

Declutterization

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Overview of the Declutterizer

1. Generate cluttered images using the Clutterizer
2. Train an SVM using clutter images
3. Use the SVM to identify clutter in a novel clutter image
4. Merge adjacent bounding boxes with the same label

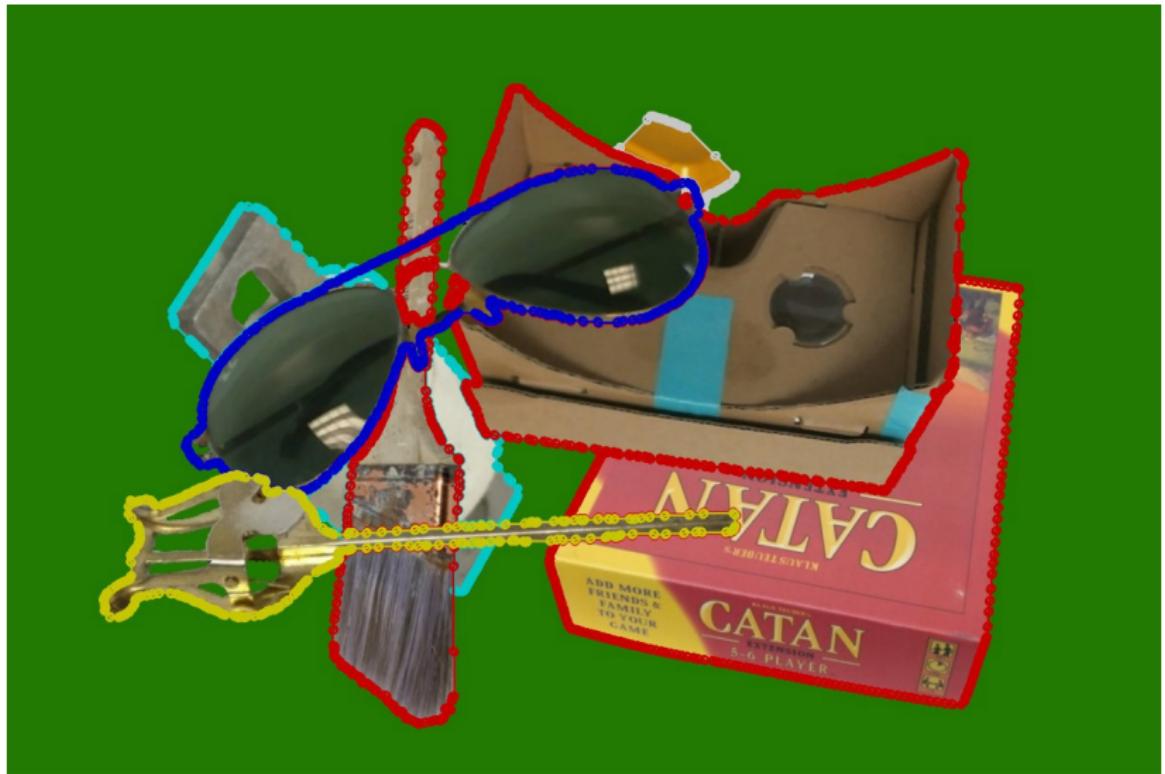
Clutterization Process

1. Images of individual objects were converted to PNGs with transparent backgrounds by hand.
2. A scene is initialized to a random color.
3. A random subset of objects are selected, resized, and rotated.
4. The modified objects are added to the scene in a random order. The algorithm keeps track of their boundaries and occlusions.
5. A labelme-formatted json file is written which corresponds to the generated clutter.

