# **Naveen Prashanna Gurumurthy**

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#### Education

Master of Science, University of Texas at Dallas (UTD) | Dallas, TX Aug 2023 - May 2025

Major: Computer Science | Specialization: Intelligent System | GPA: 3.55/4

Bachelor + Master of Technology, Indian Institute of Technology (IIT) Madras | India Aug 2017 - May 2022

Major: Mechanical Engineering | Minor: Artificial Intelligence & Machine Learning | GPA: 3.24/4

## **Technical Skills**

Languages C++, Python (Scikit Learn, PyTorch, Tensorflow), Javascript, NodeJS, React, Java, PostgreSQL

Software & Tools ROS (Robot Operating Software), DataBricks, MATLAB, Visual Studio, Android Studio, Git, LaTeX

Certifications Design and Analysis of Algorithms, Android Development by Google, Trading Algorithms

**Professional Experience** 

#### Web Developer, Kahana Group Inc | Remote, US

Aug 2023 - Jan 2024

- Proposed adv. features & coordinated with cross-functional teams to design & implement UI/UX utilizing React JS
- Integrated analytics tool & initiated data-driven upgrades to meet user demands: Increased User Retention rate by 4%

### Software Engineer, Quantitative Brokers | Chennai, India

Jul 2022 - Jun 2023

- Led the strategic integration of SonarQube & BlackDuck into Jenkins pipeline, reducing critical vulnerabilities by 20%
- Designed a robust VueJS Web-app, decentralized the database using ETL which improved database performance
- Engineered an internal tool to seamlessly create and transmit FIX (Financial Information Xchange) order messages
- Enhanced FIX tool by on-boarding functionalities for Multi-Leg orders which increased operational efficiency by 15%

## Big Data Engineer Intern, Big Data Science Research | Bangalore, India

Apr 2020 - Jun 2020

- Automated the data mining from Google Maps, elevating OpenStreetMap visualization using data overlay techniques
- Devised a proprietary map-matching algorithm to accurately model urban traffic flow, aiding in efficient city planning

### Machine Learning Engineer Intern, Alphabt – TVS Motors Ltd | Hosur, India

May 2019 - Jun 2019

- Implemented a program to scan vehicle labels leveraging openCV, boosting validation performance system by 3%
- Devised a custom TensorFlow-based object detection model, achieving an 99% accuracy in text engraving recognition

## **Projects**

#### Machine Learning Engineer: Trajectory-Aware Human Feedback for Hierarchical RL | UTD Sep 2024 - Dec 2024

- Proposed a novel Hierarchical Reinforcement Learning framework to improve subgoal generation in complex tasks
- Deployed the Deep-RL framework in the FetchReach environment, resulting in a 10% increase in task success rates
   NLP Engineer: Chatbot | UTD
   Feb 2024 May 2024
- · Built comprehensive knowledge base by web scraping & advanced NLP techniques enabling efficient data retrieval
- Engineered an LSTM-based model with an attention mechanism, improving response relevance and context by 25%

## Machine Learning Engineer: Surface Texture Analysis | IIT Madras

Aug 2021 - May 2022

- Systemized an approach in identifying machined surface textures with CV & ML techniques, achieved 99.6% accuracy
- Built Neural Network employing statistical features from GLCM for texture classification improving accuracy by 44%

#### Al Research Scientist: Optimization Algorithms | IIT Madras

Mar 2022 - May 2022

- · Assessed performance of 4 distinct Stochastic Optimization algorithms on control agents in OpenAI gym environment
- Developed & applied Gradient Descent algorithms to optimize Deep Q-Network model, attaining a 15% boost in return

## Applied Research Scientist: Multi-Agent Cricket Game | IIT Madras

Feb 2022 - May 2022

- Formulated cricket game as Markov Decision Process for optimal decision-making of actions in dynamic system
- Modeled a 2-player Monte Carlo Tree Search algorithm for better action selection which elevated match outcomes

#### **Automation Engineer: DIC's Terrace Farming Robot** | Inter-IIT TechMeet-2019

Oct 2019 - Dec 2019

- Designed a ROS-based autonomous agricultural robot capable of performing step-farming on challenging hilly terrains
- Integrated Kinect 360 for 3D mapping, enabling precise robot localization and navigation within the farmland

## Leadership Experience

## Teaching Assistant | UTD

Aug 2024 - Dec 2024

- Coordinated with Professor for effective teaching tactics & class management by facilitating projects for 50+ students
   Robotics Club Coordinator | IIT Madras
   Aug 2017 Dec 2019
- Led a team of 5 and took end-to-end ownership to build Autonomous Ground Vehicle and Water Levitation projects

#### Awards and Honors

- Granted Scholarship for Graduate Studies by securing merit score in "Graduate Aptitude Test in Engineering"
- Awarded Silver Prize in "Terrace Farming Robot for Hilly areas" robotics challenge at Inter IIT Tech Meet

2021 2019

• Secured a place in the **Asia and Limca Book of Records** for "Most number of robots cleaning an area"

2017