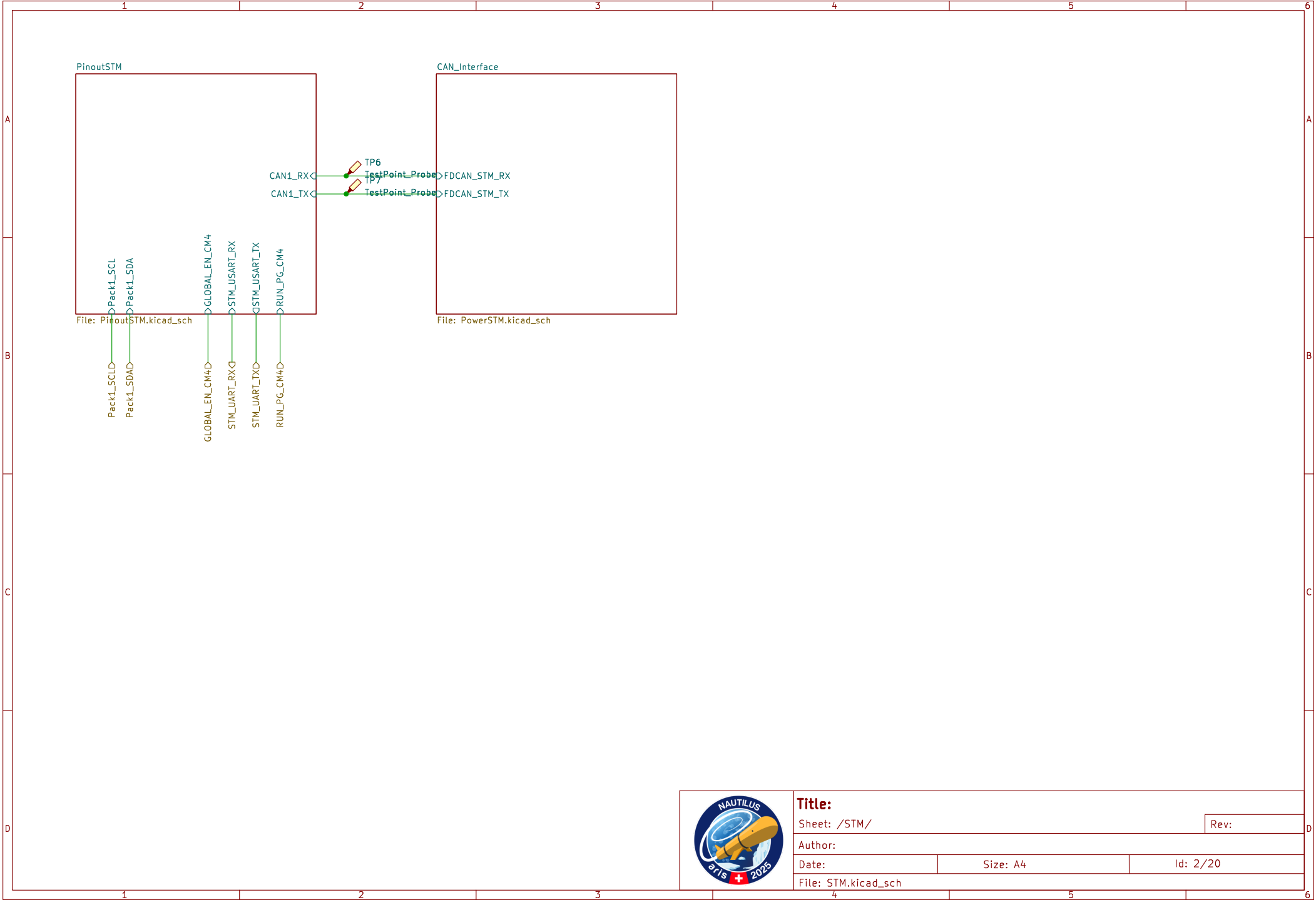
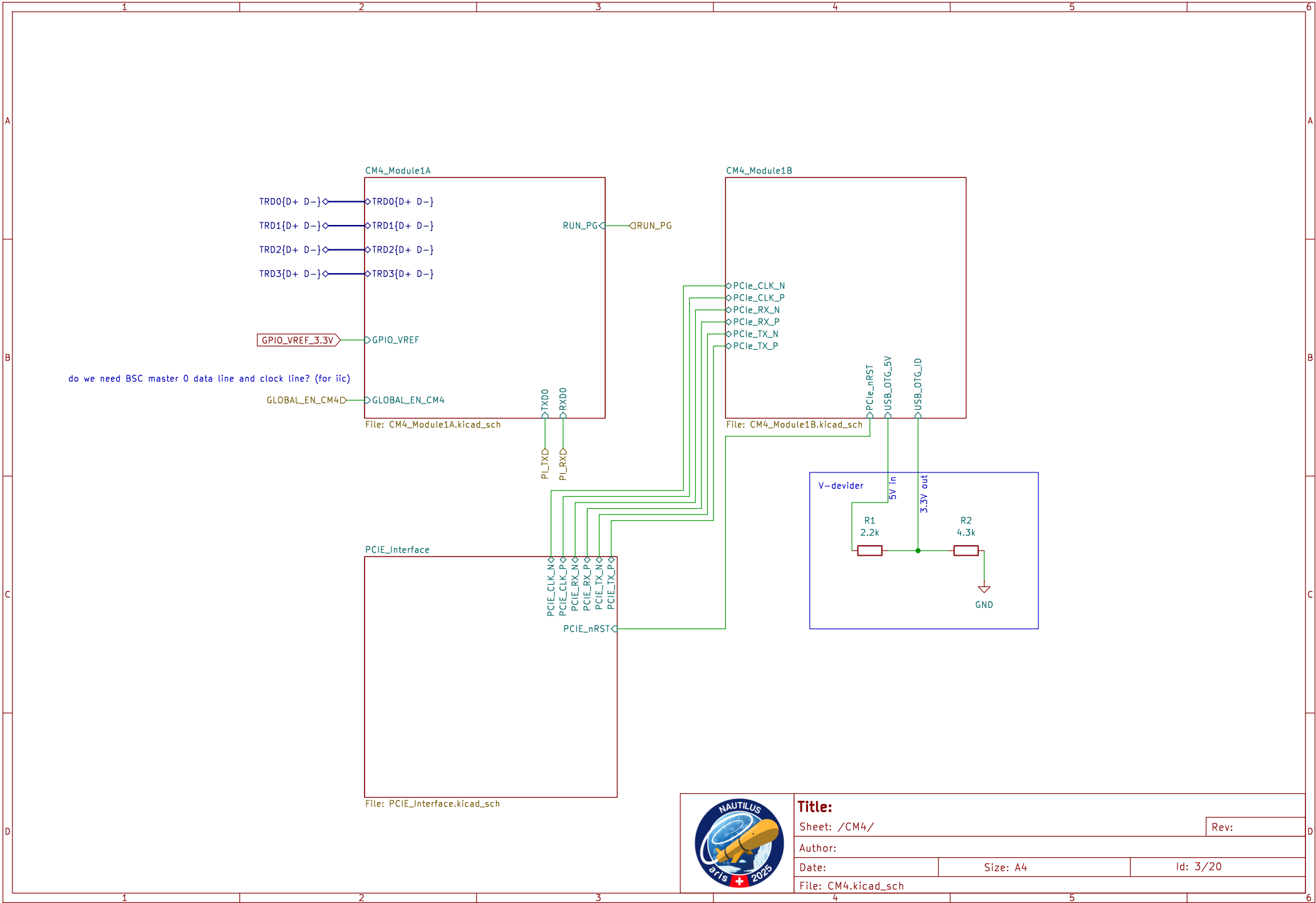
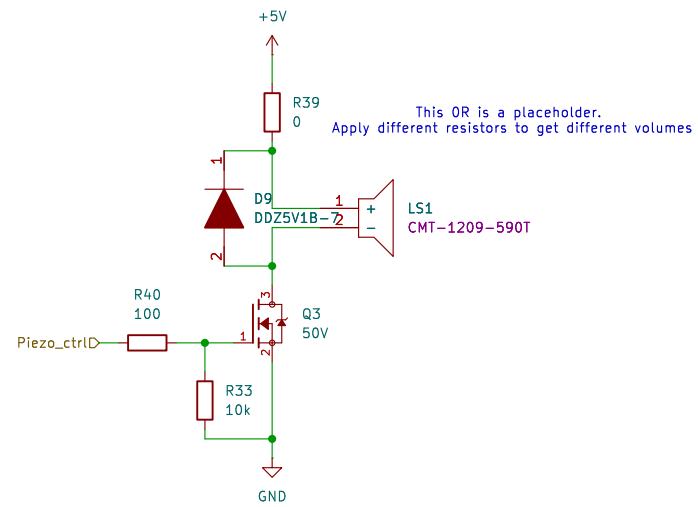
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	Author:		
	Date:	Size: A4	Id: 1/20
File: nautilus_mainboard.kicad_sch			



