```
┌─────────────────────────────────────┐
│         view_frames Result          │
│                                     │
│   Recorded at time: 1678245360.1282868   │
└─────────────────────────────────────┘
```

(map)

Broadcaster: default_authority
Average rate: 48.269
Buffer length: 5.2
Most recent transform: 312.0
Oldest transform: 306.8

(odom)

Broadcaster: default_authority
Average rate: 10.183
Buffer length: 4.91
Most recent transform: 311.8
Oldest transform: 306.89

(base_footprint)

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

(base_link)

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 19.608
Buffer length: 4.998
Most recent transform: 311.882
Oldest transform: 306.884

Broadcaster: default_authority
Average rate: 19.608
Buffer length: 4.998
Most recent transform: 311.882
Oldest transform: 306.884

(front_caster)   (gps_link)   (imu_link)   (lidar_link)   (ultrasonic_1_link)   (drivewhl_l_link)   (drivewhl_r_link)
```