

PHASE 5: PROJECT DOCUMENTATION & SUBMISSION

FLOOD MONITORING AND EARLY WARNING SYSTEM

Objectives:

- 1. Flood Monitoring:** Develop a system that can monitor water levels and weather conditions to predict and detect floods accurately.
- 2. Climate Change Adaptation:** Account for the impact of climate change, such as increased rainfall intensity and sea level rise, in flood predictions and warnings.
- 3. Early Warning:** Provide timely and accurate warnings to residents, authorities, and emergency services to minimize damage and save lives.
- 4. Scalability:** Ensure that the system can be deployed in various regions and easily expanded.
- 5. Data Analysis and Visualization:** Implement data analysis and visualization tools to make sense of the collected data and present it in a comprehensible manner.

IoT Sensor Deployment:

- 1. Sensor Selection:** Choose appropriate sensors to measure water levels, rainfall intensity, and other relevant environmental parameters. Consider factors like accuracy, durability, and power efficiency.
- 2. Sensor Placement:** Deploy sensors strategically in flood-prone areas, including riverbanks, coastal regions, and urban areas vulnerable to flash floods.
- 3. Data Transmission:** Set up a reliable data transmission infrastructure, such as IoT communication protocols, to send sensor data to a central database or cloud platform.

4. Data Quality Assurance: Implement data validation and quality checks to ensure the accuracy and reliability of sensor data.

Platform Development:

1. Database: Create a robust database system to store sensor data, historical weather information, and climate change data.

2. Machine Learning Models: Develop predictive models that can analyze historical data, climate change projections, and real-time sensor data to forecast potential floods.

3. Alerting System: Design an alerting system that triggers warnings based on predefined thresholds and predictive analytics.

4. User Interface: Build user-friendly interfaces for both end-users and administrators to access real-time data, reports, and alerts.

5. GIS Integration: Integrate Geographic Information System (GIS) data to provide location-specific flood risk assessment and visualization.

Code Implementation:

1. Sensor Data Collection: Write code to collect data from the deployed IoT sensors. Ensure it runs continuously and efficiently.

2. Data Analysis and Prediction: Implement machine learning algorithms to analyse the collected data, assess the risk of flooding, and predict potential flood events.

3. Alerting Algorithm: Develop algorithms that trigger alerts based on sensor data and predictive analytics. Consider the severity of the situation and who should be alerted (e.g., residents, emergency services).

4. Data Visualization: Create code to generate charts, maps, and other visualizations to present the data and predictions in a comprehensible format.

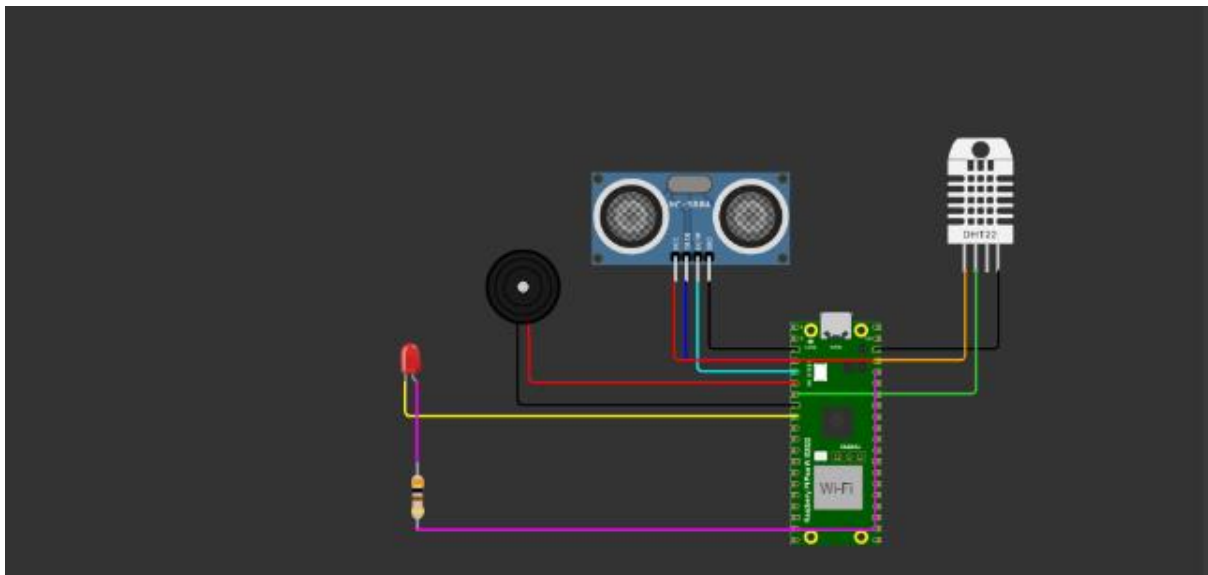
5. Testing and Validation: Rigorously test the system for accuracy, reliability, and responsiveness. Include edge cases and simulate various flood scenarios.