Title:		
Sheet: /STM/		Rev:
Author:		
Date:	Size: A4	Id: 2/20
File: STM.kicad_sch		



Not in the PCB yet as we dont know if we actually need it.



**Title:**

Sheet: /Piezzo/

Rev:

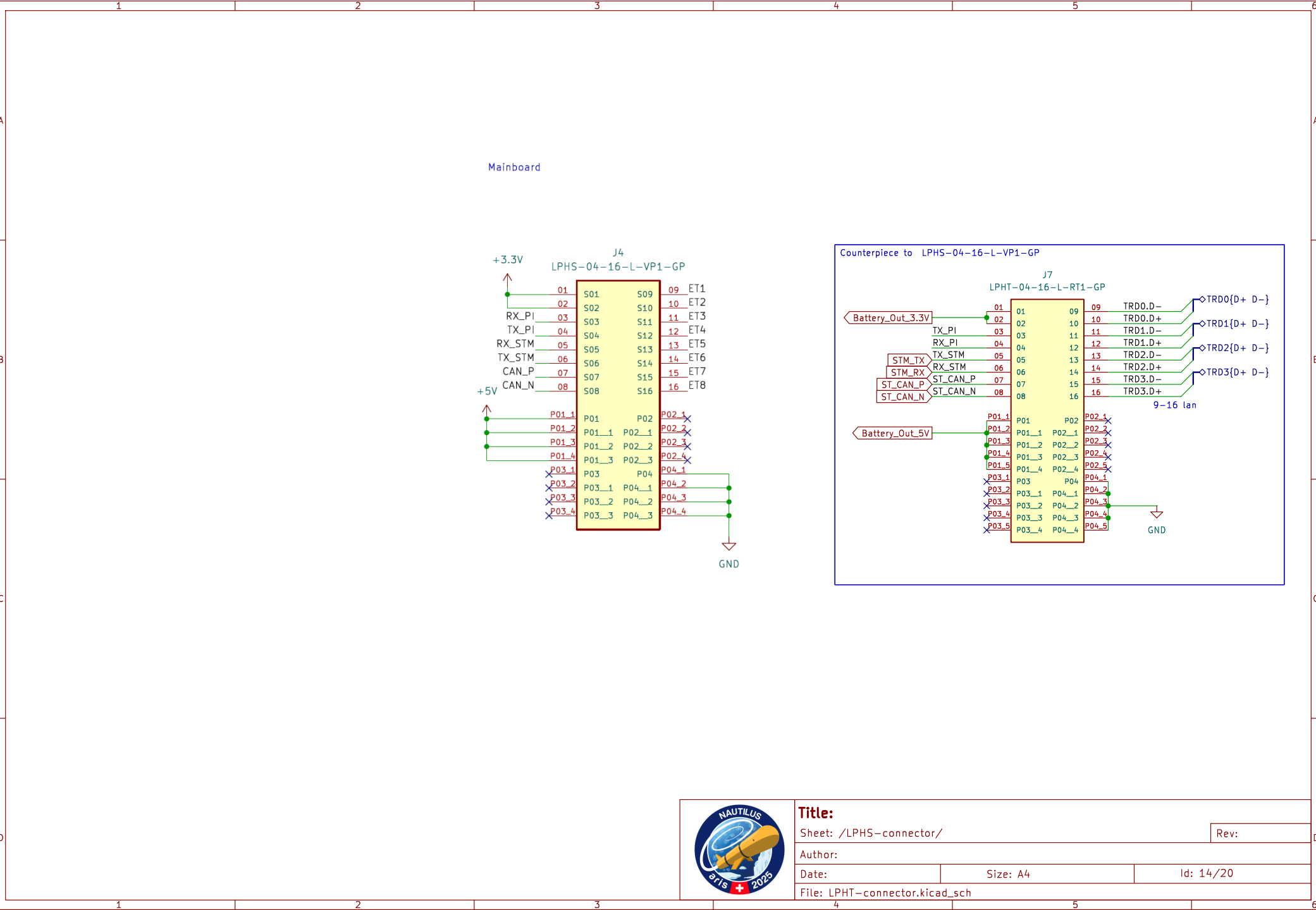
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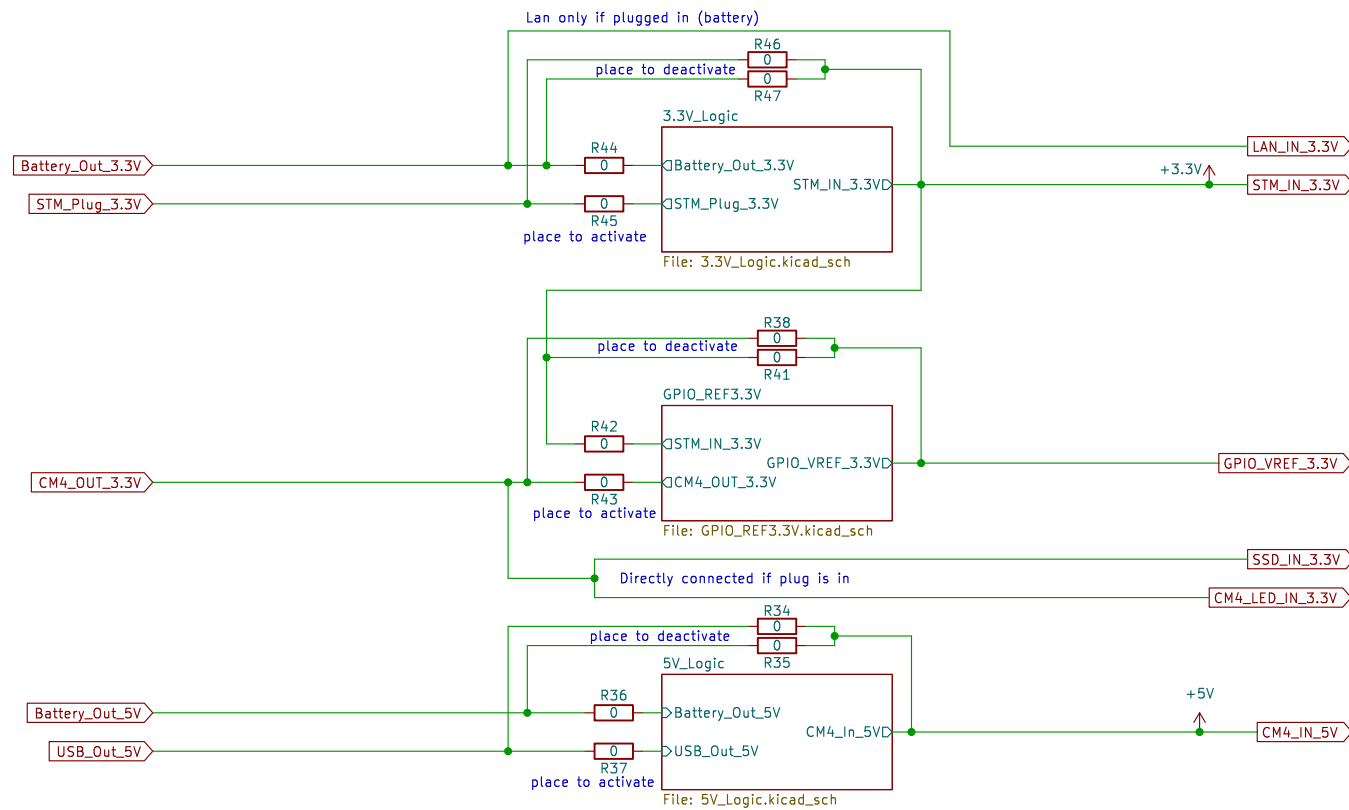
