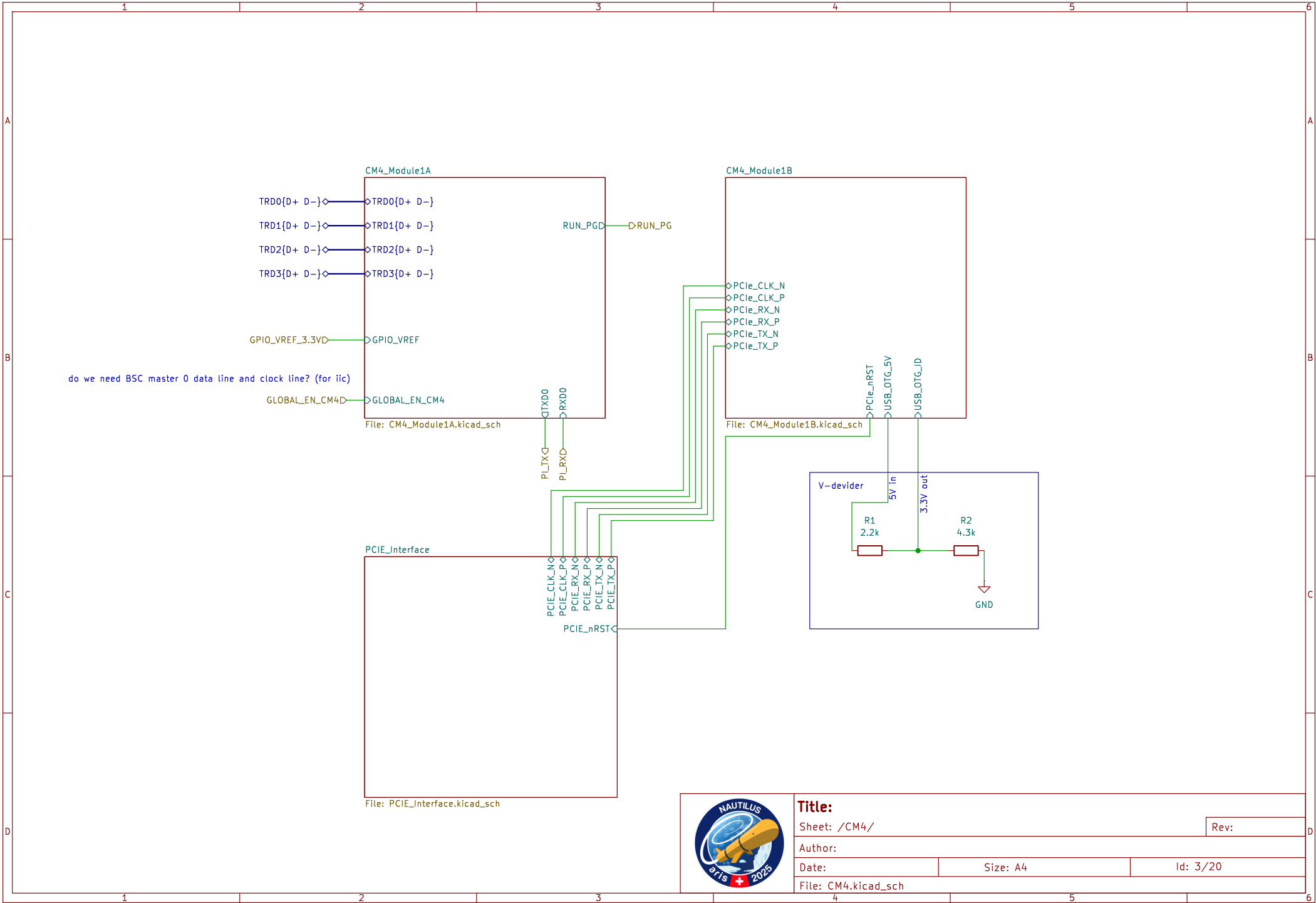
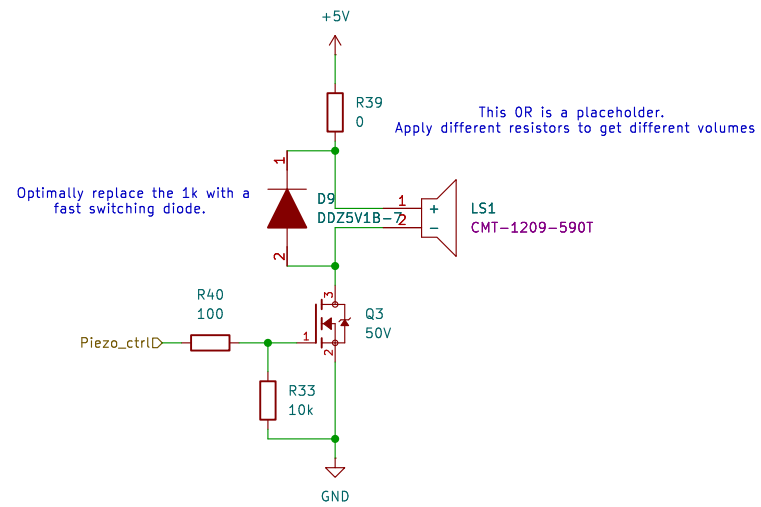


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Sheet: /STM/		Rev:
Author:		
Date:	Size: A4	Id: 2/20
File: STM.kicad_sch		



Not in the PCB yet as we dont know if we actually need it.



