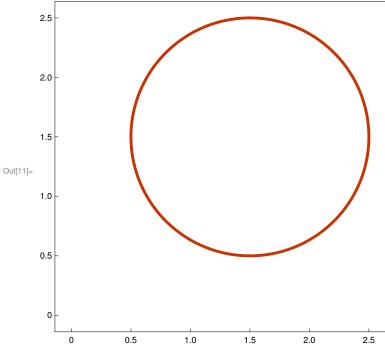
# Shapes 3

```
in[1]:= i2 = {1, 0};
j2 = {0, 1};
i3 = {1, 0, 0};
j3 = {0, 1, 0};
k3 = {0, 0, 1};
```

```
 \begin{aligned} & & \text{In}[6] := \ x = 1.5; \\ & & \text{y1} = 1.5; \\ & & \text{R} = 1; \end{aligned} \\ & & \text{In}[9] := \ x = R * \text{Sin}[t] + x1; \\ & & \text{y} = R * \text{Cos}[t] + y1; \end{aligned} \\ & & \text{In}[11] := \text{ParametricPlot}[\{x, y\}, \{t, 0, 2 \text{ Pi}\}, \text{PlotTheme} \rightarrow \text{"Web", AxesOrigin} \rightarrow \{0, 0\}] \\ & & \text{2.5} \end{aligned}
```

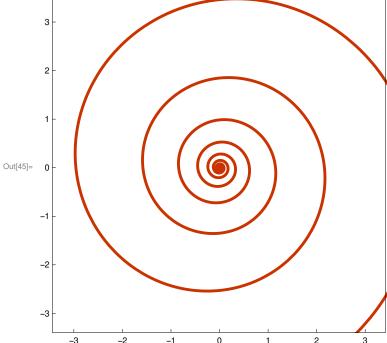


Out[30]= 15.8654

```
ln[12] := r = x * i2 + y * j2
                            r' = D[r, t]
                            Integrate [Norm[r'], \{t, 0, 2 Pi\}]
Out[12]= \{1.5 + Sin[t], 1.5 + Cos[t]\}
Out[13]= \left\{ Cos[t], -Sin[t] \right\}
Out[14]= 2\pi
                            Question 2
  In[15]:= Clear["Global`*"]
                            i2 = \{1, 0\};
                            j2 = \{0, 1\};
                            i3 = \{1, 0, 0\};
                            j3 = \{0, 1, 0\};
                           k3 = \{0, 0, 1\};
   ln[21] = x1 = 1.5;
                           y1 = 1.5;
                            a = 3;
                           b = 2;
   ln[25] = x = a * Sin[t] + x1;
                            y = b * Cos[t] + y1;
  \label{eq:local_local_local_local_local_local} $$ \ln[27]:=$ ParametricPlot[\{x,\,y\},\,\{t,\,0,\,2\,Pi\},\,PlotTheme \rightarrow "Web",\,AxesOrigin \rightarrow \{0,\,0\}] $$ $$ $$ \end{tabular} $$ $$ \end{tabular} $$ \end{tabular} $$ \end{tabular} $$ \end{tabular} $$ $$ \end{tabular} $$ $$ \end{tabular} $$$ \end{tabular} $$$ \end{tabular} $$$ 
Out[27]=
                            0
   ln[28] = r = x * i2 + y * j2;
                            r' = D[r, t];
                          N@Integrate[Norm[r'], {t, 0, 2 Pi}]
```

```
In[31]:= "Unit Normal";
         T = r' / Norm[r']
         T' = D[T, t];
         N1 = T' / Norm[T'];
         Simplify[N1];
            \frac{3 \cos[t]}{\sqrt{9 \operatorname{Abs}[\cos[t]]^2 + 4 \operatorname{Abs}[\sin[t]]^2}}, -\frac{2 \sin[t]}{\sqrt{9 \operatorname{Abs}[\cos[t]]^2 + 4 \operatorname{Abs}[\sin[t]]^2}}
Out[32]=
```

```
In[36]:= Clear["Global`*"]
      i2 = \{1, 0\};
      j2 = \{0, 1\};
      i3 = \{1, 0, 0\};
      j3 = \{0, 1, 0\};
      k3 = \{0, 0, 1\};
\ln[42] = r[u] := a * Exp[b * u] * Cos[u] * i2 + a * Exp[b * u] * Sin[u] * j2
In[43]:= a = 50
      b = -.1
      ParametricPlot[r[u], {u, 0, 100}, PlotTheme \rightarrow "Web"]
Out[43] = 50
Out[44] = -0.1
       3
       2
```