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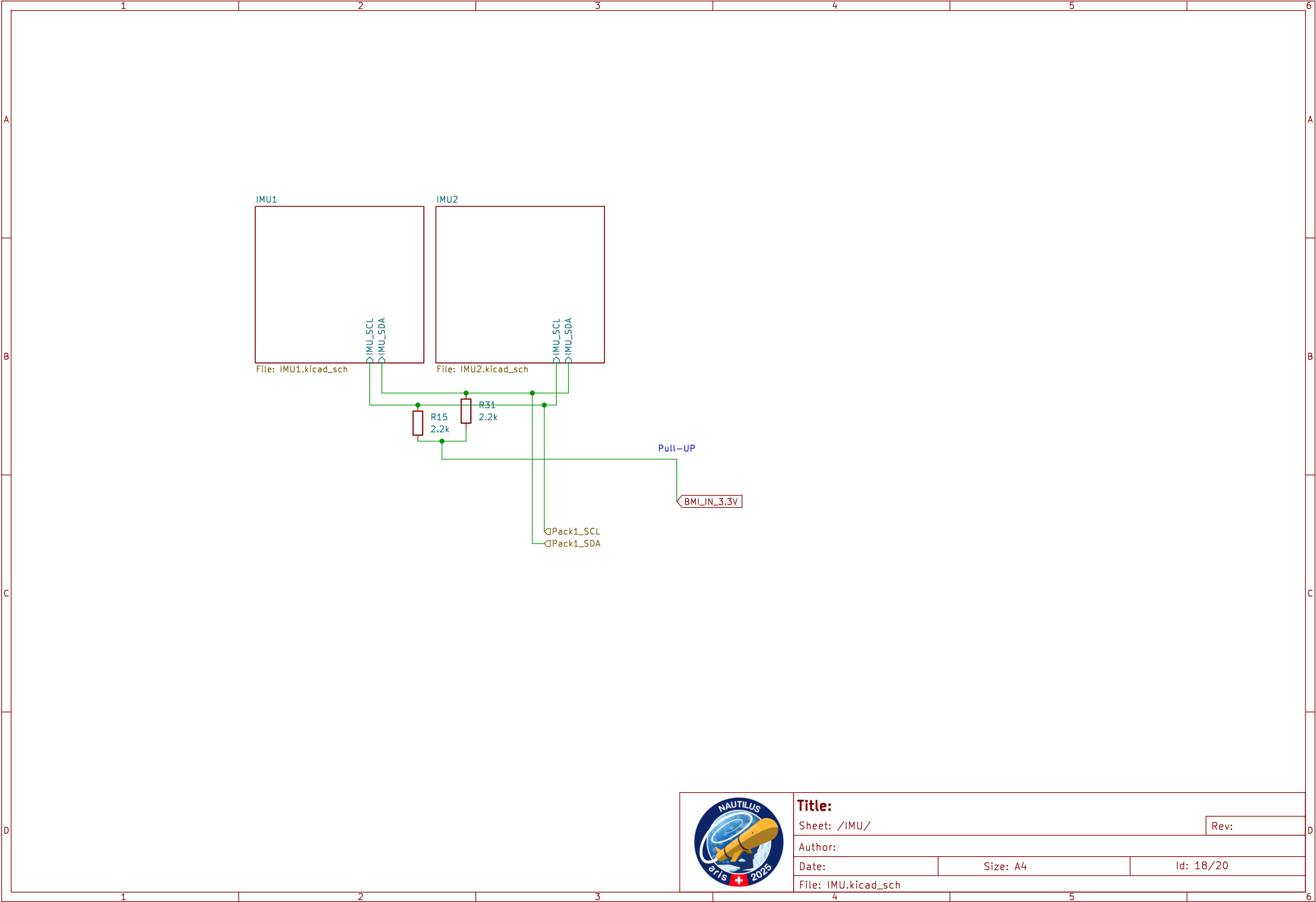
Unconditional Power routes: Whenever the CM4 runs, also run the LED signals AND the SSD voltage, all "core" tasks tied to the CM4.  
If I forgot something please let me know.



