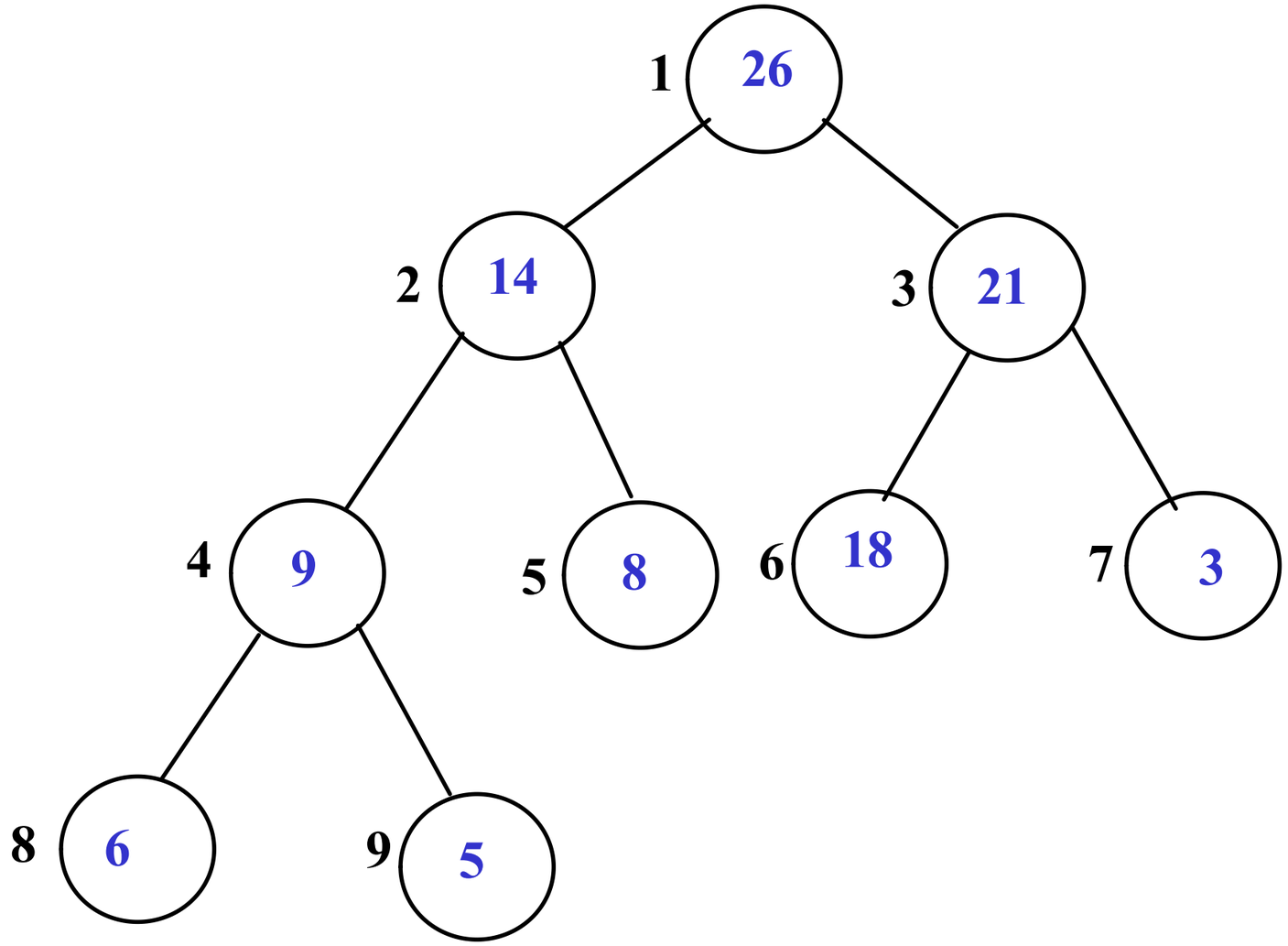
Size=9

9/2=4

