

COMP261 Lecture 22

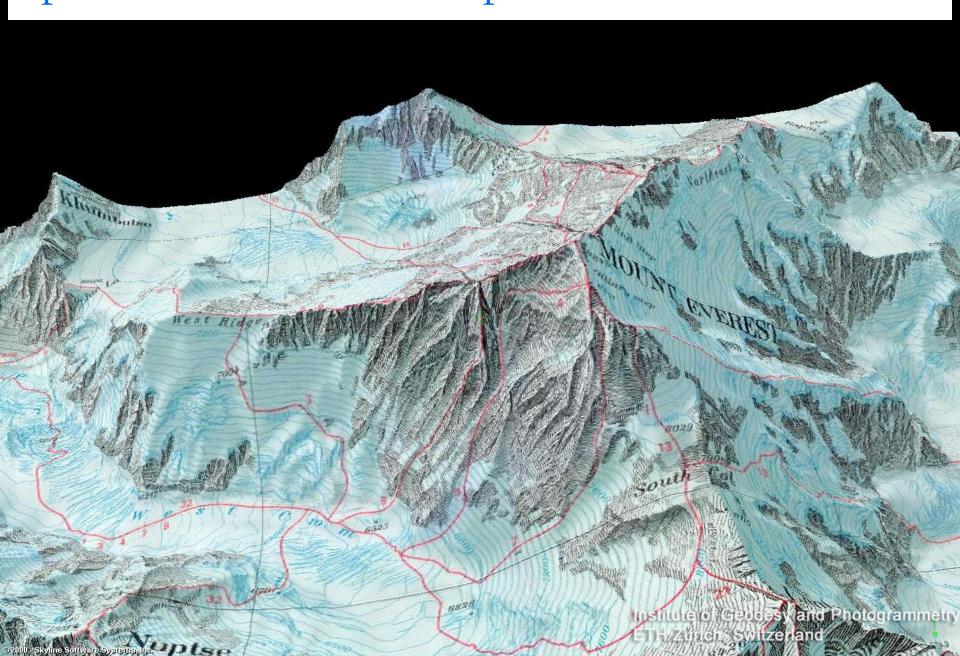
Marcus Frean

(Using Predictions 2)

