

Vectorization

Week 3

MEMS 1140—Introduction to Programming in Mechanical

Engineering





Learning Objectives (L.O.)

At the end of this lecture, you should understand/be able to:

- What vectorization is;
- Why vectorization could be useful in engineering;
- Vectorized array operations in MATLAB;
- Write vectorized code for the vector dot product.





Table of Contents (ToC)

- 1. What is vectorization
- 2. Why vectorization is useful
- 3. Vectorized array operations in MATLAB
- 4. Writing a vectorized dot product
- 5. Summary





1 – Real-life Vectorization

⇒ L.O.1
□ L.O.2
□ L.O.3

You and some friends plan a cookout grilling hot dogs.

You could grill one at a time, but then some people receive food sooner than others.

Putting an entire pack of hot dogs on the grill simultaneously ensures that more people receive food together.

This is a *vectorized* cooking operation.





1 – Definition of Vectorization

⇒ L.O.1 □ L.O.2

 $\Box I \cap 4$

The processor (you) has accessed the entire "array" (pack) and applied the function **cook** to the *array as a whole*.

Definition

Vectorized code is characterized by one instruction (one line of code) that operates on multiple data points together.

By utilizing vectorized operations, it is possible to write faster, more reliable code while also making it more readable.





1 – Disclaimer

⇒ L.O.1
□ L.O.2

□ L.O.4

This lecture blurs the lines a little bit between vectorization and parallelization.

Later lectures will introduce parallelization, but suffice it to say that they *are* different.

A more thorough comparison is provided for the interested reader.





2 – Introduction to Loops

✓ L.O.1

⇒ L.O.2

□ L.O.3

To understand the benefits of vectorization, it is necessary to first examine the alternative: loops.

Loops will be covered in more detail later in this course, but it is useful to define them now for comparison:

Definition

The program executes one or more operations repeatedly until a termination condition is met.





✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4

In our example grilling hot dogs, a loop would be used to cook each one individually.

It might look as follows:

```
hotdogs(8) = HotDog;
```

% array of 8 hot dogs

- •
- •





✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4

In our example grilling hot dogs, a loop would be used to cook each one individually.

It might look as follows:

```
hotdogs(8) = HotDog; % array of 8 hot dogs

for

.
end
```





✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4

In our example grilling hot dogs, a loop would be used to cook each one individually.

It might look as follows:





✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4

In our example grilling hot dogs, a loop would be used to cook each one individually.

It might look as follows:

This code executes **cook** on each hot dog one at a time.





2 – How to Read a Loop

```
✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4
```

In plain english, this code reads as follows:

For each hot dog in the pack, numbered 1 to 8, cook each one before beginning to cook the next.

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2 – Vectorization for Hot Dogs

In comparison, vectorized code may look something like this:

```
hotdogs(8) = HotDog; % array of 8 hot dogs
```

✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.3





2 – Vectorization for Hot Dogs

✓ L.O.1

⇒ L.O.2

□ L.O.3

In comparison, vectorized code may look something like this:

```
hotdogs(8) = HotDog; % array of 8 hot dogs cook(hotdogs); % cook all hot dogs
```

For this (fictional) example, the vectorized cooking operation is only one line ... and it is likely faster.

Vectorized code is also often easier to read *because* it is shorter and more closely matches plain language.

ToC 11/33





2 – Prepare an Experiment

✓ L.O.1

⇒ L.O.2

□ L.O.3

Let's conduct an experiment to see whether vectorization is *really* that much faster than looping.

Experiment

Multiply 1 million random numbers by 2.

The following function generates an Nx1 array of random values given a *length* (num_values) as its input:

```
random_number_array = @(num_values)
```

ToC 12/33





2 – Prepare an Experiment

✓ L.O.1

□ L.O.3

Let's conduct an experiment to see whether vectorization is *really* that much faster than looping.

Experiment

Multiply 1 million random numbers by 2.

