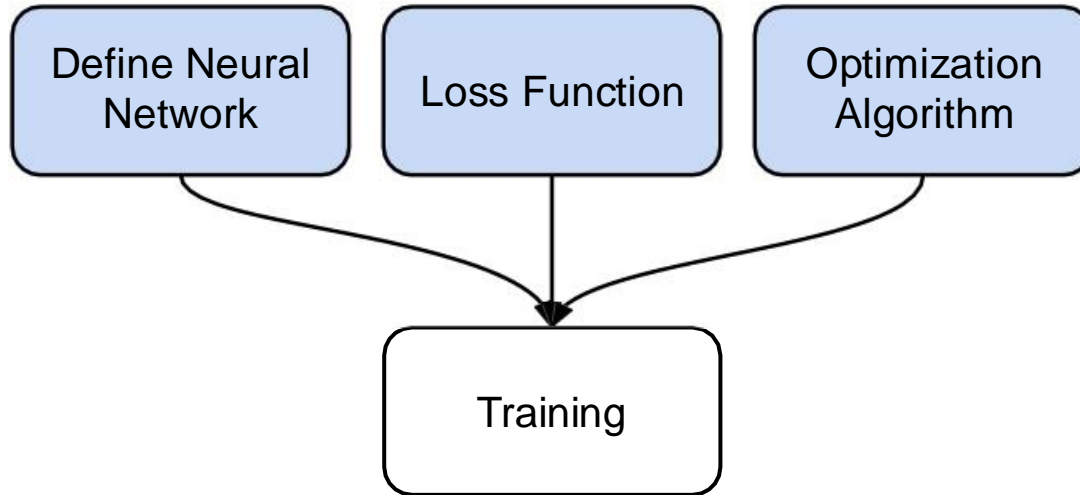
Some knowledge of **NumPy** will also be useful!

What is PyTorch?

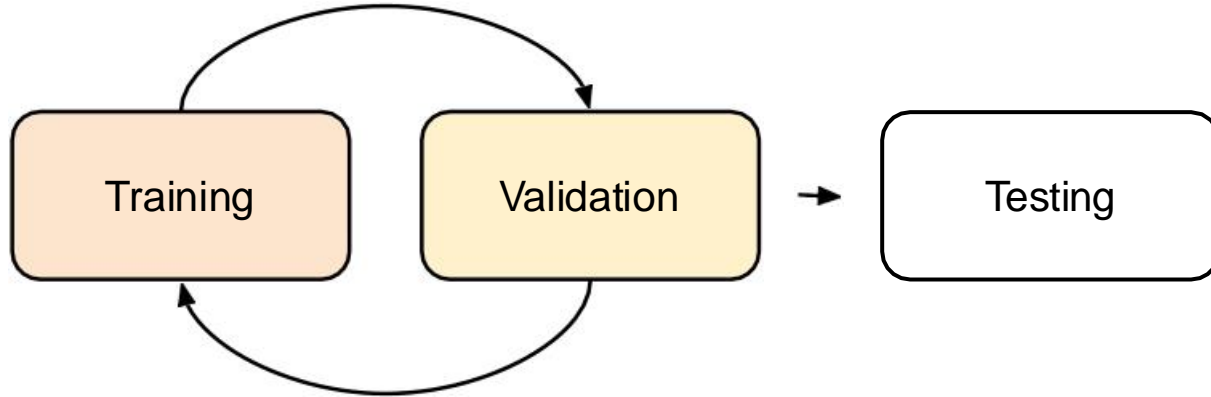
- An **machine learning framework** in Python.
- Two main features:
 - N-dimensional **Tensor** computation (like NumPy) on **GPUs**
 - **Automatic differentiation** for training deep neural networks



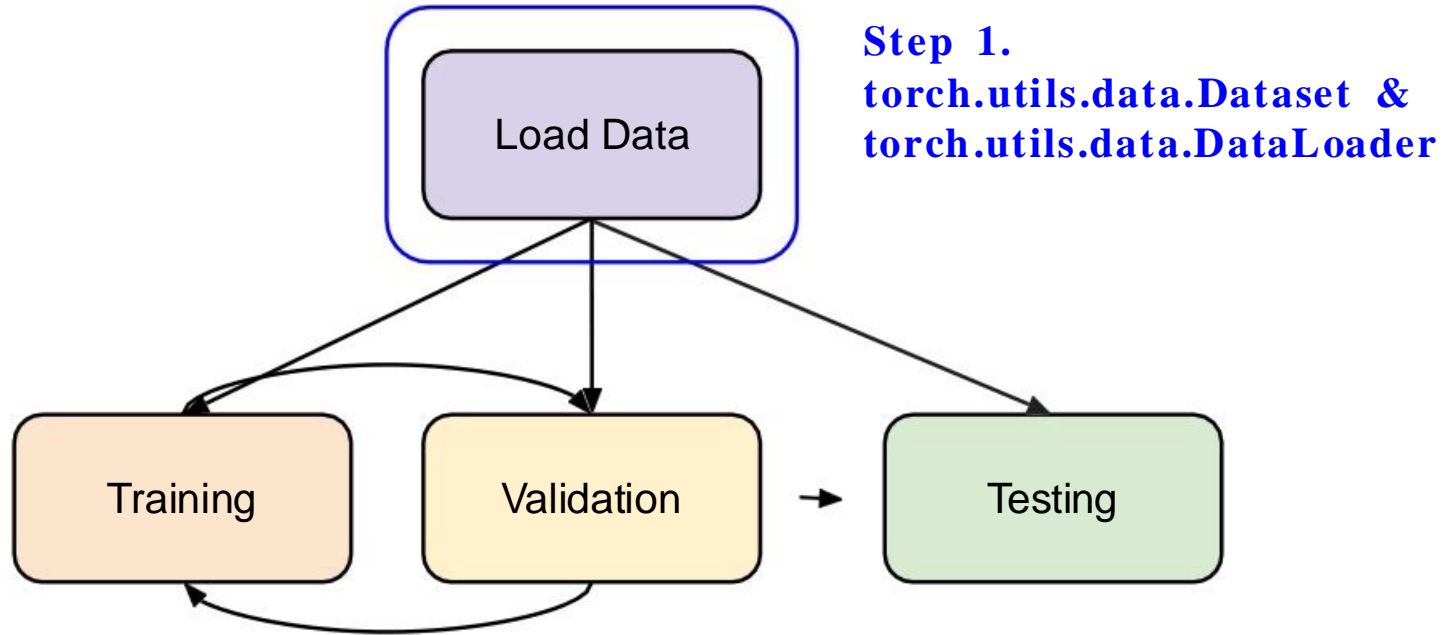
Training Neural Networks



Training & Testing Neural Networks



Training & Testing Neural Networks - in Pytorch



Dataset & Dataloader

- Dataset: stores data samples and expected values
- Dataloader: groups data in batches, enables multiprocessing
- `dataset = MyDataset(file)`
- `dataloader = DataLoader(dataset, batch_size, shuffle=True)`

↑
Training: True
Testing: False

Dataset & Dataloader

```
from torch.utils.data import Dataset, DataLoader
```

```
class MyDataset(Dataset):
```

```
    def init (self, file):  
        self.data = ...
```



Read data & preprocess

```
    def __getitem__(self, index):  
        return self.data[index]
```



Returns one sample at a time

```
    def __len__(self):  
        return len(self.data)
```

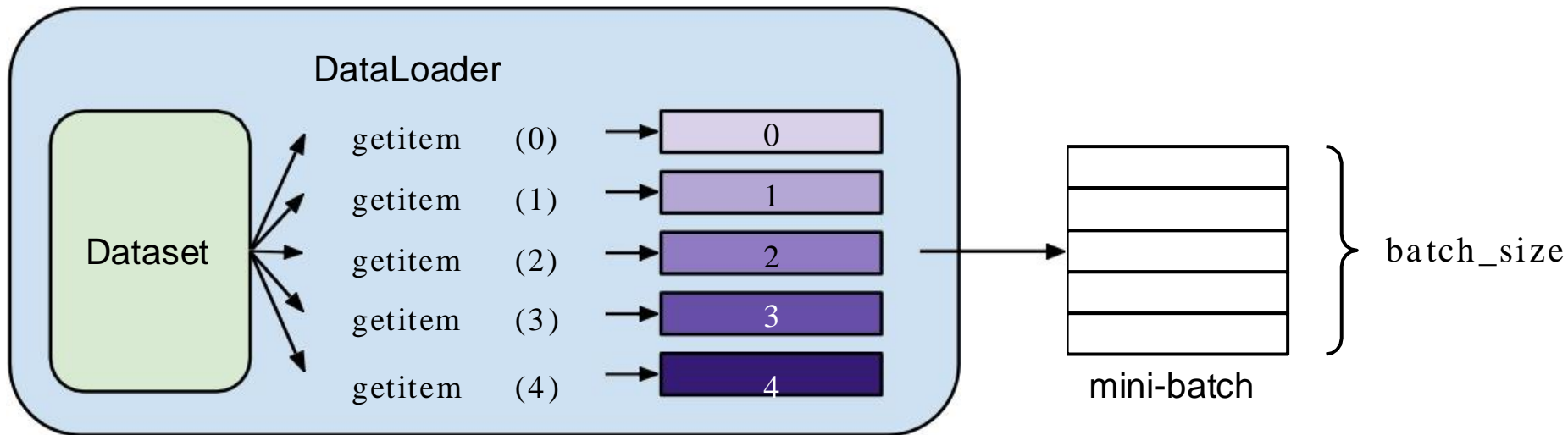


Returns the size of the dataset

Dataset & Dataloader

```
dataset = MyDataset(file)
```

```
dataloader = DataLoader(dataset, batch_size=5, shuffle=False)
```