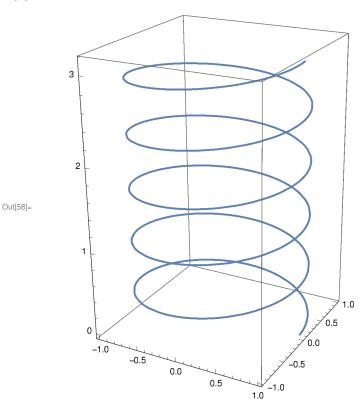
```
In[49]:= Clear["Global`*"]
    i2 = {1, 0};
    j2 = {0, 1};
    i3 = {1, 0, 0};
    j3 = {0, 1, 0};
    k3 = {0, 0, 1};

In[55]:= r[u_] = a * Cos[u] * i3 + a * Sin[u] * j3 + b * u * k3
Out[55]= {a Cos[u], a Sin[u], b u}
```

In[56]:= a = 1b = .1 $\texttt{ParametricPlot3D} \big[ \texttt{r[u], \{u, 0, 10 Pi\}} \big]$ 

 $\mathsf{Out}[56] = \ 1$ 

Out[57]= 0.1

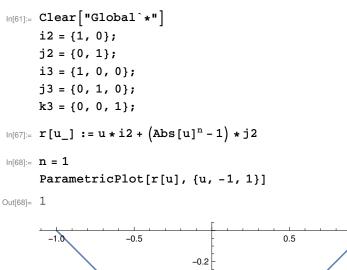


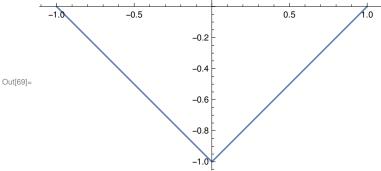
$$\begin{cases} -\frac{\sin[u]}{\sqrt{0.01 + \text{Abs}[\cos[u]]^2 + \text{Abs}[\sin[u]]^2}}, \\ \frac{\cos[u]}{\sqrt{0.01 + \text{Abs}[\cos[u]]^2 + \text{Abs}[\sin[u]]^2}}, \\ \frac{0.1}{\sqrt{0.01 + \text{Abs}[\cos[u]]^2 + \text{Abs}[\sin[u]]^2}} \end{cases}$$

- a is the diameter of the spiral
- b makes the spiral heigher or lower
- u determines the number of spirals

 $_{\text{ln[GO]:=}} \text{ Integrate} \big[ \text{Norm[r'[u]], } \big\{ \text{u, 0, 10 Pi} \big\} \big]$ 

Out[60]= 31.5726





$$ln[70]:=$$
 Integrate[Norm[r'[u]], {u, -1, 1}]

Out[70]= 
$$2\sqrt{2}$$

$$ln[71]:=$$
 Integrate [1, {x, -1, 1}, {y, Abs[x]^n - 1, d}]

Out[71]= 
$$1 + 2 d$$

$$ln[72]:= Solve[Sqrt[2] == 1 + 2 d, d]$$

Out[72]= 
$$\left\{ \left\{ d \rightarrow \frac{1}{2} \left( -1 + \sqrt{2} \right) \right\} \right\}$$

ln[73]:= Integrate[Norm[r'[u]], {u, -1, 1}]

Out[73]= 
$$2\sqrt{2}$$

In[84]:= Graphics[{BezierCurve[pts], Green, Line[pts], Red, Point[pts]}]

