



Neural Networks




- Neural Networks are a machine learning framework that attempts to mimic the learning pattern of natural biological neural networks:

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STRUCTURE OF A NEURON



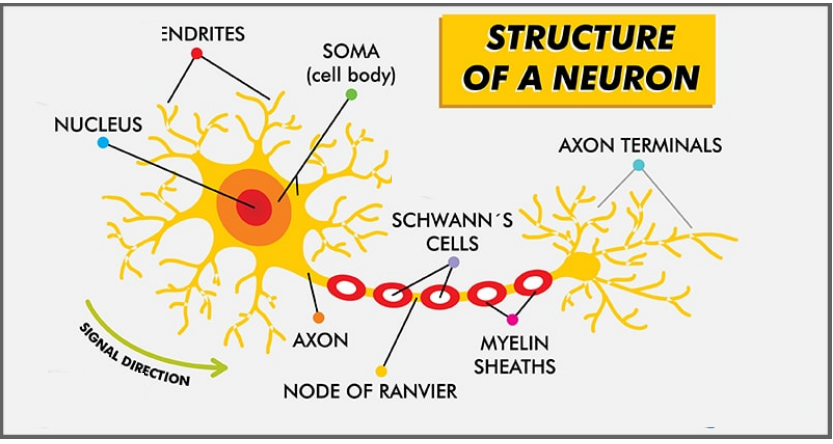
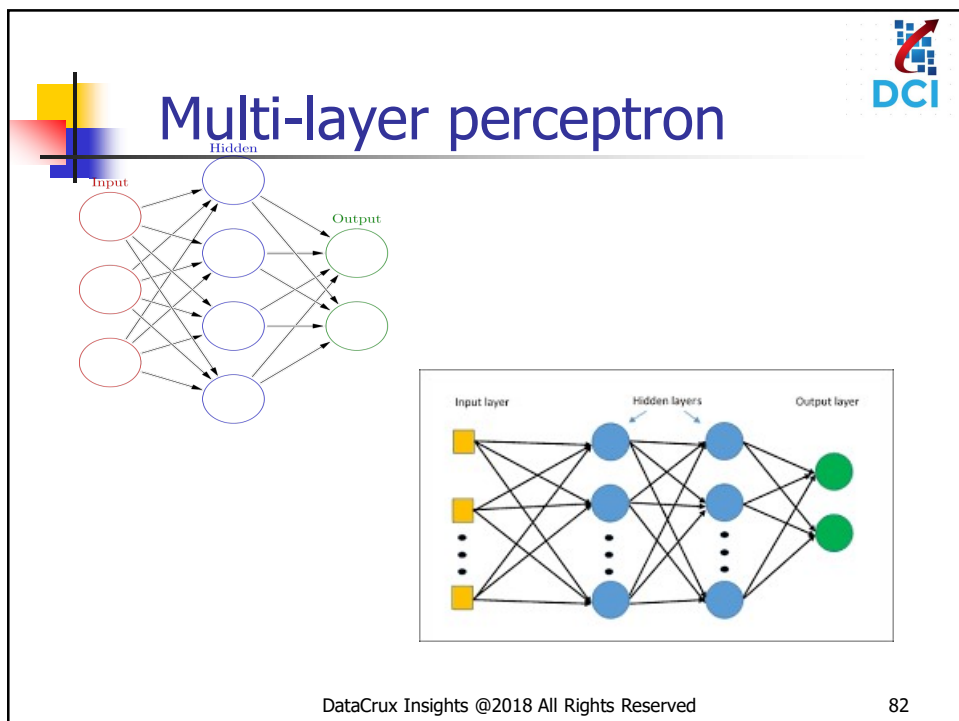
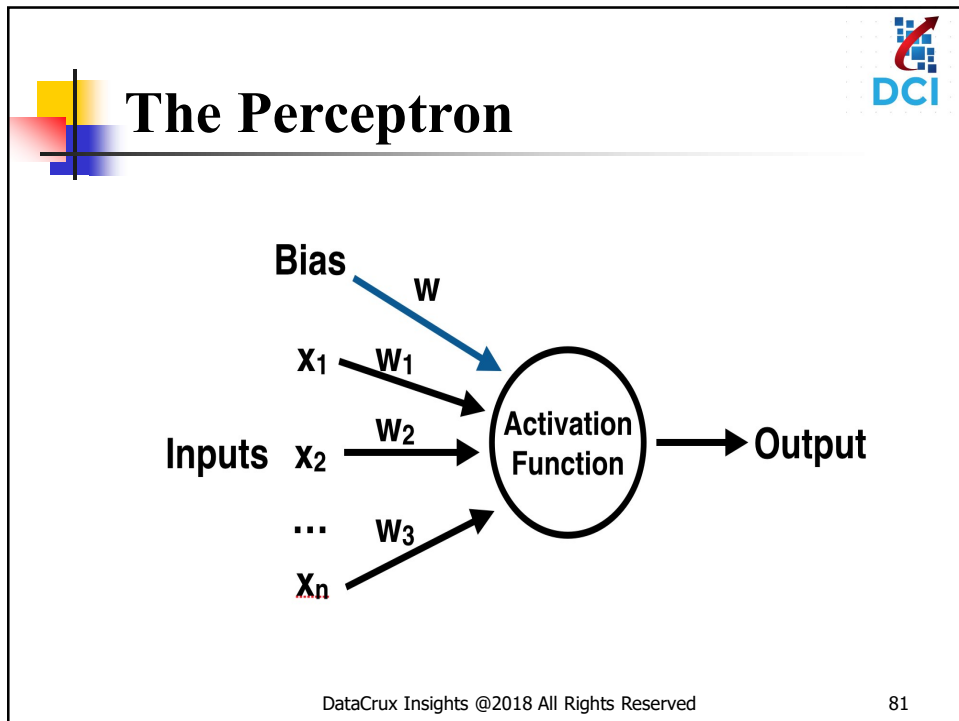