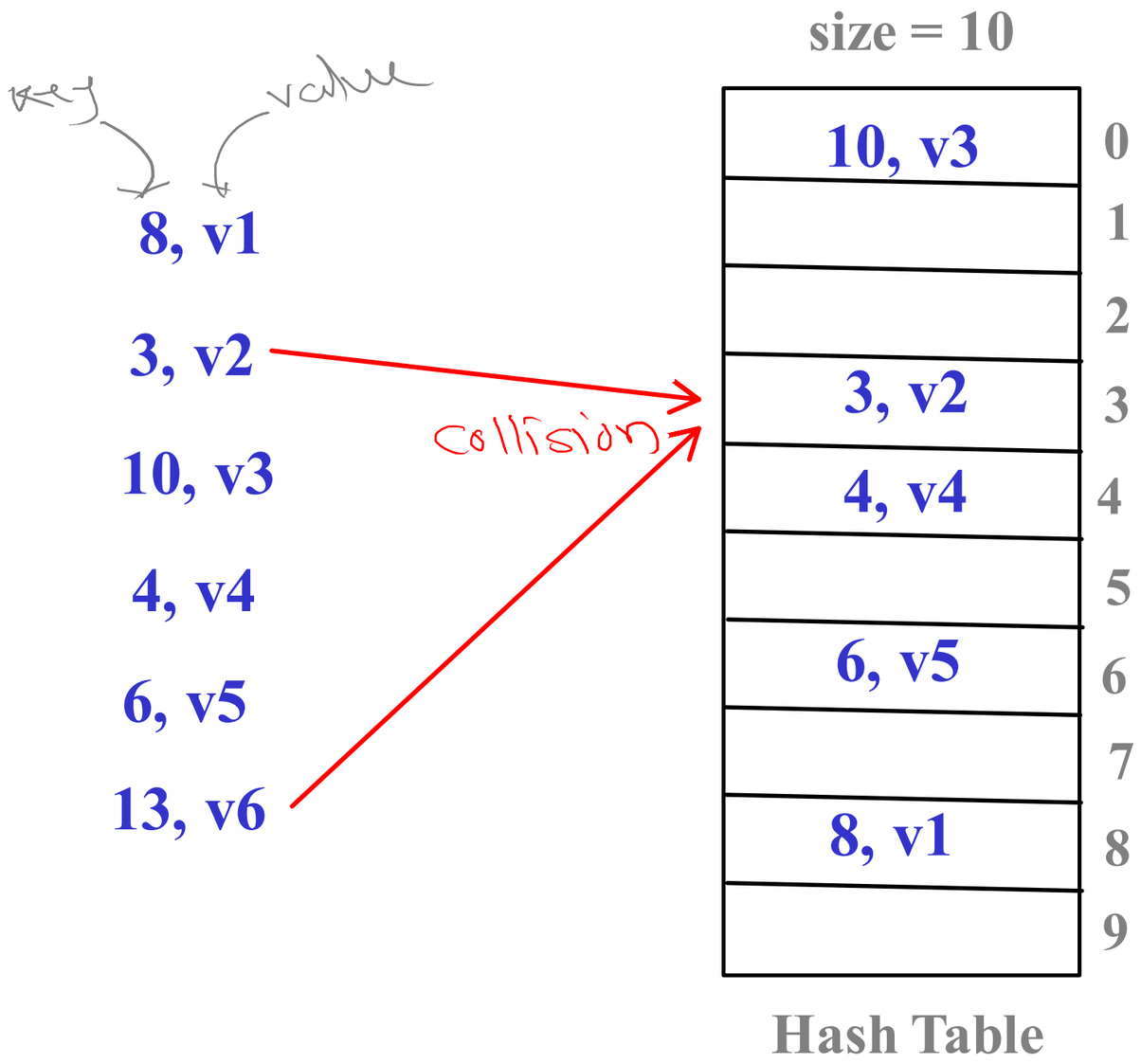


Heapify

Time : O(n)