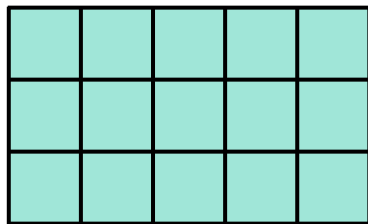


Tensors

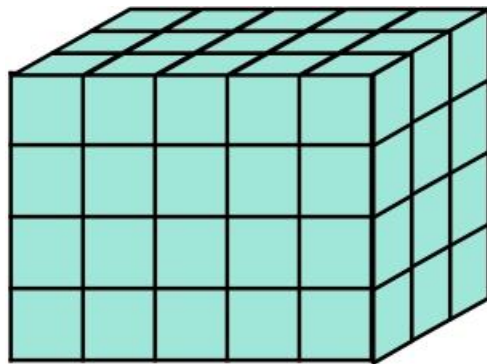
- High-dimensional matrices (arrays)



1-D tensor
e.g. audio



2-D tensor
e.g. black&white
images



3-D tensor
e.g. RGB
images

Tensors – Shape of Tensors

- Check with `.shape`

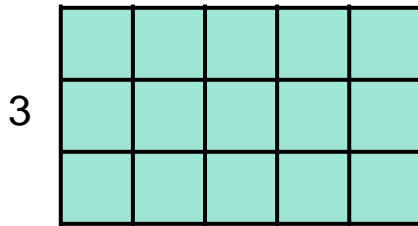


5

(5,)



dim 0



3

5

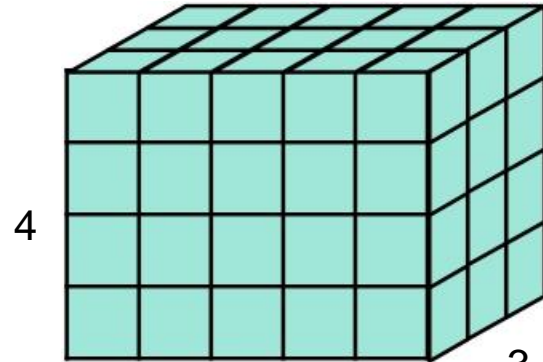
(3, 5)



dim 0



dim 1



4

5

3

(4, 5, 3)



dim 0



dim 1



dim 2

Note: **dim** in PyTorch == **axis** in NumPy

Tensors – Creating Tensors

- Directly from data (list or numpy.ndarray)

```
x = torch.tensor([[1, -1], [-1, 1]])
```

```
x = torch.from_numpy(np.array([[1, -1], [-1, 1]]))
```

```
tensor([[1., -1.],  
        [-1., 1.]])
```

- Tensor of constant zeros & ones

```
x = torch.zeros([2, 2])
```

```
x = torch.ones([1, 2, 5])
```



shape

```
tensor([[0., 0.],  
        [0., 0.]])
```

```
tensor([[[[1., 1., 1., 1., 1.],  
          [1., 1., 1., 1., 1.]]]])
```

Tensors – Common Operations

Common arithmetic functions are supported, such as:

- Addition

$$z = x + y$$

- Summation

$$y = x.\text{sum}()$$

- Subtraction

$$z = x - y$$

- Mean

$$y = x.\text{mean}()$$

- Power

$$y = x.\text{pow}(2)$$

Tensors – Common Operations

- **Transpose:** transpose two specified dimensions

```
>>> x = torch.zeros([2, 3])
```

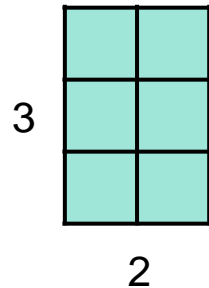
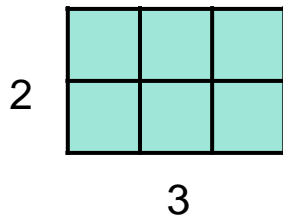
```
>>> x.shape
```

```
torch.Size([2, 3])
```

```
>>> x = x.transpose(0, 1)
```

```
>>> x.shape
```

```
torch.Size([3, 2])
```



Tensors – Common Operations

- **Squeeze:** remove the specified dimension with length = 1

```
>>> x = torch.zeros([1, 2, 3])
```

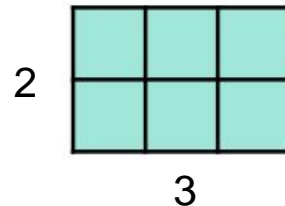
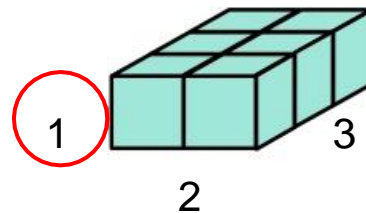
```
>>> x.shape
```

```
torch.Size([1, 2, 3])
```

```
>>> x = x.squeeze(0)  
                (dim = 0)
```

```
>>> x.shape
```

```
torch.Size([2, 3])
```



Tensors – Common Operations

- **Unsqueeze:** expand a new dimension

```
>>> x = torch.zeros([2, 3])
```

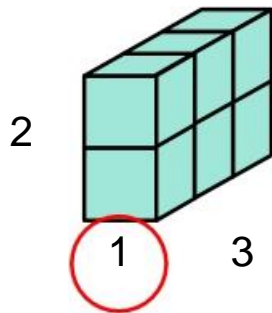
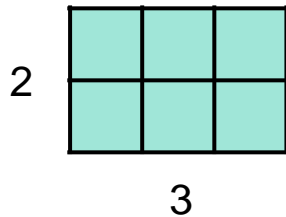
```
>>> x.shape
```

```
torch.Size([2, 3])
```

```
>>> x = x.unsqueeze(1) (dim = 1)
```

```
>>> x.shape
```

```
torch.Size([2, 1, 3])
```



Tensors – Common Operations

- **Cat**: concatenate multiple tensors

```
>>> x = torch.zeros([2, 1, 3])
```

```
>>> y = torch.zeros([2, 3, 3])
```

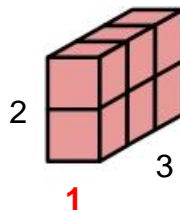
```
>>> z = torch.zeros([2, 2, 3])
```

```
>>> w = torch.cat([x, y, z], dim=1)
```

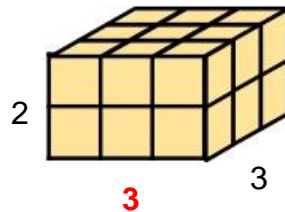
```
>>> w.shape
```

```
torch.Size([2, 6, 3])
```

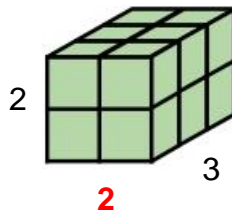
x



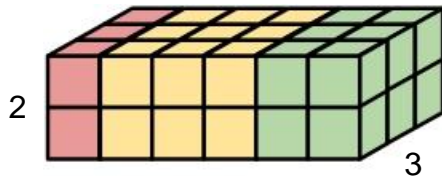
y



z



w



more operators: <https://pytorch.org/docs/stable/tensors.html>

Tensors – Data Type

- Using different data types for model and data will cause errors.

Data type	dtype	tensor
32-bit floating point	<code>torch.float</code>	<code>torch.FloatTensor</code>
64-bit integer (signed)	<code>torch.long</code>	<code>torch.LongTensor</code>

see [official documentation](#) for more information on data types.

Tensors – PyTorch v.s. NumPy

- Similar attributes

PyTorch	NumPy
<code>x.shape</code>	<code>x.shape</code>
<code>x.dtype</code>	<code>x.dtype</code>

see [official documentation](#) for more information on data types.

ref: <https://github.com/wkentaro/pytorch-for-numpy-users>

Tensors – PyTorch v.s. NumPy

- Many functions have the same names as well

PyTorch	NumPy
<code>x.reshape / x.view</code>	<code>x.reshape</code>
<code>x.squeeze()</code>	<code>x.squeeze()</code>
<code>x.unsqueeze(1)</code>	<code>np.expand_dims(x, 1)</code>

Tensors – Device

- Tensors & modules will be computed with **CPU** by default

Use `.to()` to move tensors to appropriate devices.

