# Cyber Physical System – Revision Notes

### Cyber-Physical System (CPS) - Basics

- Definition: CPS is the integration of computational (cyber) and physical processes, using embedded computers and feedback loops.
- Origin: Term coined by Helen Gill at NSF, USA around 2006.
- Focus: Intersection, not union, of cyber and physical systems.
- Key Elements: Cyber + Physical + Computation + Dynamics + Communication + Security + Safety.

#### CPS - Characteristics

- · Deep interaction between physical and software components.
- · Operates on multiple spatial and temporal scales.
- Context-aware behavior and multiple behavioral modalities.
- Uses transdisciplinary approaches (cybernetics, mechatronics, design science).

#### CPS - Applications

- · Automotive, Medical Devices, Military, Traffic Control, Power Systems, Manufacturing, Robotics, Assisted Living, Industrial Control,
- Enables: Collision avoidance, Robotic surgery, Deep-sea exploration, Air traffic control, Zero-net energy buildings, Healthcare monitoring.

#### CPS - Components

- Sensors + Actuators: Bridge between real world and cyberspace.
- Smart Networked Systems and Societies (SNSS): CPS forms their base.
- Cloud Computing: Enhances flexibility, scalability, and data processing in CPS.

#### Cyber-Physical Cloud Computing (CPCC)

- Definition: System that rapidly builds and provisions CPS using cloud-based sensor, processing, control, and data services.
- Benefits:
  - o Efficient resource use
  - Modular and scalable
  - Smart environment adaptation
  - o Reliable, resilient

#### **Spatial Cloud Computing**

- Spatial Data: Geospatial data includes location (coordinates), attributes, and time.
- Purpose: Integrates observation systems, visualization, analytics, and decision support on the cloud.
- Advantages:
  - o Elastic, on-demand infrastructure
  - o Supports multiple concurrent users
  - o Geospatial science optimized by spatiotemporal principles

# Spatial Cloud - Features

- Shared resource pooling (Network, Servers, Apps, Databases)
- Deployment flexibility (IaaS, PaaS, SaaS)
- High scalability and reliability
- · Cost-efficient and risk-mitigated

# **Traj-Cloud for Urban Dynamics**

- Goal: Analyze urban mobility and improve location-based services (LBS).
- Framework Services:
  - 1. TS1 Trajectory Indexing (Uses Google BigQuery + Cloud SQL)
  - 2. TS2 Map-Matching Service (Uses Google Compute Engine)
  - 3. TS3 Trajectory Querying (Uses Google Compute Engine + SQL)

### Cloud-Fog-Edge for Internet of Health Things (IoHT)

- Objective: Reduce latency, cost, and cloud network usage.
- Key Tools/Goals:
  - o Fog-Edge health model (tested with iFogSim)
  - o Custom wearable devices for health data
  - o Implementation and testing on real hardware
  - o Study and integrate Dew Computing

# ✓ High-Yield Keywords for MCQs

- CPS → Embedded Systems + Feedback Loops
- CPCC → Cloud + CPS + Modularity
- Spatial Data → Location + Attributes + Time
- SNSS → Smart Networked Systems
- iFogSim → Fog Simulation Tool
- Traj-Cloud → Mobility + GPS + MapReduce
- IoHT → Wearables + Fog-Edge Model
- Dew Computing → Lightweight local processing