# Week 11 Lecture 1 NWEN 241 Systems Programming

Alvin C. Valera

alvin.valera@ecs.vuw.ac.nz

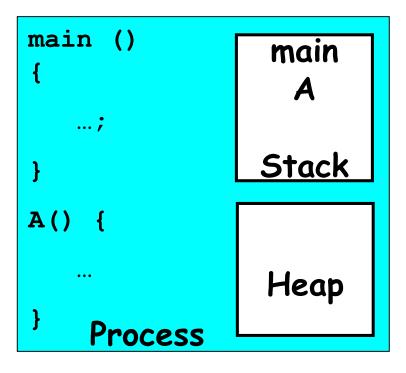
### Content

Process management in the operating system

• Interprocess communication

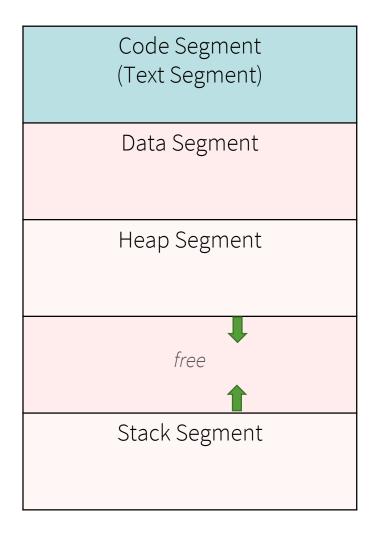
### Recap: Process vs program

```
main () {
    ...;
}
A() {
    ...
}
Program
```



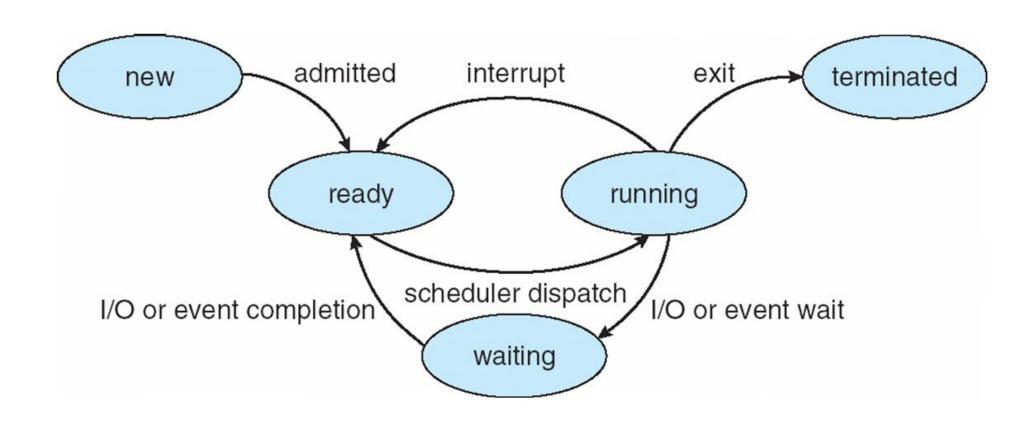
- Program is static, with the potential for execution
- Process is a program in execution and have a state
- One program can be executed several times and thus has several processes

### **Process in memory**



- Text / Code Segment
  - Contains program's machine code
- Data spread over:
  - Data Segment Fixed space for global variables and constants
  - Stack Segment For temporary data, e.g., local variables in a function; expands / shrinks as program runs
  - Heap Segment For dynamically allocated memory; expands / shrinks as program runs

### Recap: Process lifecycle

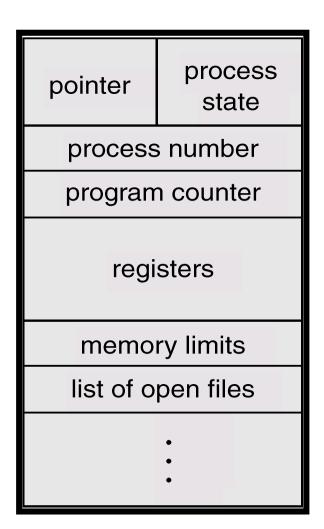


## Process lifecycle

- As a process executes, it changes state
  - new: The process is being created
  - running: Instructions are being executed
  - waiting: The process is waiting for some event to occur
  - ready: The process is waiting to be assigned to a processor
  - terminated: The process has finished execution

