• Now that you've seen the product in action on a model UGV, what are your opinions on the product overall?

Theses sensors that detect obstacle are very essential to incorporate into the product. I liked the fact that it works with the time of flight sensors - they work more reliably than ultrasonic - and the algorithm works overall. I think adding more sensors would be beneficial to avoid dead spots, because right now it seems to have dead spots. It misses skinny obstacles. Another thing that you could improve is to reduce the noise from the sensors. There seem to be a few cases where the sensors don't work right - it works 90% of the time.