Title:

Sheet: /Piezzo/

Rev:

Author:

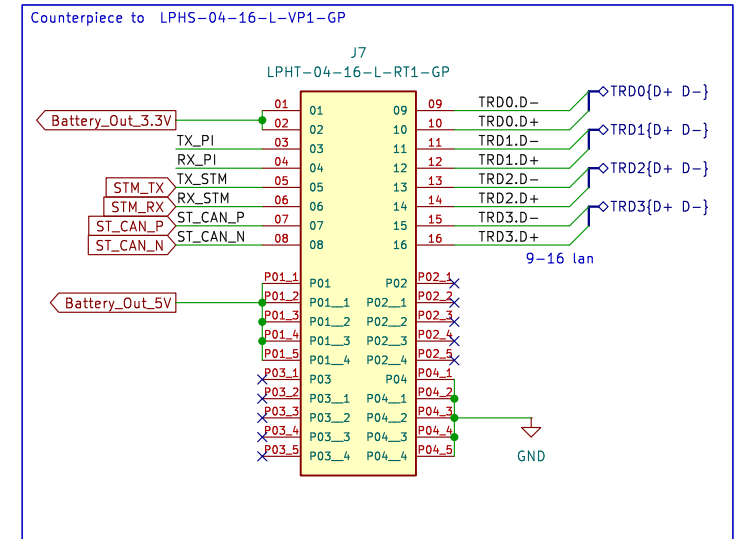
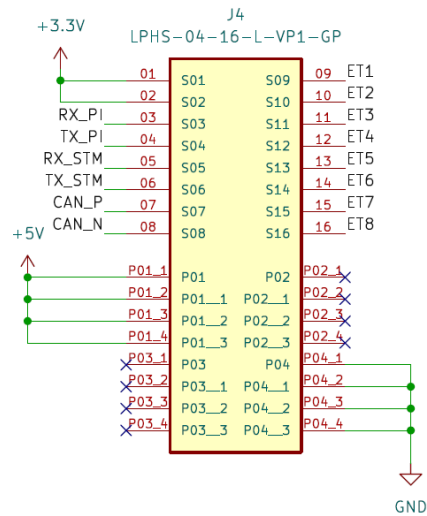
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Mainboard