6	26	21	14	8	18	3	9	5
1	2	3	4	5	6	7	8	9

Hashing



h(k) = k % size

h(8) = 8 % 10 = 8

h(3) = 3 % 10 = 3

h(10) = 10 % 10 = 0

h(4) = 4 % 10 = 4

h(6) = 6 % 10 = 6

h(13) = 13 % 10 = 3

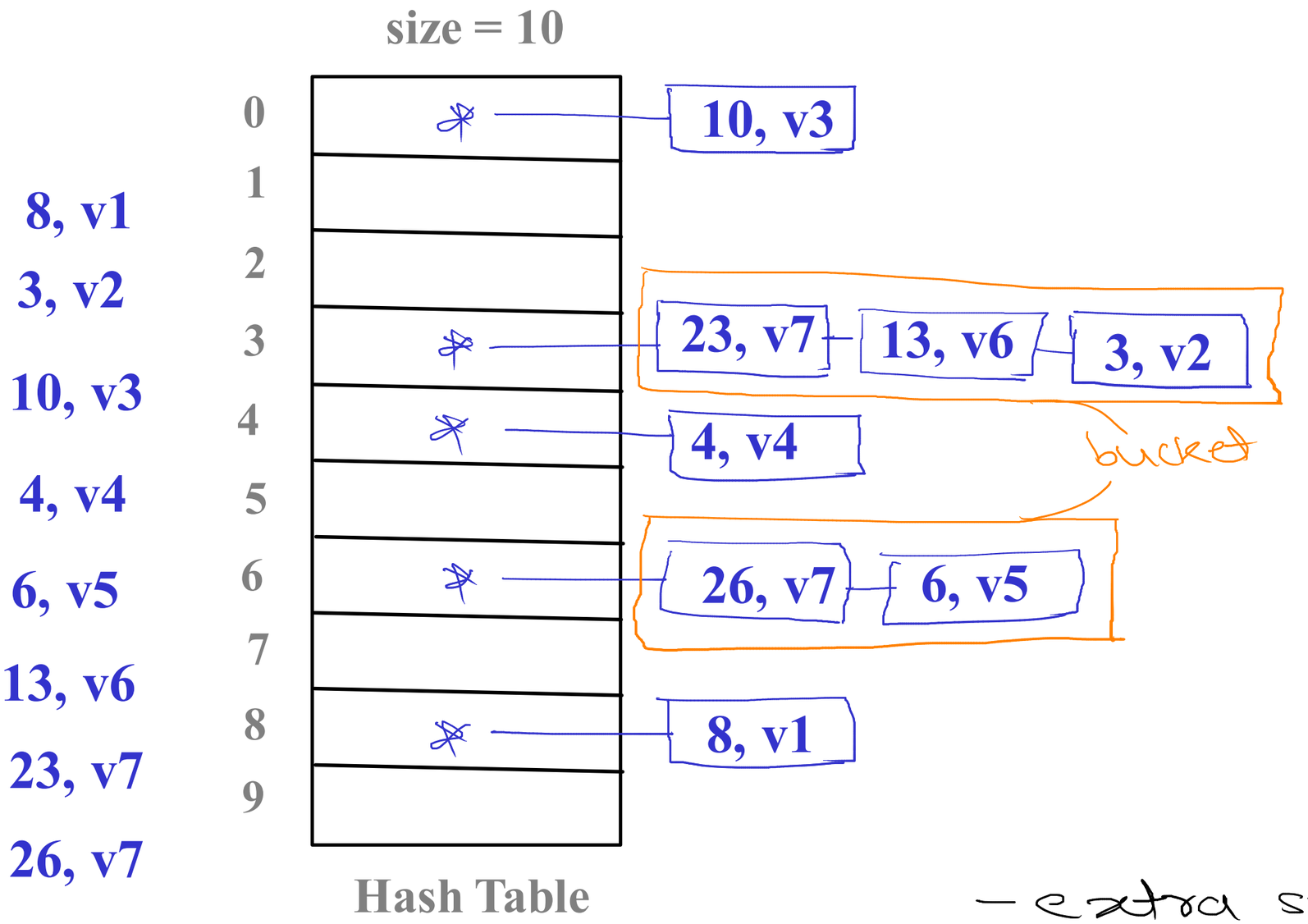
insert/add: — O(1)

```
slot = k % size;
arr[slot] = entry;
```