- CPU

```
x = x.to('cpu')
```

- GPU

```
x = x.to('cuda')
```

Tensors – Device (GPU)



- Check if your computer has NVIDIA GPU

```
torch.cuda.is_available()
```

- Multiple GPUs: specify 'cuda:0', 'cuda:1', 'cuda:2', ...
- Why use GPUs?
 - Parallel computing with more cores for arithmetic calculations
 - See [What is a GPU and do you need one in deep learning?](#)

Tensors – Gradient Calculation

1 >>> x = torch.tensor([[1., 0.], [-1., 1.]], **requires_grad=True**)

2 >>> z = x.pow(2).sum()

3 >>> z.backward()

4 >>> x.grad

tensor([[2., 0.],
 [-2., 2.]])

1 $x = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$

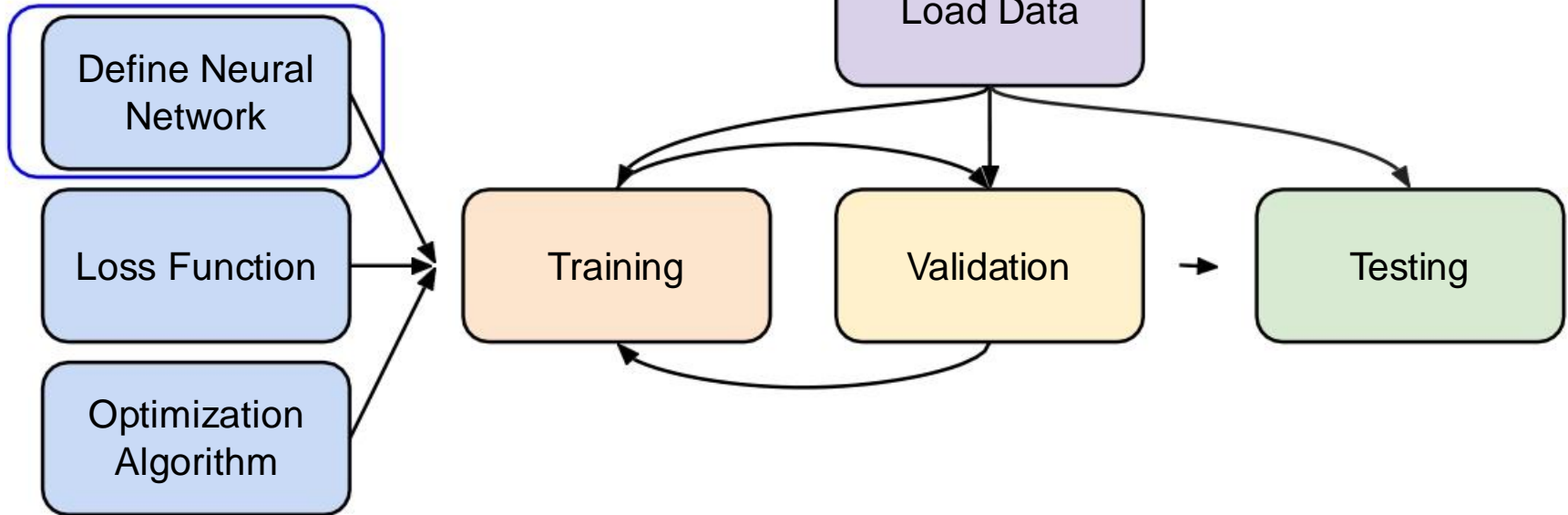
2 $z = \sum_i \sum_j x_{i,j}^2$

3 $\frac{\partial z}{\partial x_{i,j}} = 2x_{i,j}$

4 $\frac{\partial z}{\partial x} = \begin{bmatrix} 2 & 0 \\ -2 & 2 \end{bmatrix}$

Training & Testing Neural Networks – in Pytorch

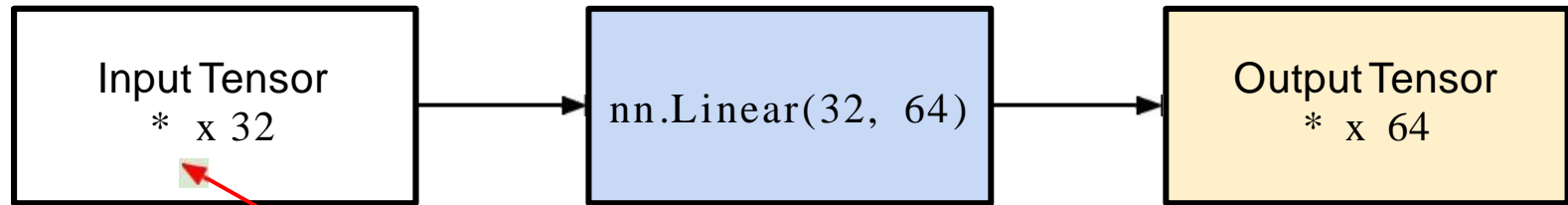
Step 2.
`torch.nn.Module`



torch.nn – Network Layers

- Linear Layer (**Fully-connected** Layer)

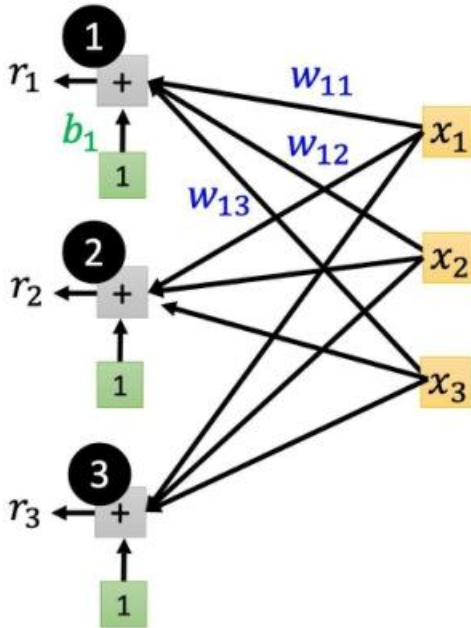
```
nn.Linear(in_features, out_features)
```



can be any shape (but last dimension must be 32)
e.g. (10, 32), (10, 5, 32), (1, 1, 3, 32), ...

torch.nn – Network Layers

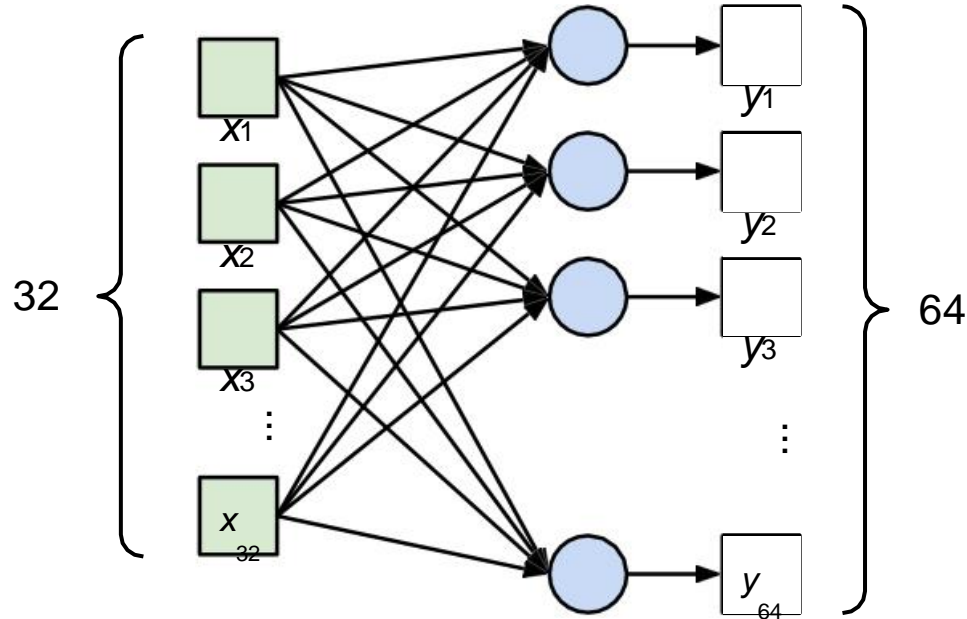
- Linear Layer (**Fully-connected** Layer)



$$b + Wx$$

torch.nn – Neural Network Layers

- Linear Layer (**Fully-connected** Layer)



$$\mathbf{W}_{(64 \times 32)} \times \mathbf{x} + \mathbf{b} = \mathbf{y}$$

torch.nn – Network Parameters

- Linear Layer (**Fully-connected** Layer)

```
>>> layer = torch.nn.Linear(32, 64)
```

```
>>> layer.weight.shape
```

```
torch.Size([64, 32])
```

```
>>> layer.bias.shape
```

