# A Gentle Introduction to Machine Learning

Third Lecture Deep Learning - A Closer Look



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# Outline of the Deep Learning Lecture

- What is deep learning
- Some motivation
- Enablers
  - Data
  - Computation
  - Training Algorithms & Tools
  - Network Architectures
- Closing examples

### Al In The News Lately

- "The development of full artificial intelligence could spell the end of the human race ... it would take off on its own, and re-design itself at an ever increasing rate. Humans, who are limited by slow biological evolution, couldn't compete, and would be superseded." – Stephen Hawking
- "I think we should be very careful about artificial intelligence. If I had to
  guess at what our biggest existential threat is, I'd probably say that. So we
  need to be very careful." Elon Musk
- "Artificial intelligence is the future, not only for Russian, but for all of humankind. It comes with colossal opportunities, but also threats that are difficult to predict. Whoever becomes the leader in this sphere will become the ruler of the world." – Vladimir Putin

There is **a lot of hype** about the capabilities of AI, mainly driven by recent advances in **deep learning** 

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### But Deep Learning Is Not All Hype

No threat to humanity in sight, but impressive applications...

- Google: "1000 deep learning projects"
  - Extending across search, Android, Gmail, photo, maps, translate, YouTube, and self-driving cars. In 2014 it bought DeepMind, whose deep reinforcement learning project, AlphaGo, defeated the world's Go champion.
- Microsoft
  - Speech-recognition products (e.g. Bing voice search, X-Box voice commands), search rankings, photo search, translation systems, and more.
- Facebook
  - Uses DL to translate about 2 billion user posts per day in more than 40 languages (About half its community does not speak English.)
- Baidu (China's Google)
  - Uses DL for speech recognition, translation, photo search, and a self-driving car project, among others.

Source: Fortune.com

Rapid progress, hardly a day without some new application

# The State of Deep Learning

### State-of-the-art results in:

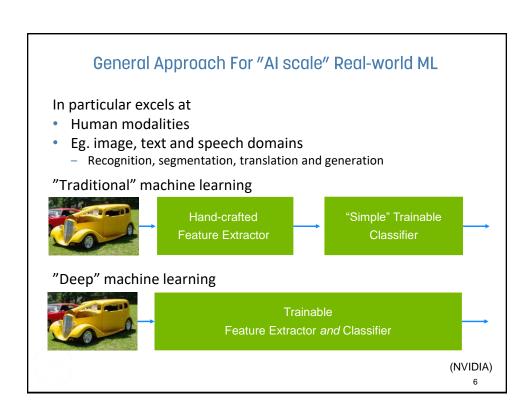
- · Computer vision (e.g. object detection)
- Natural language processing (e.g. translation)
- Speech recognition/synthesis

### Promising results:

- Robotics
- Content generation

Real-world applications are mainly in **supervised learning**, deep reinforcement and unsupervised learning are still less mature

### So, what is deep learning?!



### What Learning Algorithm Goes In The Box?

Why did we want feature extraction in the first place?

- Remember the limitations and pitfalls of supervised learning
- Curse of dimensionality: Input dimension increases data requirements, worst-case exponentially
- If we can also learn feature extractors, we can get around this

E.g,  $y = f_{\text{classifier}}(g_{\text{features}}(D))$ , want to learn both f() and g() from raw data D

- Must be a powerful model, ideally able to approximate arbitrary functions f and g...
- Want something that can learn compositions of functions f(g(...)), like layers...

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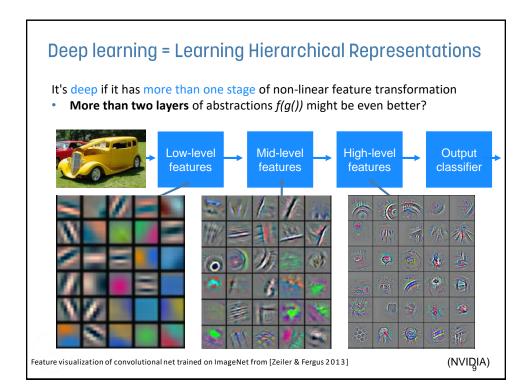
# What Learning Algorithm Goes In The Box?