# Out[84]=

```
In[85]:= Clear ["Global`*"]

i2 = {1, 0};

j2 = {0, 1};

i3 = {1, 0, 0};

j3 = {0, 1, 0};

k3 = {0, 0, 1};

In[91]:= a1 = {0, 0};

a2 = {2, 3};

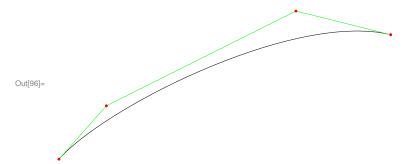
a3 = {4, 5};

In[94]:= r[u_{-}] := (1-u)^{2} a1 + 2 * u * (1-u) a2 + u^{2} * a3

In[95]:= pts = {r[1/2], r[1], r[3], r[4]}

Out[95]= \left\{\left\{2, \frac{11}{4}\right\}, \left\{4, 5\right\}, \left\{12, 9\right\}, \left\{16, 8\right\}\right\}
```

In[96]:= Graphics[{BezierCurve[pts], Green, Line[pts], Red, Point[pts]}]

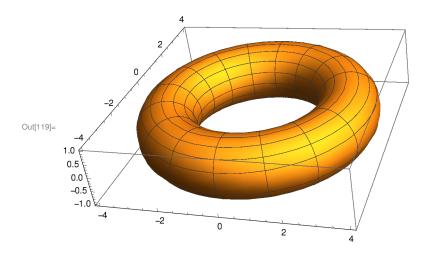


```
In[97]:= Clear["Global`*"]
      i2 = \{1, 0\};
       j2 = \{0, 1\};
       i3 = \{1, 0, 0\};
       j3 = \{0, 1, 0\};
      k3 = \{0, 0, 1\};
ln[103]:= a1 = \{0, 0\};
      a2 = \{1, 2\};
       a3 = \{2, 1\};
       a4 = \{2, 2\};
ln[107] = r[u] := (1-u)^3 * a1 + 3 * u * (1-u)^2 * a2 + 3 * u^2 * (1-u) * a3 + u^3 * a4
```

```
ln[108]:= pts = {r[0], r[.1], r[-.3], r[.3], r[.7], r[1]}
          Graphics[{BezierCurve[pts], Green, Line[pts], Red, Point[pts]}]
\texttt{Out[108]=} \ \left\{ \left\{ 0\,,\,0 \right\},\, \left\{ 0.299\,,\,0.515 \right\},\, \left\{ -0.873\,,\,-2.745 \right\},\, \left\{ 0.873\,,\,1.125 \right\},\, \left\{ 1.757\,,\,1.505 \right\},\, \left\{ 2\,,\,2 \right\} \right\}
Out[109]=
```

```
In[110]:= Clear["Global`*"]
      i2 = \{1, 0\};
      j2 = \{0, 1\};
      i3 = \{1, 0, 0\};
      j3 = \{0, 1, 0\};
      k3 = \{0, 0, 1\};
In[116]:= a = 3;
      R = 1;
      r[u_{\_}, v_{\_}] := (a + R * Cos[u]) * Cos[v] * i3 + (a + R * Cos[u]) * Sin[v] * j3 + R * Sin[u] * k3
```

```
ln[119]:= ParametricPlot3D[r[u, v], {u, 0, 2\pi}, {v, 0, 2\pi}]
```



```
ln[120]:= du = D[r[u, v], u];
       dv = D[r[u, v], v];
       cross = Cross[du, dv];
In[123]:= n = cross / Norm[cross];
In[124]:= Integrate[Norm[cross], \{u, 0, 2\pi\}, \{v, 0, 2\pi\}]
Out[124]= 12 \pi^2
```

```
In[125]:= Clear["Global`*"]
      i2 = \{1, 0\};
      j2 = \{0, 1\};
      i3 = \{1, 0, 0\};
      j3 = \{0, 1, 0\};
      k3 = \{0, 0, 1\};
ln[131] := x[x] := x
      z[x_] := -H + H * (16/L^4) * x^4
      y[x_{]} := (W/2) (4/L^{2}) x^{2} - (W/2) Sqrt[(z[u] + H) / H]
      r[u_{, v_{]} := x[v] * i3 + y[v] * j3 + z[u] * k3
```

0 -100

0 10500-5000

```
In[135]= W = 10
L = 30
H = 10
r[u]
ParametricPlot3D[r[u, v], {u, -100, 100}, {v, -100, 100}]

Ou[135]= 10

Ou[137]= 10

Ou[138]= r[u]

Ou[139]=

Ou[139]=
```