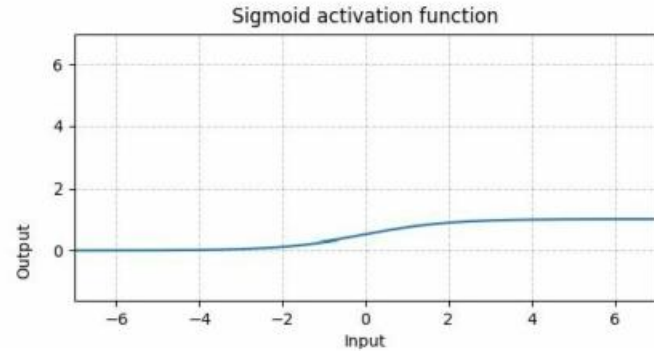
```
torch.Size([64])
```

$$\begin{matrix} \mathbf{W} \\ (64 \times 32) \end{matrix} \times \mathbf{x} + \mathbf{b} = \mathbf{y}$$

torch.nn – Non-Linear Activation Functions

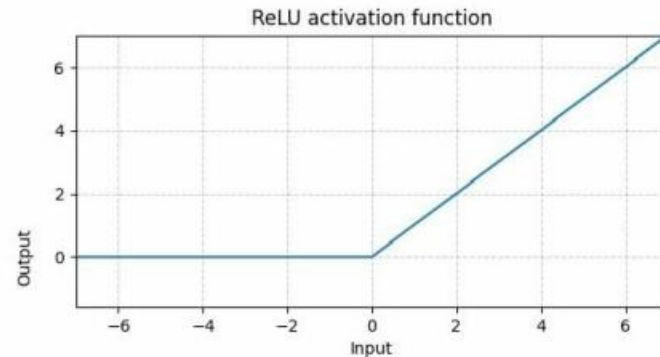
- Sigmoid Activation

`nn.Sigmoid()`



- ReLU Activation

`nn.ReLU()`



torch.nn – Build your own neural network

```
import torch.nn as nn
```

```
class MyModel(nn.Module):
```

```
    def init(self):
```

```
        super(MyModel, self).init ()
```

```
        self.net = nn.Sequential(
```

```
            nn.Linear(10, 32),
```

```
            nn.Sigmoid(),
```

```
            nn.Linear(32, 1)
```

```
        )
```

```
    def forward(self, x):
```

```
        return self.net(x)
```

Initialize your model & define layers

Compute output of your NN

torch.nn – Build your own neural network

```
import torch.nn as nn    import torch.nn as nn
```

```
class MyModel(nn.Module):  
    def __init__(self):  
        super(MyModel,  
              self).__init__() self.net =  
        nn.Sequential(  
            nn.Linear(10, 32),  
            nn.Sigmoid(),  
            nn.Linear(32, 1)  
        )  
  
    def forward(self, x):  
        return self.net(x)
```

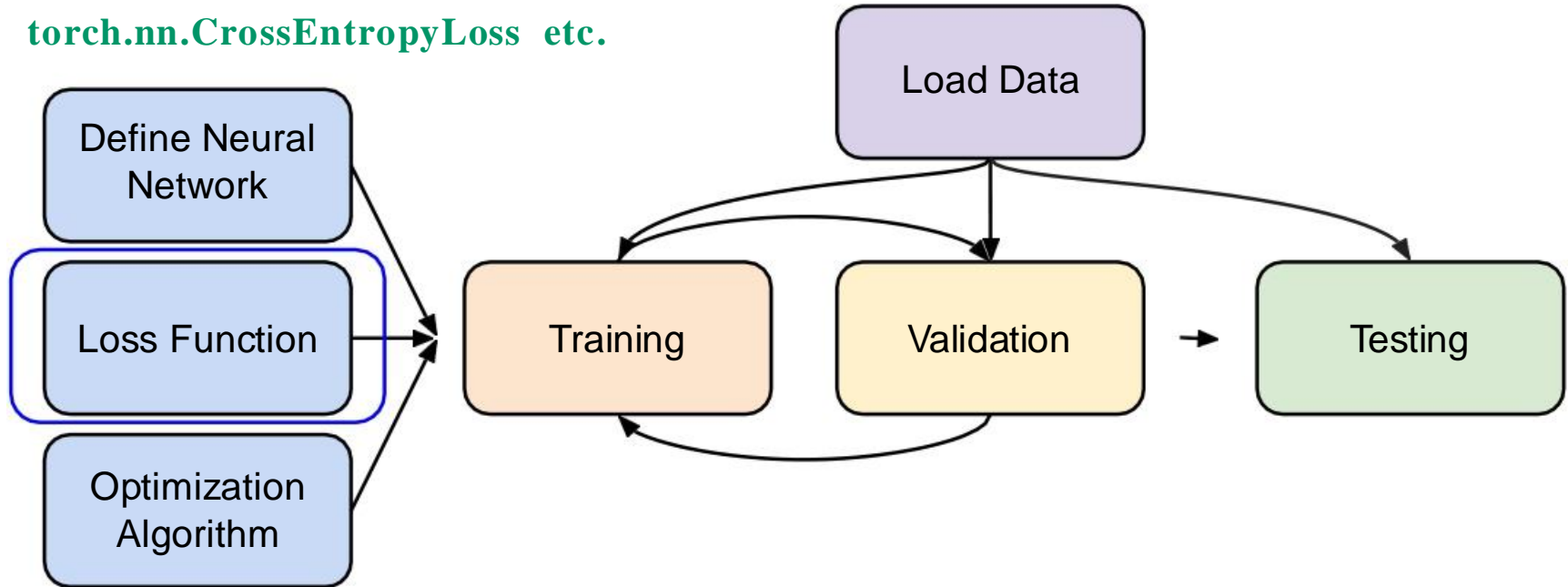
```
class MyModel(nn.Module):  
    def __init__(self):  
        super(MyModel, self).__init__()  
        self.layer1 = nn.Linear(10, 32)  
        self.layer2 = nn.Sigmoid()  
        self.layer3 = nn.Linear(32, 1)  
  
    def forward(self, x):  
        out = self.layer1(x)  
        out = self.layer2(out)  
        out = self.layer3(out)  
        return out
```

Training & Testing Neural Networks – in Pytorch

Step 3.

`torch.nn.MSELoss`

`torch.nn.CrossEntropyLoss` etc.



torch.nn – Loss Functions

- Mean Squared Error (for regression tasks)

```
criterion = nn.MSELoss()
```

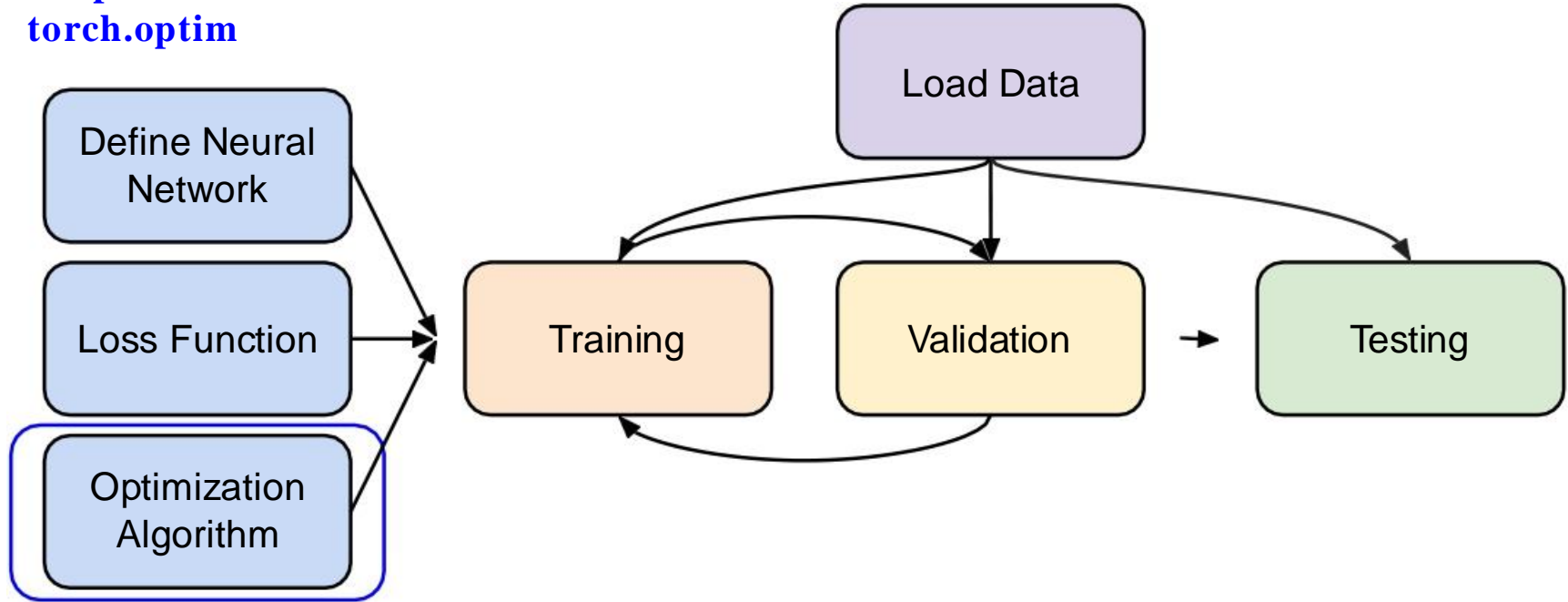
- Cross Entropy (for classification tasks)

```
criterion = nn.CrossEntropyLoss()
```