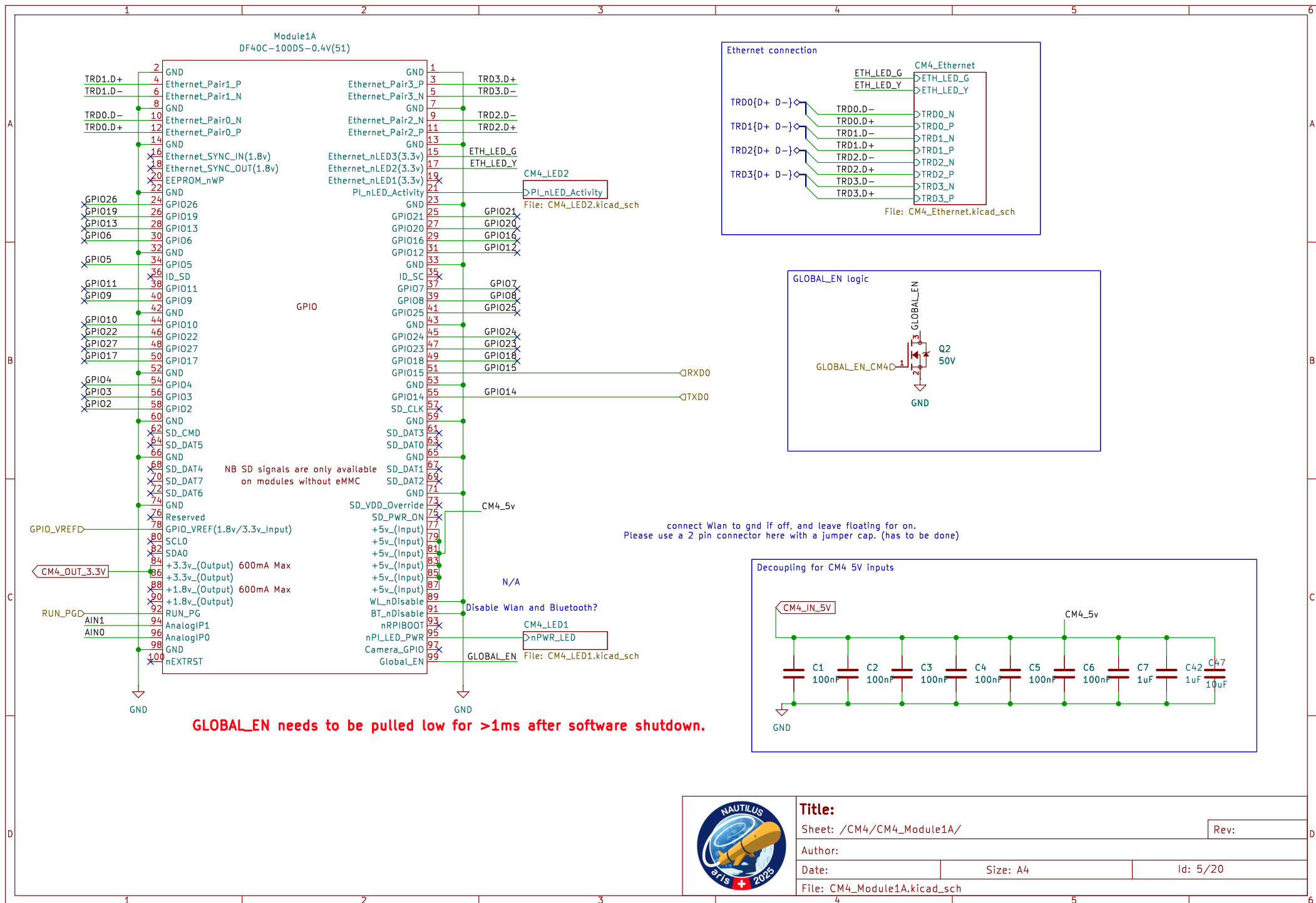
some rules:  
USB wont power the STM32.  
STM\_Plug wont power the CM4  
The GPIO\_VREF of the CM4 needs to be STM32's 3.3V  
The Lan Vin is only powered when running on Battery  
Battery preferrably powers everything.