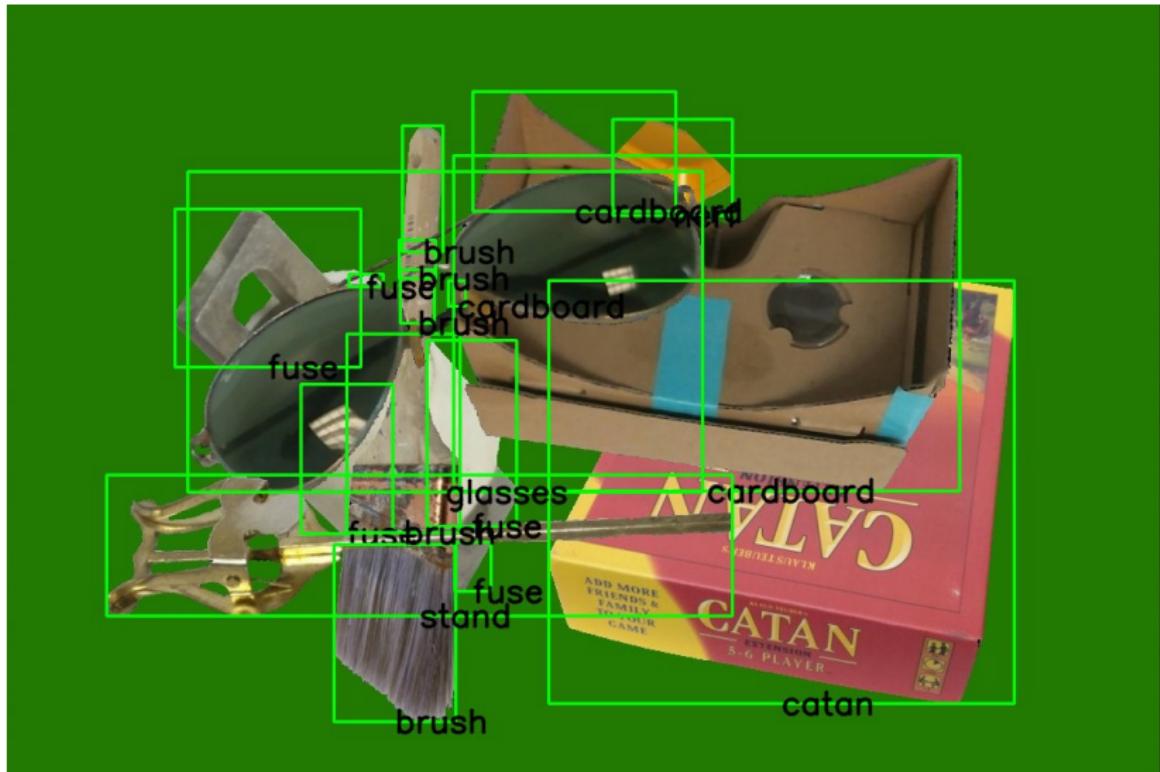
Clutterization Example



Clutterization Example (cont)



Clutterization Example (cont)



Feature Extraction

The following features are extracted:

- ▶ Normalized color histogram for the Hue channel in HSV colorspace
- ▶ Normalized LBP histograms for:
 - ▶ 24 points at a radius of 8 pixels
 - ▶ 16 points at a radius of 4 pixels
 - ▶ 12 points at a radius of 2 pixels
 - ▶ 8 points at a radius of 1 pixel (standard LBP)
- ▶ Both feature spaces are rotation invariant.

SVMs

Two models were employed in the solution:

- ▶ An SVM with an RBF kernel for classification (NuSVC in sklearn)
- ▶ A K-nearest-neighbors model for anomaly detection (LocalOutlierFactor in sklearn)

Training

The models were trained using two different sources:

- ▶ The 92 images of the 10 objects that were converted to PNG, with backgrounds masked
- ▶ 70 clutterized images (generated from the PNG images)

In each case, the images were traversed with a sliding window.
The system was then validated on 30 clutterized images.