- `loss = criterion(model_output, expected_value)`

Training & Testing Neural Networks – in Pytorch

Step 4. `torch.optim`



torch.optim

- Gradient-based **optimization algorithms** that adjust network parameters to reduce error. (See [Adaptive Learning Rate](#) lecture video)
- E.g. Stochastic Gradient Descent (SGD)

```
torch.optim.SGD(model.parameters(), lr, momentum = 0)
```

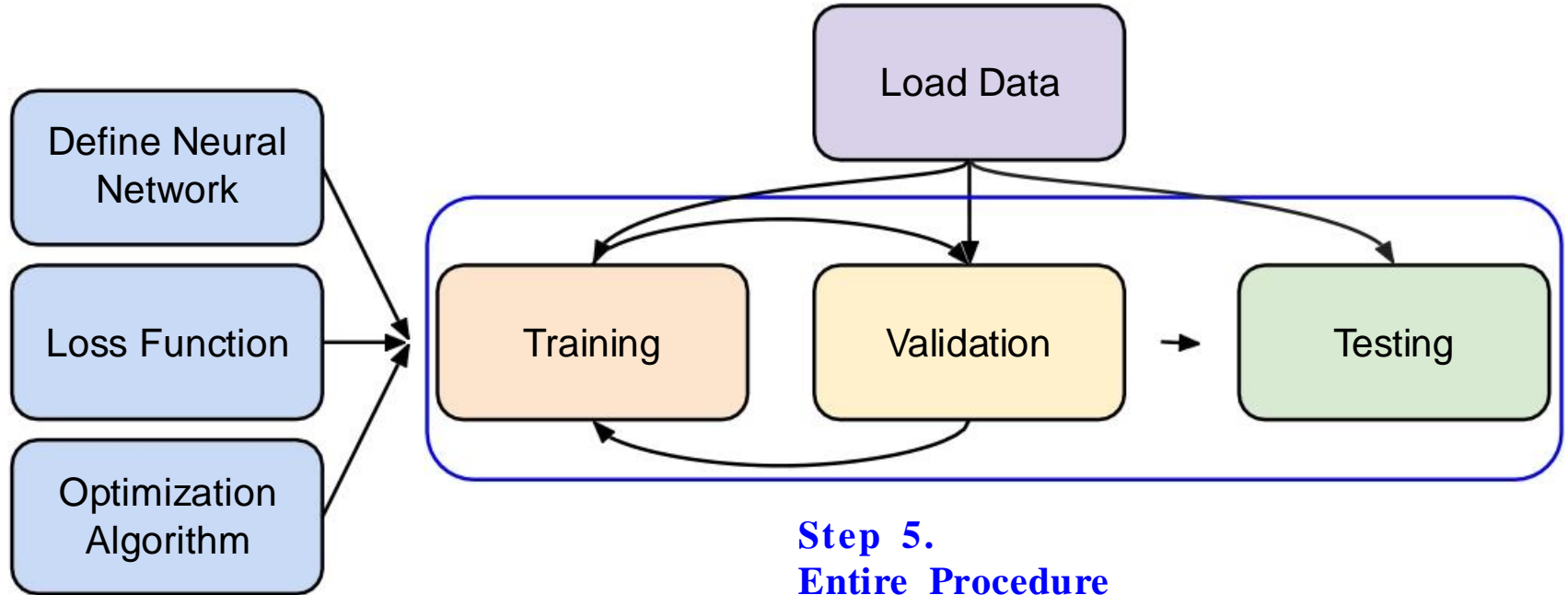

torch.optim

```
optimizer = torch.optim.SGD(model.parameters(), lr, momentum = 0)
```

- For every batch of data:
 1. Call `optimizer.zero_grad()` to reset gradients of model parameters.
 2. Call `loss.backward()` to backpropagate gradients of prediction loss.
 3. Call `optimizer.step()` to adjust model parameters.

See [official documentation](#) for more optimization algorithms.

Training & Testing Neural Networks – in Pytorch



Neural Network Training Setup

```
dataset = MyDataset(file)
```

read data via MyDataset

```
tr_set = DataLoader(dataset, 16, shuffle=True)
```

put dataset into Dataloader

```
model = MyModel().to(device)
```

construct model and move to device (cpu/cuda)

```
criterion = nn.MSELoss()
```

set loss function

```
optimizer = torch.optim.SGD(model.parameters(), 0.1)
```

set optimizer

Neural Network Training Loop

```
for epoch in range(n_epochs):
```

```
    model.train()
```

```
    for x, y in tr_set:
```

```
        optimizer.zero_grad()
```

```
        x, y = x.to(device), y.to(device)
```

```
        pred = model(x)
```

```
        loss = criterion(pred, y)
```

```
        loss.backward() optimizer.step()
```

iterate n_epochs

set model to train mode

iterate through the dataloader

set gradient to zero

move data to device (cpu/cuda)

forward pass (compute output)

compute loss

compute gradient (backpropagation)

update model with optimizer

Neural Network Validation Loop

model.eval()

set model to evaluation mode

```
total_loss = 0
```

```
for x, y in dv_set:
```

iterate through the dataloader

```
    x, y = x.to(device), y.to(device)
```

move data to device (cpu/cuda)

```
    with torch.no_grad():
```

disable gradient calculation

```
        pred = model(x)
```

forward pass (compute output)

```
        loss = criterion(pred, y)
```

compute loss

```
total_loss += loss.cpu().item() * len(x)
```

accumulate loss

```
avg_loss = total_loss / len(dv_set.dataset)
```

compute averaged loss

Neural Network Testing Loop

```
model.eval()
```

set model to evaluation mode

```
preds = []
```

```
for x in tt_set:
```

iterate through the dataloader

```
    x = x.to(device)
```

move data to device (cpu/cuda)

```
    with torch.no_grad():
```

disable gradient calculation

```
        pred = model(x)
```

forward pass (compute output)

```
        preds.append(pred.cpu())
```

collect prediction

Notice - `model.eval()`, `torch.no_grad()`

- **`model.eval()`**
Changes behaviour of some model layers, such as dropout and batch normalization.
- **with `torch.no_grad()`**
Prevents calculations from being added into gradient computation graph.
Usually used to prevent accidental training on validation/testing data.

Save/Load Trained Models

- Save

```
torch.save(model.state_dict(), path)
```

- Load

```
ckpt = torch.load(path)  
model.load_state_dict(ckpt)
```


More About PyTorch

- torchaudio
 - speech/audio processing
- torchtext
 - natural language processing
- torchvision
 - computer vision
- skorch
 - scikit-learn + pyTorch

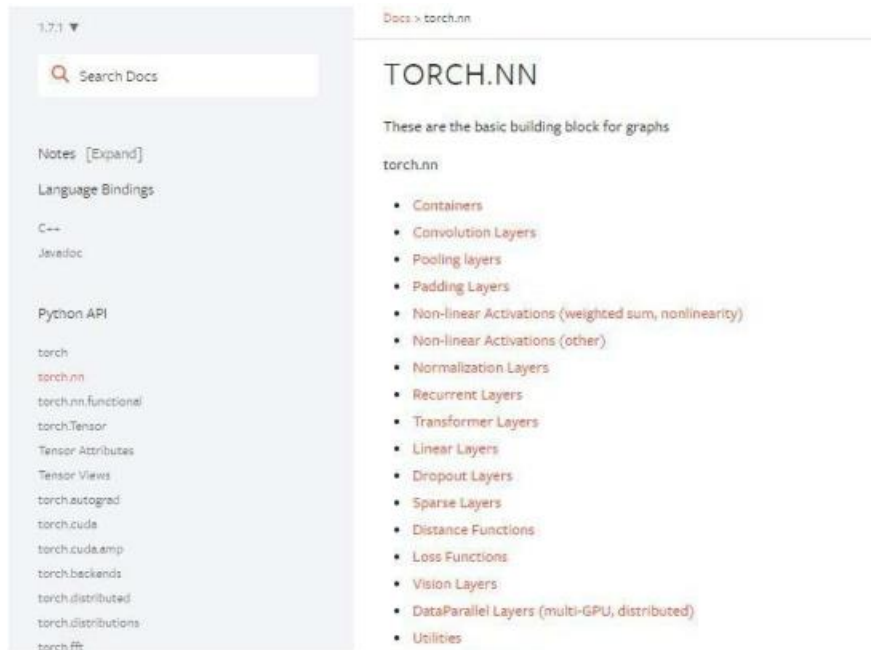
More About PyTorch

- Useful github repositories using PyTorch
 - [Huggingface Transformers](#) (transformer models: BERT, GPT, ...)
 - [Fairseq](#) (sequence modeling for NLP & speech)
 - [ESPnet](#) (speech recognition, translation, synthesis, ...)
 - Most implementations of recent deep learning papers
 - ...

