(872) 233 - 9671 Chicago, Illinois ntouboul@hawk.iit.edu

# Nathan Touboul

## **Software Engineer**

SKILLS

**Programming** Python - C++ - JavaScript - Linux - BASH

**Tools** Git - LaTeX - Matlab/Simulink Language French (Native) - English (Fluent)

#### TECHNICAL EXPERIENCE

#### Research Project: Navigation Integrity of Lidar-based localization

Navigation Lab - Illinois Institute of Technology

Sep 2021 - Dec 2021

GitHub: NathanTouboul

LinkedIn: nathantouboul

Chicago, Illinois

- Lidar-based localization of autonomous vehicles, in an area with low GNSS availability, with Velodyne's Puck sensor and MATLAB modelization, to compensate for IMU drift. Building a method to ensure landmark identification against the misassociation problem.

- I established a Misdetection Error Model to quantify the Probability of Hazardously Misleading Information. I derived precise  $\sigma$  and  $3\sigma$ probabilities of tree misdetection, considering the noise parameters of the vehicle, the sensor, and the landmarks. I also researched the implementation of the Error Correction Codes domain (Hamming and BCH codes) to navigation safety.

#### Assistant Engineer Internship: Machine Learning and Data Science Project Kapaix Ltd

Jun 2021 - Aug 2021

London, England (Remote)

- Assessing the data quality of a time-series database for a Big Data Management Company. I designed neural network architectures for anomaly detection purposes by analyzing discrepancies of frequency and amplitude. Two models: classification (MLP architecture) and pattern recognition (auto-encoder) models built with Python: Keras - TensorFlow - Pandas.
- I preprocessed the dataset through the construction of histograms with variable time frames. I used **Principal Component Analysis** and k-means clustering as a first analysis tool.

## Master's Thesis: Isogeometric Representation of Turbojet Blades

Sep 2020 - Dec 2020

Structure Mechanics laboratory - INSA

Lyon, France

- Building an algorithmic solution to merge CAD and FEA methods through Non-Uniform Rational Basis Spline (NURBS) manipulations. I designed an adaptive fillet to join the blade and its root volumes by implementing a fillet patch mesh on Python: NumPy - geomdl.
- I analyzed the structure of engine blades using parametrization models by projection, interpolation, and approximation.

**Management Internship** Jul 2018- Aug 2018

**Firplast** 

Lyon, France

I contributed to the daily operations of a local French company, from materials handling and inventory management to accounting and HR communications. This hands-on business experience allowed me to discover every level of a company.

## **EDUCATION**

### Master of Engineering - Illinois Institute of Technology

Jan 2021 - Dec 2021

Robotic Motion Planning (SLAM, Kalman filter) – EV Powertrain (EPA drive cycles) – Machine Learning (PCA, clustering, Bayesian, CNN, RNN) - CAD/CAM (Fusion 360)

- > Drive cycle designed for autonomous vehicles; testing Wh SOC consumption; simulation of the pursuit of a standard vehicle
- > Graph SLAM algorithm implementation on the Victoria Park dataset

### Master of Science in Mechatronics- National Institute of Applied Sciences - France

2018 - 2020

- Control Theory (PID, optimal control LQR) Robotics, State-Space Analysis (Simulink) FEA (Ansys, Abaqus) Fluid dynamics, Thermodynamics CAD (CATIA, SolidWorks) > CAD project on SolidWorks: conception of a planter subsystem for the agricultural Company "L'Atelier Paysan"
- > Kinematics and dynamics modeling of a Scara Robot; PID and linearized command control
- > Consciousness and Neuroscience project: Statistical and Bayesian brain research

#### Bachelor of Engineering in Electronics and Computer Science - CPE Lyon - France

2015 - 2018

2019 - 2020

Analog and Digital Systems (Microcontrollers implementation) - Electronic Architectures (VHDL Design on FPGA) - Programming - Mathematics - Physics - Business

#### **ACTIVITIES**

**Graduate Student Ambassador** Apr 2021 — Dec 2021 Job on Campus, Admissions Office at Illinois Tech (Salesforce and GeckoEngage Chatbot)

**Student Government Association at INSA Lyon** 

2017 - 2020

**Physics and Mathematics tutor**