Title:		
Sheet: /Power_logic/		Rev:
Author:		
Date:	Size: A4	Id: 14/20
File: Power_logic.kicad_sch		

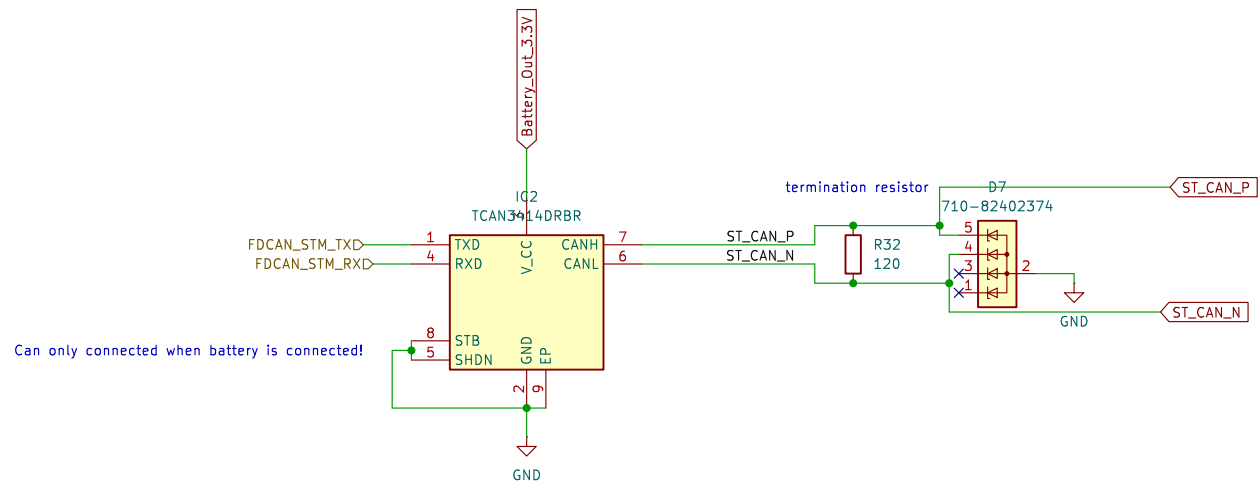


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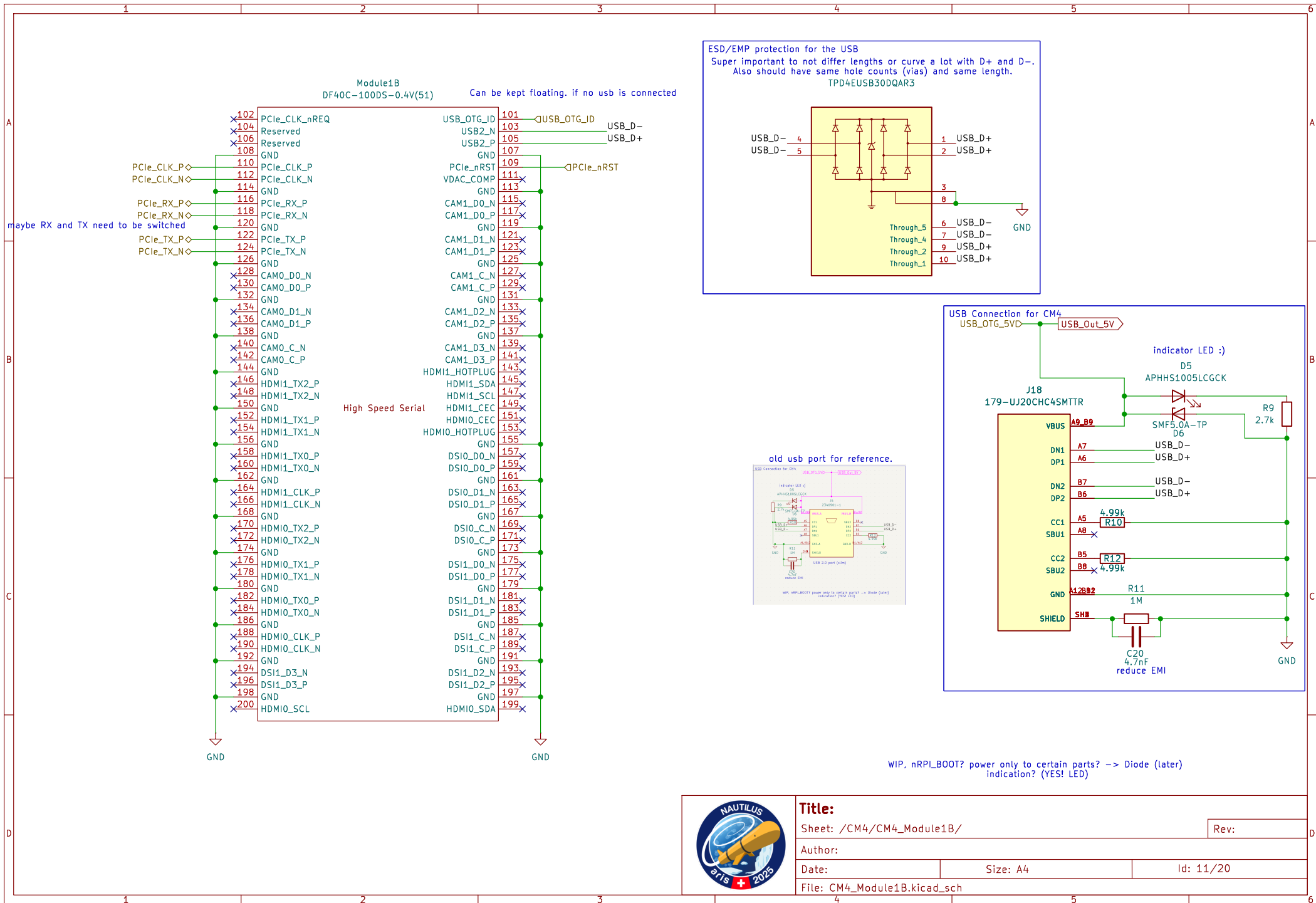