### Process control block

- Information associated with each process
  - Process state
  - Program counter
  - CPU registers
  - CPU scheduling information
  - Memory-management information
  - Accounting information
  - I/O status information
- A process is named using its process ID (PID) or process #
- Data is stored in a process control block (PCB)



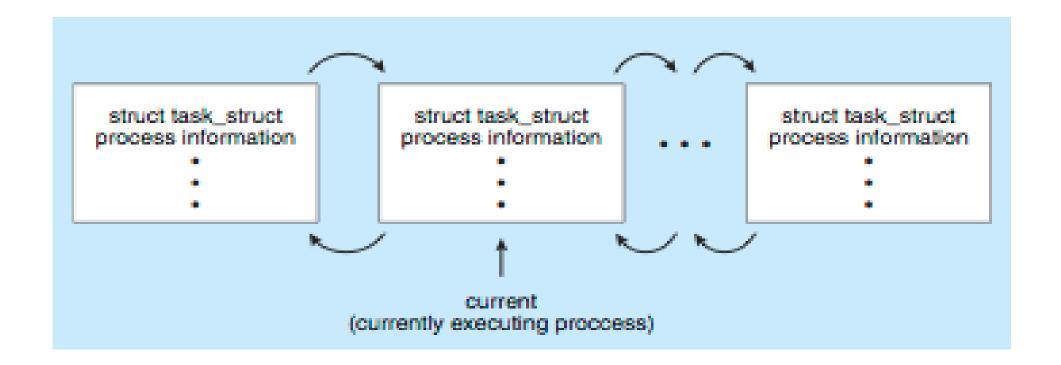
### **Process representation in Linux**

- Represented by structure task\_struct
  - See <a href="https://github.com/torvalds/linux/blob/master/include/linux/sched.h">https://github.com/torvalds/linux/blob/master/include/linux/sched.h</a>
    for more information
- Some of the structure members

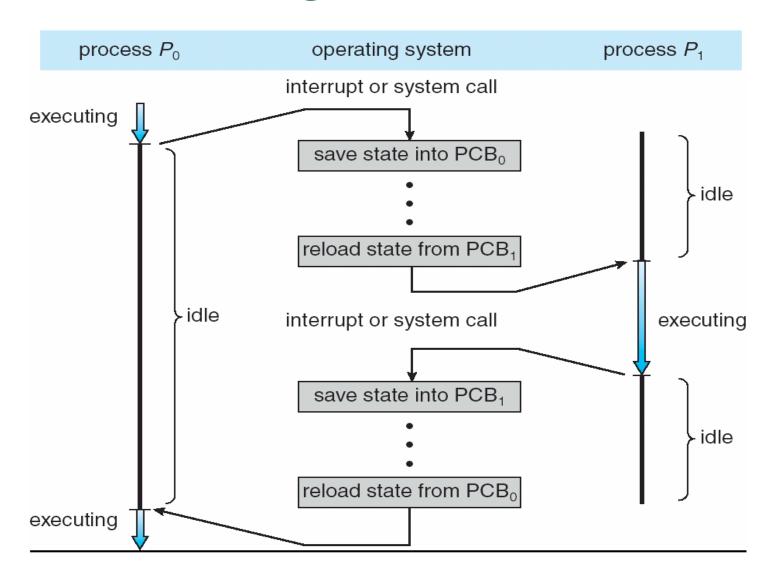
```
pid t_pid; /* process identifier */
long state; /* state of the process */
unsigned int time_slice /* scheduling information */
struct task_struct *parent; /* this process's parent */
struct list_head children; /* this process's children */
struct files_struct *files; /* list of open files */
struct mm_struct *mm; /* address space of this process */
```

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# **Process switching**



### **Context switch**

 When CPU switches to another process, the system must save the state of the old process and load the saved state for the new process via a context switch

- Context-switch time is overhead
  - System does no useful work while switching
  - The more complex the OS and the PCB -> longer the context switch
- Time dependent on hardware support
  - Some hardware provides multiple sets of registers per CPU -> multiple contexts loaded at once

# Why perform process switching?

 A running process may reach an instruction requiring user input

- While waiting for input, CPU is not doing anything
- To maximize CPU use, quickly switch ready processes onto CPU for time sharing