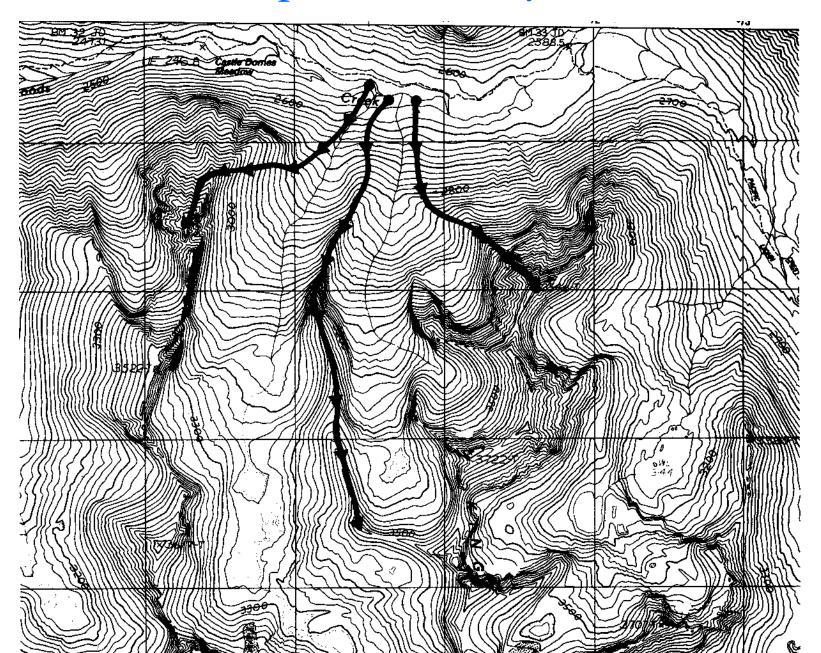
Optimization of an expensive function



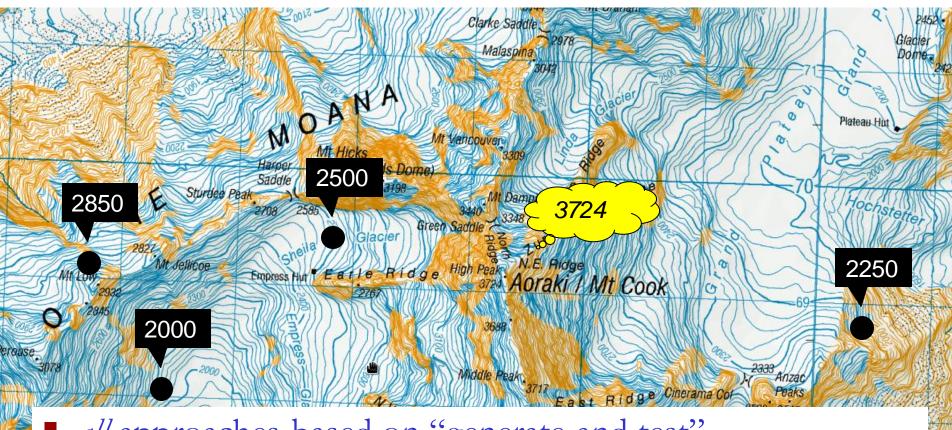
optimization: find the top of the hill



optimization: depends where you start



suppose all you get is elevation, at specific points



- all approaches based on "generate and test"
- so: how to wisely generate the next sample point to test?
- all methods that blindly try lots samples are wasteful

eg: optimizations that are "sample expensive"

application	search space	per-sample expense
new hull for boat, wing for plane	shape parameters (e.g. 18 for hull)	build & test it?fancy simulation?
design a new robot	joint lengths, torque ratios, weight spread	just build & see?build simulation, and test in that?
tuning any complex "engine" (eg. any AI)	various parameters	Testing takes time / money / effort.

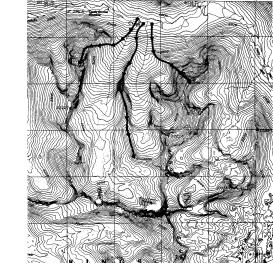
- all approaches based on "generate and test"
- so: how to wisely generate the next sample point to test?
- all methods that blindly try lots samples are wasteful

Some heuristic optimization ideas

- Try to go up (or down) hills...
- Don't revisit previous points...?
- Explore around the best point so far...?
- Sometimes, try something *completely* new...(when?)
- Balance exploitation versus exploration (somehow?)...
- → hill-climbing, evolutionary algorithms, etc.....these seem sensible, yet... *ad hoc*.

ideally:

- those behaviours should be emergent, not "wired in" by us
- algorithm should learn surface properties as it goes



Optimizing an unknown function ("surface")

- find the x that maximizes y(x), just by measuring y at some test points x.
- assume as little as possible about the surface *a priori*.

- get there as quickly as possible, e.g.
 - min computation
 - min # samples

- min computation case is easy: take *lots* of samples
 - fine if data is "free"
 - what if it's not?

- min # samples:
 - make the most of every piece of information about the surface

