

## Properties of Determinants

**Theorem** (Row Operations and Determinants).

Let  $A$  be a square matrix.

- If a multiple of one row in  $A$  is added to another row (row replacement operation performed on  $A$ ) to produce a matrix  $B$ , then  $\det(B) = \det(A)$ .
- If two rows in  $A$  are interchanged to produce  $B$ , then  $\det(B) = -\det(A)$ .
- If one row in  $A$  is scaled by  $c$  to produce  $B$ , then  $\det(B) = c\det(A)$ .

**Example.** Compute  $\det(A)$ , where  $A = \begin{bmatrix} 1 & -4 & 2 \\ -2 & 8 & -9 \\ -1 & 7 & 0 \end{bmatrix}$ .

Recall that the determinant of a triangular matrix is the product of the diagonal entries. Using this result,  $\det(A)$  can be computed by reducing  $A$  to echelon form while concurrently using the preceding theorem to examine how  $\det(A)$  changes. The first two row replacements in column 1 do not change  $\det(A)$ , and thus:

$$\det(A) = \begin{vmatrix} 1 & -4 & 2 \\ -2 & 8 & -9 \\ -1 & 7 & 0 \end{vmatrix} = \begin{vmatrix} 1 & -4 & 2 \\ 0 & 0 & -5 \\ -1 & 7 & 0 \end{vmatrix} = \begin{vmatrix} 1 & -4 & 2 \\ 0 & 0 & -5 \\ 0 & 3 & 2 \end{vmatrix}$$

An interchange of rows 2 and 3 reverses the sign of  $\det(A)$  and also reduces  $A$  to echelon form. Thus  $\det(A)$  is defined by the following.

$$\det(A) = - \begin{vmatrix} 1 & -4 & 2 \\ 0 & 3 & 2 \\ 0 & 0 & -5 \end{vmatrix} = -(1)(3)(-5) = 15$$

■

**Example.** Compute  $\det(A)$ , where  $A = \begin{bmatrix} 2 & -8 & 6 & 8 \\ 3 & -9 & 5 & 10 \\ -3 & 0 & 1 & -2 \\ 1 & -4 & 0 & 6 \end{bmatrix}$ .

Observe that property (c) of the preceding theorem can be used to factor 2 (the common multiple) out of row 1, and hence simplify the arithmetic of reducing  $A$  to echelon form. The row replacements operations on column 1 that follow the factoring operation do not change  $\det(A)$ .

$$\det(A) = 2 \begin{vmatrix} 1 & -4 & 3 & 4 \\ 3 & -9 & 5 & 10 \\ -3 & 0 & 1 & -2 \\ 1 & -4 & 0 & 6 \end{vmatrix} = 2 \begin{vmatrix} 1 & -4 & 3 & 4 \\ 0 & 3 & -4 & -2 \\ 0 & -12 & 10 & 10 \\ 0 & 0 & -3 & 2 \end{vmatrix}$$

Two more row replacement operations show that  $\det(A)$  is defined as follows.

$$\begin{aligned} \det(A) &= 2 \begin{vmatrix} 1 & -4 & 3 & 4 \\ 0 & 3 & -4 & -2 \\ 0 & 0 & -6 & 2 \\ 0 & 0 & -3 & 2 \end{vmatrix} = \det(A) = 2 \begin{vmatrix} 1 & -4 & 3 & 4 \\ 0 & 3 & -4 & -2 \\ 0 & 0 & -6 & 2 \\ 0 & 0 & 0 & 1 \end{vmatrix} \\ &= 2 \cdot (1)(3)(-6)(1) = -36 \end{aligned}$$

■

## Determinants and Invertible Matrices

Consider the  $n \times n$  matrix  $A$ , which has been reduced to an echelon form  $U$  through row replacements and row interchanges. If  $A$  has undergone  $r$  interchanges to produce  $U$ , then the preceding theorem shows that  $\det(A) = (-1)^r \det(U)$ . Since  $U$  is an echelon matrix, it must be triangular and thus  $\det(U) = u_{11} \times \cdots \times u_{nn}$ , the product of the diagonal entries  $u_{11}, \dots, u_{nn}$ . Notice that if  $A$  is invertible, then the entries  $u_{ij}$ , where  $i = j$ , are all nonzero pivots, and hence  $\det(A) \neq 0$ . Also observe that if  $A$  is *not* invertible, then at least  $u_{nn} = 0$ , and hence  $\det(A) = 0$ .

