

# Assignment 2: Question 5

October 29, 2023 3:39 PM

## Target Registration

- Module to register tumor target point from CT  $\rightarrow$  Ch frame

Input:  $TP_{CT}$ ,  $M1_{CT}$ ,  $M2_{CT}$ ,  $M3_{CT}$ ,  $M1_{Ch}$ ,  $M2_{Ch}$ ,  $M3_{Ch}$

Output:  $TP_{Ch}$

Testing: Sketch  $F_{Ch \leftarrow CT}$ , prove  $M_{1,2,3 CT} \rightarrow M_{1,2,3 Ch}$

### Strategy:

- Make Frames of  $M_{1,2,3 CT}$  using generate Ortho Frame Function with  $M_{1,2,3}$  as A, B, C
- Make Frames of  $M_{1,2,3 Ch}$  " "
- Find the Transformation Matrix using Frame Transform to Home with  $O_C, e_1, e_2, e_3$  from new ortho frames
- Take the Transformation matrices and multiply to find  $F_{CT \rightarrow Ch}$

### Solution:

We can see that a trivial linear transformation exists:

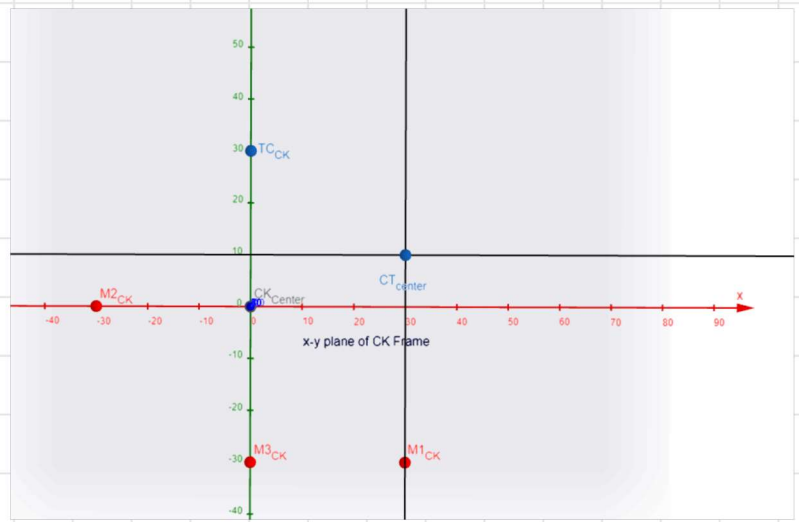
From markers it is clear

that the transformation is

$$M_{1,Ch} - M_{1,CT} = (30-0, -30+40, 0+10) = \begin{matrix} x & y & z \\ (30, 10, 10) \end{matrix}$$

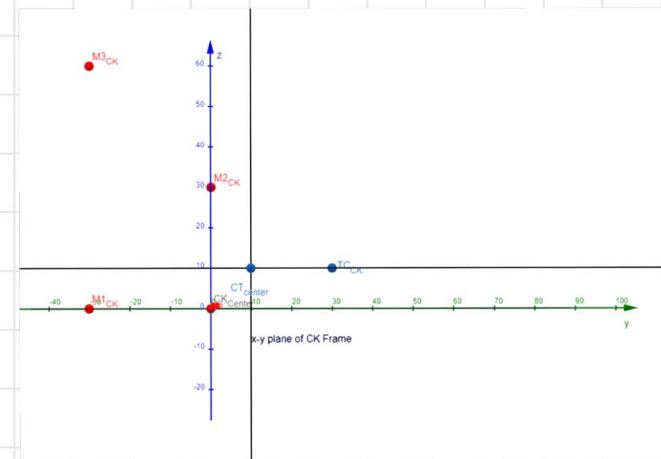
$$\begin{matrix} F_{CT \rightarrow Ch} \\ \begin{bmatrix} 1 & 0 & 0 & 30 \\ 0 & 1 & 0 & 10 \\ 0 & 0 & 1 & 10 \\ 0 & 0 & 0 & 1 \end{bmatrix} \end{matrix} \begin{matrix} TP_{CT} \\ \begin{bmatrix} -30 \\ 20 \\ 20 \\ 1 \end{bmatrix} \end{matrix} = \begin{matrix} \begin{bmatrix} -30+30 \\ 20+10 \\ 20+10 \\ 1 \end{bmatrix} \\ \begin{matrix} TP_{Ch} \\ \begin{bmatrix} 0 \\ 30 \\ 30 \\ 1 \end{bmatrix} \end{matrix}$$

If we did not jump to a transformation matrix from the observation that each points is linearly transformed (30, 10, 10) in x,y,z then we could generate planes using the markers as input



We can see how to generate an orthonormal frame given any 3 points on the left:

We can then use the orthonormal frames from the MCK and MCT points to populate a transformation matrix



### Orthonormal vector



Given any three unique points:

(or for orthonormal basis  $i, j, k$ )

$i = \text{normalized}(B-A)$  (vector from A to B)

$k = \text{normalized}(i \times (C-A))$  // vector orthogonal to AB and AC

$j = i \times k$  (orthogonal to  $i$  and  $k$ )

Complete basis  $i, j, k$

where  $i = e_1, j = e_2, k = e_3$

Center of gravity point between A, B, C

$$O_c = \frac{A+B+C}{3}$$

For MCK

$$O_c = [-30, -30, 20]$$

$$e_1 = [-0.9165, 0.4082, 0.4082]$$

$$e_2 = [0.412, -0.4364, 0.8724]$$

$$e_3 = [0.5345, 0.8018, 0.1673]$$

For MCT

$$O_c = [0, -20, 30]$$

$$e_1 = [-0.8165, 0.4082, 0.4082]$$

$$e_2 = [0.2182, -0.4044, 0.8724]$$

$$e_3 = [0.53, 0.80, 0.17]$$

We can see from the basis vectors that the following matrices get created:

```
T_CK =  
  
-0.8165    0.2182    0.5345   -30.0000  
 0.4082   -0.4364    0.8018   -30.0000  
 0.4082    0.8729    0.2673    20.0000  
      0         0         0      1.0000
```

```
T_CT =  
  
-0.8165    0.2182    0.5345         0  
 0.4082   -0.4364    0.8018   -20.0000  
 0.4082    0.8729    0.2673    30.0000  
      0         0         0      1.0000
```

which by taking the multiple of  $T_{CT} \times T_{CK}^{-1}$   
We find the transformation matrix as predicted:

```
T_CT_to_CK =  
  
 1.0000         0    0.0000   30.0000  
-0.0000    1.0000   -0.0000   10.0000  
 0.0000    0.0000    1.0000   10.0000  
      0         0         0      1.0000
```