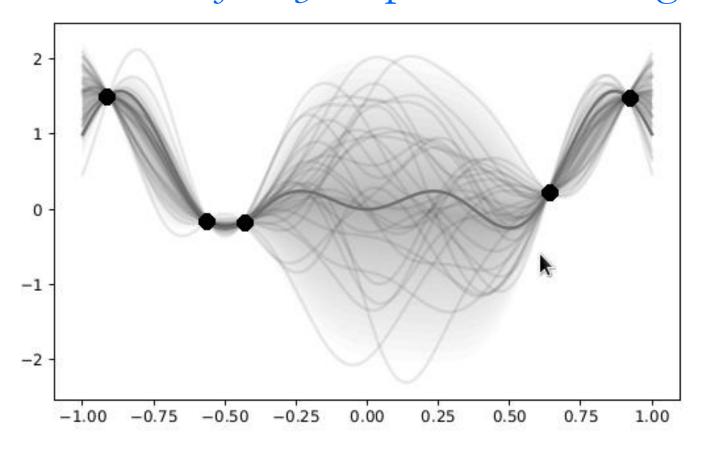
Note: it doesn't matter where the <u>latest</u> point was

idea: fit existing data with a plausible "surrogate"

take next sample here?

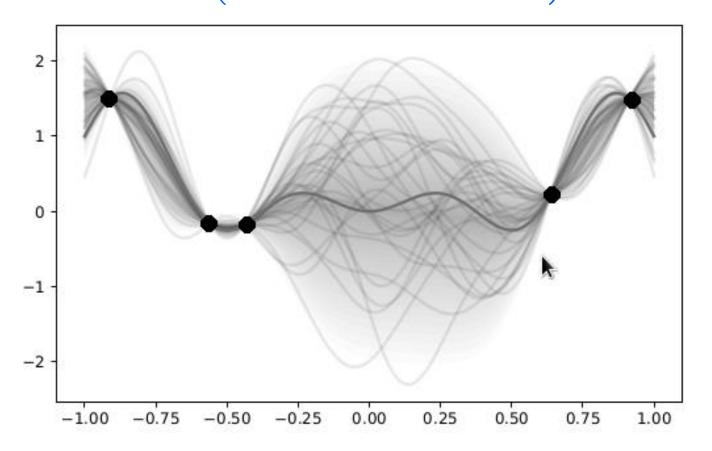
- there's a whole family of functions that could go through some data
- we could pick the "best" one, and try at its peak...
- bad idea

better idea: fit a family of plausible surrogates



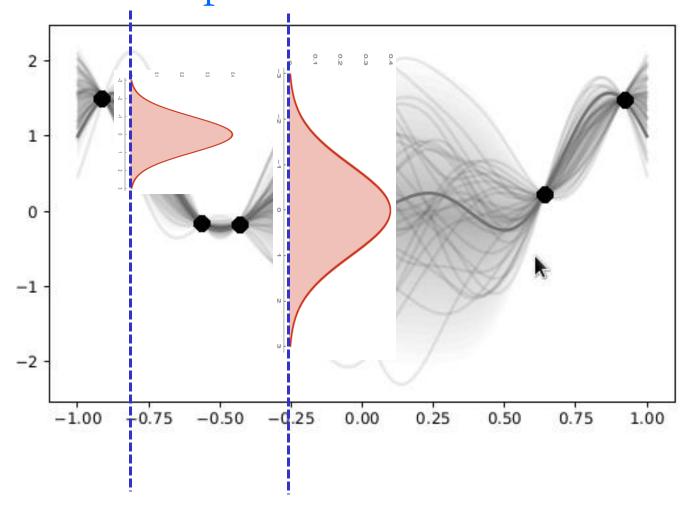
- there's a whole family of functions that could go through some data....
- new data points constrain the family more and more
- "error bars" rise as you move away from test points

how to do that (*not examinable*)