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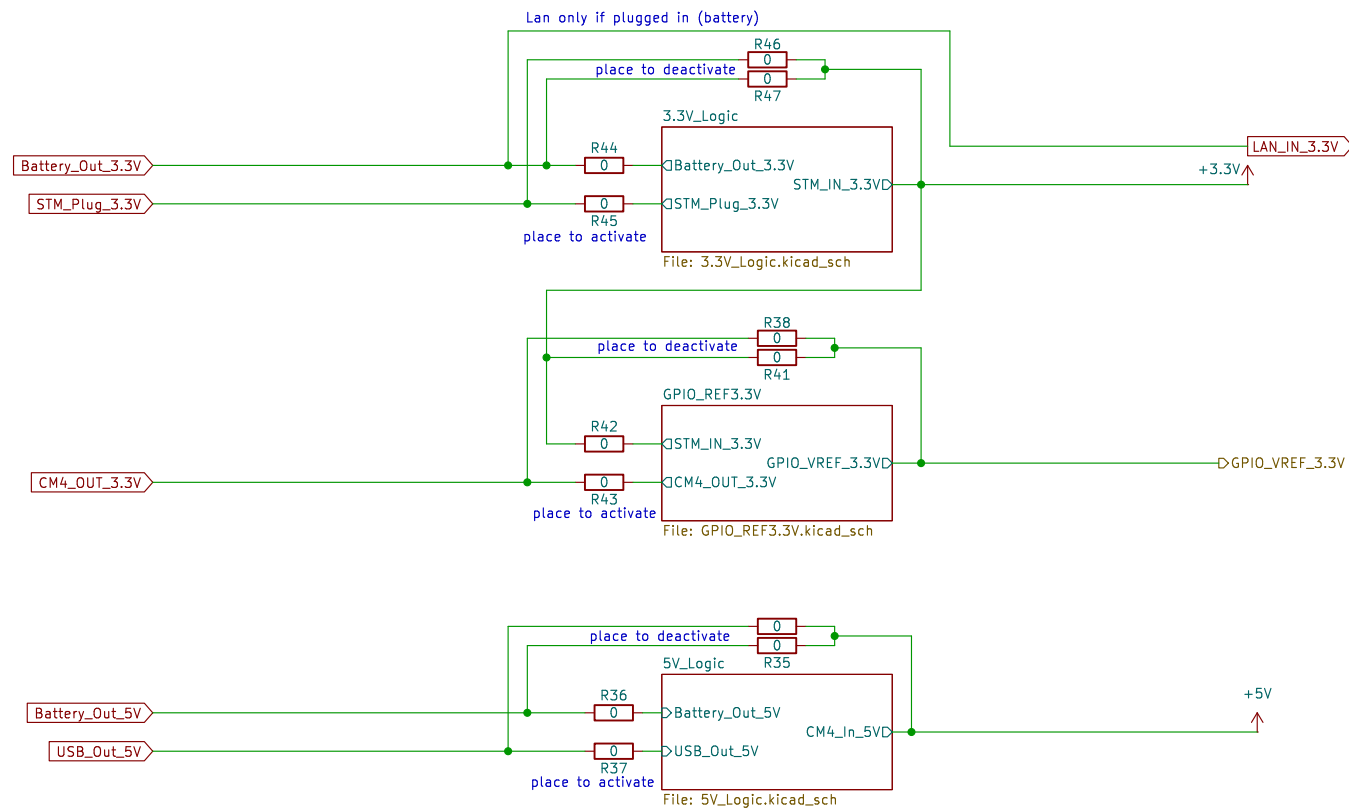
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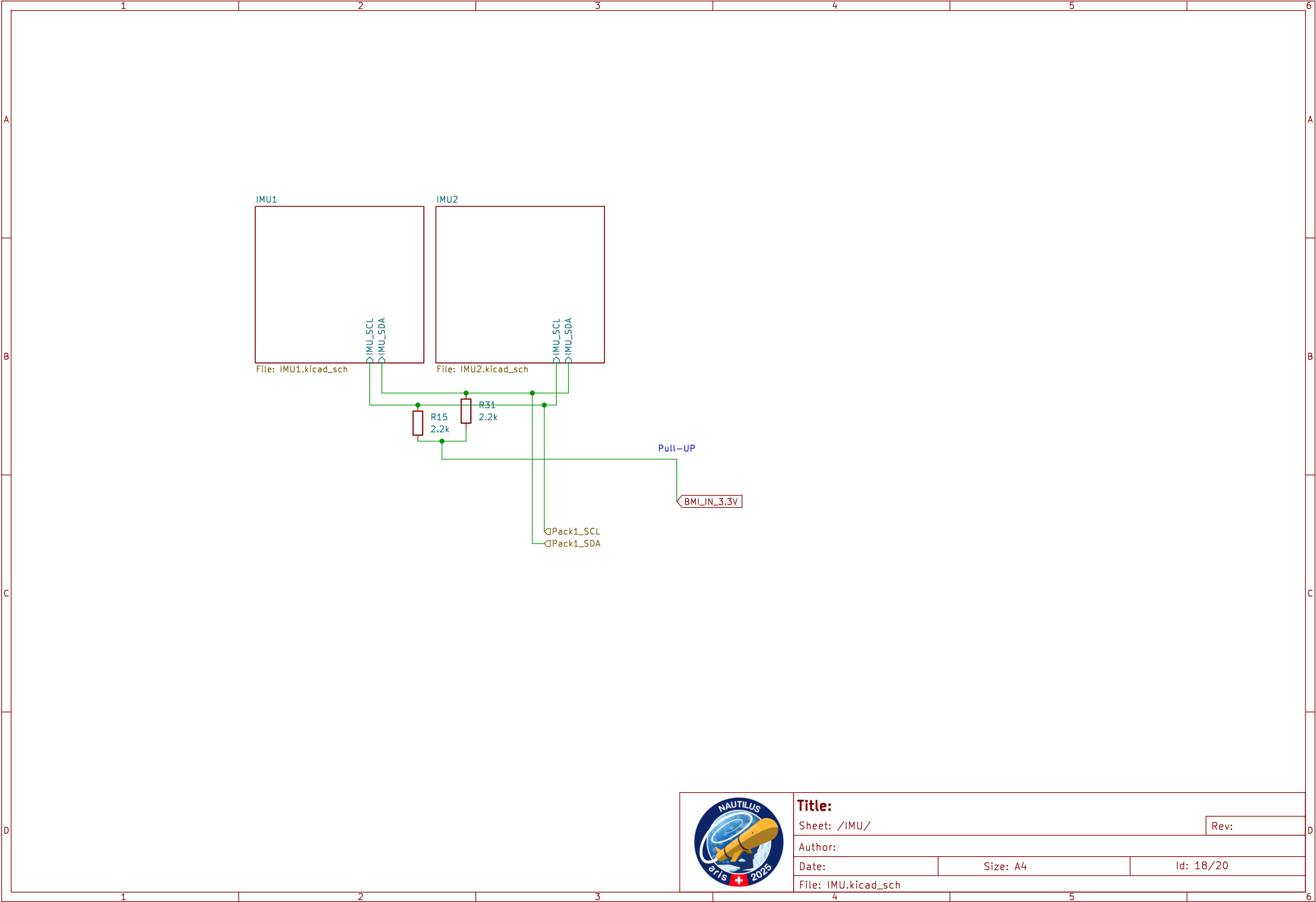
Unconditional Power routes: Whenever the CM4 runs, also run the LED signals AND the SSD voltage, all "core" tasks tied to the CM4.
If I forgot something please let me know.