Diagram illustrating the structure of a neuron, showing the following components:

- DENDRITES
- NUCLEUS
- SOMA (cell body)
- AXON
- SCHWANN'S CELLS
- MYELIN SHEATHS
- NODE OF RANVIER
- AXON TERMINALS


SIGNAL DIRECTION is indicated by a green arrow pointing from the dendrites towards the axon terminals.

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Structure of a Neural Network




How many hidden layers should be there in Neural Network?

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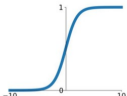
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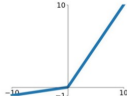
Activation Functions



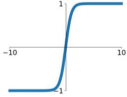
Sigmoid

$$\sigma(x) = \frac{1}{1+e^{-x}}$$


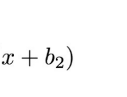
Leaky ReLU

$$\max(0.1x, x)$$


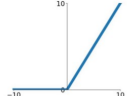
tanh

$$\tanh(x)$$


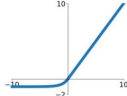
Maxout

$$\max(w_1^T x + b_1, w_2^T x + b_2)$$


ReLU


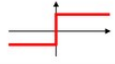

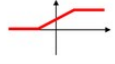
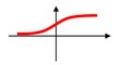
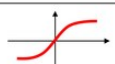
$$\max(0, x)$$