Additional parameters

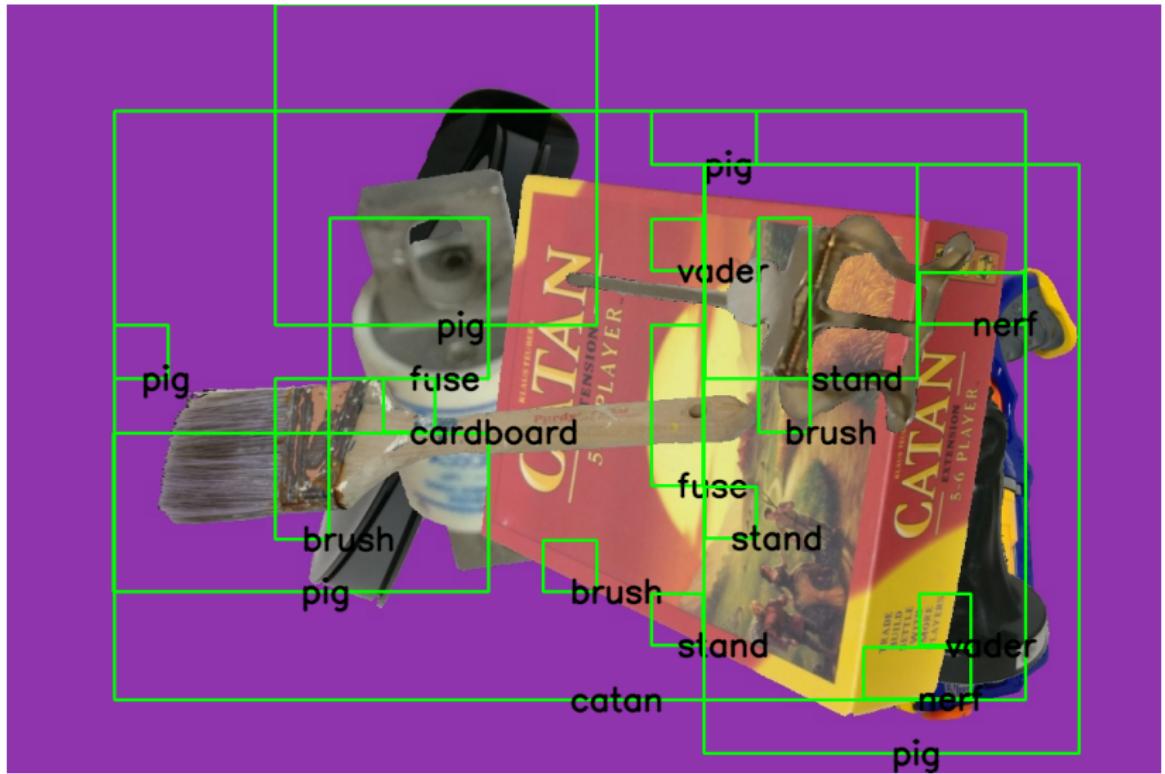
The following additional parameters were used:

- ▶ Sliding window size: 100x100 pixels
- ▶ Sliding window stride: 50 pixels
- ▶ Likelihood threshold to classify: 0.15

Validation example



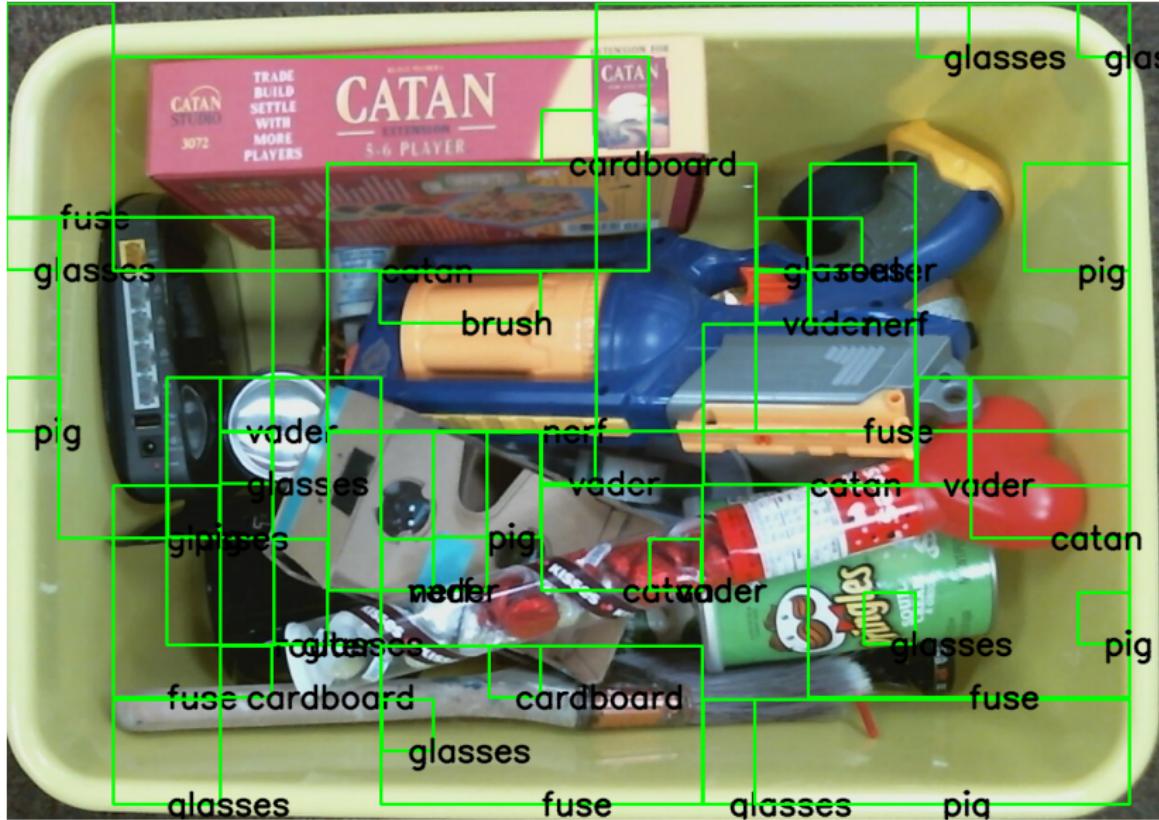
Validation example (bad)