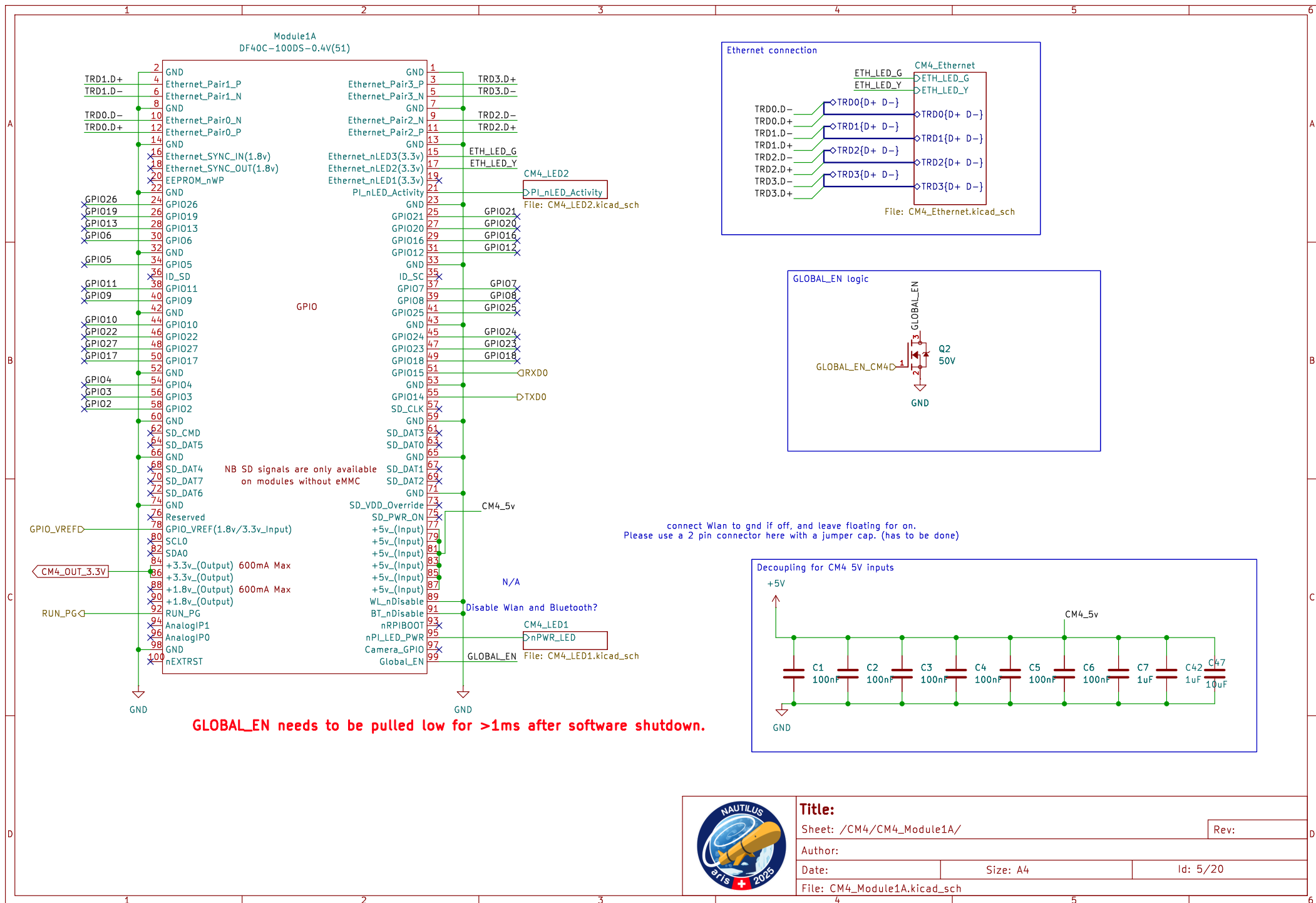
some rules:
USB wont power the STM32.
STM_Plug wont power the CM4
The GPIO_VREF of the CM4 needs to be STM32's 3.3V
The Lan Vin is only powered when running on Battery
Battery preferrably powers everything.