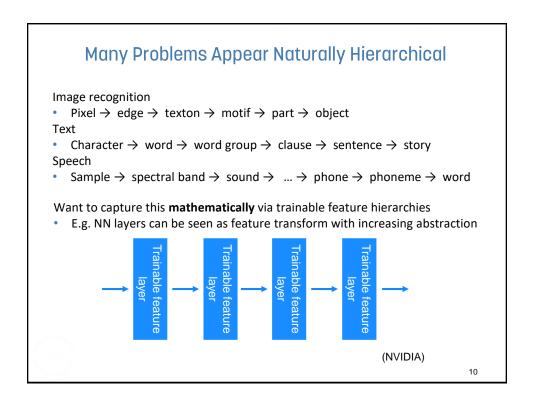
Why did we want feature extraction in the first place?

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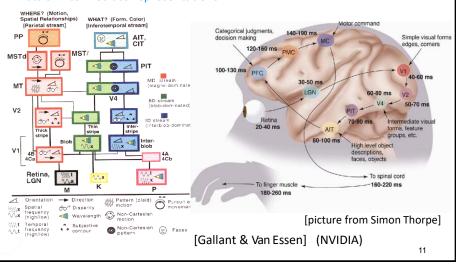
- Must be a powerful model, ideally able to approximate arbitrary functions f and g...
- Want something that can learn compositions of functions f(g(...)), like layers...
- Multi-layer Neural Networks is by far the most common choice





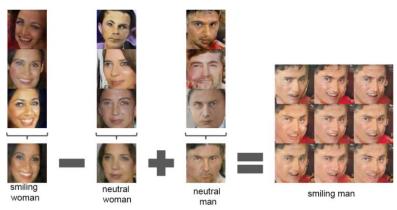
### Additional Support: The Visual Cortex is Also Hierarchical

- The ventral (recognition) pathway in the visual cortex has multiple stages Retina LGN V1 V2 V4 PIT AIT ....
- Lots of intermediate representations





Generated similar examples using learned high-level features



Input examples -> Arithmetic on high-level features -> Results

Clearly learning some kind of abstraction

Such "concept arithmetic" doesn't always work this well...



# So Why Is Deep Learning Taking Off Now?

People have been using Neural Networks for decades

 BUT, it turns out you need massive scale to really see the benefits of multiple layers

Learning deep models means more layers = more parameters

- More parameters requires more data ("identifiability", overfitting)
- More parameters means more computation

Deep Neural Networks (DNNs) may have **millions to billions** parameters, trained on very large data sets

Until recently, this was not feasible

# Overview: Deep Learning Driven By...

### Larger data sets

"Big data" trend, cheap storage, internet collaboration

### **Faster training**

• Hardware, algorithms and tools (e.g. Tensorflow)

### Network architectures tailored for input type

• E.g. images, sequential data. Can be combined (e.g. video)

Heuristics for reducing overfitting during training

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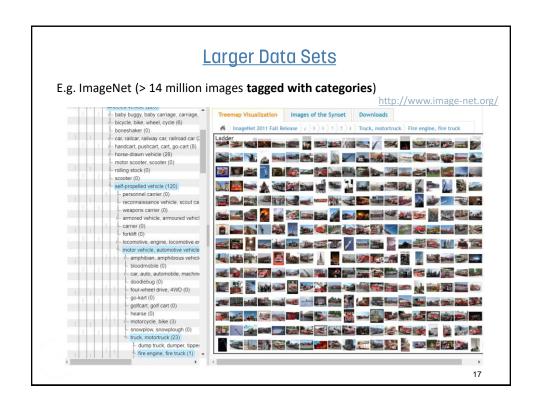


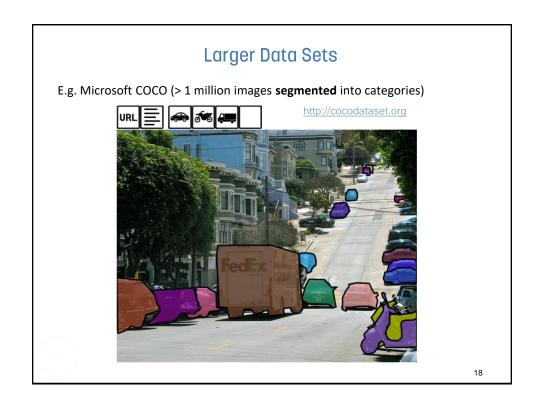
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### Companies Collect Large Private Data Sets

Internet companies like Google, Facebook and Microsoft collect plenty of data, only some of it is public (e.g. Youtube data set)

- · Can get much for free from users
- Data is a competitive advantage

All major car manufacturers are researching autonomy, many are betting on deep learning

- E.g. Tesla is betting heavily on object detection from cameras
  - Can automatically collect raw images from their autopilot(?)