6. Maintenance and Updates: Ensure regular maintenance and updates to adapt to changing climate patterns and improve system performance.

7. Security: Implement robust security measures to protect the system from cyber threats and unauthorized access.

8. Scalability: Develop the code with scalability in mind, allowing for the addition of more sensors and features as needed.

Diagram



Screenshots

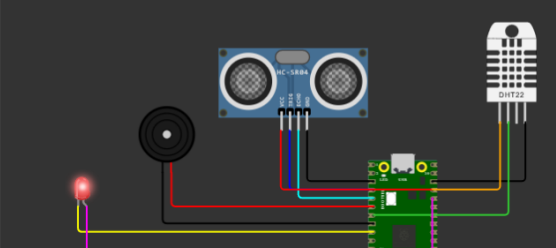
WOKWI

main.py diagram.json

```
1 import time
2 import machine
3 import dht
4
5 # Define GPIO pins
6 TRIG_PIN = machine.Pin(2, machine.Pin.OUT)
7 ECHO_PIN = machine.Pin(3, machine.Pin.IN)
8 BUZZER_PIN = machine.Pin(4, machine.Pin.OUT)
9 DHT_PIN = machine.Pin(5)
10 LED_PIN = machine.Pin(6, machine.Pin.OUT)
11
12 def distance_measurement():
13     # Trigger ultrasonic sensor
14     TRIG_PIN.on()
15     time.sleep_us(10)
16     TRIG_PIN.off()
17
18     # Wait for echo to be HIGH (start time)
19     while not ECHO_PIN.value():
20         pass
21     pulse_start = time.ticks_us()
22
23     # Wait for echo to be LOW (end time)
24     while ECHO_PIN.value():
25         pass
26     pulse_end = time.ticks_us()
27
28     # Calculate distance
29     pulse_duration = time.ticks_diff(pulse_end, pulse_start)
30     distance = pulse_duration / 58 # Speed of sound (343 m/s) divided by 2
31
```

Simulation

00:04.214 99%



Distance: 260.57 cm
Temperature: 24.00°C, Humidity: 40.00%
Status: No Flooding Detected
Distance: 260.64 cm
Temperature: 24.00°C, Humidity: 40.00%
Status: No Flooding Detected

WOKWI

main.py diagram.json

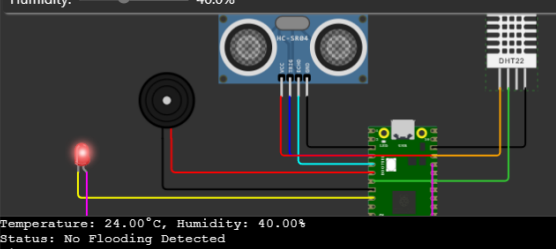
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Simulation