The following function generates an Nx1 array of random values given a *length* (num_values) as its input:

```
random_number_array = @(num_values) rand(num_values, 1);
```

ToC 12/33





✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4

Multiplying each element of an array by 2 using a loop is as follows:

```
initial_values = random_number_array(1e6);
.
.
.
.
```





✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4

Multiplying each element of an array by 2 using a loop is as follows:

```
initial_values = random_number_array(1e6);
output_values = zeros( size(initial_values) ); % initialize output array
.
.
.
```





✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4

Multiplying each element of an array by 2 using a loop is as follows:





✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4

Multiplying each element of an array by 2 using a loop is as follows:

```
initial_values = random_number_array(1e6);
output_values = zeros( size(initial_values) );
for i = 1 : length(initial_values)
  output_values(i) = initial_values(i) * 2;  % loop multiplication
end
```

Note: The array **output_values** is initialized **before** the loop. It is possible, but much slower, to skip this step.





2 - Vectorized Version

✓ L.O.1

⇒ L.O.2

□ L.O.4

The vectorized version of this operation is significantly simpler:

```
initial_values = random_number_array(1e6);
```

ToC 14/33





2 - Vectorized Version

```
✓ L.O.1

⇒ L.O.2

□ L.O.3
```

The vectorized version of this operation is significantly simpler:

Note: The array output_values no longer needs to be initialized before the operation.

It is initialized at the same time that the multiplication step is executed on the array initial_values.

ToC 14/33





2 – Adding a Timer

✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4

The last piece in our test is to wrap a timer around the code.

In MATLAB, the tic command starts a timer and toc ends it.

```
timer_start = tic;
.
```

ToC 15/33





2 – Adding a Timer

✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4

The last piece in our test is to wrap a timer around the code.

In MATLAB, the tic command starts a timer and toc ends it.

```
timer_start = tic;
<some code>
.
```

ToC 15/33





2 – Adding a Timer

✓ L.O.1

⇒ L.O.2

□ L.O.3

The last piece in our test is to wrap a timer around the code.

In MATLAB, the tic command starts a timer and toc ends it.

```
timer_start = tic;
<some code>
total_time = toc(timer_start)
```

We now have all the pieces to put together an actual experiment!

ToC 15/33





```
NICAL & MATERIALS SCIENCE
```

⇒ L.O.2□ L.O.3□ L.O.4

```
initial_values = random_number_array(1e6);
```

- .





```
✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4
```

```
initial_values = random_number_array(1e6);
output_values = zeros( size(initial_values) ); % initialize output array
.
.
.
.
.
.
```





```
⇒ L.O.2
□ L.O.3
□ L.O.4
```

/I 01





```
✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4
```





```
✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4
```





```
✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4
```

The above code evaluates how long it takes to multiply 1 million elements by 2 *using a for loop*.





```
✓ L.O.1

⇒ L.O.2

□ L.O.3
```

```
initial values = random number array(1e6);
output values = zeros( size(initial values) );
% ----- TIME THE OPERATION -----
matlab for loop timer = tic;
for i=1 : length(initial values)
 output values(i) = initial values(i) * 2;
end
matlab for loop time = toc(matlab for loop timer)
matlab for loop time =
    1.5195e-02 % [s]
```

Command Window Output





2 – Testing Vectorization

```
✓ L.O.1

⇒ L.O.2
```

□ L.O.3

```
initial_values = random_number_array(1e6);
.
.
.
.
```





2 - Testing Vectorization

```
⇒ L.O.2
□ L.O.3
```

√ L.O.1

```
initial_values = random_number_array(1e6);
% ----- TIME THE OPERATION ----- %
vectorization_timer = tic;
.
```





2 – Testing Vectorization

```
✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4
```

```
initial_values = random_number_array(1e6);
% ------   TIME THE OPERATION ------ %
vectorization_timer = tic;
output_values = initial_values .* 2;   % vectorized multiplication
.
```





2 – Testing Vectorization

```
✓ L.O.1

⇒ L.O.2

□ L.O.3

□ L.O.4
```

The above code evaluates how long it takes to multiply 1 million elements by 2 *using vectorized code*.