Validation results

Average Precision	(AP)	@[IoU=0.50:0.95	area= all	maxDets=100] = 0.008
Average Precision	(AP)	@[IoU=0.50	area= all	maxDets=100] = 0.028
Average Precision	(AP)	@[IoU=0.75	area= all	maxDets=100] = 0.003
Average Precision	(AP)	@[IoU=0.50:0.95	area= small	maxDets=100] = 0.000
Average Precision	(AP)	@[IoU=0.50:0.95	area=medium	maxDets=100] = 0.000
Average Precision	(AP)	@[IoU=0.50:0.95	area= large	maxDets=100] = 0.021
Average Recall	(AR)	@[IoU=0.50:0.95	area= all	maxDets= 1] = 0.030
Average Recall	(AR)	@[IoU=0.50:0.95	area= all	maxDets= 10] = 0.040
Average Recall	(AR)	@[IoU=0.50:0.95	area= all	maxDets=100] = 0.040
Average Recall	(AR)	@[IoU=0.50:0.95	area= small	maxDets=100] = 0.000
Average Recall	(AR)	@[IoU=0.50:0.95	area=medium	maxDets=100] = 0.003
Average Recall	(AR)	@[IoU=0.50:0.95	area= large	maxDets=100] = 0.070

Declutterization example



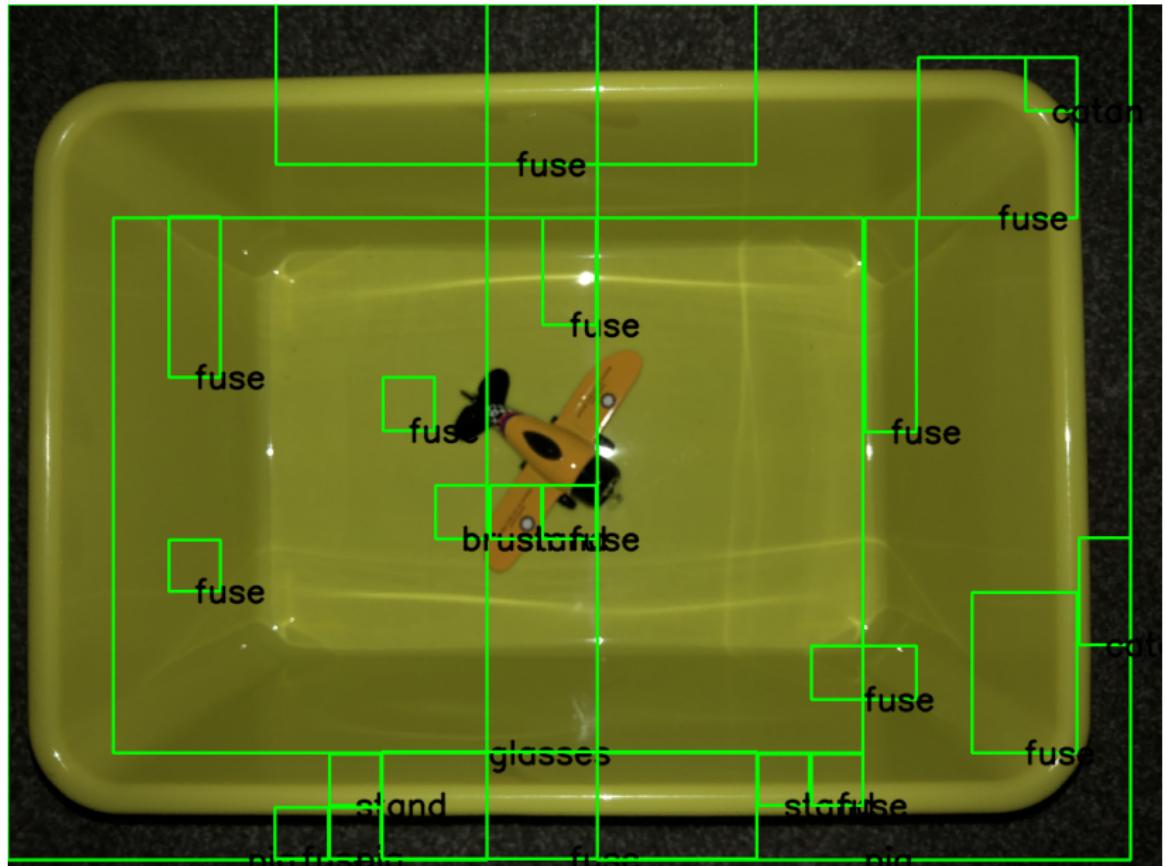
Declutterization example (bad)



