USING ARIMA MODELS TO MAKE CAUSAL STATEMENTS

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OUTLINE

- 1 Empirical problem & Research Goal
- C-ARIMA APPROACH
 - Causal framework
 - Inference

PRACTICAL SESSION

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FIGURE: Store brands (first row) and direct competitor brands (second row).

















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Research Goal

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Not so easy! Inference of a proper "causal" effect is complicated by several issues, including:

- Autocorrelation
- Seasonality
- Holiday effects



Infer the effect attributable to the policy netting out the portion due to other factors e.g., increasing trends started in the past Christmas rush purchases, Sunday effect

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C-ARIMA shares many features with "CausalImpact" [1], but it is based on ARIMA models — frequentist alternative to BSTS models, easy to implement, used for a wide class of processes.

Assumptions

Let $W_{i,t} \in \{0,1\}$ be a random variable describing the treatment assignment of unit $i \in \{1, ..., N\}$ at time $t \in \{1, ..., T\}$, where 1 denotes that a "treatment" (or "intervention") has taken place and 0 denotes control. We maintain the following assumptions:

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(A1: SINGLE PERSISTENT INTERVENTION)

$$\exists t^* \in \{1, \dots, T\} \text{ s.t } w_{i,t} = 0 \ \forall t \leq t^* \text{ and } \forall t > t^*, w_{i,t} \in \{(1, \dots, 1), (0, \dots, 0)\}$$

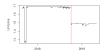
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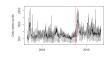
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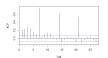
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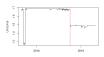
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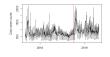
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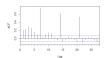
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(A2: Temporal no-interference)

For all $i \in \{1, ..., N\}$, $Y_{i,t}(w_{1:N,t^*+1:T}) = Y_{i,t}(w_{i,t^*+1:T})$

ASSUMPTIONS

(A3: Covariates-treatment independence)

$$X_{i,t}(w_{i,t^*+1:T}) = X_{i,t}(w'_{i,t^*+1:T}).$$

(A4: Non-anticipating individualistic treatment)

$$\begin{split} \Pr(\mathsf{W}_{1:N,t^*+1} &= \mathsf{w}_{1:N,t^*+1} \,|\, \mathsf{W}_{1:N,1:t^*}, \mathsf{Y}_{1:N,1:T}(\mathsf{w}_{1:N,1:T}), \mathsf{X}_{1:N,1:T}) = \\ &= \prod_{i=1}^N \Pr(\mathsf{W}_{i,t^*+1} = \mathsf{w}_{i,t^*+1} \,|\, \mathsf{Y}_{i,1:t^*}(\mathsf{w}_{i,1:t^*}), \mathsf{X}_{i,1:t^*}). \end{split}$$

Above assumptions are essential to define, estimate and attribute the causal effect to the intervention. Moreover, they allow us to ease notation: under Assumption 1, for all $t > t^*$ we can write $w_{i,t} = w_i$ and if Assumption 2 holds we can also drop the i subscript. From now on, we can use $Y_t(w)$ to denote the potential outcome of a generic unit at time $t > t^*$.

Causal estimands

DEFINITION

The point causal effect at time $t > t^*$ is,

$$\tau_t(1;0) = Y_t(1) - Y_t(0). \tag{1}$$

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The temporal average causal effect is

$$\bar{\tau}_t(1;0) = \frac{1}{t-t^*} \sum_{s=t^*+1}^t \tau_s(1;0) = \frac{\Delta_t(1;0)}{t-t^*}.$$
 (3)

let us assume $\{Y_t(w)\}$ evolving as

$$Y_t(w) = \frac{\theta_q(L)}{\phi_p(L)} \varepsilon_t + \tau_t \mathbb{1}_{\{w=1\}}$$
 (4)

where,

- ullet $\phi_p(L)$ and $heta_q(L)$ are lag polynomials having roots all outside the unit circle
- given this representation, the point causal effect at time $t > t^*$ is $\tau_t \equiv \mathsf{Y}_t(\mathsf{w}=1) \mathsf{Y}_t(\mathsf{w}=0)$
- ullet $au_t=0 \ orall t \leq t^*$ and $1\!\!1_{\{\mathsf{w}=1\}}$ is an indicator function which is one if $\mathsf{w}=1$
- ε_t is white noise with mean 0 and variance σ_{ε}^2

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C-ARIMA

let us assume $\{Y_t(w)\}$ evolving as

$$(1 - L^{s})^{D} (1 - L)^{d} Y_{t}(w) = \frac{\Theta_{Q}(L^{s})\theta_{q}(L)}{\Phi_{P}(L^{s})\phi_{p}(L)} \varepsilon_{t} + (1 - L^{s})^{D} (1 - L)^{d} X_{t}' \beta + \tau_{t} \mathbb{1}_{\{w=1\}}$$
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- given this representation, the point causal effect at time $t > t^*$ is $\tau_t \equiv \mathsf{Y}_t(\mathsf{w}=1) - \mathsf{Y}_t(\mathsf{w}=0)$
- $\tau_t = 0 \ \forall t \leq t^*$ and $\mathbb{1}_{\{w=1\}}$ is an indicator function which is one if w=1
- ε_t is white noise with mean 0 and variance σ_{ε}^2
- $\Theta_O(L^s)$, $\Phi_P(L^s)$ are the lag polynomials of the seasonal part of the model having roots all outside the unit circle
- $(1-L^s)^D$ and $(1-L)^d$ are the differencing operators to ensure stationarity