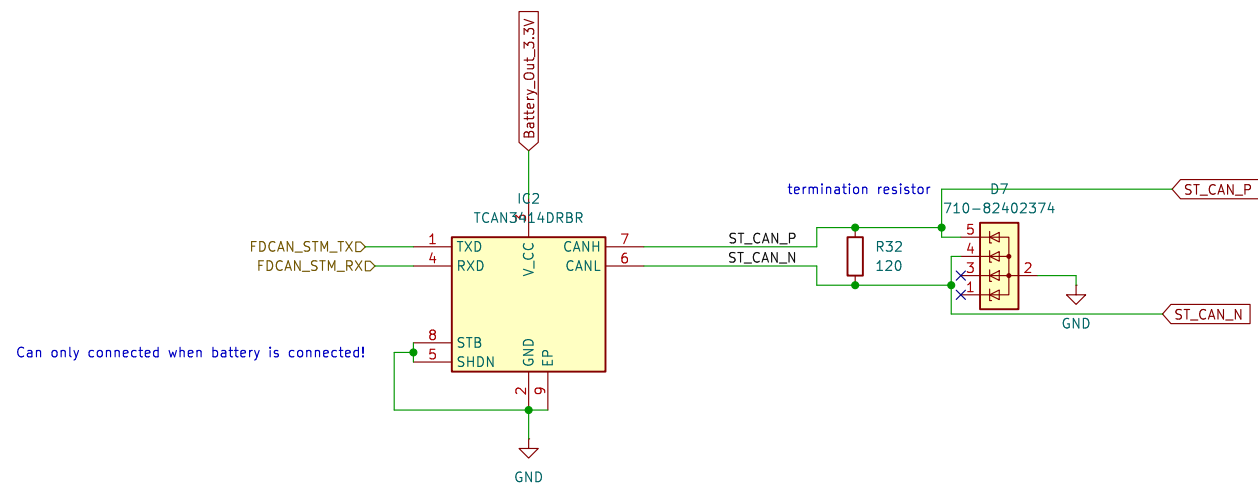


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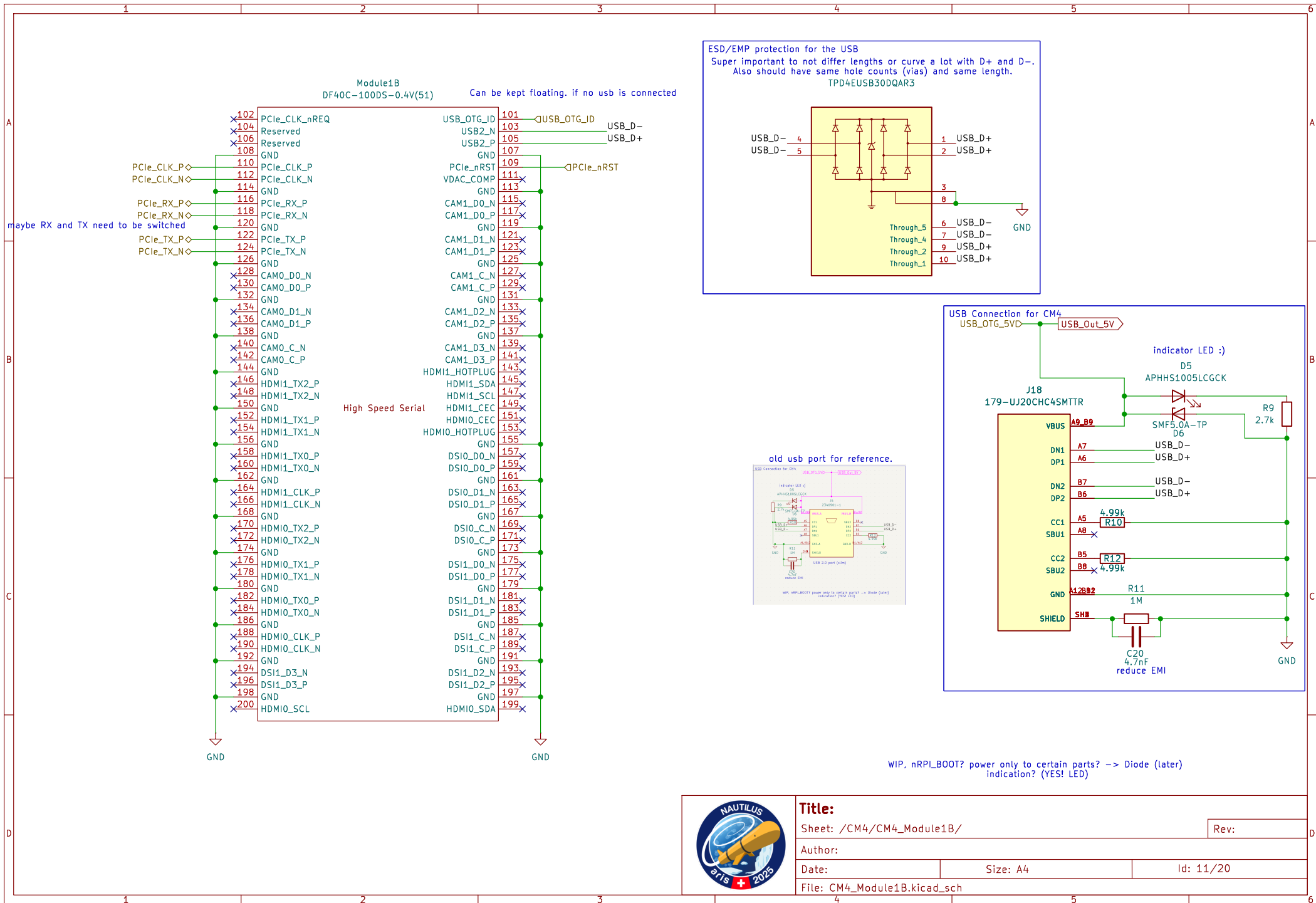


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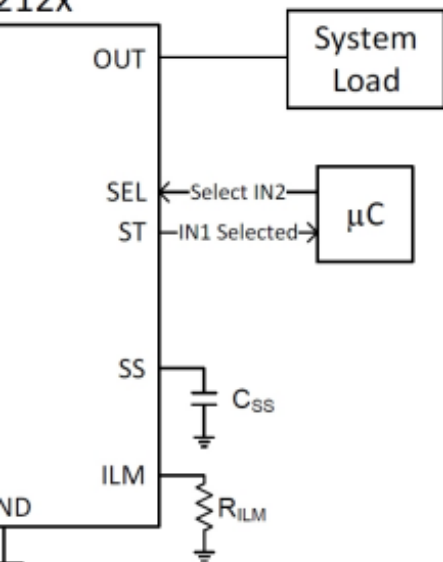




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Sheet: /STM/CAN_Interface/		Rev:
Author:		
Date:	Size: A4	Id: 7/20
File: PowerSTM.kicad_sch		



212x



for questions about wiring etc please consult the datasheet...
<https://www.ti.com/lit/ds/symlink/tps2120.pdf?ts=1761678178328>

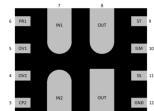
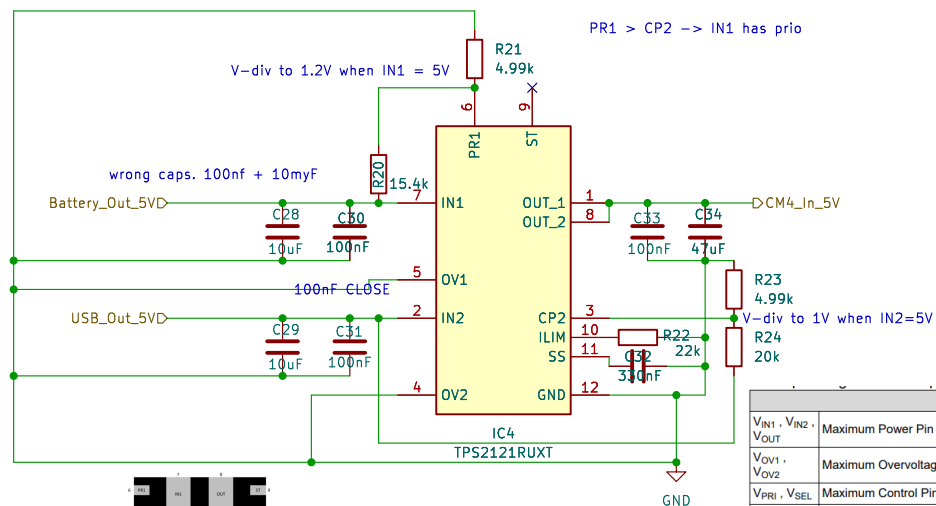