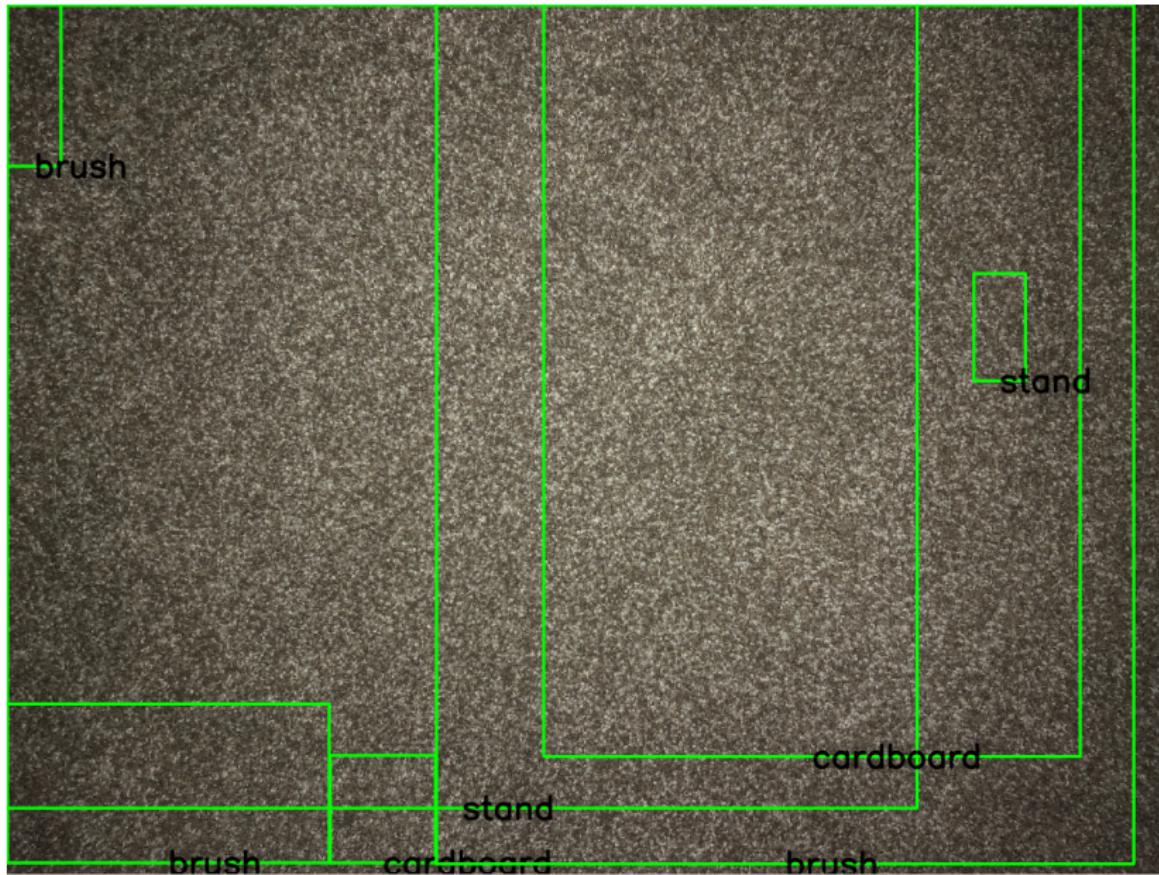
Declutterization results

Average Precision	(AP) @[IoU=0.50:0.95	area=	all	maxDets=100] = 0.001
Average Precision	(AP) @[IoU=0.50	area=	all	maxDets=100] = 0.002
Average Precision	(AP) @[IoU=0.75	area=	all	maxDets=100] = 0.000
Average Precision	(AP) @[IoU=0.50:0.95	area=	small	maxDets=100] = 0.000
Average Precision	(AP) @[IoU=0.50:0.95	area=	medium	maxDets=100] = 0.000
Average Precision	(AP) @[IoU=0.50:0.95	area=	large	maxDets=100] = 0.001
Average Recall	(AR) @[IoU=0.50:0.95	area=	all	maxDets= 1] = 0.009
Average Recall	(AR) @[IoU=0.50:0.95	area=	all	maxDets= 10] = 0.016
