

Fig1. SONAR and IR sensors setup

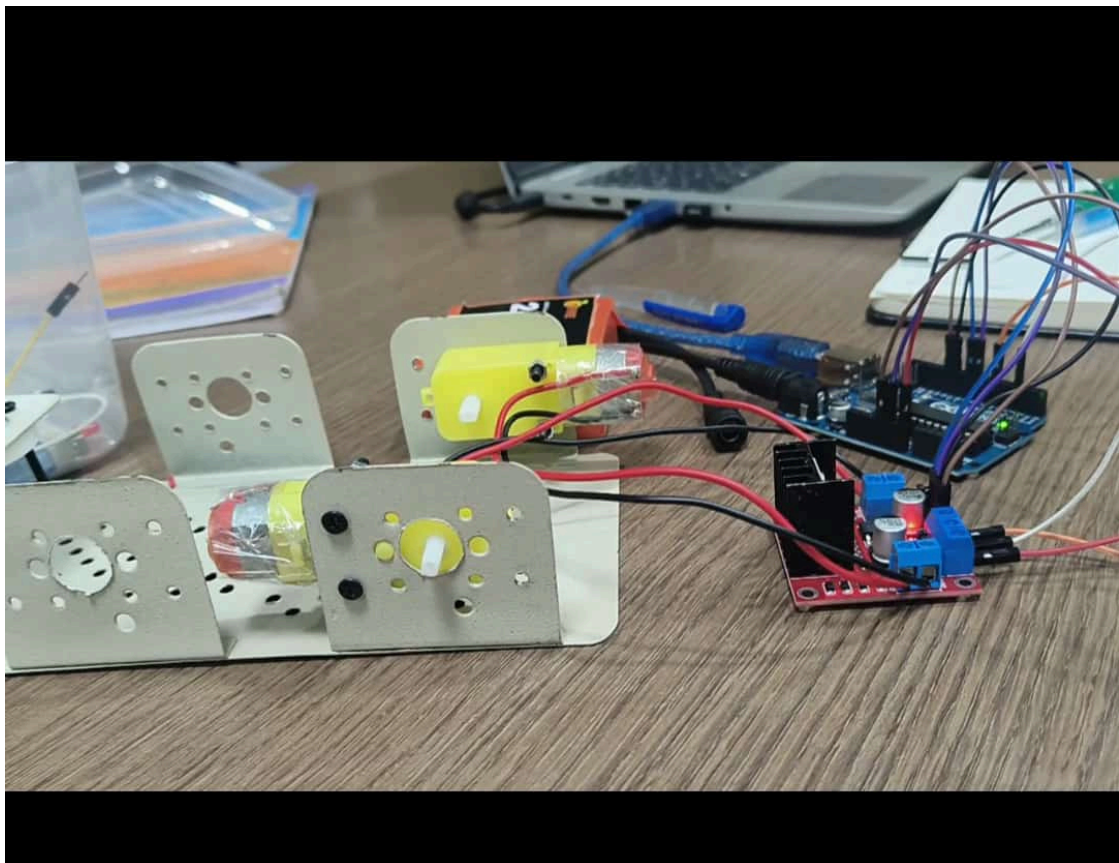


Fig2. Motors and Audrino Setup

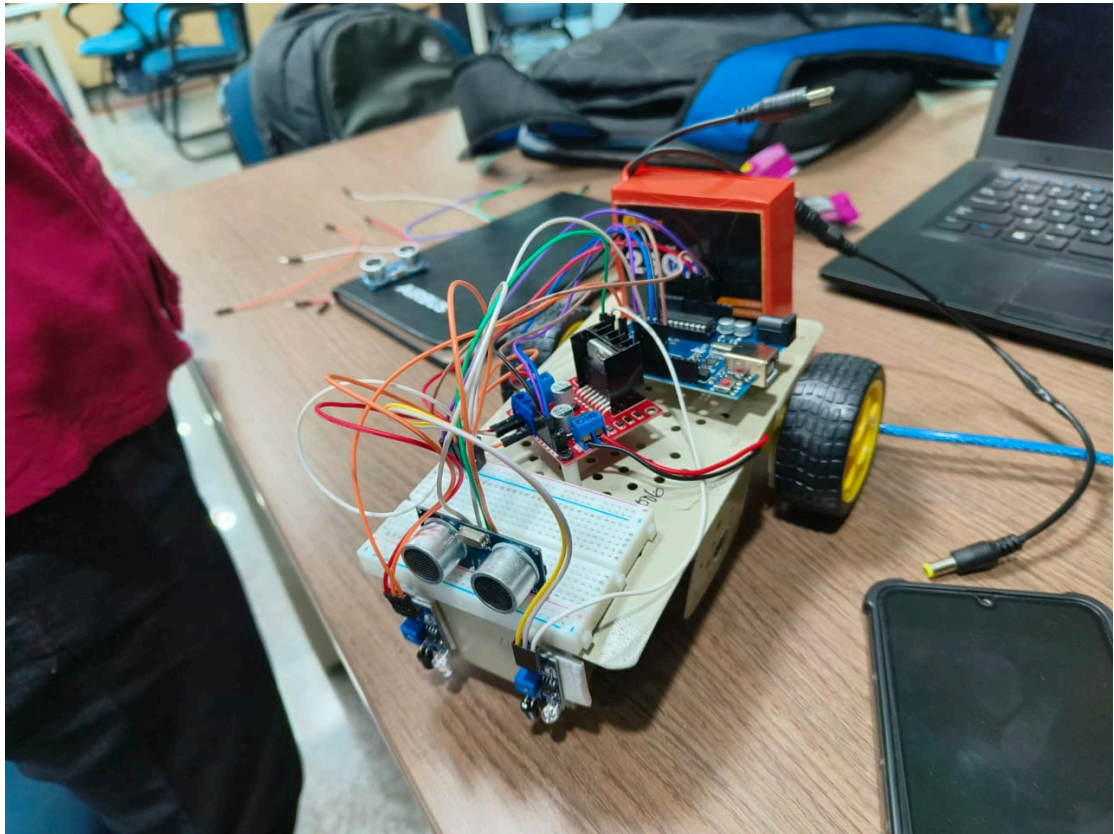


Fig3. LineNavigator-Bot