2 – Testing Vectorization

```
✓ L.O.1

⇒ L.O.2

□ L.O.3
```

Command Window Output

ToC 18/33





2 - Comparing Results

```
✓ L.O.1
```

⇒ L.O.2

```
□ L.O.3
```

```
\label{eq:matlab_for_loop_time} \begin{array}{ll} \texttt{matlab\_for\_loop\_time} = \\ 1.5195 \texttt{e-} 02 & \text{% [s]} \\ . \end{array}
```

Command Window Output

ToC 19/33





2 – Comparing Results

```
✓ L.O.1
```

```
⇒ L.O.2
□ L.O.3
```

```
matlab_for_loop_time =
    1.5195e-02 % [s]
vectorization_time =
    5.7600e-04 % [s]
```

Command Window Output

In this example, vectorization is \approx 26x faster!

```
>> matlab_for_loop_time / vectorization_time =
    2.6380e+01
```

Command Window

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✓ L.O.1 ✓ L.O.2 ⇒ L.O.3

MATLAB has specific syntax for writing vectorized operations.

Rules

The + and - operators don't require any modification

The *, /, and ^ operators require the addition of a preceding period to indicate that it should be vectorized. For example:

```
a = u + v; % [ u(1) + v(1), etc. ] .
.
.
```



✓ L.O.1 ✓ L.O.2 ⇒ L.O.3

MATLAB has specific syntax for writing vectorized operations.

Rules

The + and - operators don't require any modification

The *, /, and ^ operators require the addition of a preceding period to indicate that it should be vectorized. For example:

```
a = u + v;
b = u - v; % [ u(1) - v(1), etc. ]
```



✓ L.O.1 ✓ L.O.2 ⇒ L.O.3

MATLAB has specific syntax for writing vectorized operations.

Rules

The + and - operators don't require any modification

The *, /, and ^ operators require the addition of a preceding period to indicate that it should be vectorized. For example:

```
a = u + v;
b = u - v;
```

```
c = u .* v; % [ u(1) * v(1), etc. ]
```



✓ L.O.1 ✓ L.O.2 ⇒ L.O.3

MATLAB has specific syntax for writing vectorized operations.

Rules

The + and - operators don't require any modification

The *, /, and ^ operators require the addition of a preceding period to indicate that it should be vectorized. For example:

```
a = u + v;

b = u - v;

c = u .* v;

d = u ./ v; % [ u(1) / v(1), etc. ]
```



✓ L.O.1 ✓ L.O.2 ⇒ L.O.3

MATLAB has specific syntax for writing vectorized operations.

Rules i

The + and - operators don't require any modification

The *, /, and ^ operators require the addition of a preceding period to indicate that it should be vectorized. For example:

```
a = u + v;
b = u - v;

d = u ./ v;
e = u .^ v; % [ u(1) ^ v(1), etc. ]
```





4 – Applying this Knowledge

✓ L.O.1 ✓ L.O.2 ✓ L.O.3

Knowing the basics of writing vectorized operations, we can build upon the **dot_product** function from Lecture 2.1.

The old function was hardcoded to multiply all three components and then add them together:

```
dot_product = @(v1, v2) (v1(1)*v2(1)) + (v1(2)*v2(2)) + (v1(3)*v2(3));
```

Element-wise multiplication is easily replaced with the vectorized operation between the arrays **v1** and **v2**.

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4 – First Improvement

✓ L.O.1 ✓ L.O.2

This returns another vector containing the results of each element-wise multiplication:

```
v = v1 .* v2;
```

✓ L.O.3

⇒ L.O.4

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4 – First Improvement

✓ L.O.1 ✓ L.O.2 ✓ L.O.3

⇒1 0 4

This returns another vector containing the results of each element-wise multiplication:

```
v = v1 .* v2; % v = [v1(1) * v2(1), v1(2) * v2(2), v1(3) * v2(3)]
```

To return the dot product, the sum command can be applied to add each component together:

```
s = sum(v1 .* v2); % s = v1(1) * v2(1) + v1(2) * v2(2) + v1(3) * v2(3)
```

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4 – **Mx**3 **Inputs**

✓ L.O.1 ✓ L.O.2 ✓ L.O.3

Previously, the inputs were both 1x3 vectors.

This function can be expanded to accommodate solving for **M** dot products by passing **v1** and **v2** as **Mx3** arrays.

