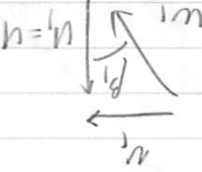
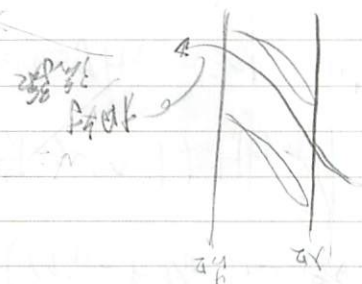


工完一換工: Dec/14/2019 (T)

神農氏

軸流式羽根車

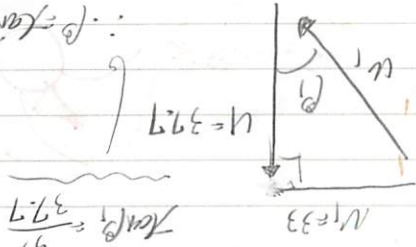


羽根車の平均半径 $r = 300 \text{ mm}$

$$u = r\omega = 2\pi n r$$

$$= 3.77 \text{ m/s} - (2\pi)$$

軸流式羽根車



$$\beta = \tan^{-1} \left(\frac{3.3}{3.77} \right)$$

$$= 41.2^\circ$$

起角 $\Delta = 2$ 度

$$\beta_2 = \beta_1 + \Delta = 59.2^\circ$$

速度式 (1)

$$\pi r^2 u_1 = \pi r^2 u_2$$

軸流式羽根車

軸流式羽根車

$$u_1 = u_2$$

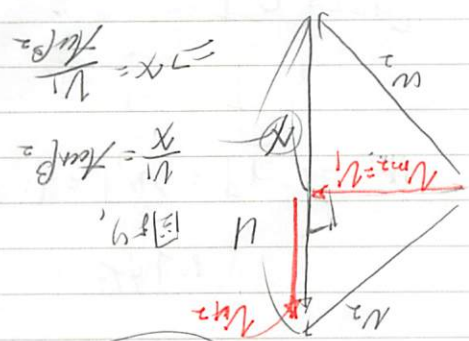
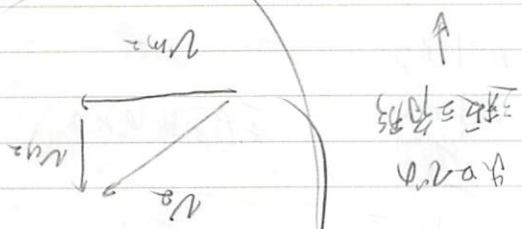
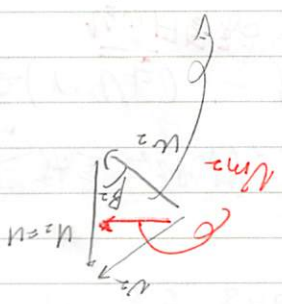


図 4.1

$$v_2 = v_1 - \frac{v_1^2}{2\pi n^2} \quad (26)$$

速度を求めると、

$$v_2 = \sqrt{v_1^2 - \frac{v_1^4}{2\pi n^2}} \quad (27)$$

$$f(26)$$

速度を求めると、

角運動量の保存則、

$$J_0(r v_1) - J_0(r v_2) = 0$$

角運動量の保存則、

$$= 1$$

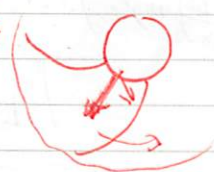
角運動量の保存則、

角運動量の保存則、

$$= 2\pi n^2$$

$$L = F r = \frac{F}{r} = 2\pi n^2$$

$$= 2\pi n^2$$



角運動量の保存則、

角運動量の保存則、

角運動量の保存則、

$$= 69.2m$$

$$H_1 = 2\pi n^2 (v_1 - v_2) v_2$$

$$J_0 g H_1$$

$$2\pi n^2 (v_1 - v_2)$$

$$f(26) \times f(30) \times f(10) \times f(10) \times f(10)$$

角運動量の保存則、

$$L = \frac{1}{2} m g H_1 = J_0 g H_1 - (30)$$

角運動量の保存則、

$$L = 2\pi n^2 (v_1 - v_2) - (29)$$

工機一巻換工 第11回

4.3 - 7.1

$L = 80 \text{ g Hk}$

$[W] \text{ (給分)} \quad [kg/m^3] [m/s] [m]$
 $(密度) \times (速度) \times (断面積) \times (長さ)$

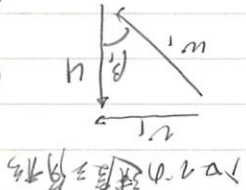
$\left[\frac{kg \cdot m^2}{s^3} \right]$

$\frac{5}{N \cdot m} = \frac{5}{kg \cdot m/s^2 \cdot m}$

羽根車の平均半径 $r = 300 \text{ mm}$

$N = 1200 \text{ rpm} = \frac{1200}{60} \text{ rps}$

$u = 2\pi N \times r = 37.7 \text{ m/s} \quad (a)$



$v_1 = 33 \text{ m/s}$
 $\tan \beta_1 = \frac{u}{v_1}$

$\Rightarrow \beta_1 = \tan^{-1} \left(\frac{u}{v_1} \right)$

$= \tan^{-1} \left(\frac{37.7}{33} \right) \approx 41.19 \text{ deg}$

$v_{u2} = u - x$

$= u - \frac{v_{m2}}{v_{m1}} = 18.0 \text{ m/s}$

$v_2 = \sqrt{v_{u2}^2 + v_{m2}^2}$

$= \sqrt{v_1^2 + v_{m2}^2} = 37.6 \text{ m/s}$



$T_{99-95\%}$

$50 \times v_{u2} = T$

$L = F \times r = T \times r = T \times 2\pi r$

速度角の差が3桁.

$\beta_2 = \beta_1 + \Delta$

$\beta_2 = 41.19^\circ + 18^\circ$

$\approx 59.2^\circ$

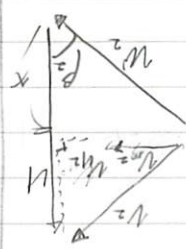
$\tan \beta_2 = \frac{v_{m2}}{v_{u2}} = \frac{v_{m2}}{u - x}$

$\therefore v_{m2} = v_1$

$v_{m2} = v_1$

$\tan \beta_2 = \frac{v_{m2}}{v_{u2}} = \frac{v_1}{u - x}$

$\Rightarrow x = \frac{v_{m2}}{\tan \beta_2}$



$\beta_1 v_1 = \beta_2 v_2$

速度角の差が3桁.