Supervised (deep) learning is the most mature technology, inputs  $\mathbf{x}$  often collected automatically, but they still need somebody to provide correct outputs  $\mathbf{y}$  (e.g. labels, segmentation etc)

- Such companies can have large teams just doing labeling
- Sometimes outsourced to other countries, or Amazon Mechanical Turk

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# **Faster Training**

### Consumer Desktop CPU as of 2016

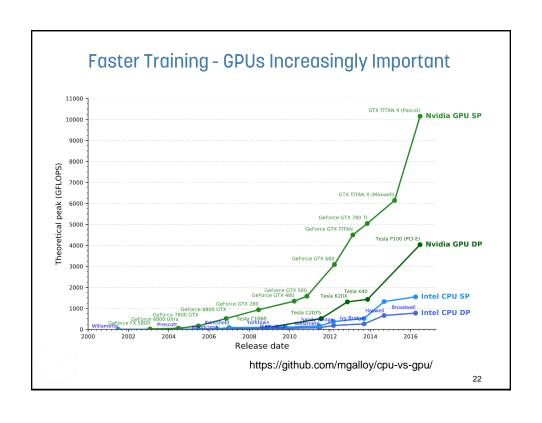
• Speed: ~1 TFLOPS (10^12 Floating Point Operations Per Second)



### Consumer Graphics Card (GPU)

- ~Speed: 10 TFLOPS (single precision)
- Cost: ~\$1000
- Task must be extremely parallellizable
- Neural networks are, e.g. all neurons in each layer are independent given inputs
- GPUs key enabler of deep learning





### Faster Training - Deep Learning "Supercomputer"

- Computation for deep learning is increasingly big business
- NVIDIA has recent integrated solutions based on their GPU-technology



- Speed: 80-170 TFLOPS (as of 2017)
- Cost: \$150 000 and up...



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# Faster Training - Beyond GPU's -> Custom Hardware

Google recently designed custom chips (ASICs) speficially for neural networks

These "Tensor Processing Units" are organized into "pods"



- Speed: 11 500 TFLOPS per pod (2017)
- Cost: Trade secret
- The speed of custom hardware usually comes at the cost of flexibility

# Faster Training - Algorithms

Many algorithms proposed to speed up training

Mainly fall into two categories,

- Approximate gradient calculation of your NN
  - E.g. stochastic gradient descent (SGD) variants
- Modifying your NN for faster derivatives or converging in fewer iterations
  - E.g. different activation functions or network structure

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# Faster Training - Stochastic Gradient Descent I

Remember, training objective is a loss function against **all examples**  $(x_i, y_i)$  for different weights w

$$L(w) = \sum_{i=1}^{n} (NN_{w}(x_{i}) - y_{i})^{2}$$

Want to find w that gives low loss against examples

• Gradient descent: Update w by computing gradient,  $O(n \cdot w)$  using the backpropagation algorithm (lecture 1)

If we have millions of data points, do we really need all of it for useful gradients?

### Faster Training - Stochastic Gradient Descent

Insight: If we just compute gradients for a **randomly selected subset m** of the total n examples, we get a *faster approximation* 

Mini-batch SGD:

- 1. Put data set in random order, start at position p = 1
- 2. Compute gradients of partial loss for m data points at a time,

$$\widehat{L}(w) = \sum_{i=p}^{p+m} (NN_w(x_i) - y_i)^2$$

3. Set p = p + m. When end of data set reached, restart at step 1.

Complexity:  $O(m \cdot w)$ , where **m** typically 1-50, much less than n = millions.

 The approximation over sevaral steps will average out, and have much lower computational cost

SGD Exact GD

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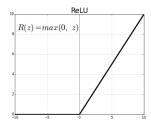
Sigmoid activation

# Faster Training - Modifying the Network

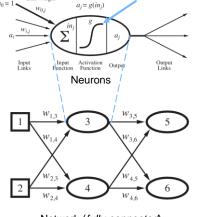
Remember the mathematical structure of neural network models:

To make optimization take fewer steps, we can change **activation function** or **connections** 

The **most common** activation function these days is the **RelU**, R(z) = max(0,z)



Simpler gradients and more stable over time!



Network (fully-connected)

# Training Tools - Generalized Backpropagation

Learning these advanced representations raises two issues:

- Deep learning often uses very large networks with very large ("Big Data") training set
- Advanced representations may require modifications to backpropagation

**Reverse-mode Automatic Differentiation** is a technique that generalizes backpropagation to differentiate arbitrary scalar (loss) functions

Recent data flow languages like **Tensorflow** (Google), **Torch** and **Theano** let you define **arbitrary models** from primitive mathematical operations and optimize them on or several **GPUs** 

Can be orders of magnitude faster!