For example, consider the following two inputs:

```
v1 = [1, 2, 3; ... % 2x3 array (each row is a 1x3 vector)
4, 5, 6];
```

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4 – **Mx**3 **Inputs**

✓ L.O.1 ✓ L.O.2 ✓ L.O.3

Previously, the inputs were both 1x3 vectors.

This function can be expanded to accommodate solving for **M** dot products by passing **v1** and **v2** as **Mx3** arrays.

For example, consider the following two inputs:

```
v1 = [1, 2, 3; ...
4, 5, 6];
v2 = [6, 5, 4; ... % 2x3 array (each row is a 1x3 vector)
3, 2, 1];
```

ToC 23/33



4 – Extracting Component Columns

✓ L.O.1 ✓ L.O.2 ✓ L.O.3

Then, the x-, y-, and z-components of v1 and v2 are all Mx1 vectors. In our example:





4 – Extracting Component Columns

✓ L.O.1 ✓ L.O.2 ✓ L.O.3 ⇒ L.O.4

Then, the x-, y-, and z-components of v1 and v2 are all Mx1 vectors. In our example:

ToC 24/33





4 – Extracting Component Columns

✓ L.O.1 ✓ L.O.2 ✓ L.O.3 ⇒ L.O.4

Then, the x-, y-, and z-components of v1 and v2 are all Mx1 vectors. In our example:

```
v1(:,1) = [1; ...
4]
v1(:,2) = [2; ...
5]
v1(:,3) = [3; ... % z-components of both 1x3 vectors in v1
6]
```

Note: the colon in parentheses indicates accessing the entirety of **v1** along that dimension — every **row** in this example.

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ToC





4 – A Preliminary Rewrite

✓ L.O.1 ✓ L.O.2 ✓ L.O.3

At this point, the component-wise multiplication in the dot product can be vectorized as follows:

```
dot_product = @(v1, v2) (v1(:,1) .* v2(:,1)) ... % multiply x-components
    .
    .
```

ToC 25/33



4 – A Preliminary Rewrite

✓ L.O.1 ✓ L.O.2 ✓ L.O.3

At this point, the component-wise multiplication in the dot product can be vectorized as follows:

```
dot_product = @(v1, v2) (v1(:,1) .* v2(:,1)) ...
+ (v1(:,2) .* v2(:,2)) ... % multiply y-components
.
```

ToC 25/33





4 – A Preliminary Rewrite

✓ L.O.1 ✓ L.O.2 ✓ L.O.3

At this point, the component-wise multiplication in the dot product can be vectorized as follows:

This mirrors the original form for the **dot_product** function.

This can be further improved using vectorized multiplication.

ToC 25/33





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4 – Using the sum Command

✓ L.O.1 ✓ L.O.2 ✓ L.O.3

v1 and v2 are both Mx3, so the operation v1.*v2 returns an Mx3 array from each element-wise multiplication.

```
v1 .* v2 = [v1(:,1) .* v2(:,1), ...
```





4 – Using the sum Command

✓ L.O.1 ✓ L.O.2 ✓ L.O.3

v1 and v2 are both Mx3, so the operation v1.*v2 returns an Mx3 array from each element-wise multiplication.

```
v1 .* v2 = [v1(:,1) .* v2(:,1), ...
v1(:,2) .* v2(:,2), ...
```

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4 – Using the sum Command

✓ L.O.1 ✓ L.O.2 ✓ L.O.3

v1 and v2 are both Mx3, so the operation v1.*v2 returns an Mx3 array from each element-wise multiplication.

```
v1 \cdot * v2 = [v1(:,1) \cdot * v2(:,1), \dots \\ v1(:,2) \cdot * v2(:,2), \dots \\ v1(:,3) \cdot * v2(:,3)];
```

The **sum** command can be used to condense this into an **Mx1** vector of every dot product: **sum** along each row.

```
sum(a, <dimension>) % sums a along the specified dimension
```

ToC 28/33





4 – Specifying an Axis for sum

✓ L.O.1 ✓ L.O.2 ✓ L.O.3

The **sum** documentation details the options for specifying the dimension along which to add elements:

- sum(a,1) sum along each column
- sum(a,2) sum along each row
- sum(a, 'all') sum every element

Therefore, the dimension 2 is appropriate for our application.