<b>Title:</b>		
Sheet: /STM/CAN_Interface/		Rev:
Author:		
Date:	Size: A4	Id: 7/20
File: PowerSTM.kicad_sch		



for questions about wiring etc please consult the datasheet...  
<https://www.ti.com/lit/ds/symlink/tps2120.pdf?ts=1761678178328>

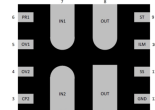
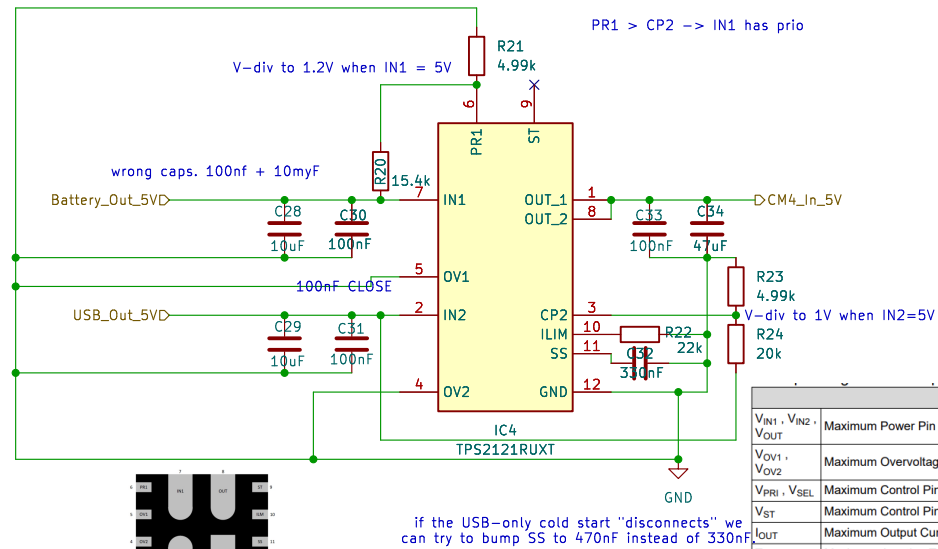


Figure 6-2. TPS2121 (RUXT) Package 12-Pin VQFN-HR Bottom View

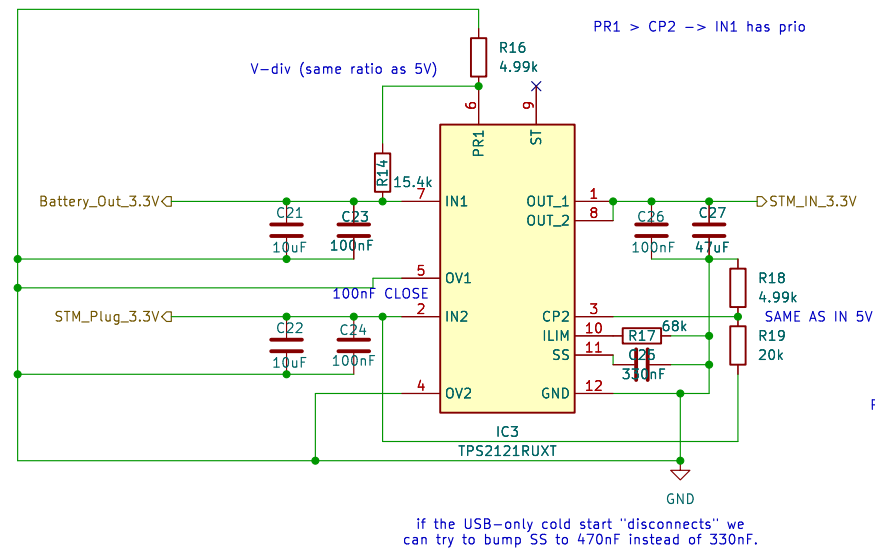
PIN		Pin Functions		
NAME	TPS2120 WCSP	TPS2121 VQFN-HR	DESCRIPTION	
IN1	B1, B2, C1	7	1	Power Input for Source 1
IN2	B3, B4, C4	2	1	Power Input for Source 2
OUT	C2, C3, D1, D2, D3, D4	1, 8	1	Power Output
ST	E1	9	0	Status output indicating which channel is selected. Connect to GND if not required.
ILIM	E2	10	0	Output Current Limiting for both channels.
ISL	E3	11	0	Adjusts Input Settling Delay Time and Output Soft Start Time
GND	E4	12	—	Device Ground
PRI1	A1	6	1	Enables Priority Operation. Connect to IN1 to set switchover voltage. Connect to GND if not required.
OV1	A2	5	1	Active Low Enable Supervisor for IN1 Overvoltage Protection. Connect to GND if not required.
OV2	A3	4	1	Active Low Enable Supervisor for IN2 Overvoltage Protection. Connect to GND if not required.
SEL	A4	—	1	Active Low Enable for IN1. Allows GPIO to override priority operation and manually select IN2. TPS2120 only.
CP2	—	3	1	Enables Comparator Operation and is compared to PRI1 to set switchover voltage. Connect to GND if not required. TPS2121 only.