ELU

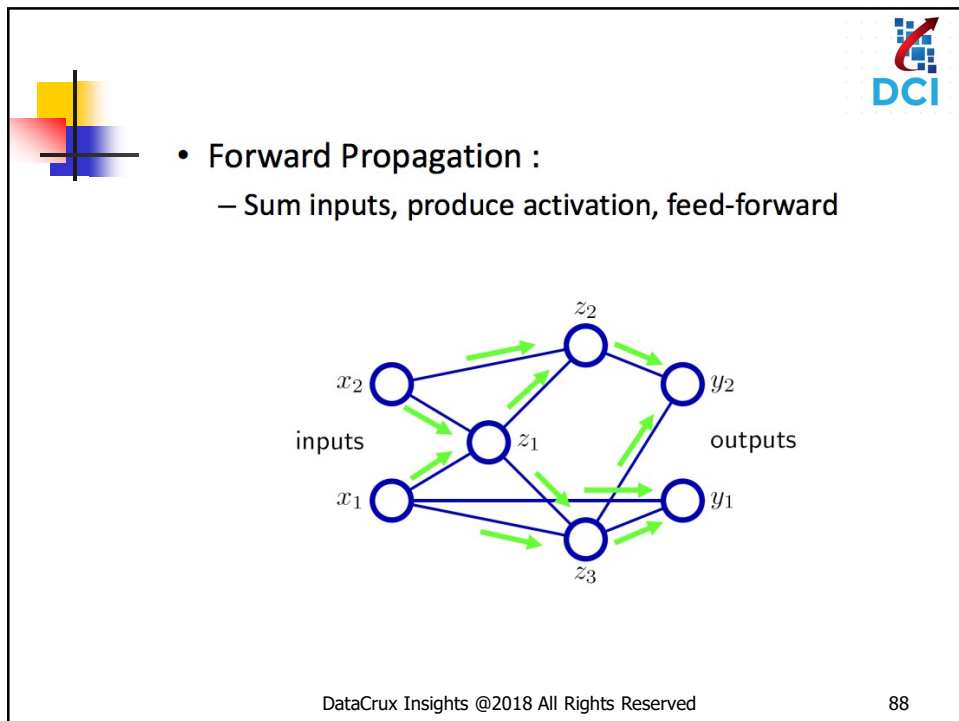
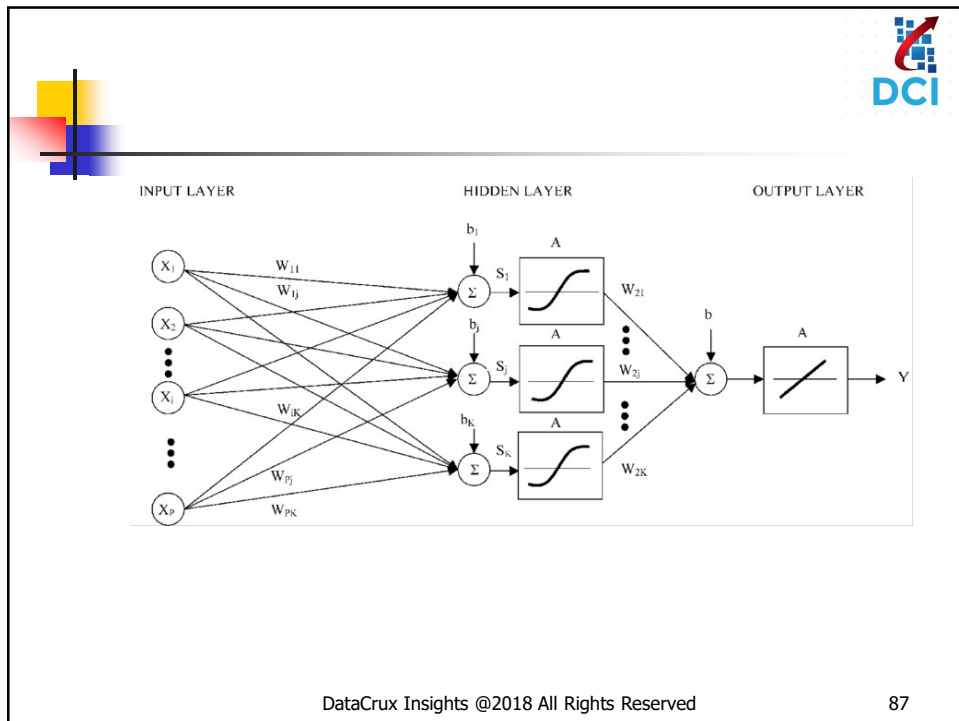
$$\begin{cases} x & x \geq 0 \\ \alpha(e^x - 1) & x < 0 \end{cases}$$