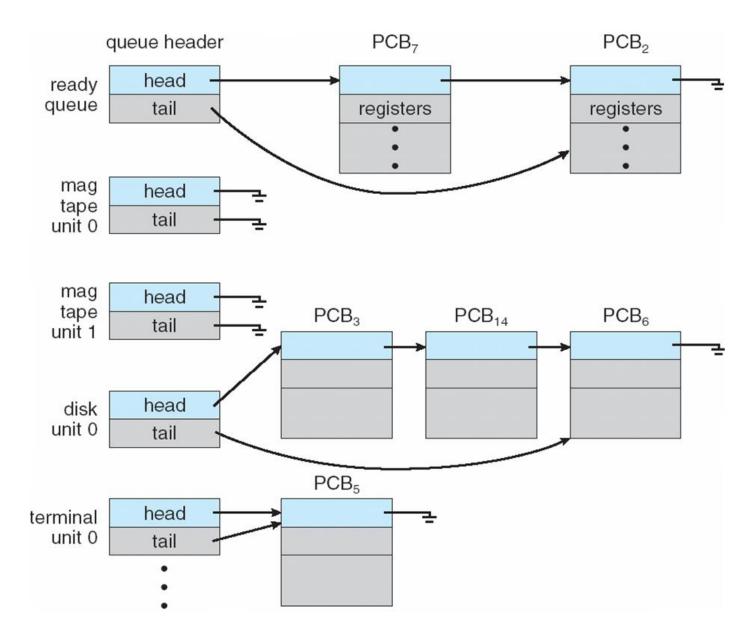
# Process scheduling

Process scheduler selects among ready processes for next execution on CPU

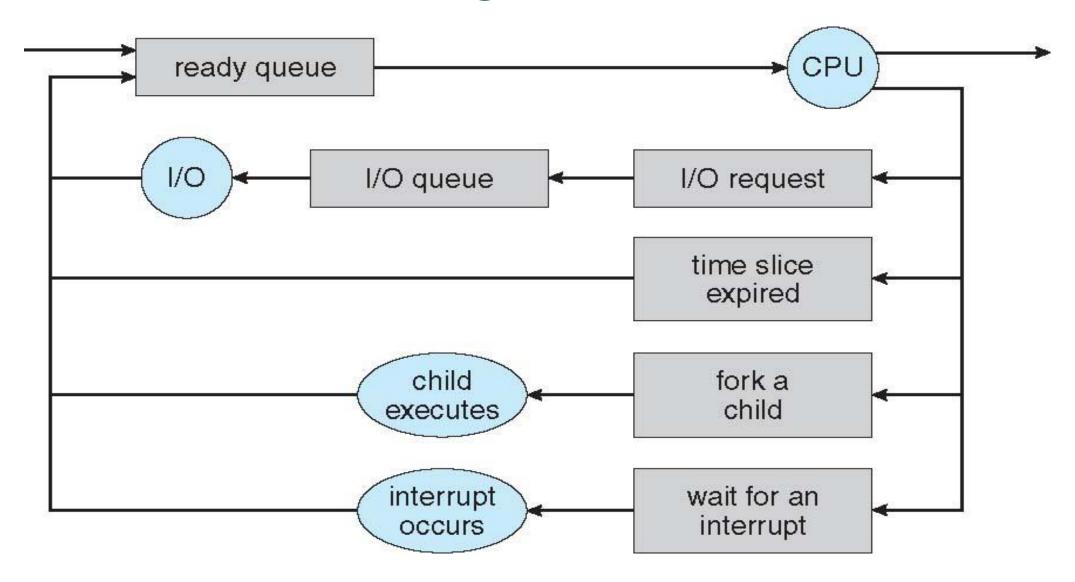
- Maintains scheduling queues of processes
  - Job queue set of all processes in the system
  - Ready queue set of all processes residing in main memory, ready and waiting to execute
  - **Device queues** set of processes waiting for an I/O device
  - Processes migrate among the various queues

