



```
1 def turn_right():
      turn_left()
      turn_left()
      turn left()
6 while front_is_clear():
      move()
8 turn_left()
while not at goal():
      if right_is_clear():
          turn_right()
          move()
      elif front_is_clear():
          move()
      else:
          turn_left()
```

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