Will we ever have to manually differentiate again? ©

# Tensorflow.org

# Code Examples: Tensorflow NN Training

- See workbook at: <a href="https://goo.gl/UHdwBX">https://goo.gl/UHdwBX</a>
  - Choose File->Save Copy in Drive to run and edit your own version
- Recall, in the ML Lecture 1 code examples we used a grad() function to compute the gradients of the loss function.
- This was from the Autograd package which also uses automatic differentiation like Tensorflow, but directly on python code (slower but easier to use)

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**Heuristics** for **reducing overfitting** during training

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# Network Architectures Tailored to Input Type

The best results have been achieved mixing in other **network structures** than just fully-connected

Fully connected scales poorly with high-dimensional inputs such as images,

- e.g. RGB HD image is 3x1920x1080 = 6M inputs
- Assume 1000 neurons in first layer
- Then each fully-connected neuron will have a weight for each input,
   1000x6M = 6 billion weights just in the first layer

The idea is to reduce the number of connections by capturing the **structure in the problem** 

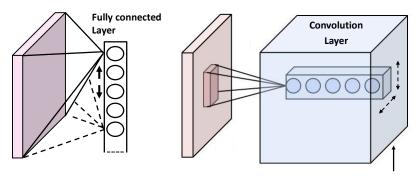
One very successful network structure is convolutional neural networks

- "Convolution" layers
- "Pooling" layers
- Fully-connected output layers

# **Architectures - Convolutional Layers**

Insight: Patterns (objects) in an image are translation "invariant"

In a convolutional layer, the same neurons are applied to a sliding window over the inputs (e.g. image), for each input coordinate (e.g. pixel in image)



Each CNN neuron is a 2D pattern extractor ideal for image data CNNs retain a lot of information even **with few neurons** 

Input (image) sized outputs

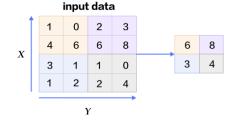
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# **Architectures - CNN Pooling Layers**

Insight: Patterns exist at different scales, want capture increasingly higher levels of abstraction

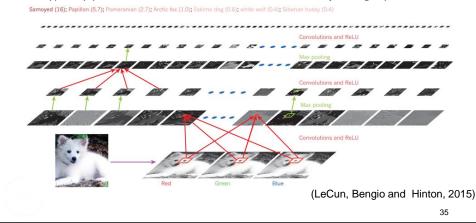
**Pooling layers** force the network to summarize information by "downsampling"

- In an image we go from higher to lower resolution
- Typically done by splitting image into regions and taking the max value
- E.g, used after convolutional layers, selects highest signaling neuron (pattern extractor)



### **Architectures - Convolutional Neural Networks**

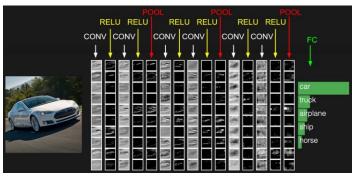
- Bringing it together into one network, in summary
- "Convolutional" layers are for each pixel only fed inputs only from the local neighborhood to capture object translation
- "Pooling" (downsampling) layers to work at different scales (abstraction)
- Typically you interleave convolutions with ReIU and pooling layers



# **Architectures - CNNs for Object Recognition**

Object recognition from images is a typical classification task.

You typically add **fully-connected layer**(s) **at the end** to train a traditional classifier and the CNN features, jointly

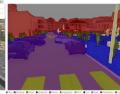


Karpathy, http://cs231n.github.io/convolutional-networks/



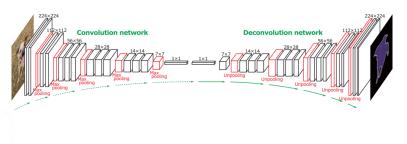
Segmentation (typically images) requires us to classifiy each input (pixel),
 e.g. network output is same dimension as input





Classes: Road, car, pedestrian, building, pole, etc. (NVIDIA)

Deconvolutional networks do reverse convolution and pooling



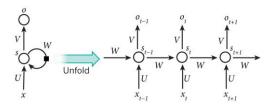
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### Architectures - CNN Demo