Figure 6-2. TPS2121 (RUX) Package 12-Pin VQFN-HR Bottom View

PIN		Pin Functions	
NAME	TPS2120 WCSP	TPS2121 VQFN-HR	DESCRIPTION
IN1	B1, B2, C1	7	Power Input for Source 1
IN2	B3, B4, C4	2	Power Input for Source 2
OUT	C2, C3, D1, D2, D3, D4	1, 8	Power Output
ST	E1	9	Status output indicating which channel is selected. Connect to GND if not required.
ILM	E2	10	Output Current Limiting for both channels.
SS	E3	11	Adjusts Input Settling Delay Time and Output Soft Start Time
GND	E4	12	Device Ground
PR1	A1	6	Enables Priority Operation. Connect to IN1 to set switchover voltage. Connect to GND if not required.
OV1	A2	5	Active Low Enable Supervisor for IN1 Overvoltage Protection. Connect to GND if not required.
OV2	A3	4	Active Low Enable Supervisor for IN2 Overvoltage Protection. Connect to GND if not required.
SEL	A4	—	Active Low Enable for IN1. Allows GPIO to override priority operation and manually select IN2. TPS2120 only.
CP2	—	3	Enables Comparator Operation and is compared to PR1 to set switchover voltage. Connect to GND if not required. TPS2121 only.

		Pins	MIN	MAX	UNIT
V _{IN1} , V _{IN2} , V _{OUT}	Maximum Power Pin Voltage	IN1, IN2, OUT	-0.3	24	V
V _{OV1} , V _{OV2}	Maximum Overvoltage Pin Voltage	OV1, OV2	-0.3	6	V
V _{PR1} , V _{SEL}	Maximum Control Pin Voltage	PR1, SEL	-0.3	6	V
V _{ST}	Maximum Control Pin Voltage	ST	-0.3	6	V
I _{OUT}	Maximum Output Current	OUT	Internally Limited		
T _{J, MAX}	Maximum Junction Temperature		Internally Limited		
T _{STG}	Storage temperature		-65	150	°C



Title:

Sheet: /Power_logic/5V_Logic/

Rev:

Author:

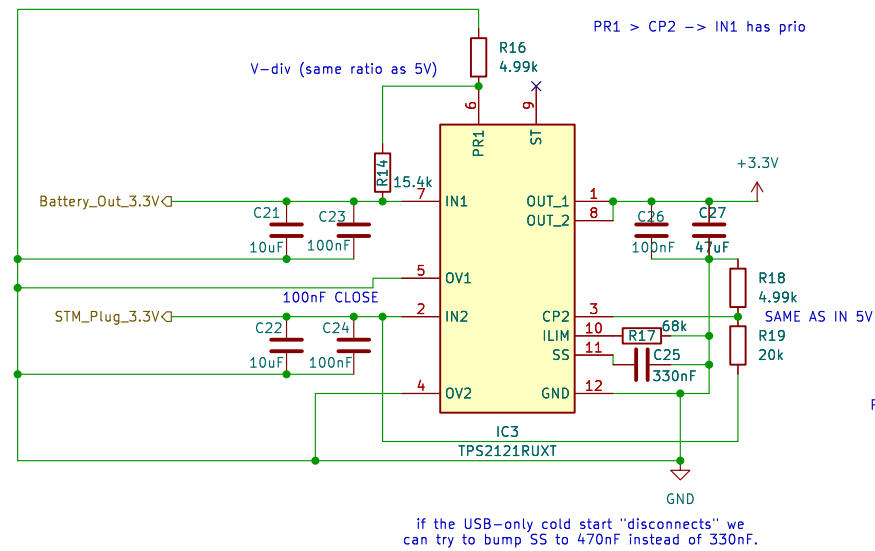
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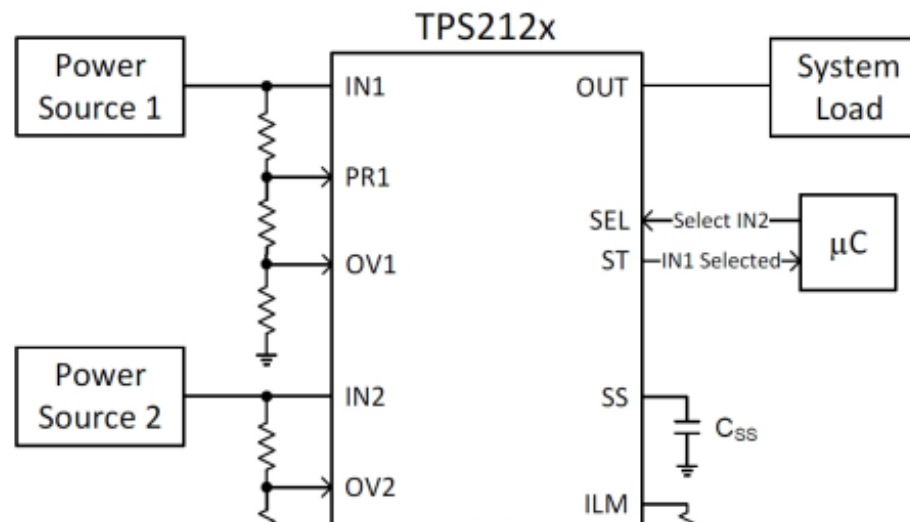
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Pin 10: 68k leads to about 1.72A (should be enough for STM)

