

# 1 Manifolds

## 1.1 Manifolds on Euclidean Spaces

### 1.1.1 Taylor's theorem with remainder [Theorem 1.1.1]

A smooth function  $f$  on an open ball  $U \in \mathcal{O}_n$  can be written as

$$f(x) = f(p) + \sum (x^i - p^i)g_i(x)$$

where  $p \in U$  and  $g_i \in C^\infty(U)$  with  $g_i(p) = (\partial f / \partial x^i)(p)$ .

Adapting this to  $g_i$  repeatedly gives the Taylor's expansion of  $f$ .

### 1.1.2 Tangent vector as an arrow from a point [Definition 1.1.2]

The *tangent space*  $T_p(\mathbb{R}^n)$  at  $p \in \mathbb{R}^n$  is the set of arrows from  $p$ .

### 1.1.3 Directional derivative [Definition 1.1.3]

The *directional derivative* of a smooth function  $f$  in the direction  $v \in T_p(\mathbb{R}^n)$  at  $p \in \mathbb{R}^n$  is

$$D_v f = \lim_{t \rightarrow 0} \frac{f(c(t)) - f(p)}{t} = \left. \frac{d}{dt} \right|_{t=0} f(c(t))$$

with  $c^i(t) = p^i + tv^i$ .

By the chain rule,

$$D_v f = \sum \frac{dc^i}{dt}(0) \frac{\partial f}{\partial x^i}(p) = \sum v^i \frac{\partial f}{\partial x^i}(p).$$

### 1.1.4 Derivation at a point [Definition & Proposition 1.1.4]

A linear map  $D: C_p^\infty \rightarrow \mathbb{R}$  satisfying the Leibniz rule (i.e.,  $D(fg) = (Df)g(p) + f(p)Dg$  for any  $f, g \in C_p^\infty$ ) is called a *derivation at  $p$*  or a *point-derivation* of  $C_p^\infty$ .

The set of all derivations at  $p$   $\mathcal{D}_p(\mathbb{R}^n)$  is a real vector space, and a map  $\phi: T_p(\mathbb{R}^n) \rightarrow \mathcal{D}_p(\mathbb{R}^n)$  assigning  $D_v$  to each  $v$  is a linear map.

### 1.1.5 Point-derivation of a constant is zero [Lemma 1.1.5]

If  $D$  is a point-derivation of  $C_p^\infty$ , then  $D(c) = 0$  for any constant function  $c$ .

### 1.1.6 Tangent space is isomorphic to the set of point-derivations [Theorem 1.1.6]

The linear map  $\phi: T_p(\mathbb{R}^n) \rightarrow \mathcal{D}_p(\mathbb{R}^n)$  in 1.1.4 is an isomorphism of vector spaces.

### 1.1.7 Tangent vector as a derivation [Definition 1.1.7]

By 1.1.6,  $v \in T_p(\mathbb{R}^n)$  is identified as

$$v = \sum v^i \left. \frac{\partial}{\partial x^i} \right|_p \in \mathcal{D}_p(\mathbb{R}^n).$$

### 1.1.8 Vector fields on an open set [Definition 1.1.8]

A *vector field* on  $U \in \mathcal{O}_n$  is a map  $X: U \rightarrow T_p(\mathbb{R}^n)$ .  $X = \sum a^i \partial / \partial x^i$  means

$$X(p) = X_p = \sum a^i(p) \left. \frac{\partial}{\partial x^i} \right|_p \quad \text{with } a^i(p) \in \mathbb{R}$$

## 2 P-adic Numbers

### 2.1 Foundations

#### 2.1.1 Absolute value on a field [Definition 2.1.1]

An *absolute value* on a field  $\mathbb{K}$  is a function  $|\cdot|: \mathbb{K} \rightarrow \mathbb{R}_{>0}$  that satisfies:

- i)  $|x| = 0$  iff  $x = 0$ .
- ii)  $\forall x, y \in \mathbb{K}, |xy| = |x| |y|$ .
- iii)  $\forall x, y \in \mathbb{K}, |x + y| \leq |x| + |y|$ .

An absolute value that satisfies the condition

- iv)  $\forall x, y \in \mathbb{K}, |x + y| \leq \max\{|x|, |y|\}$

is said to be *non-archimedean*; otherwise, it is said to be *archimedean*.

#### 2.1.2 Trivial absolute value [Definition 2.1.2]

The absolute value on a field that assigns 0 to  $x = 0$  and 1 otherwise is called the *trivial absolute value*.

An absolute value on a finite field must be trivial.

#### 2.1.3 Valuation on a field [Definition 2.1.3]

A function  $v: \mathbb{A}^\times \rightarrow \mathbb{R}$  with an integral domain  $\mathbb{A}$  is called a *valuation* on  $\mathbb{A}$  if it satisfies the following conditions:

- i)  $\forall x, y \in \mathbb{A}^\times, v(xy) = v(x) + v(y)$
- ii)  $\forall x, y \in \mathbb{A}^\times, v(x + y) \geq \min\{v(x), v(y)\}$

#### 2.1.4 Value group of a valuation [Definition & Proposition 2.1.4]

The image of a valuation  $v$  on a field is an additive subgroup of  $\mathbb{R}$ .  $\text{im } v$  is called the *value group* of  $v$ .

#### 2.1.5 Correspondence between valuations and non-archimedean absolute values [Proposition 2.1.5]

Let  $\mathbb{A}$  be an integral domain and  $\mathbb{K} = \text{Frac } \mathbb{A}$ . Let  $v: \mathbb{A}^\times \rightarrow \mathbb{R}$  be a valuation on  $\mathbb{A}$  and extend  $v$  to  $\mathbb{K}$  by setting  $v(a/b) = v(a) - v(b)$ , then the function  $|\cdot|_v: \mathbb{K} \rightarrow \mathbb{R}_{>0}$  defined by

$$|x|_v = \begin{cases} e^{-v(x)} & \text{for } x \neq 0 \\ 0 & \text{for } x = 0 \end{cases}$$

is a non-archimedean absolute value on  $\mathbb{K}$ . Conversely,  $-\log |\cdot|_v$  is a valuation on  $\mathbb{K}$  for a non-archimedean absolute value  $|\cdot|_v$  on  $\mathbb{K}$ .

### 2.1.6 $p$ -adic valuation [Definition 2.1.6]

The  $p$ -adic valuation on  $\mathbb{Q}$  with a prime  $p$  is a valuation  $v_p: \mathbb{Q}^\times \rightarrow \mathbb{R}$  defined as follows: for each  $n \in \mathbb{Z}^\times$ , let  $v_p(n)$  be the greatest integer such that  $p^{v_p(n)} \mid n$ , and for each  $x = a/b \in \mathbb{Q}^\times$ ,  $v_p(x) = v_p(a) - v_p(b)$ .

We often set  $v_p(0) = \infty$ .

### 2.1.7 $p$ -adic absolute value [Definition 2.1.7]

The  $p$ -adic absolute value  $|\cdot|_p: \mathbb{Q} \rightarrow \mathbb{R}$  with a prime  $p$  is defined as

$$|x|_p = p^{-v_p(x)}.$$

The usual absolute value is looked as  $|\cdot| = |\cdot|_\infty$ .

## 参考文献

- [1] Fernando Q. Gouvêa. *p-adic Numbers - An Introduction, Second Edition*. Springer, 1997.
- [2] Loring W. Tu. *An Introduction to Manifolds, Second Edition*. Springer, 2011.