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## Cloud Segmenter

The parameter on the number of points were varied. But the best plane fits were observed when "a" and "b" of the function generating plane were exchanged.

Two of the best outputs that were observed are saved as a .png file in "Output" directory in the Package.

## RRT Planner

For the RRT planner, the parameters psi and delta_step were varied. A few good results that were observed are saved as a .png file in "Output" directory in the Package, according to different step sizes.