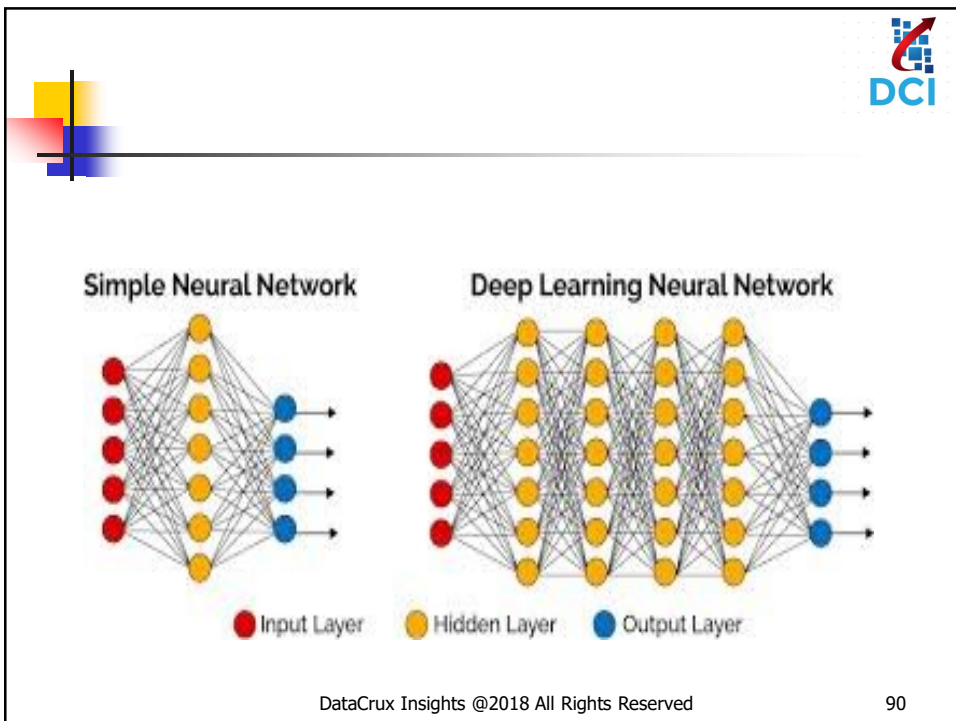
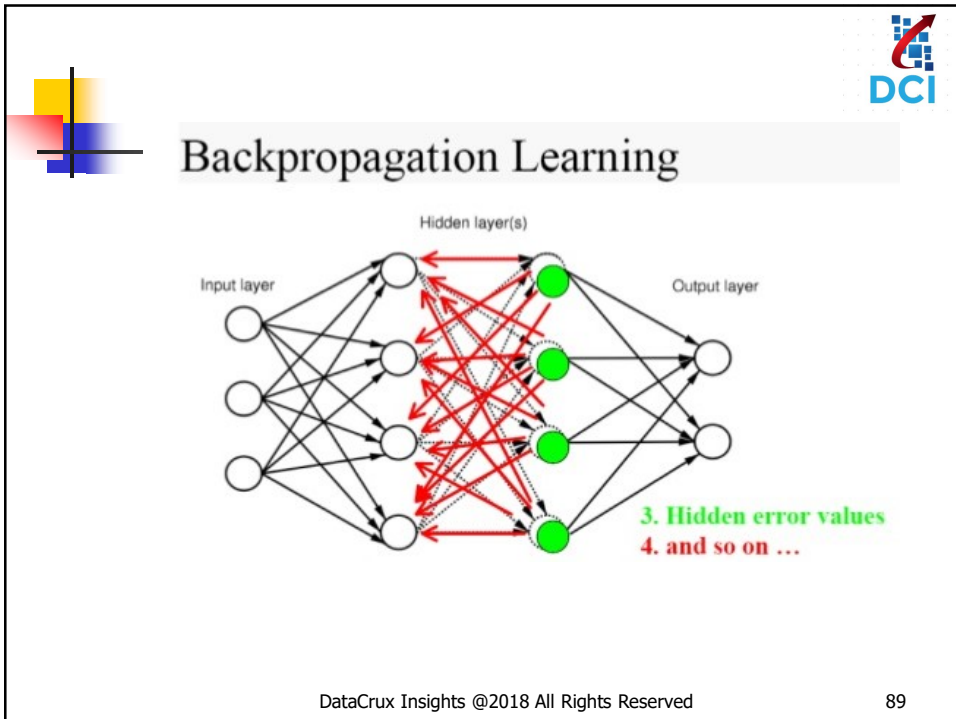
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Activation function	Equation	Example	1D Graph
Unit step (Heaviside)	$\phi(z) = \begin{cases} 0, & z < 0, \\ 0.5, & z = 0, \\ 1, & z > 0, \end{cases}$	Perceptron variant	
Sign (Signum)	$\phi(z) = \begin{cases} -1, & z < 0, \\ 0, & z = 0, \\ 1, & z > 0, \end{cases}$	Perceptron variant	
Linear	$\phi(z) = z$	Adaline, linear regression	
Piece-wise linear	$\phi(z) = \begin{cases} 1, & z \geq \frac{1}{2}, \\ z + \frac{1}{2}, & -\frac{1}{2} < z < \frac{1}{2}, \\ 0, & z \leq -\frac{1}{2}, \end{cases}$	Support vector machine	
Logistic (sigmoid)	$\phi(z) = \frac{1}{1 + e^{-z}}$	Logistic regression, Multi-layer NN	
Hyperbolic tangent	$\phi(z) = \frac{e^z - e^{-z}}{e^z + e^{-z}}$	Multi-layer NN	


