
test_coordonees_perceptives

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```
In [1]: import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline
```

```
In [2]: from parametres import VPs, volume, p, d_x, d_y, d_z, calibration, DEBUG
from modele_dynamique import arcdistance, orientation, xyz2azel, rae2xyz
DEBUG parametres , position croix: [ 0.          3.76999998  1.37
]
```

```
In [3]: print xyz2azel.__doc__
renvoie le vecteur de coordonnées perceptuelles en fonction des
coordonnées physiques
```

xyz = 3 x N x ...

Le vecteur OV désigne le centre des coordonnées sphériques,
- O est la référence des coordonnées cartésiennes et
- V les coordonnées cartésiennes du centre (typiquement du
videoprojecteur).

cf. https://en.wikipedia.org/wiki/Spherical_coordinates

Plotting function:

```
In [4]: def plot_xyz2azel(motion, vp=VPs[0]):
        """
        Let's define a function that displays for a particular motion
        (a collection of poistions in the x, y, z space --- usually
        continuous) the resulting spherical coordinates (wrt to vp).

        """
        fig = plt.figure(figsize=(18,10))
        t = np.linspace(0, 1, motion.shape[1])[ :, np.newaxis]*np.ones((1, motion.shape[2]))
        rae_VC = xyz2azel(motion, np.array([vp['x'],
                                            vp['y'],
                                            vp['z']]))

        #print rae_VC.shape
        for i_ax, axe_perc in enumerate(['t', 'r', 'az', 'el']):
            for j_ax, axe_xyz in enumerate(['x', 'y', 'z']):
                #print i_ax, j_ax, 3*i_ax + j_ax
                ax = fig.add_subplot(4, 3, 1 + 3*i_ax + j_ax)
                if i_ax == 0:
                    #ax.plot(t, rae_VC[i_ax, :, :])
                    #print motion_x[j_ax, :, :].shape, t.shape
                    ax.plot(motion[j_ax, :, :], t)
                else:
```

```

        if axe_perc in ['az', 'el']: scale = 180./np.pi
        else: scale = 1.
        #print motion_x[j_ax, :, :].shape, rae_VC[i_ax-1, :, :].shape
        ax.plot(motion[j_ax, :, :], rae_VC[i_ax-1, :, :]*scale)
        ax.plot([vp[axe_xyz]], [0.], 'D')
        ax.set_xlabel(axe_xyz)
        ax.set_ylabel(axe_perc)
    plt.show()
    return rae_VC
print plot_xyz2azel.__doc__

```

Let's define a function that displays for a particular motion (a collection of positions in the x, y, z space -- usually continuous) the resulting spherical coordinates (wrt to vp).

```

In [5]: vp = VPs[1]
print vp
{'cz': 1.36, 'cy': 4.0, 'cx': 11.057115384615384, 'pc_min': 0.001,
'address': '10.42.0.52', 'y': 4.0, 'x': 0.9428846153846154, 'pc_max':
1000000.0, 'z': 1.36, 'foc': 21.802535306060136}

```

1 Motion in depth

Let's define N_player trajectories of N_t points, where players are distributed in the width (y) and move in the axis of the VP (x):

```

N_player, N_t = 10, 1000

In [6]: x = vp['x']*(np.linspace(0., 5., N_t)[np.newaxis, :, np.newaxis]*np.ones((1, 1, N_player, N_t)))
In [7]: y = vp['y']*(np.ones((1, N_t, 1))*np.linspace(0, 2, N_player, endpoint=True)[np.newaxis, :, np.newaxis])
z = vp['z']*np.ones((1, N_t, N_player)) # constant
#print x.shape, y.shape, z.shape
motion_x = np.vstack((x, y, z))
motion_x += .01*np.random.randn(3, N_t, N_player)
motion_x.shape
rae_VC = plot_xyz2azel(motion_x, vp=vp)

```

Note the small elevation:

```

In [8]: el = rae_VC[2, :, :]
print el.min(), el.max(), el.mean(), el.std()

```

2 Motion in width

```

In [9]: x = vp['x']*(np.ones((1, N_t, 1))*np.linspace(0., 2., N_player, endpoint=True)[np.newaxis, :, np.newaxis])
y = vp['y']*(np.linspace(0, 2, N_t)[np.newaxis, :, np.newaxis]*np.ones((1, 1, N_player, N_t)))
z = vp['z']*np.ones((1, N_t, N_player)) # constant
motion_y = np.vstack((x, y, z))
motion_y += .01*np.random.randn(3, N_t, N_player)
rae_VC = plot_xyz2azel(motion_y, vp=vp)

```

3 Motion in height

```
In [10]: x = vp['x']*np.ones((1, N_t, 1))*np.linspace(0, 5., N_player, endpoint=True)[np.newaxis]
y = vp['y']*np.ones((1, N_t, N_player)) # constant
z = vp['z']*(np.linspace(0, 2., N_t)[np.newaxis, :, np.newaxis]*np.ones((1, 1, N_player)))
motion_z = np.vstack((x, y, z))
motion_z += .01*np.random.randn(3, N_t, N_player)
rae_VC = plot_xyz2azel(motion_z, vp=vp)
```

```
In [10]:
```