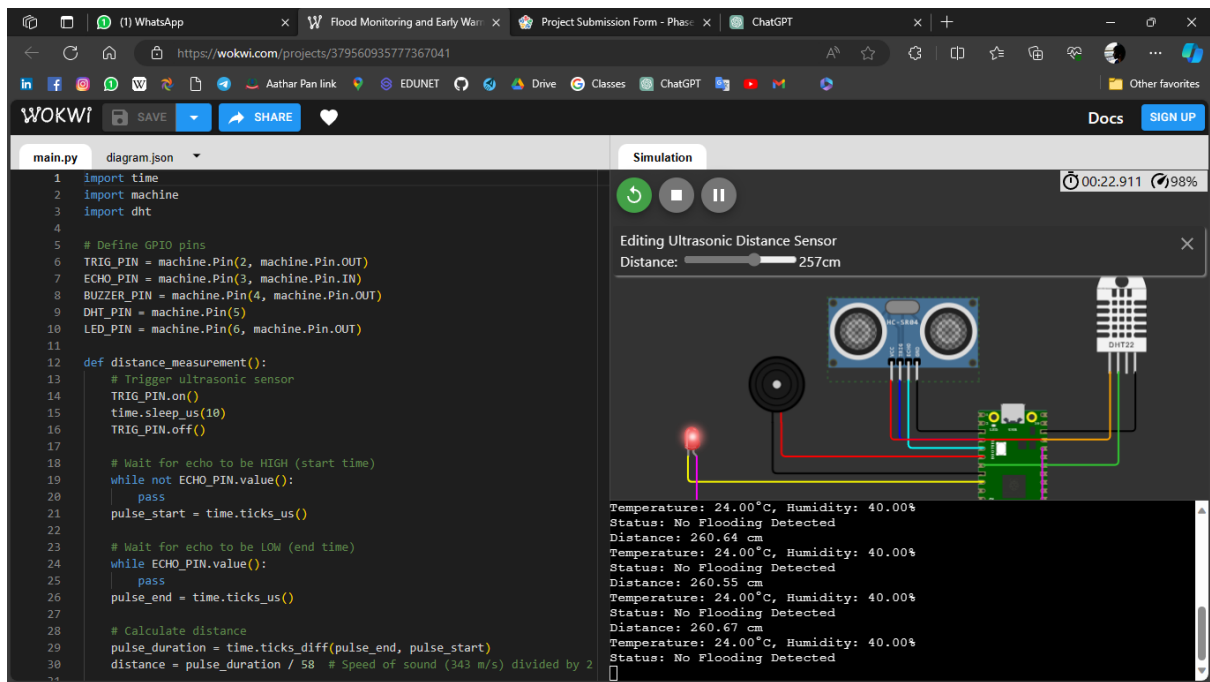
00:18.991 56%

Editing DHT22

Temperature: 24.0°C
Humidity: 40.0%



Temperature: 24.00°C, Humidity: 40.00%
Status: No Flooding Detected
Distance: 260.55 cm
Temperature: 24.00°C, Humidity: 40.00%
Status: No Flooding Detected
Distance: 260.64 cm
Temperature: 24.00°C, Humidity: 40.00%
Status: No Flooding Detected
Distance: 260.55 cm
Temperature: 24.00°C, Humidity: 40.00%
Status: No Flooding Detected



Code:

```
import time
```

```
import machine
```

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import dht
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```
# Define GPIO pins
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DHT_PIN = machine.Pin(5)
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```
def distance_measurement():
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```
    # Trigger ultrasonic sensor
```

```
    TRIG_PIN.on()
```

```
time.sleep_us(10)
```

```
TRIG_PIN.off()
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```
# Wait for echo to be HIGH (start time)
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while not ECHO_PIN.value():
```

```
    pass
```

```
pulse_start = time.ticks_us()
```

```
# Wait for echo to be LOW (end time)
```

```
while ECHO_PIN.value():
```

```
    pass
```

```
pulse_end = time.ticks_us()
```

```
# Calculate distance
```

```
pulse_duration = time.ticks_diff(pulse_end, pulse_start)
```

```
distance = pulse_duration / 58 # Speed of sound (343 m/s) divided by 2
```

```
return distance
```

```
def read_dht_sensor():
```

```
    d = dht.DHT22(DHT_PIN)
```

```
    d.measure()
```

```
    return d.temperature(), d.humidity()
```

```
buzz_start_time = None # To track when the buzzer started
```

```
while True:
```

```

dist = distance_measurement()
temp, humidity = read_dht_sensor()

# Check if the distance is less than a threshold (e.g., 50 cm)
if dist < 50:
    # Turn on the buzzer and LED
    BUZZER_PIN.on()
    LED_PIN.on()
    status = "Flooding Detected"
    buzz_start_time = time.ticks_ms()
    elif buzz_start_time is not None and time.ticks_diff(time.ticks_ms(),
buzz_start_time) >= 60000: # 1 minute
        # Turn off the buzzer and LED after 1 minute
        BUZZER_PIN.off()
        LED_PIN.off()
        status = "No Flooding Detected"
else:
    status = "No Flooding Detected"

print(f"Distance: {dist:.2f} cm")
print(f"Temperature: {temp:.2f}°C, Humidity: {humidity:.2f}%")
print("Status:", status)

time.sleep(2)

```