	Propagation	Back-propagation
Sigmoid	$y_s = \frac{1}{1 + e^{-x_s}}$	$\left[\frac{\partial E}{\partial x}\right]_s = \left[\frac{\partial E}{\partial y}\right]_s \frac{1}{(1 + e^{x_s})(1 + e^{-x_s})}$
Tanh	$y_s = \tanh(x_s)$	$\left[\frac{\partial E}{\partial x}\right]_s = \left[\frac{\partial E}{\partial y}\right]_s \frac{1}{\cosh^2 x_s}$
ReLu	$y_s = \max(0, x_s)$	$\left[\frac{\partial E}{\partial x}\right]_s = \left[\frac{\partial E}{\partial y}\right]_s \mathbb{I}\{x_s > 0\}$
Ramp	$y_s = \min(-1, \max(1, x_s))$	$\left[\frac{\partial E}{\partial x}\right]_s = \left[\frac{\partial E}{\partial y}\right]_s \mathbb{I}\{-1 < x_s < 1\}$








Disadvantages




- Need large processing and storage resources
- Require a large diversity of training for real-world operation
- Black Box “Difficult to understand”

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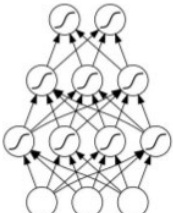
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CNN vs RNN