PyTorch Documentation

<https://pytorch.org/docs/stable/>

- torch.nn -> Neural Network
- torch.optim -> Optimization Algorithms
- torch.utils.data -> Dataset, Dataloader



PyTorch Documentation Example

TORCH.MAX

Function inputs and outputs



`torch.max(input) → Tensor`

Returns the maximum value of all elements in the `input` tensor.

• WARNING

This function produces deterministic (sub)gradients unlike `max(dim=0)`

Data type and explanation of each input



Parameters

input (*Tensor*) – the input tensor.

PyTorch Documentation Example

- Some functions behave differently with different inputs
- Parameters : You don't need to specify the name of the argument (Positional Arguments)
- Keyword Arguments : You have to specify the name of the argument

*They are separated by **

```
torch.max(input, dim, keepdim=False*, out=None) -> (Tensor, LongTensor)
```

Returns a namedtuple (values, indices) where values is the maximum value of each row of the input tensor in the given dimension dim. And indices is the index location of each maximum value found (argmax).

If keepdim is True, the output tensors are of the same size as input except in the dimension dim where they are of size 1. Otherwise, dim is squeezed (see `torch.squeeze()`), resulting in the output tensors having 1 fewer dimension than input.

• NOTE

If there are multiple maximal values in a reduced row then the indices of the first maximal value are returned.

Parameters

- **input** (*Tensor*) – the input tensor.
- **dim** (*int*) – the dimension to reduce.
- **keepdim** (*bool*) – whether the output tensor has dim retained or not. Default: False.

Keyword Arguments

out (*tuple, optional*) – the result tuple of two output tensors (max, max_indices)

PyTorch Documentation Example

- Some functions behave differently with different inputs
- Arguments with default value :
Some arguments have a default value (keepdim=False), so passing a value of this argument is optional

```
torch.max(input, dim, keepdim=False, *, out=None) -> (Tensor, LongTensor)
```

Returns a namedtuple (values, indices) where values is the maximum value of each row of the input tensor in the given dimension dim. And indices is the index location of each maximum value found (argmax).

If keepdim is True, the output tensors are of the same size as input except in the dimension dim where they are of size 1. Otherwise, dim is squeezed (see `torch.squeeze()`), resulting in the output tensors having 1 fewer dimension than input.

• NOTE

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Parameters

- **input** (*Tensor*) – the input tensor.
- **dim** (*int*) – the dimension to reduce.
- **keepdim** (*bool*) – whether the output tensor has dim retained or not. Default: False.

Keyword Arguments

out (*tuple, optional*) – the result tuple of two output tensors (max, max_indices)

PyTorch Documentation Example

Three Kinds of torch.max

1. `torch.max(input) → Tensor`
2. `torch.max(input, dim, keepdim=False, *, out=None) → (Tensor, LongTensor)`
3. `torch.max(input, other, *, out=None) → Tensor`

`input : Tensor, dim : int, keepdim : bool`
`other : Tensor`

PyTorch Documentation Example

1. `torch.max(input)` → **Tensor**

Find the maximum value of a tensor, and return that value.

input

[[1 2 3]

[5 6 4]]

PyTorch Documentation Example

```
2. torch.max(input, dim, keepdim=False, *,  
out=None) → (Tensor, LongTensor)
```

Find the maximum
value of a tensor
along a dimension,
and return that value,
along with the index
corresponding to that
value.

PyTorch Documentation Example

3. `torch.max(input, other) → Tensor`

Perform element-wise comparison between two tensors of the same size, and select the maximum of the two to construct a tensor with the same size.

ut



```
[ [2  4  6]  
  [1  3  5]]
```

Common Errors - torch.max (Colab)

Three Kinds of torch.max

1. `torch.max(input)`
→ Tensor
2. `torch.max(input, dim, keepdim=False, *, out=None)` →
(Tensor, LongTensor)
3. `torch.max(input, other, *, out=None)` → Tensor

`input` : Tensor

`dim` : int

`keepdim` : bool

`other` : Tensor

Colab code

```
x = torch.randn(4,5)
y = torch.randn(4,5)
m, idx = torch.max(x,0,False,p)→x
    *out is a keyword argument
m, idx = torch.max(x,True)→x
    *did not specify dim
```

Common Errors – Tensor on Different Device to Model

```
model = torch.nn.Linear(5,1).to("cuda:0")  
x = torch.randn(5).to("cpu")  
y = model(x)
```

Tensor for * is on CPU, but expected them to be on GPU

=> send the tensor to GPU

```
x = torch.randn(5).to("cuda:0")  
y = model(x)  
print(y.shape)
```

Common Errors – Mismatched Dimensions

```
x = torch.randn(4,5)
y = torch.randn(5,4)
z = x + y
```

The size of tensor a (5) must match the size of tensor b (4) at non-singleton dimension 1

=> the shape of a tensor is incorrect, use **transpose**, **squeeze**, **unsqueeze** to align the dimensions

```
y = y.transpose(0,1)
z = x + y
print(z.shape)
```

Common Errors – Cuda Out of Memory

```
import torch
import torchvision.models as models
resnet18 = models.resnet18().to( "cuda:0" ) # Neural Networks for Image
data = torch.randn( 512,3,244,244) # Create fake data (512
out = resnet18(data.to( "cuda:0" )) # Use Data as Input and Feed to
print(out.shape)
```

CUDA out of memory. Tried to allocate 350.00 MiB (GPU 0; 14.76 GiB total capacity; 11.94 GiB already allocated; 123.75 MiB free; 13.71 GiB reserved in total by PyTorch)

=> The batch size of data is too large to fit in the GPU. Reduce the batch size.

Common Errors – Mismatched Tensor Type

```
import torch.nn as nn
L = nn.CrossEntropyLoss()
outs = torch.randn(5,5)
labels = torch.Tensor([1,2,3,4,0])
lossval = L(outs, labels) # Calculate CrossEntropyLoss between outs and labels
```

expected scalar type Long but found Float

=> labels must be long tensors, cast it to type “Long” to fix this issue

```
labels = labels.long()
lossval = L(outs, labels)
print(lossval)
```

Colab Tutorial

Outline

- Introduction
- Getting Started
- Changing Runtime
- Executing Code Block
- Check GPU type
- File Manipulation
- Mounting Google Drive
- Saving Notebook
- Useful Linux Commands
- Problems You May Encounter... (very important)
- References

Introduction

What is Colab?

Colab, or "Colaboratory", allows you to write and execute Python in your browser, with

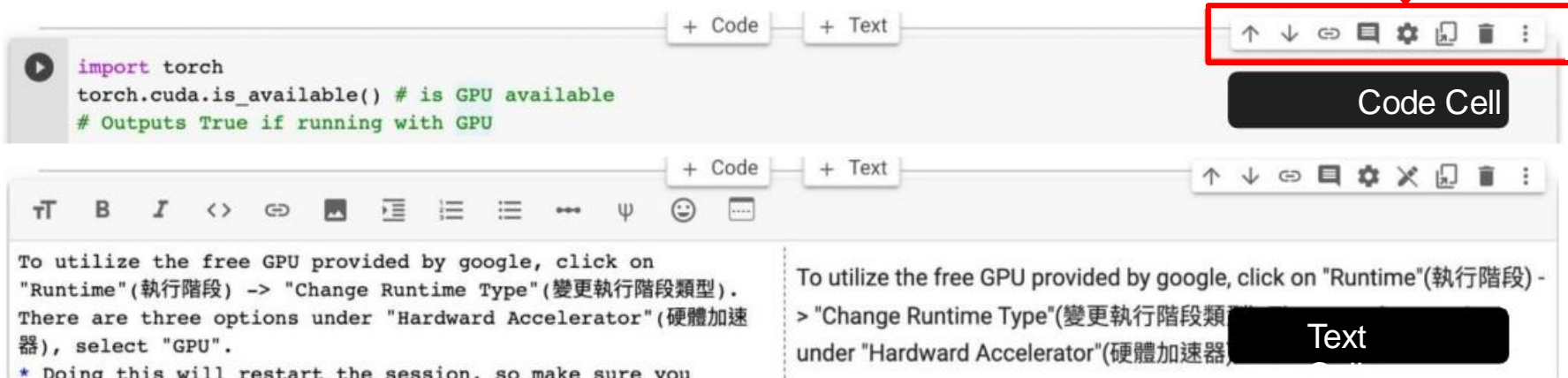
- Zero configuration required
- Free access to GPUs
- Easy sharing

Getting Started

Creating a new cell

You can create a new code cell by clicking on +Code, clicking on +Text generates a text cell

There are options for moving your cell up/down or copy or delete it



The screenshot displays two cells in a Jupyter Notebook interface. The top cell is a **Code Cell**, containing Python code to check for GPU availability using the `torch` library. The bottom cell is a **Text Cell**, containing instructions on how to utilize the free GPU provided by Google. Both cells have a toolbar on the right side with icons for moving the cell up or down, linking, commenting, settings, copying, and deleting. A red box highlights the toolbar of the top cell, and a red arrow points to the settings icon (gear) within that toolbar.

```
import torch
torch.cuda.is_available() # is GPU available
# Outputs True if running with GPU
```

To utilize the free GPU provided by google, click on "Runtime"(執行階段) -> "Change Runtime Type"(變更執行階段類型). There are three options under "Hardward Accelerator"(硬體加速器), select "GPU".