Ready queue and various I/O device

queues



# Process scheduling flow



# Interprocess Communication

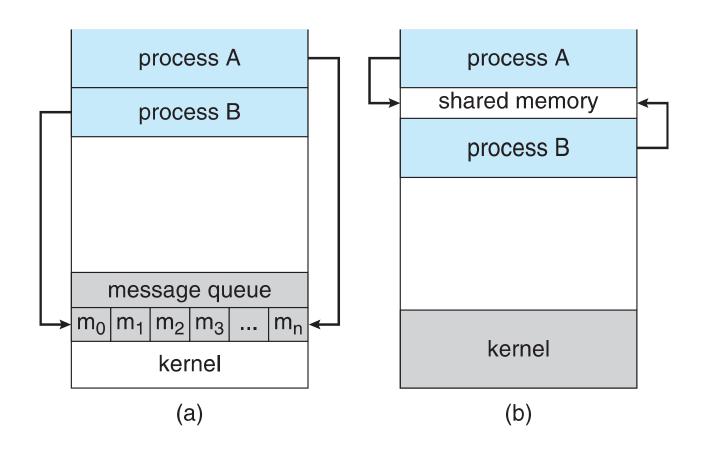
### Independent process

- So far, we have talked about **independent** processes: processes that don't interact with other processes
- Processes can be designed to cooperate process can affect or be affected by other processes, including sharing data
- Reasons for cooperating processes:
  - Information sharing
  - Computation speedup
  - Modularity
  - Convenience

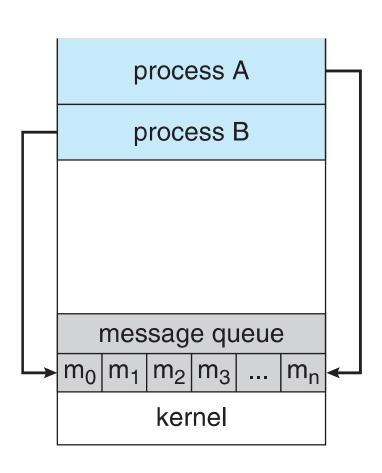
### Interprocess communication

 Cooperating processes need interprocess
 communication (IPC)

- Two models of IPC
  - Shared memory
  - Message passing



# Message passing



 Processes communicate with each other without resorting to shared variables

- IPC facility provides two primitive operations:
  - send(*message*)
  - receive(message)
- If *P* and *Q* wish to communicate, they need to:
  - establish a communication link between them
  - exchange messages via send/receive

### **Synchronization**

Message passing may be either blocking or non-blocking

#### Blocking / synchronous

- Blocking send has the sender block until the message is received
- Blocking receive has the receiver block until a message is available

### Non-blocking / asynchronous

- Non-blocking send has the sender send the message and continue
- Non-blocking receive has the receiver receive a valid message or null

### **Synchronization**

- Different combinations possible
  - If both send and receive are blocking, we have a rendezvous
  - Producer-consumer interaction becomes trivial

• Producer-consumer paradigm: a cooperation paradigm in IPC

# Buffering

Queue of messages attached to the link

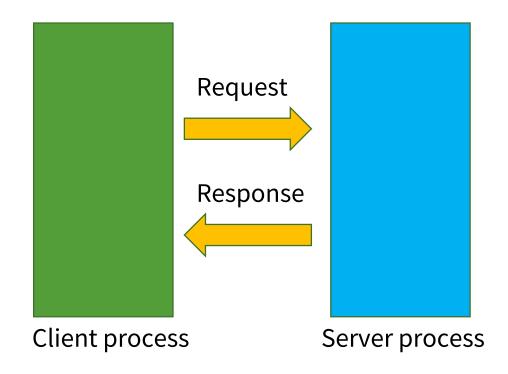
- Implemented in one of three ways:
  - Zero capacity 0 messages
     Sender must wait for receiver (rendezvous)
  - Bounded capacity finite length of n messages
     Sender must wait if link full
  - Unbounded capacity infinite length Sender never waits

### Client-server model

 Based on the producer-consumer model of process cooperation

 Client makes the request for some resource or service to the server process

 Server process handles the request and sends the response (result) back to the client



### Client-server model

 Client process needs to know the existence and the address of the server

 However, the server does not need to know the existence or address of the client prior to the connection

 Once a connection is established, both sides can send and receive information

### Client-server communication

Remote Procedure Calls

Pipes

Remote Method Invocation (Java)

Sockets

### **Next lecture**

Socket programming