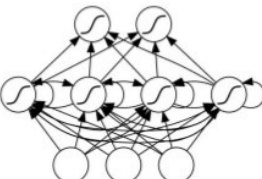
Feedforward NN vs. Recurrent NN



Output Layer

Hidden Layers

Input Layer



Output Layer

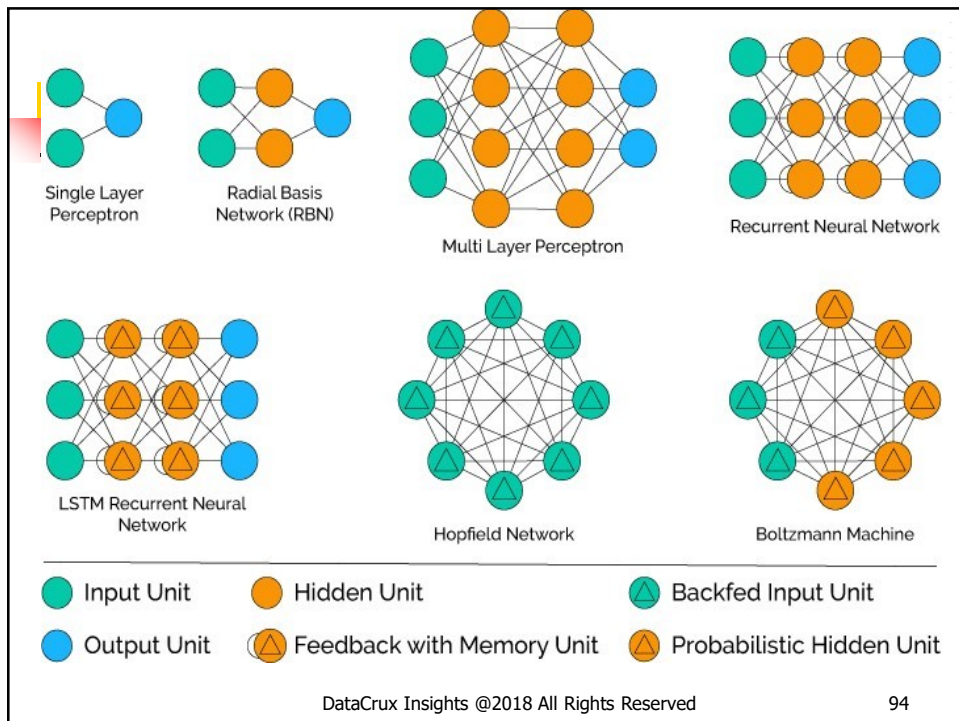
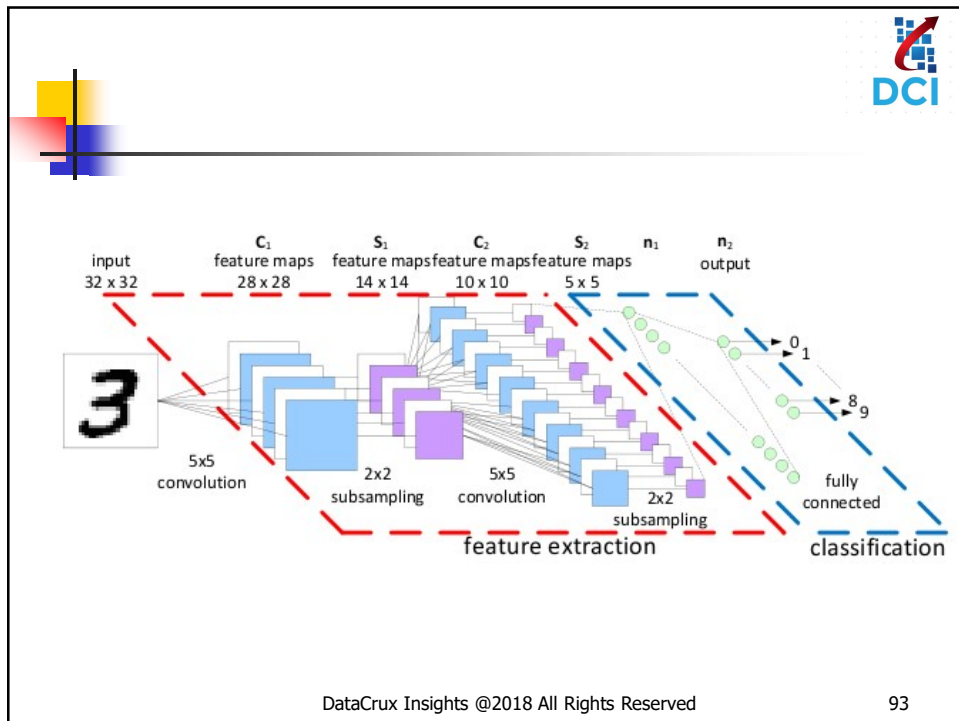
Hidden Layer

