

# Naveen Siddappa Kattimani

B.Tech in Computer Science and Engineering

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## CAREER OBJECTIVE

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A self-motivated and curious second-year B.Tech in Computer Science and Engineering student at Sapthagiri NPS University. To gain practical experience and grow professionally by contributing to a dynamic organization where I can apply my skills, learn new technologies, and build a strong foundation for my career

## EDUCATION

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**Sapthagiri NPS University, Bengaluru,** 2024 – 2028 | Bengaluru

*B.Tech in Computer Science and Engineering*

SGPA (1st Semester): 8.05 SGPA (2nd Semester): 8.73 SGPA

**Govt PU College, Varthur, Class XII** 2022–2024 | Bengaluru

[Govt PU college], [Bengaluru] | [85%]

**St Therasa School, Hidkal Dam, Class X** 2021–2022 | belagavi

[CBSE, 2021-2022], [St Theresa School], [Belagavi] | [72%]

## SKILLS

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**Programming Languages** – C | Java | Python, **Web Technologies** – HTML | CSS | JAVASCRIPT,

**Tools/Platforms** – MS Office | git | github, **Soft Skills** – Communication Teamwork Time

Management

## LANGUAGES KNOWN

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English

Hindi

Kannada

## CERTIFICATION

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**[Introduction to Cybersecurity],**

02/2026 | Bengaluru

*Cisco Networking Academy*

- Learned fundamentals of cybersecurity, cyber threats, malware, phishing, and network security concepts.
- Gained understanding of data protection, CIA triad, and basic security practices.

## **ACADEMIC PROJECTS**

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### **Smart Classroom – Web-Based Classroom Management System**

- Developed a web application to allocate teachers to classrooms based on schedule and availability.
- Implemented features like teacher assignment, timetable management, and classroom tracking.
- Designed user-friendly interface for admin and faculty access.
- Improved efficiency in classroom allocation and reduced manual scheduling errors.

### **Obstacle Avoiding Car – Autonomous Robot Vehicle**

- Developed an automated robotic car capable of detecting and avoiding obstacles.
- Used ultrasonic sensors to measure distance and control movement.
- Implemented microcontroller-based logic to change direction when obstacles are detected.
- Demonstrated basic concepts of embedded systems and automation.