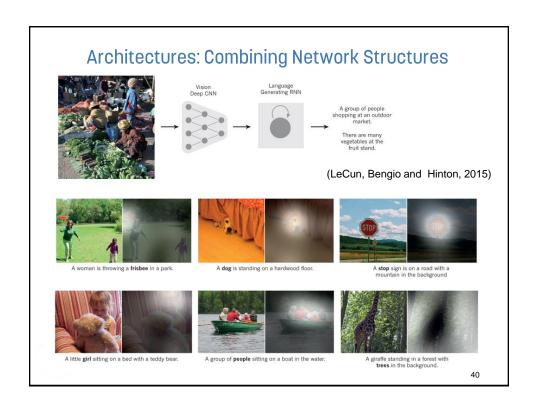
- Online javascript CNN demo: http://cs.stanford.edu/people/karpathy/convnetjs/demo/cifar10.html
- See also the CNN code example in our Tensorflow workbook
  - https://goo.gl/UHdwBX

### **Architectures: Recurrent Neural Networks**

- We used the Bag of Words feature vector in the spam classification example. It's simple but it discards the sequential structure in text
- This is flawed since the meaning of a text strongly depends on the order of the words!
- **Recurrent Neural Networks (RNN)** depend not only on current input **x**, but also **remembers** internal state *s* from previous inputs (e.g. words)
- RNNs can be difficult to train (variants: "Long Short-Term Memory",
   "Gated Recurrent Unit")



(LeCun, Bengio and Hinton, 2015)





Paper: <a href="http://cs.stanford.edu/people/karpathy/deepimagesent/">http://cs.stanford.edu/people/karpathy/deepimagesent/</a>

Demo: <a href="http://cs.stanford.edu/people/karpathy/deepimagesent/rankingdemo/">http://cs.stanford.edu/people/karpathy/deepimagesent/rankingdemo/</a>

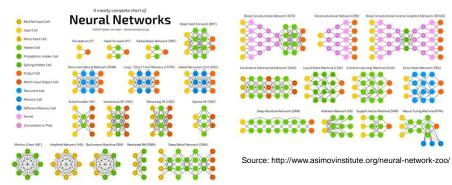
Impressive, but not perfect. Some "weird" mistakes highlight on-going debate on what neural networks have really learned.



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### **Architectures: The Neural Network Zoo**

Many different types of structure, more or less modular components



...and more keeps being invented

### **Applications - What About Reinforcement Learning?**

Examples so far have been mostly supervised learning, as it is the most mature and has most real applications

Several impressive research results, e.g:

The ATARI video-game playing example from the RL lecture used "fitted"
 Q-learning, where the Q-function Q(s,a) was fed raw pixels as state s,
 enabled by representing it as a CNN

That was two years ago, although not as mature as SL, deep RL is a hot research area

From 80's 2D ATARI to 90's "3D" Doom in <2 years</li>

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# Deep Reinforcement Learning - Example

In first-person shooters like Doom the player can only observe part of the map at a time

The agent needs memory!

Q-learning Doom directly from **video** by using **CNN + RNN** for Q-function



### Deep Reinforcement Learning - Example II

Last year, the OpenAI research institute beat human experts in the popular game of Dota 2, although a simplified scenario

- Towards learning strategies in team games
- This year they played human pro's in full scenarios
  - Example: <a href="https://youtu.be/TFOQnzvBHdw">https://youtu.be/TFOQnzvBHdw</a>

### Dota 2

We've created a bot which beats the world's top professionals at 1v1 matches of Dota 2 under standard tournament rules. The bot learned the game from scratch by self-play, and does not use imitation learning or tree search. This is a step towards building AI systems which accomplish well-defined goals in messy, complicated situations involving real humans.

□ REWATCH LIVE EVENT

DEAD MODE

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### Heuristics for reducing overfitting during training

- Several: Dropout, BatchNormalization, etc..
- Outside the scope of this course, but lots of DL material out there on the web.

### If Time Permits - Exjobb Opportunities

- I do research at intersection of AI, machine learning and robotics
  - Remember e.g. deep learning + quadcopter video in previous lecture
- Students interested in an academic exjobb can mail me at olov.a.andersson@liu.se
- Example topics include deep learning applications and optimization-based control
  - Math background corresponding to engineering or statistics degree helps

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# **Closing Remarks**

- Deep learning tries to learn multiple levels of abstraction to overcome the curse of dimensionality
- Bottlenecks: requires lots of data (and computation) to train
- Mainly based on multi-layer neural networks of various architectures
- An area with great potential. Lots of hype but also some impressive results
- Quickly evolving, best practices for training DNNs change almost every year

Thank you for listening!

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