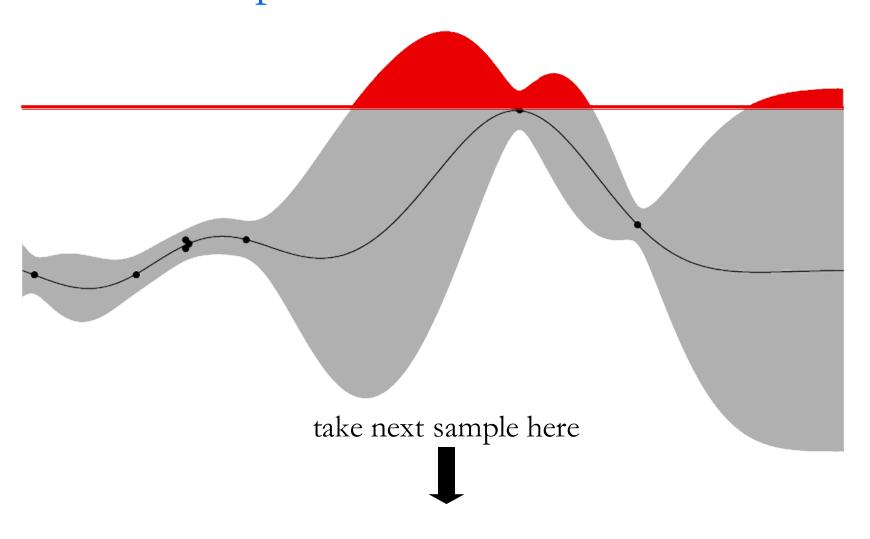


- there are several possibilities
- details are beyond us here, but for example we could:
 - ✓ e.g. apply a machine learning algorithm + randomness
 - ✓ e.g. apply "Bayesian" statistical methods instead

how to use the predicted distribution of values?

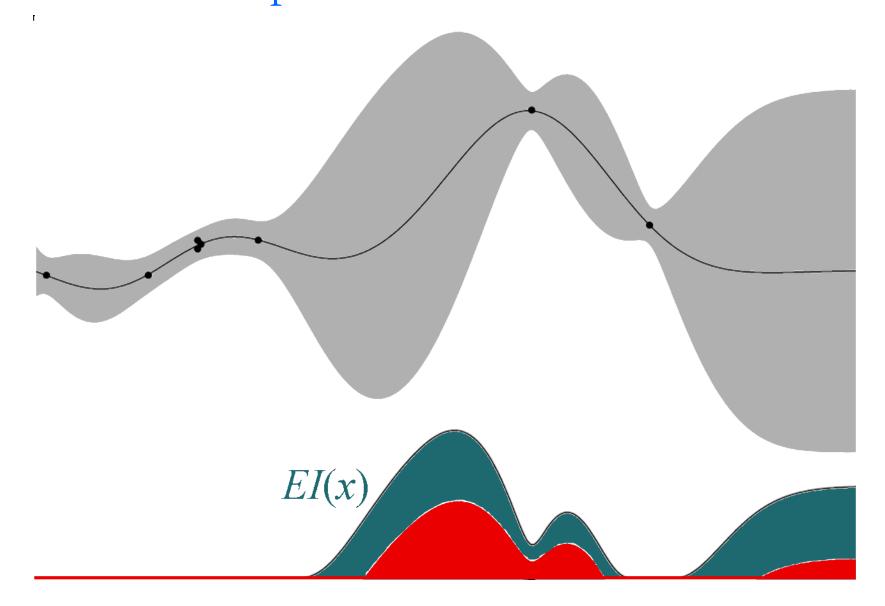


how to use the predicted distribution of values?

