## Optimization Problem

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## 1 Problem

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Algorithm: set t_0=0 while t_i < t_{final} for i=1,\ldots to end solve: min_{t_i}-t_i-\alpha\int_{t_{i-1}}^{t_i}ln(v(t))dt-\alpha\int_{t_{i-1}}^{t_i}ln(v_{thresh}-v(t))dt s.t. v'-av=I(t), \quad t_i>t_{i-1}, \quad v(t_i)=v(t_{i-1})=0 end
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On the last interval  $[t_i, t_{final}]$  we gaurentee the solution will not jump, therefore we only need to solve the ODE with initial condition  $v(t_i) = 0$   $\alpha$  is barrier parameter (small i.e  $10^{-6}$ ). We can eventually get derivatives with this approach. The barrier terms enforce that we require  $0 \le v(t) \le v_{thresh}$  for all t.