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from functions import *
import matplotlib.pyplot as plt
import numpy as np
import pickle
# Functions
def LoadBatch(file): # Excercise 1.1
    with open("data/"+file, 'rb') as fo:
        dict = pickle.load(fo, encoding='bytes')
    pixelDat = dict[b'data']
    labels = dict[b'labels']
    labelsOneHot = np.zeros((len(labels),10))
    for index in range(len(labels)): # Not efficient :)
        labelsOneHot[index][labels[index]] = 1
    return pixelDat, labelsOneHot, labels
def EvaluateClassifier(X, W, b): # Excercise 1.4, no need to transpose x!
    s = W @ X + b # @ is matrix multiplication
    return softmax(s)
def ComputeCost(X, Y, W, b, lamb): # Excercise 1.5
    P = EvaluateClassifier(X, W, b)
    P t = P.T
    for i in range(len(P t)):
        J \leftarrow -np.dot(Y[i], np.log(P_t[i]))
    J \neq len(X[0]) # Divide by dimensionality
    loss = J # For documentation
    J += lamb * np.sum(np.power(W,2)) # WTerm
    return J, P, loss
def ComputeAccuracy(X, y, W, b): # Excercise 1.6
   nCorr = 0
    P = EvaluateClassifier(X, W, b)
    for index in range(X.T.shape[0]):
       p = P.T[index]
        predClass = np.argmax(p)
        if predClass == y[index]:
            nCorr += 1
    acc = nCorr/X.T.shape[0]
    return acc
def ComputeGradients(X, Y, P, W, lamb, b start=0, b size=None): # Excercise 1.7
    if b size is None:
       b size = len(Y)
    # Get random subset of X and Y (not implemented as not required)
    X batch = X.T[b start:b start+b size].T # Because Python
    Y_batch = Y[b_start:b_start+b_size].T
    P batch = P.T[b start:b start+b size].T
    G_{vec} = - (Y_{batch} - P_{batch}) # G_{vec} is nxK
    dldw = np.dot(G_vec, X_batch.T)/b_size # dldw is KxD
    dldb = np.sum(G_vec, axis=1)/b_size # dldb is Kx1
    grad W = dldw + 2*lamb*W # gradW is KxD
    grad b = dldb # gradB is Kx1
    return grad_W, grad_b
def init variables():
    # Excercise 1.2
    X train, Y train, X val, Y val, X test, Y test = None, None, None, None, None, None
    for file in ["data batch 1", "data batch 2", "test batch"]:
        X, Y, Y = LoadBatch(file)
        mean X = np.mean(X, axis=0)
        std_X = np.std(X, axis=0)
        X = X - mean X
        X = X / std X
        X = X.T \# Make x stored in columns
        if file == "data batch 1":
            X_{train}, Y_{train}, y_{train} = X, Y, y
        elif file == "data batch 2":
            X \text{ val, } Y \text{ val, } y \text{ val } = X, Y, y
        else:
            X_{\text{test}}, Y_{\text{test}}, y_{\text{test}} = X, Y, y
    # Excercise 1.3
    np.random.seed(111)
    K = 10 # Number of labels
    d = len(X.T[0]) # dimensionality
    W = np.random.normal(0, 0.01, (K, d)) # Wierd, check here
    b = np.random.normal(0, 0.01, (K,1))
    return X train, Y train, Y train, X val, Y val, Y val, X test, Y test, Y test, W, b
def check gradients():
    X, Y, y, _, _, _, _, W, b = init_variables()
    lamb = 0
    P = EvaluateClassifier(X, W, b)
         = ComputeCost(X, Y, W, b, lamb) # P is now nxK for easier handling
    acc = ComputeAccuracy(X, y, W, b)
    c, d = ComputeGradsNumSlow(X.T[0:20].T, Y[0:20], P.T[0:20].T, W, b, lamb, 10**-8)
    a, b = ComputeGradients(X, Y, P, W, lamb, 20)
    print("Gradient check:")
    print("W:")
    print("Derived:", a)
    print("Check:", c)
    print("b:")
    print("Derived:", b)
    print("Check:", d)
    maxDiff = 0
    for val in enumerate(np.nditer(a-c)):
        diff = np.abs(val[1])
        if diff > maxDiff:
            maxDiff = diff
    print("Max gradient difference:", maxDiff)
    maxDiff = 0
    for val in enumerate(np.nditer(b-d)):
        diff = np.abs(val[1])
        if diff > maxDiff:
            maxDiff = diff
    print("Max gradient difference:", maxDiff)
if False:
    check gradients()
def MiniBatchGD(X, Y, y, W, b, lamb, n epochs, n batch, eta, X val, Y val, y val): # Excercise 1.8
    acc hist, cost hist, loss hist, acc hist val, cost hist val, loss hist val, loss hist val = [], [], [],
    # Train, initial val
    acc = ComputeAccuracy(X, y, W, b)
    cost, , loss = ComputeCost(X, Y, W, b, lamb)
    acc hist.append(acc), cost hist.append(cost), loss hist.append(loss)
    # Validation, initial val
    acc = ComputeAccuracy(X_val, y_val, W, b)
    cost, , loss = ComputeCost(X val, Y val, W, b, lamb)
    acc hist val.append(acc), cost hist val.append(cost), loss hist val.append(loss)
    for epoch in range(n epochs): # Main loop
        for batch in range(int(len(Y)/n batch)):
            P = EvaluateClassifier(X, W, b)
            grad W, grad b = ComputeGradients(X, Y, P, W, lamb, b start=batch*n batch, b size=n batch)
            W = W - grad W*eta
            grad b = grad b.reshape(b.shape)
            b = b - grad b*eta
        # Train
        acc = ComputeAccuracy(X, y, W, b)
        cost, , loss = ComputeCost(X, Y, W, b, lamb)
        acc_hist.append(acc), cost_hist.append(cost), loss_hist.append(loss)
        # Validation
        acc = ComputeAccuracy(X_val, y_val, W, b)
               _, loss = ComputeCost(X_val, Y_val, W, b, lamb)
        acc hist val.append(acc), cost hist val.append(cost), loss hist val.append(loss)
        print("Epoch:", epoch, "Accuracy:", acc hist[-1])
    return W, b, cost_hist, acc_hist, loss_hist, cost_hist_val, acc_hist val, loss hist val
X_train, Y_train, y_train, X_val, Y_val, y_val, X_test, Y_test, Y_test, W, b = init_variables()
lamb = 1
n epochs = 2
n \text{ batch} = 100
eta = 0.001
W, b, cost hist, acc hist, loss hist, cost hist val, acc hist val, loss hist val = MiniBatchGD(X=X train, Y=Y t
x = [i \text{ for } i \text{ in } range(n epochs+1)]
plt.clf()
plt.title("Cost graph")
plt.plot(x, cost hist, label = "Training")
plt.plot(x, cost hist val, label = "Valuation")
plt.legend()
plt.show()
plt.clf()
plt.title("Loss graph")
plt.plot(x, loss hist, label = "Training")
plt.plot(x, loss hist val, label = "Valuation")
plt.legend()
plt.show()
plt.clf()
plt.title("Accuracy graph")
plt.plot(x, acc hist, label = "Training")
plt.plot(x, acc hist val, label = "Valuation")
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plt.legend()
plt.show()

montage (W)

print("Final test accuracy:", ComputeAccuracy(X test, y test, W, b))