[R] = [kOhm]	22 kΩ	→ -4.55 A
65.2 / R*0.861	39 kΩ	→ -2.78 A
	50 kΩ	→ -2.25 A
	56 kΩ	→ -2.04 A
	68 kΩ	→ -1.72 A
	100 kΩ	→ -1.24 A

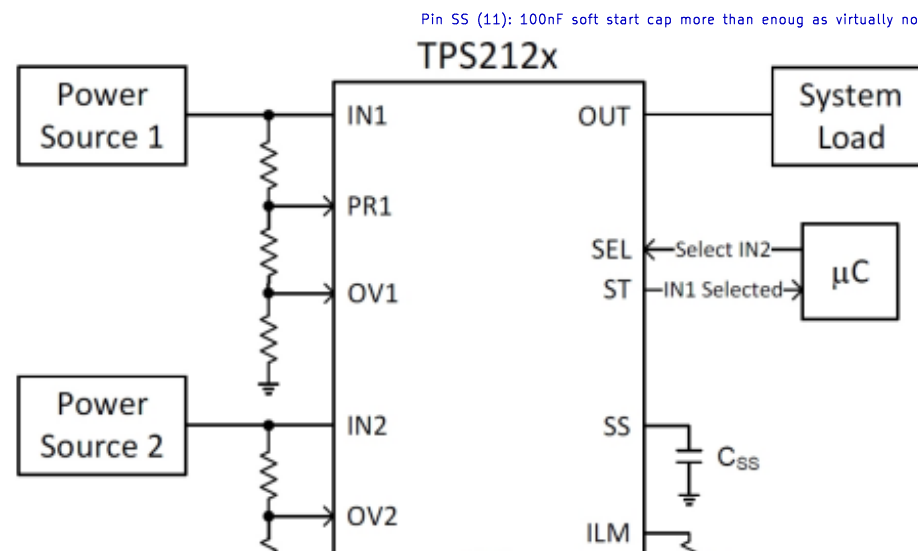
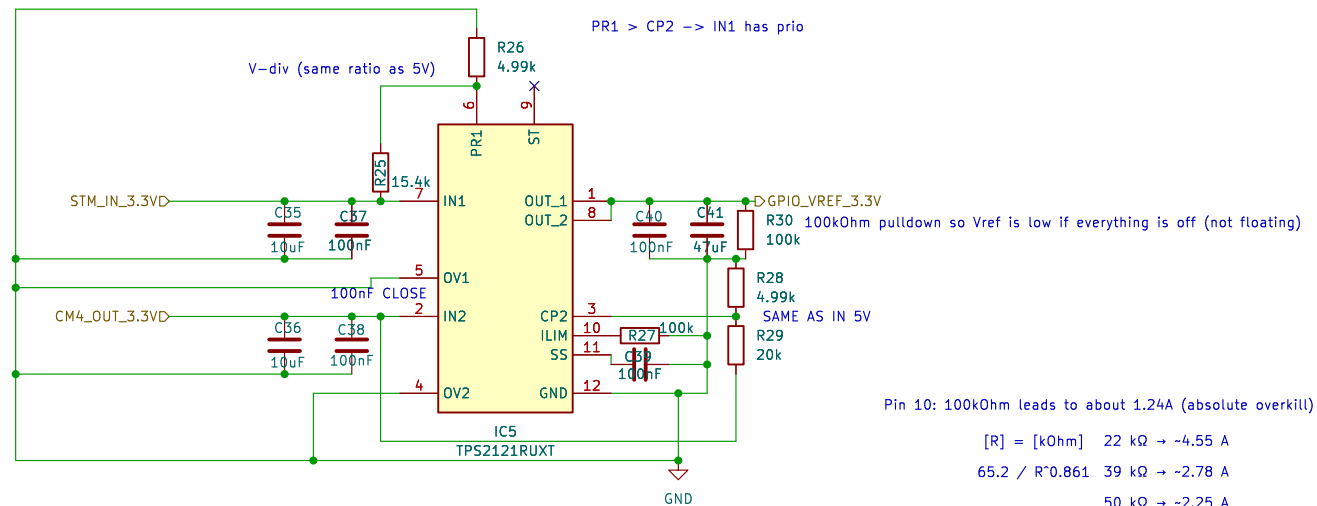