		Pins	MIN	MAX	UNIT
V <sub>IN1</sub> , V <sub>IN2</sub> , V <sub>OUT</sub>	Maximum Power Pin Voltage	IN1, IN2, OUT	-0.3	24	V
V <sub>OV1</sub> , V <sub>OV2</sub>	Maximum Overvoltage Pin Voltage	OV1, OV2	-0.3	6	V
V <sub>PRI</sub> , V <sub>SEL</sub>	Maximum Control Pin Voltage	PRI, SEL	-0.3	6	V
V <sub>ST</sub>	Maximum Control Pin Voltage	ST	-0.3	6	V
I <sub>OUT</sub>	Maximum Output Current	OUT	Internally Limited		
T <sub>J, MAX</sub>	Maximum Junction Temperature		Internally Limited		
T <sub>STG</sub>	Storage temperature		-65	150	°C



<b>Title:</b>		
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Author:		
Date:	Size: A4	Id: 12/20
File: 5V_Logic.kicad_sch		

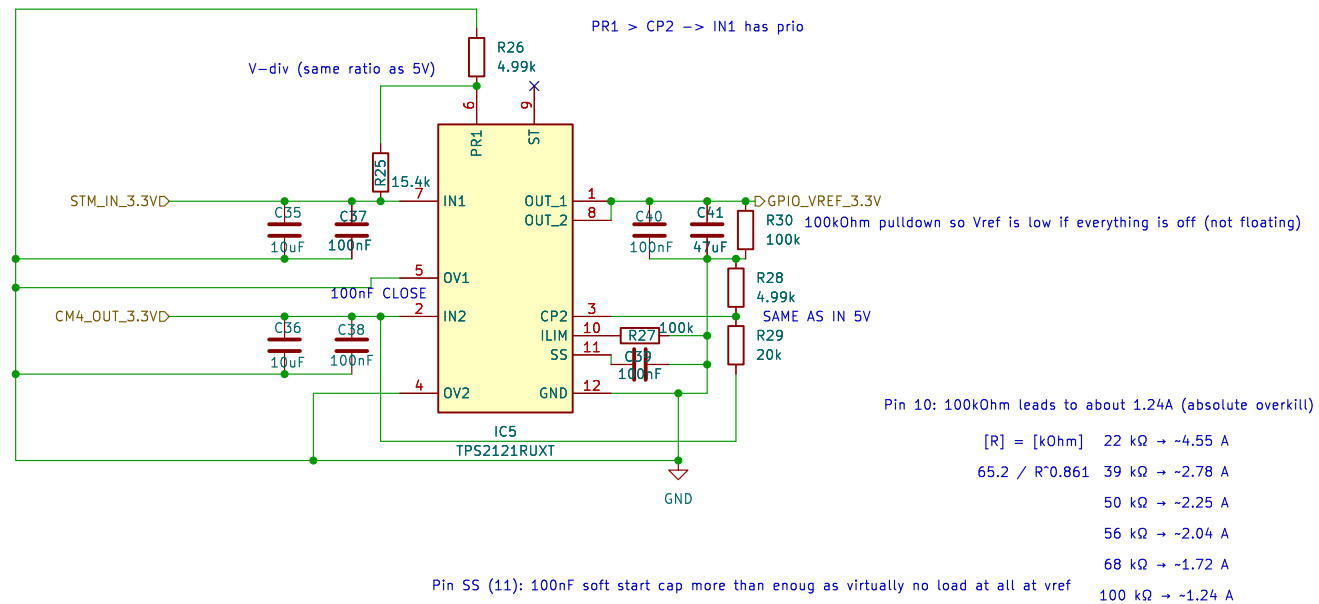




[R] = [kOhm]	22 kΩ	→ -4.55 A
65.2 / R*0.861	39 kΩ	→ -2.78 A
	50 kΩ	→ -2.25 A
	56 kΩ	→ -2.04 A
	68 kΩ	→ -1.72 A
	100 kΩ	→ -1.24 A



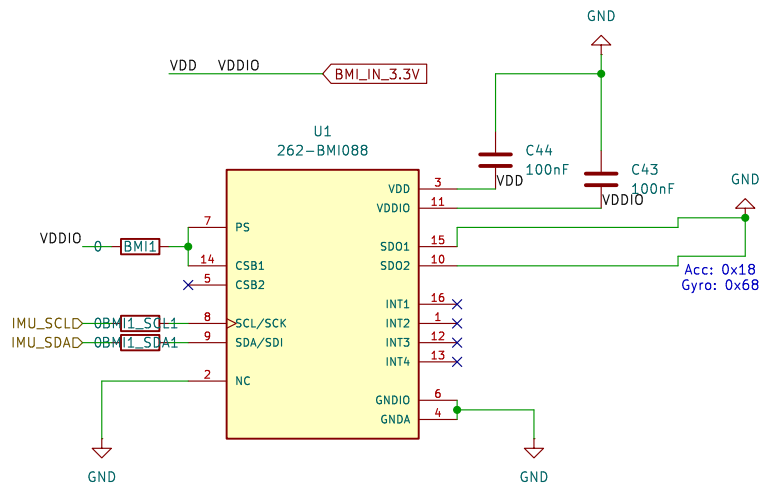
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Author:		
Date:	Size: A4	Id: 15/20
File: 3.3V_Logic.kicad_sch		



<b>Title:</b>		
Sheet: /Power_logic/GPIO_REF3.3V/		Rev:
Author:		
Date:	Size: A4	Id: 16/20
File: GPIO_REF3.3V.kicad_sch		

PS -> 3.3V IIC  
CSB1 -> 3.3V NOT SPI

PB8 on STM  
PB9 on STM



**Title:**

Sheet: /IMU/IMU1/

Rev:

Author:

Date:

Size: A4

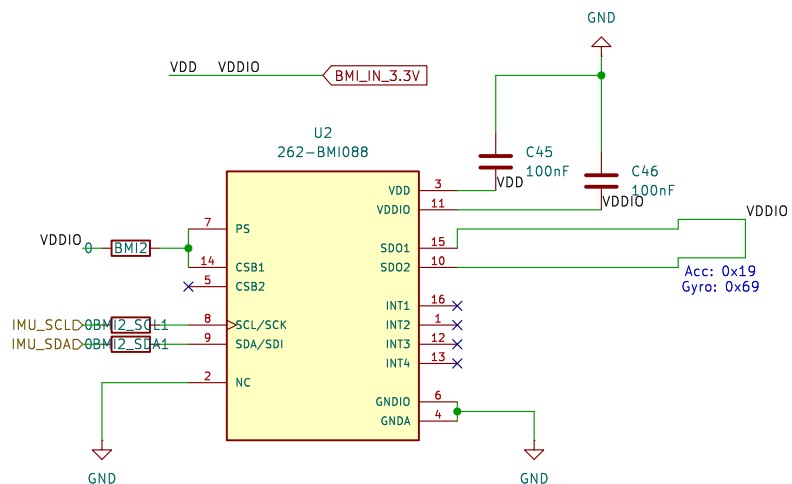
Id: 19/20

File: IMU1.kicad\_sch



PS -> 3.3V IIC  
CSB1 -> 3.3V NOT SPI

PB8 on STM  
PB9 on STM



Accelerometer  
SD01 pin pulled to GND (0x18)  
SD01 pin pulled to VDDIO: (0x19)

Gyroscope:  
SD02 pin pulled to GND: (0x68)  
SD02 pin pulled to VDDIO: (0x69)



# Title:

Sheet: /IMU/IMU2/

Rev:

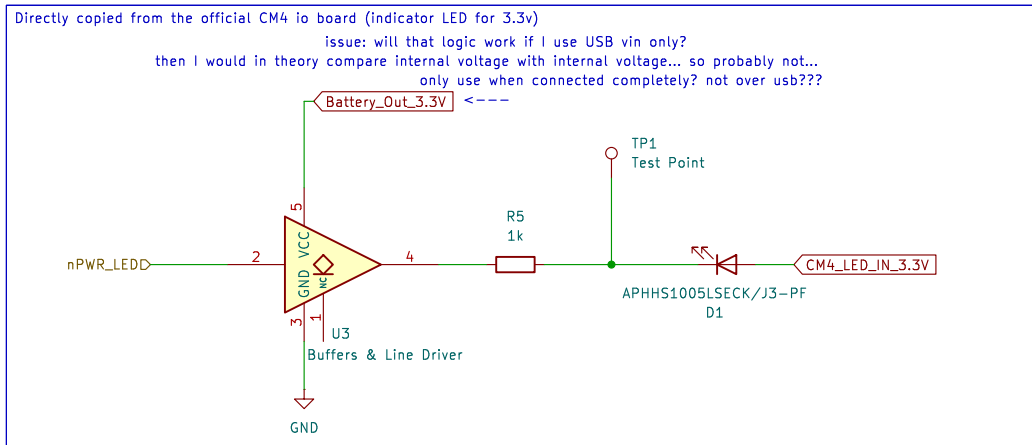
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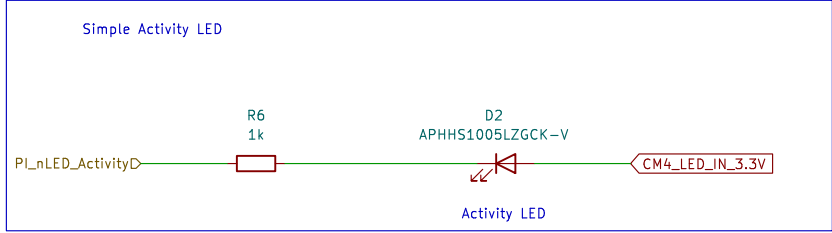
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File: CM4_LED1.kicad_sch		



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Rev:

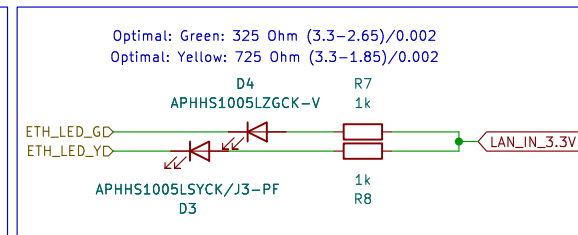
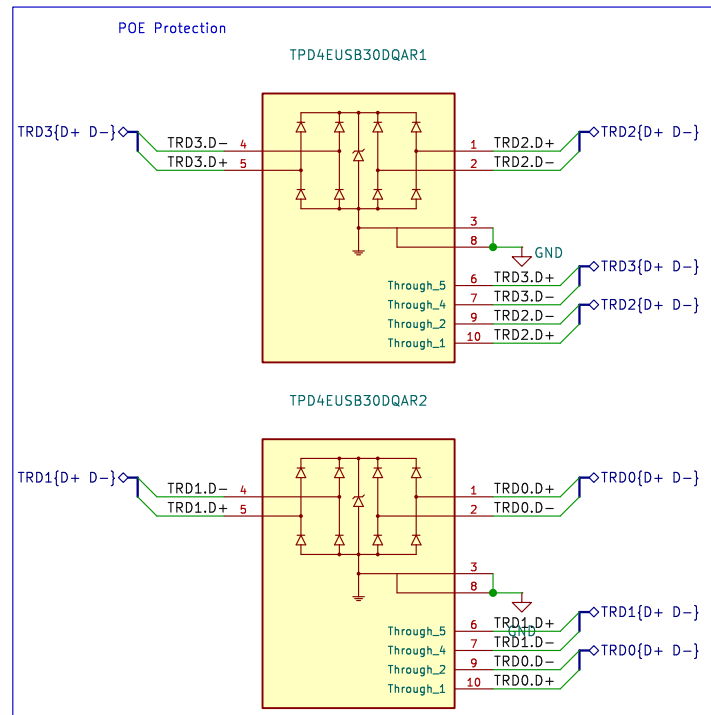
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Date:

Size: A4

Id: 9/20

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Author:		
Date:	Size: A4	Id: 10/20
File: CM4_Ethernet.kicad_sch		