To utilize the free GPU provided by google, click on "Runtime"(執行階段) -> "Change Runtime Type"(變更執行階段類型) under "Hardward Accelerator"(硬體加速器)

Getting Started

You can type python code in the code cell, or use a leading exclamation mark ! to change the code cell to treating the input as a shell script

```
[ ] import torch
    torch.cuda.is_available() # is GPU available
    # Outputs True if running with GPU
```

→ **python**

```
[ ] # List all the files under the working directory
    !ls
```

→ **shell script**

Getting Started

Using an exclamation mark (!) starts a new shell, does the operations, and then kills that shell, while percentage (%) affects the process associated with the notebook, and it is called a magic command.

Use % instead of ! for cd (change directory) command

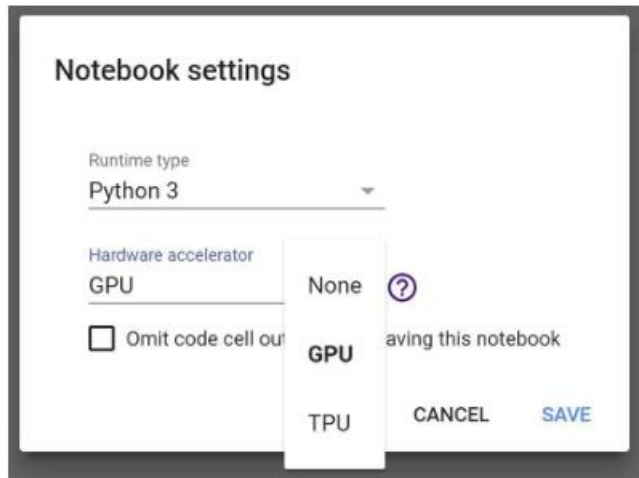
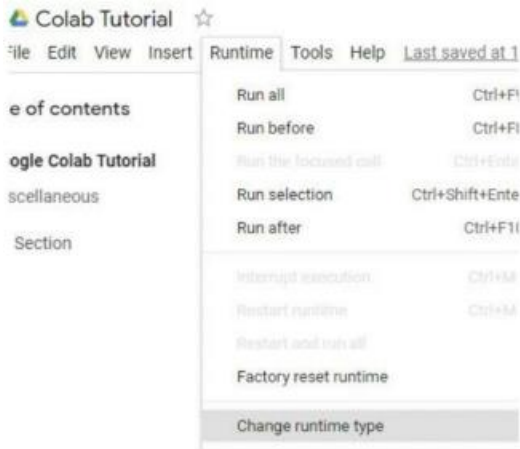
other magic commands are listed [here](#)

Changing Runtime

To utilize the free GPU provided by google,
click on "Runtime"(執行階段) → "Change Runtime
Type"(變更執行階段類型).

select "**GPU**" for "Hardware Accelerator"(硬體加速器)

*Doing this will restart the session, so make sure you
change to the desired runtime before executing any
code.*



Executing Code Block

Click on the play button to execute a specific code cell



```
import torch
torch.cuda.is_available() # is GPU available
# Outputs True if running with GPU
```

Executing Code Block

Other options to run your code



The screenshot shows the Google Colab Tutorial 2023 interface. The top navigation bar includes the Google Colab logo, the title "Google Colab Tutorial 2023", and a star icon. Below the title, there are tabs: "檔案" (File), "編輯" (Edit), "檢視畫面" (View), "插入" (Insert), "執行階段" (Execution), "工具" (Tools), "說明" (Help), and "已儲存所有變更" (Save all changes). The "執行階段" tab is currently selected. On the left side, there is a sidebar with a "目錄" (Table of Contents) icon, a search icon, and the text "Google Colab Tutorial". Below this, there is a "+ 區段" (Add section) button and a folder icon. The main content area displays a list of execution options, each with a keyboard shortcut. The first five options are highlighted with a red border:

全部執行	⌘/Ctrl+F9
執行上方的儲存格	⌘/Ctrl+F8
執行聚焦的儲存格	⌘/Ctrl+Enter
執行選取範圍	⌘/Ctrl+Shift+Enter
執行下方的儲存格	⌘/Ctrl+F10

Below these, there are three more options:

中斷執行	⌘/Ctrl+M
重新啟動執行階段	⌘/Ctrl+M .
重新啟動並執行所有儲存格	
中斷連線並刪除執行階段	

Check GPU Type

Use the command **nvidia-smi** to check the allocated GPU type

Available GPUs:

T4 > K80

(but most of the time you get K80 using the free Colab)

```
[ ] # check allocated GPU type
!nvidia-smi
```

Sun Feb 5 07:30:36 2023

```
NVIDIA-SMI 510.47.03   Driver Version: 510.47.03   CUDA Version: 11.6   |
+-----+-----+-----+-----+-----+-----+
| GPU Name      Persistence-M| Bus-Id        Disp.A | Volatile Uncorr. ECC |
| Fan  Temp  Perf  Pwr:Usage/Cap|     Memory-Usage | GPU-Util  Compute M. |
|               |                 MIG M. |                     |
+-----+-----+-----+-----+-----+-----+
|    0   Tesla T4       Off | 00000000:00:04:0 | Off  |            0 |
| N/A   43C    P0      26W / 70W | 3MiB / 15360MiB |      0%    Default |
|               |                 N/A |                     |
+-----+-----+-----+-----+-----+
|
+-----+-----+-----+-----+-----+
| Processes:                                     |
|  GPU   GI    CI          PID    Type    Process name                        Usage      | GPU Memory |
|  ID   ID                                 Usage                                  |           |
+-----+-----+-----+-----+-----+-----+
| No running processes found                    |           |
+-----+-----+-----+-----+-----+
```

File Manipulation

Download files via Google Drive

1. Download Files via google drive

A file stored in Google Drive has the following sharing **link** :

<https://drive.google.com/file/d/14FK5G6DOh7EdLyoj4D5teRSzriTOUPD7/view?usp=sharing>

It is possible to download the file via Colab knowing the **link**, using the **--fuzzy** command.

```
[ ] # Download the file with the following link, and rename it to pikachu.png  
!gdown --fuzzy https://drive.google.com/file/d/14FK5G6DOh7EdLyoj4D5teRSzriTOUPD7/view?usp=sharing --output pikachu.png
```

Downloading...

From: <https://drive.google.com/uc?id=14FK5G6DOh7EdLyoj4D5teRSzriTOUPD7>

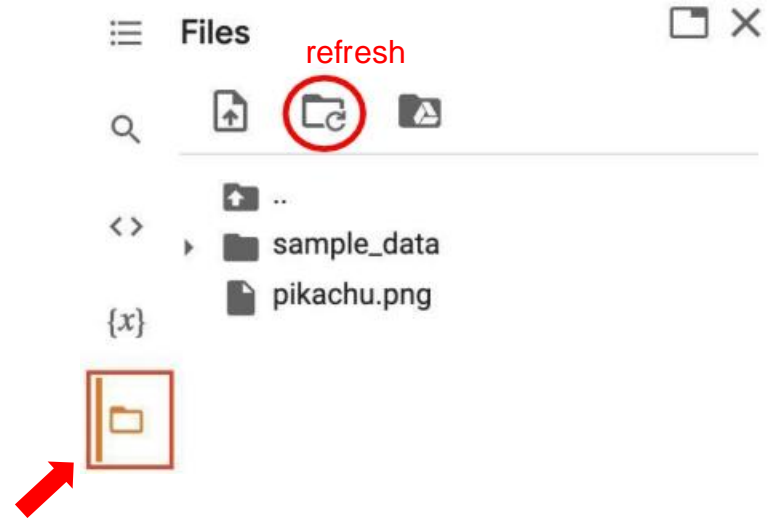
To: /content/pikachu.png

100% 890k/890k [00:00<00:00, 155MB/s]

File Manipulation

File Structure

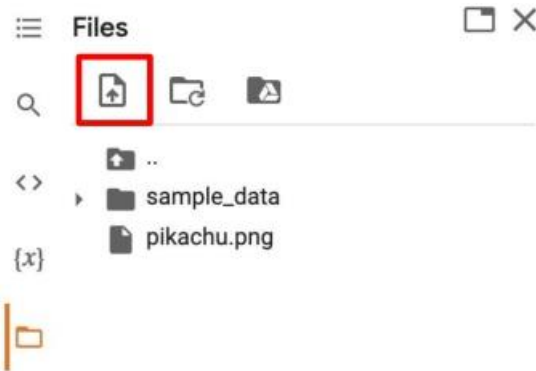
- You may click on the folder icon on the left to view your current files
- After downloading files, if the files are not immediately shown, click the refresh button
- Files are temporarily stored, and will be removed once you end your session.