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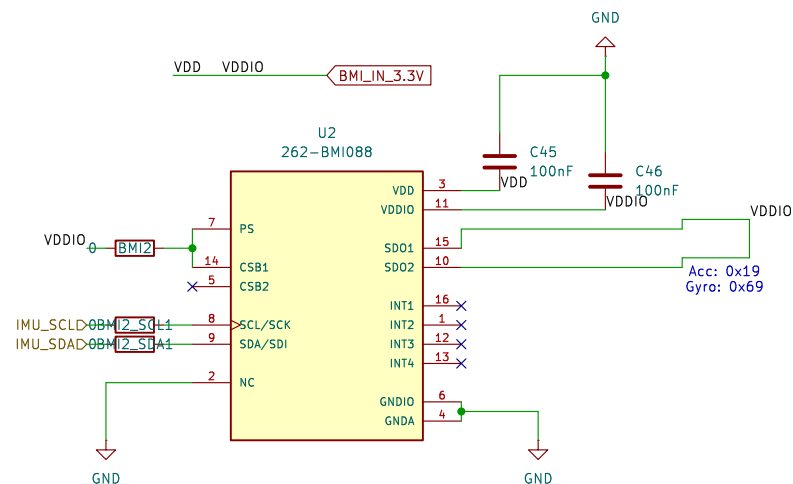
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5

PS -> 3.3V IIC
CSB1 -> 3.3V NOT SPI

PB8 on STM
PB9 on STM

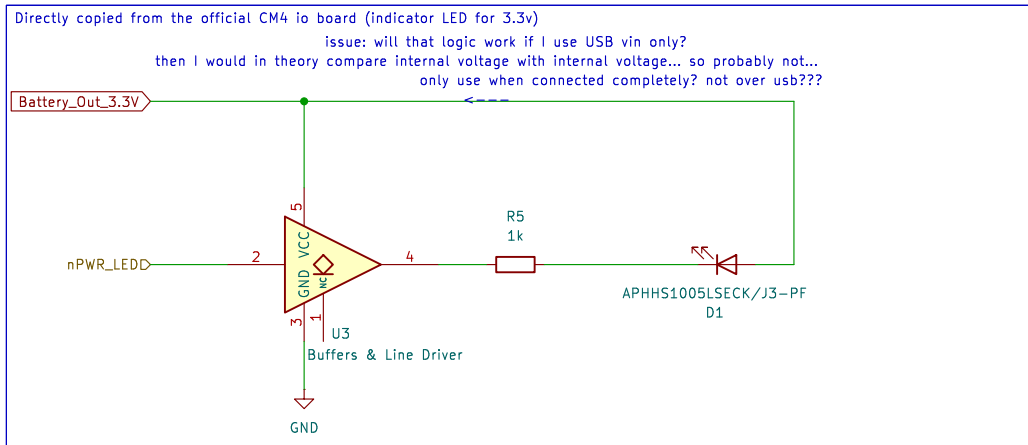


Accelerometer
SD01 pin pulled to GND (0x18)
SD01 pin pulled to VDDIO: (0x19)

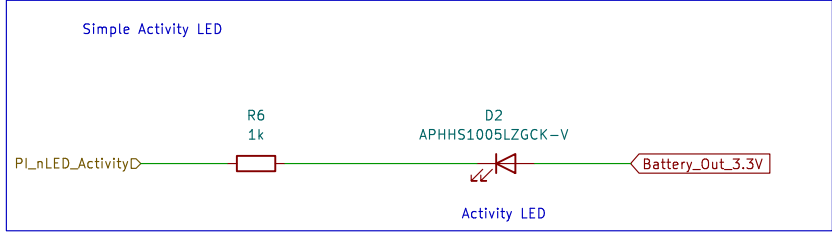
Gyroscope:
SD02 pin pulled to GND: (0x68)
SD02 pin pulled to VDDIO: (0x69)



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Author:		
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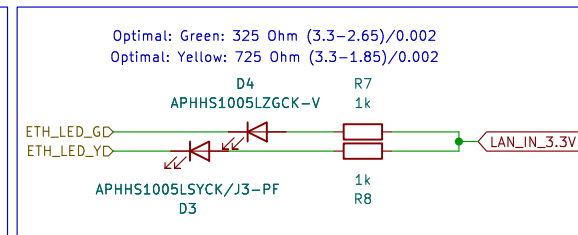
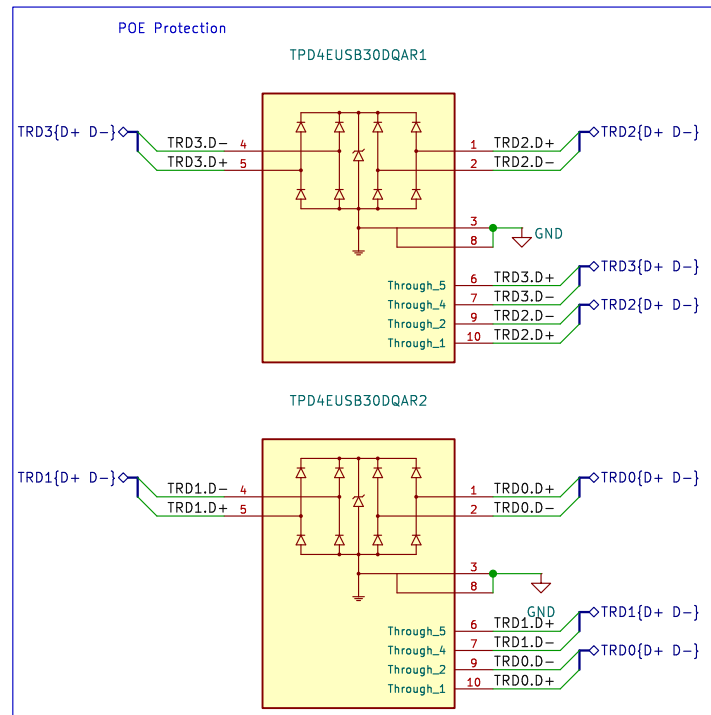
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