After some manipulation, Equation (4) becomes

$$S_t = z_t + \tau_t \mathbb{1}_{\{w=1\}}$$

where, $S_t = T(Y_t) - T(X_t)'\beta$ and $T(\cdot)$ is the transformation of Y_t needed to achieve stationarity, i.e. $T(Y_t) = (1 - L^s)^D (1 - L)^d Y_t$; z_t includes the stationary part of the model, namely,

$$z_t = \frac{\Theta_Q(L^s)\theta_q(L)}{\Phi_P(L^s)\phi_p(L)}\varepsilon_t$$

If w = 0, absence of intervention, the k-step ahead forecast of S_t conditionally on the information up to time t^* is

$$\hat{S}_{t^*+k}(0) = E[S_{t^*+k}(0)|\mathcal{I}_{t^*}] = E[z_{t^*+k}|\mathcal{I}_{t^*}] = \hat{z}_{t^*+k|t^*}$$



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Point causal effect estimator!

INFERENCE

THEOREM (PART 1)

Let $\{Y_t\}$ follow the regression model with ARIMA errors defined in Equation (4) and, for any k>0 let $H_0:\tau_{t^*+k}(1;0)=0$ the null hypothesis that the intervention has no effect. Then, the estimators of the point, cumulative and temporal average effects under H_0 can be expressed as,

$$\hat{\tau}_{t^*+k}(1;0)|H_0 = \sum_{i=0}^{k-1} \psi_i \varepsilon_{t^*+k-i}$$
 (5)

$$\hat{\Delta}_{t^*+k}(1;0)|H_0 = \sum_{h=1}^k \varepsilon_{t^*+h} \sum_{i=0}^{k-h} \psi_i$$
 (6)

$$\hat{\bar{\tau}}_{t^*+k}(1;0)|H_0 = \frac{1}{k} \sum_{h=1}^k \varepsilon_{t^*+h} \sum_{i=0}^{k-h} \psi_i, \tag{7}$$

where, the ψ_i 's are the coefficients of a moving average of order k-1 whose values are functions of the ARMA parameters in Equation (4).

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THEOREM (PART 2)

In case the ε_t error term is assumed normally distributed, Equations (5)–(7) become

$$\hat{\tau}_{t^*+k}(1;0)|H_0 \sim N\left[0, \sigma_{\varepsilon}^2 \sum_{i=0}^{k-1} \psi_i^2\right]$$
 (8)

$$\widehat{\Delta}_{t^*+k}(1;0)|H_0 \sim N\left[0, \sigma_{\varepsilon}^2 \sum_{h=1}^k \left(\sum_{i=0}^{k-h} \psi_i\right)^2\right]$$
(9)

$$\hat{\bar{\tau}}_{t^*+k}(1;0)|H_0 \sim N \left[0, \frac{1}{k^2} \sigma_{\varepsilon}^2 \sum_{h=1}^k \left(\sum_{i=0}^{k-h} \psi_i\right)^2\right]$$
 (10)

If one relies on the normality of the error term, inference can be based on Equations (8)–(10); otherwise, one can compute empirical critical values from Equations (5)–(7) by bootstrapping the errors from the model residuals.

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Inference

Summarizing, to estimate the effect of an intervention with C-ARIMA we need to follow these steps:

- estimate the ARIMA model only in the pre-intervention period, so as to learn the dynamics of the dependent variable and the links with the covariates without being influenced by the treatment
- based on the process learned in the pre-intervention period, perform a prediction step and obtain an estimate of the counterfactual outcome during the post-intervention period
- by comparing the observations with the corresponding forecasts at any time point after the intervention, evaluate the resulting differences, which represent the estimated point causal effects

Concluding remarks

- The proposed C-ARIMA approach can be used for policy evaluation (e.g., new regulation, passage of a law) and, in general, to estimate the causal effect of interventions in time series settings where there are no control units available, as in those cases where all units are treated
- In observational panel studies where a group of control units is also present, difference-in-differences and synthetic control methods may be preferred when the temporal dimension is short compared to the cross-sectional dimension

PRACTICAL SESSION



FMenchetti/CausalArima

In the past few days, you were given sales data of one of the store brand products analyzed in the paper. We will now show how to use C-ARIMA to answer the following questions:

- What is the total number of units sold due to the price reduction after 1-week, 1 month and 3 months from the intervention?
- What is the total number of units sold at the end of the analysis period?
- Plot the causal effect and residual diagnostics
- Assume a multiplicative effect, how much more did the product sold due to the premanent price reduction?

Go to the exercise!

REFERENCES

Thanks for your attention!

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- [2] Menchetti, F., Cipollini, F. and Mealli, F. [2021]. Estimating the causal effect of an intervention in a time series setting: the C-ARIMA approach, *Preprint. Available at* https://arxiv.org/abs/2103.06740.