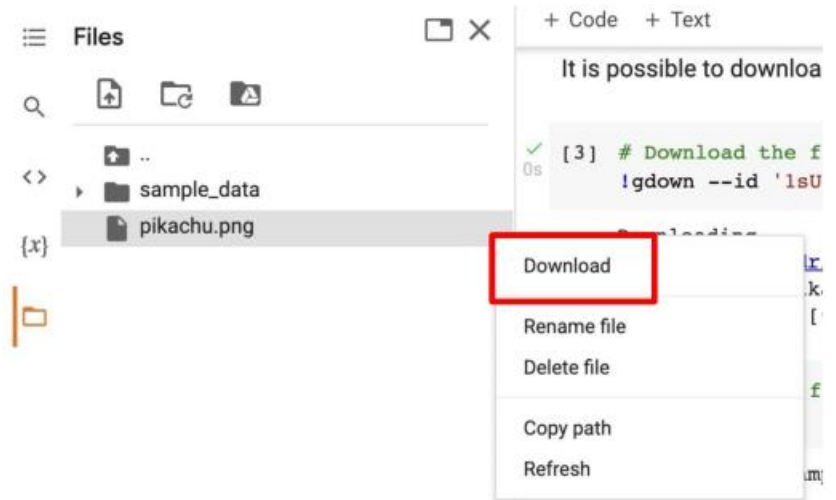
File Manipulation

Upload and Download Files

Click the upload icon to upload local files to your session



click  to download files to your local



Mounting Google Drive

If you don't want to download the data every time you start a new session, or you want some files to be saved permanently,

you can mount your own google drive to colab and directly download/save the data to your google drive.

Mount Drive:

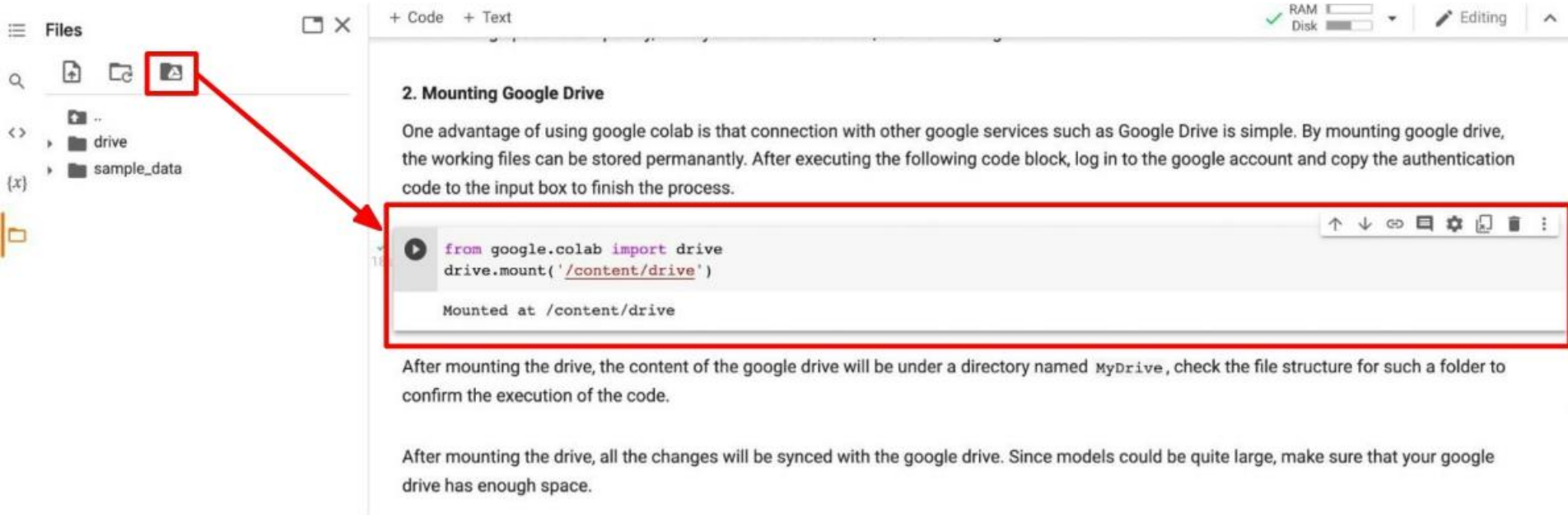
```
from google.colab import drive  
drive.mount('/content/drive')
```

Mounted at /content/drive



Mounting Google Drive

Click on the Google Drive icon, the **Mount Drive** code block will be generated



The screenshot shows the Google Colab interface. On the left, the 'Files' pane displays a file explorer with a red box around the Google Drive icon. A red arrow points from this icon to a code block in the main editor. The code block is titled '2. Mounting Google Drive' and contains the following code:

```
from google.colab import drive
drive.mount('/content/drive')
```

Below the code, the output shows 'Mounted at /content/drive'. The text below the code block explains that after mounting, the content of the Google Drive will be under a directory named `MyDrive`, and users should check the file structure for such a folder to confirm the execution of the code. It also notes that after mounting, all changes will be synced with the Google Drive, and users should ensure their Google Drive has enough space.

Mounting Google Drive

Execute the following three code blocks in order

This will download the image to your google drive, and you can access it later

```
[ ] %cd /content/drive/MyDrive
    #change directory to google drive
    !mkdir ML2023 #make a directory named ML2023
    %cd ./ML2023
    #change directory to ML2023
```

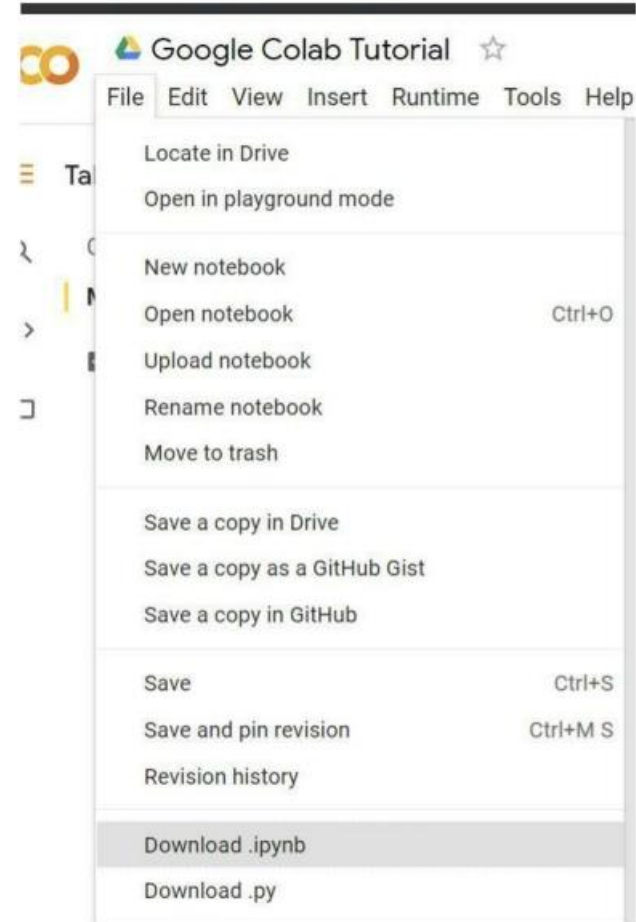
```
[ ] !pwd #output the current directory
```

```
[ ] !gdown --fuzzy https://drive.google.com/file/d/14FK5G6DOh7EdLyoj4D5teRSzriTOUPD7/view?usp=sharing --output pikachu.png
```



Saving Notebook

- Download the .ipynb file to your local device (File > Download .ipynb)
- Save the colab notebook to your google drive (File > Save a copy in Drive).
- Convert .ipynb to .py and download (File > Download .py)



Useful Linux Commands (in Colab)

ls : List all files in the current directory

ls -l : List all files in the current directory with more detail

pwd : Output the working directory

mkdir <dirname> : Create a directory <dirname>

cd <dirname> : Move to directory <dirname>

gdown : Download files from google drive

wget : Download files from the internet

python <python_file>: Executes a python file

Problems You May Encounter...

- Colab will **automatically disconnect** if idle timeout(90 min., sometimes varying) or when your screen goes black
→ solution: keep your screen on or try using [javascript](#)
- GPU usage is **not unlimited** ! (your account will be stopped for a period if you reached the max gpu usage 12 hrs)
*** The cooldown period before you can connect to another GPU will extend from hours to days to weeks depending on your usage**
→ solution: open another account

Best solution:

1. buy [colab pro](#) :)
2. use your own resource (if able)

Reference

- <https://colab.research.google.com>
- <https://research.google.com/colaboratory/faq.html>