Average Recall	(AR) @[IoU=0.50:0.95	area=	all	maxDets=100] = 0.016
Average Recall	(AR) @[IoU=0.50:0.95	area=	small	maxDets=100] = 0.000
Average Recall	(AR) @[IoU=0.50:0.95	area=	medium	maxDets=100] = 0.000
Average Recall	(AR) @[IoU=0.50:0.95	area=	large	maxDets=100] = 0.019

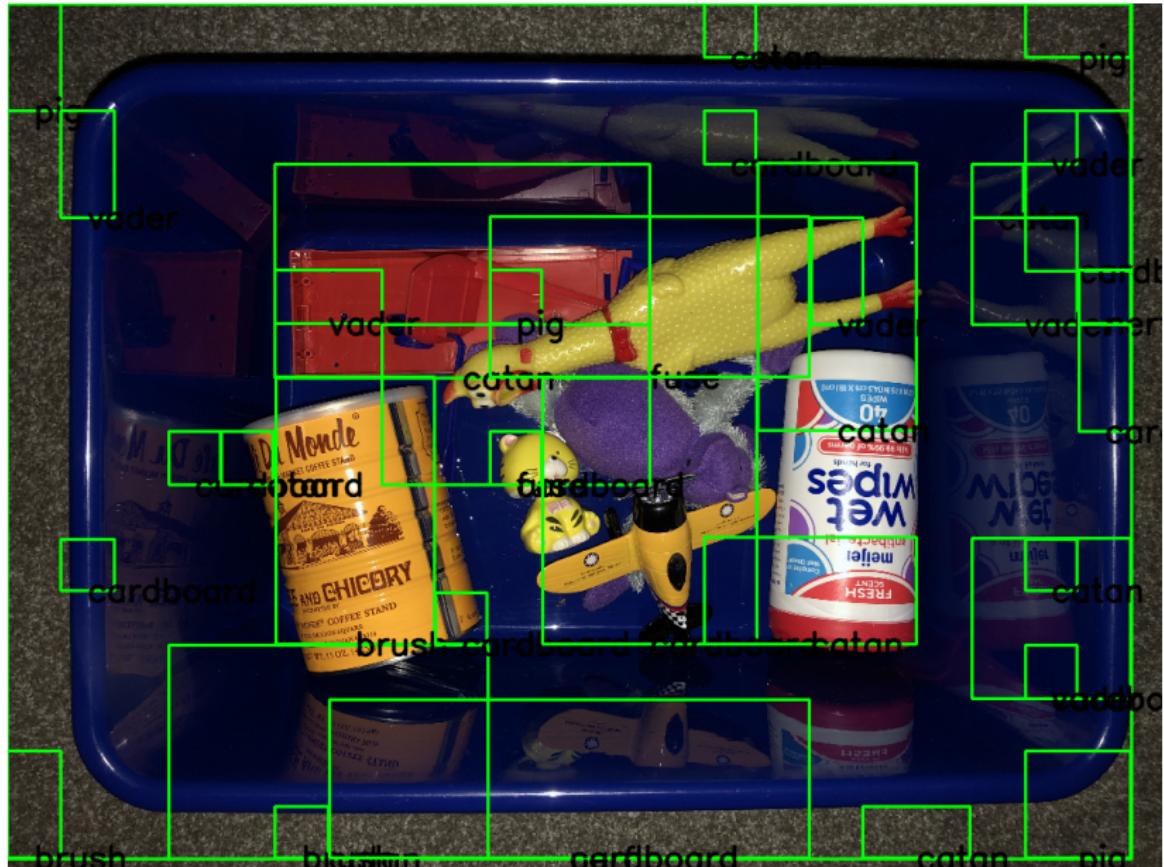
Unknown input



Unknown input



Unknown input



Conclusions

- ▶ Qualitatively, the system does provide useful results.
- ▶ Using the official COCO scoring method, the system looks really bad.
- ▶ When tested on the unknown input, the system produces many false-positives.