$$\det(A) = \begin{cases} (-1)^r \cdot (u_{11} \times \cdots \times u_{nn}) & \text{when } A \text{ is invertible} \\ 0 & \text{when } A \text{ is not invertible} \end{cases} \quad (1)$$

Equation (1) serves as a proof of the following theorem, and therefore adds the statement “ $\det(A) \neq 0$ ” to the Invertible Matrix Theorem.

**Theorem** (Determinant of Invertible Matrix).

An  $n \times n$  matrix  $A$  is invertible if and only if  $\det(A) \neq 0$ .

Observe that if the columns of an  $n \times n$  matrix  $A$  are linearly dependent, then  $A$  is not invertible and, as a corollary of the preceding theorem,  $\det(A) = 0$ . Also observe that if the columns of  $A^T$  (that is, the rows of  $A$ ) are linearly dependent, then as a corollary of the preceding theorem,  $\det(A) = 0$ , because if  $A^T$  is not invertible, then  $A$  is not invertible by the Invertible Matrix Theorem.

**Example.** Compute  $\det(A)$ , where  $A = \begin{bmatrix} 3 & -1 & 2 & -5 \\ 0 & 5 & -3 & -6 \\ -6 & 7 & -7 & 4 \\ -5 & -8 & 0 & 9 \end{bmatrix}$ .

Performing the row replacement operation  $R_3 = (2)R_1 + R_3$  on  $A$  produces the matrix  $B$ , which is defined by the following.

$$B = \begin{bmatrix} 3 & -1 & 2 & -5 \\ 0 & 5 & -3 & -6 \\ 0 & 5 & -3 & -6 \\ -5 & -8 & 0 & 9 \end{bmatrix}$$

The matrix  $B$  was obtained by performing a row replacement operation on  $A$ , and thus  $\det(B) = \det(A)$ . Rows 2 and 3 of the matrix  $B$  are equal, so the rows of  $B$  (and the columns of  $B^T$ ) are linearly dependent. Therefore,  $B$  is not invertible by the Invertible Matrix Theorem and hence  $\det(B) = \det(A) = 0$ . ■

**Example.** Compute  $\det(A)$ , where  $A = \begin{bmatrix} 0 & 1 & 2 & -1 \\ 2 & 5 & -7 & 3 \\ 0 & 3 & 6 & 2 \\ -2 & -5 & 4 & -2 \end{bmatrix}$ .

First note that column 1 can be simplified through the replacement operation  $R_4 = R_2 + R_4$ , which doesn't change the determinant. Observe that resulting matrix has a first column of mostly zero entries, so a cofactor expansion down column 1 can be used to reduce the size of the determinant as follows.

$$\det(A) = \begin{vmatrix} 0 & 1 & 2 & -1 \\ 2 & 5 & -7 & 3 \\ 0 & 3 & 6 & 2 \\ -2 & -5 & 4 & -2 \end{vmatrix} = \begin{vmatrix} 0 & 1 & 2 & -1 \\ 2 & 5 & -7 & 3 \\ 0 & 3 & 6 & 2 \\ 0 & 0 & -3 & 1 \end{vmatrix} = -2 \begin{vmatrix} 1 & 2 & -1 \\ 3 & 6 & 2 \\ 0 & -3 & 1 \end{vmatrix}$$

The row replacement  $R_2 = -3R_1 + R_2$  followed by the interchange  $R_2 \leftrightarrow R_3$  produces a triangular determinant, and thus  $\det(A)$  is defined by the following.

$$\det(A) = -2 \begin{vmatrix} 1 & 2 & -1 \\ 0 & 0 & 5 \\ 0 & -3 & 1 \end{vmatrix} = 2 \begin{vmatrix} 1 & 2 & -1 \\ 0 & -3 & 1 \\ 0 & 0 & 5 \end{vmatrix} = 2(-15) = -30$$

■