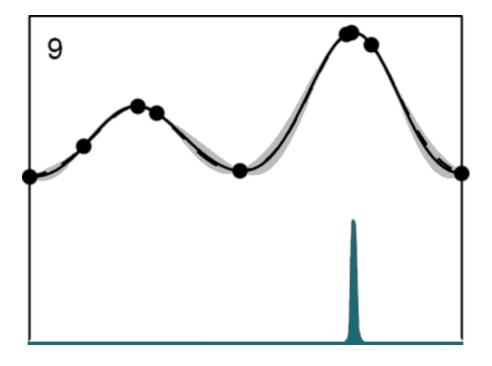


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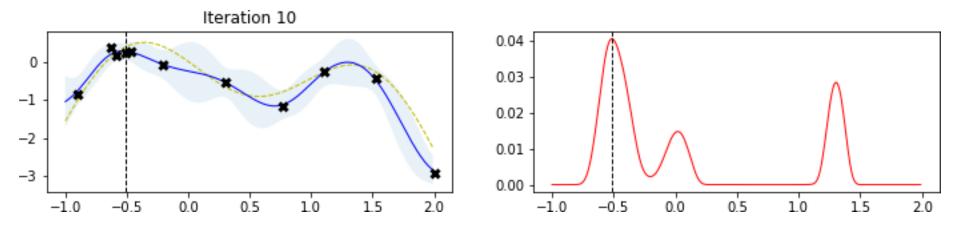
how to use the predicted distribution of values?



example in 1 dimension



another example in 1 dimension



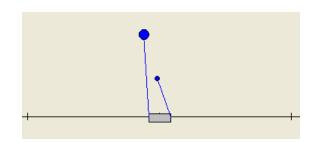
(made by running this python notebook)

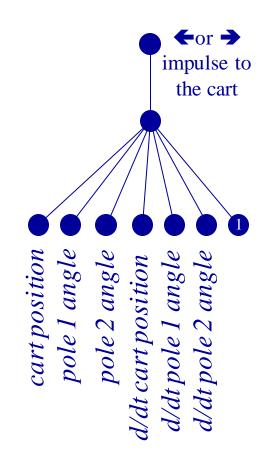
the "acquisition function" (eg. probability of improvement)

example in 8d: learning to balance 2 poles (at once)

- two poles on one cart
- cart has to stay "in bounds"
- learner knows the cart position, the pole angles, and their rates of change
- evaluation: average time spent near-vertical, from a near-vertical start
- measuring "performance" of a robot is really expensive

- controller is to be a neural network
- \rightarrow a search problem in 8 dimensions
- the competition takes ~3500 samples to find a decent controller

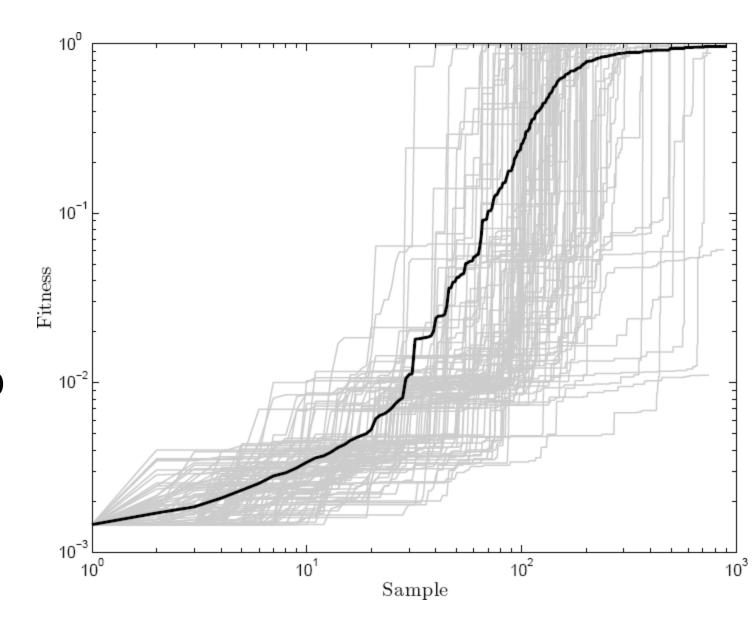




example: learning to balance 2 poles at once



cf. bestoppositiontakes ~3500samples



name of this algorithm: Bayesian Optimization

(the "Bayesian" refers to Bayes theorem, which is usually the basis for generating a *family* of surfaces, as needed)

Advantages:

o fewest samples to get to a good solution!

Drawbacks?

- o need to make that family, somehow
- o need to optimize over the Prob-of-improvement surface, which could itself be a tough problem (although cheaper...)
- o both the above get harder in high dimensions ©
- see also: if you like python notebooks, I highly recommend trying this one (from a blog by Martin Krasser). There's also this.