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4 – Full Vectorized Rewrite

✓ L.O.1

All together, the new and improved **dot_product** anonymous function is written as follows:

```
dot_product = @(v1, v2)
```

✓ L.O.2 ✓ L.O.3

✓ L.O.3

ToC





4 – Full Vectorized Rewrite

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⇒1 0 4

All together, the new and improved dot_product anonymous function is written as follows:

```
dot product = @(v1, v2) sum(v1 .* v2)
```

1102 **ZIO3**





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4 – Full Vectorized Rewrite

✓ L.O.1 ✓ L.O.2

⇒1 0 4

All together, the new and improved **dot_product** anonymous function is written as follows:

```
dot_product = @(v1, v2) sum(v1 .* v2, 2);
```

This function accepts two Mx3 arrays as inputs.

It computes **M** dot products between each **1x3** vector.

And most importantly, it is very easy to read!

ToC





4 – Bigger Random Inputs

✓ L.O.1

✓ L.O.3

Consider the following update to the earlier random array function:

```
random_number_array = @(size) rand(size);
```

Then, we can define two input arrays, as follows:

```
v1 = random_number_array([100, 3]);
.
```

ToC 31/33





4 – Bigger Random Inputs

✓ L.O.1

✓ L.O.3

Consider the following update to the earlier random array function:

```
random_number_array = @(size) rand(size);
```

Then, we can define two input arrays, as follows:

```
v1 = random_number_array([100, 3]);
v2 = random_number_array([100, 3]);
```

Both v1 and v2 are now Mx3 arrays.

ToC 31/33





✓ L.O.1 ✓ L.O.2

⇒1 0 4

These Mx3 arrays can be tested in the fully vectorized form of the dotProduct function:

```
>> v1 = random_number_array([100, 3]);
.
.
```

Command Window





✓ L.O.1 ✓ L.O.2 ✓ L.O.3

These Mx3 arrays can be tested in the fully vectorized form of the dotProduct function:

```
>> v1 = random_number_array([100, 3]);
>> v2 = random_number_array([100, 3]);
.
```

Command Window





✓ L.O.1 ✓ L.O.2 ✓ L.O.3

These Mx3 arrays can be tested in the fully vectorized form of the dotProduct function:

```
>> v1 = random_number_array([100, 3]);
>> v2 = random_number_array([100, 3]);
>> dot_products =
```

Command Window





✓ L.O.1 ✓ L.O.2

⇒1 0 4

These Mx3 arrays can be tested in the fully vectorized form of the dotProduct function:

```
>> v1 = random_number_array([100, 3]);
>> v2 = random_number_array([100, 3]);
>> dot_products = dot_product(v1, v2)
```

Command Window





✓ L.O.1 ✓ L.O.2 ✓ L.O.3

These Mx3 arrays can be tested in the fully vectorized form of the dotProduct function:

```
>> v1 = random_number_array([100, 3]);
>> v2 = random_number_array([100, 3]);
>> dot_products = dot_product(v1, v2)
<100x1 vector output>
```

Command Window





5 – Summary

✓ L.O.1 ✓ L.O.2

1104

This lecture covered:

✓ What vectorization is

The ability for code to execute a single operation on a whole set of data.

✓ Why vectorization could be useful in engineering

It enables large problems to be solved more quickly and in a much more visually clean manner, which simplifies the code for comprehension and debugging.

ToC 33/33





5 – Summary

✓ L.O.1 ✓ L.O.2 ✓ L.O.3

- ✓ Vectorized array operations in MATLAB
 - For addition and subtraction, no modification is required.
 - Multiplication, division, and exponentiation require the addition of a preceding period to indicate a vectorized array operation.
- ✓ Vectorization of the dot product
 - In the previous lecture, we wrote a custom function to take the dot product between two vectors. Now, we use the directional **sum** command and element-wise vectorized multiplication to solve the dot product for *many* pairs of vectors.

ToC