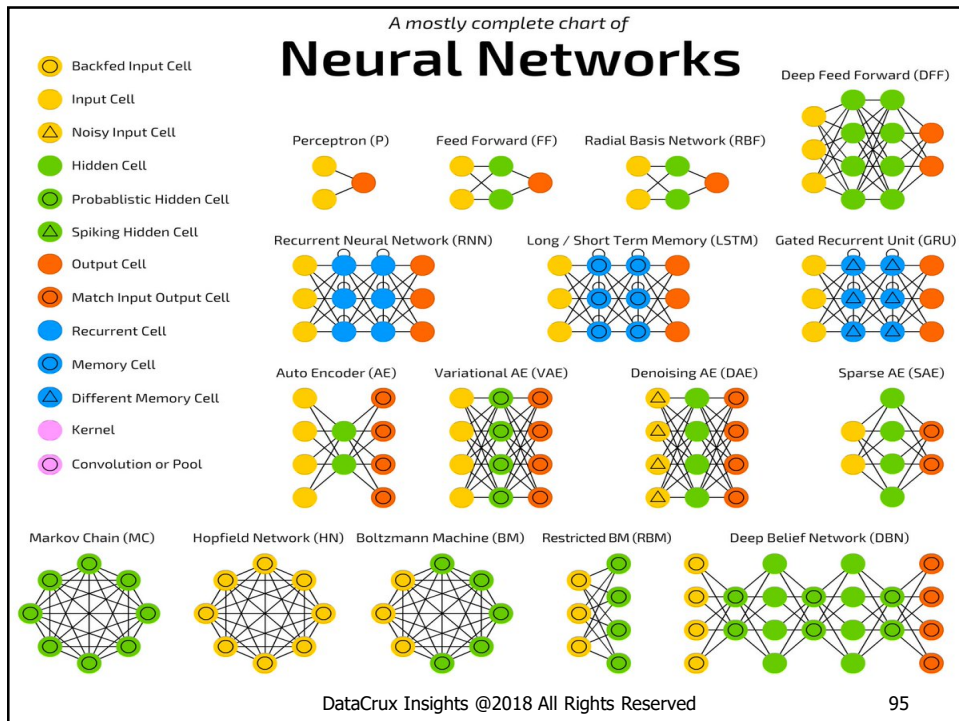
Input Layer



Recurrent neural networks (RNNs) allow cyclical connections.

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Convolutional Neural Network

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- The process of building a Convolutional Neural Network always involves four major steps.
- **Step - 1 : Convolution**
- **Step - 2 : Pooling**
- **Step - 3 : Flattening**
- **Step - 4 : Full connection**


```
classifier.add(Conv2D(32, (3, 3),  
input_shape = (64, 64, 3), activation =  
'relu'))
```

32=>Number of filters


Conv2D ->images , Conv3D ->videos

input_shape=>image shape

3=>RGB colours




CNN –Filter




- every network layer acts as a detection filter for the presence of specific features or patterns present in the original data

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1	1	1	0	0
0	1	1	1	0
0	0	1	1	1
0	0	1	1	0
0	1	1	0	0

Image

4	3	4
2	4	3
2	3	

Convolved Feature

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