search: — O(1)

```
slot = k % size
return arr[slot].vale
```

Closed Addressing/ Seperate Chaining / Chaining



Hash Table

h(k) = k % size

h(8) = 8 % 10 = 8

h(3) = 3 % 10 = 3

h(10) = 10 % 10 = 0

h(4) = 4 % 10 = 4

h(6) = 6 % 10 = 6

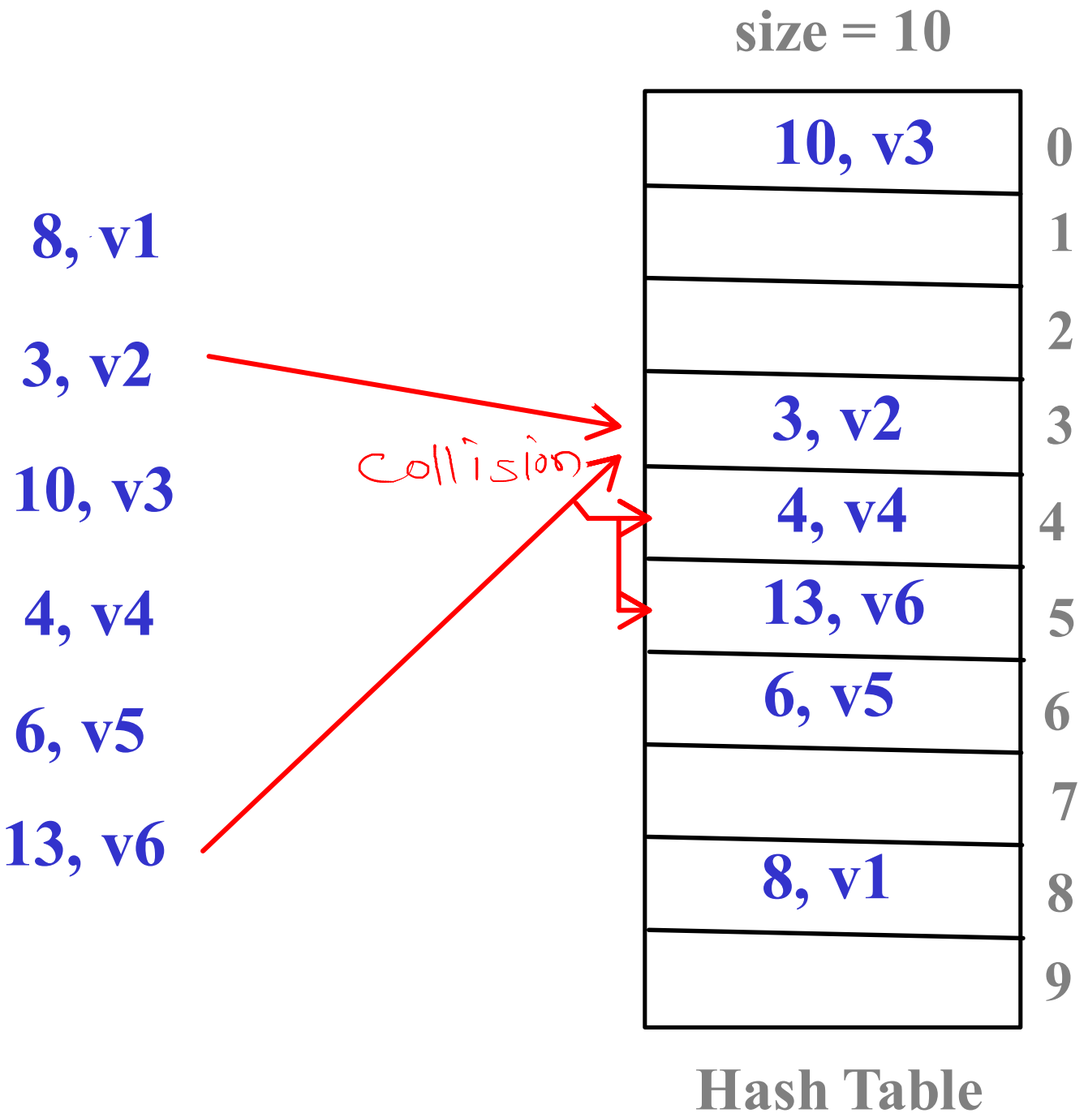
h(13) = 13 % 10 = 3 (c)

h(23) = 23 % 10 = 3 (c)

h(26) = 26 % 10 = 6 (c)

- extra space is needed
- data(key-value) is kept outside the table
- Worst case : O(n)
  - if all keys yield same slot

Open Addressing - Linear Probing



Hash Table

Probing — find new slot for key when collision is occured

Primary clustering — take long runs of filled slots "near" key position

h(k) = key % size

h(k, i) = [h(k) + f(i)] % size

f(i) = i

where i = 1, 2, 3, ...

↳ probe number

h(8) = 8 % 10 = 8

h(3) = 3 % 10 = 3

h(10) = 10 % 10 = 0

h(4) = 4 % 10 = 4

h(6) = 6 % 10 = 6

h(13) = 13 % 10 = 3 (collision)

h(13,1) = [3 + 1] % 10
= 4 (1st probe) (collision)

h(13,2) = [3 + 2] % 10
= 5 (2nd probe)

Open Addressing - Quadratic Probing

8, v1

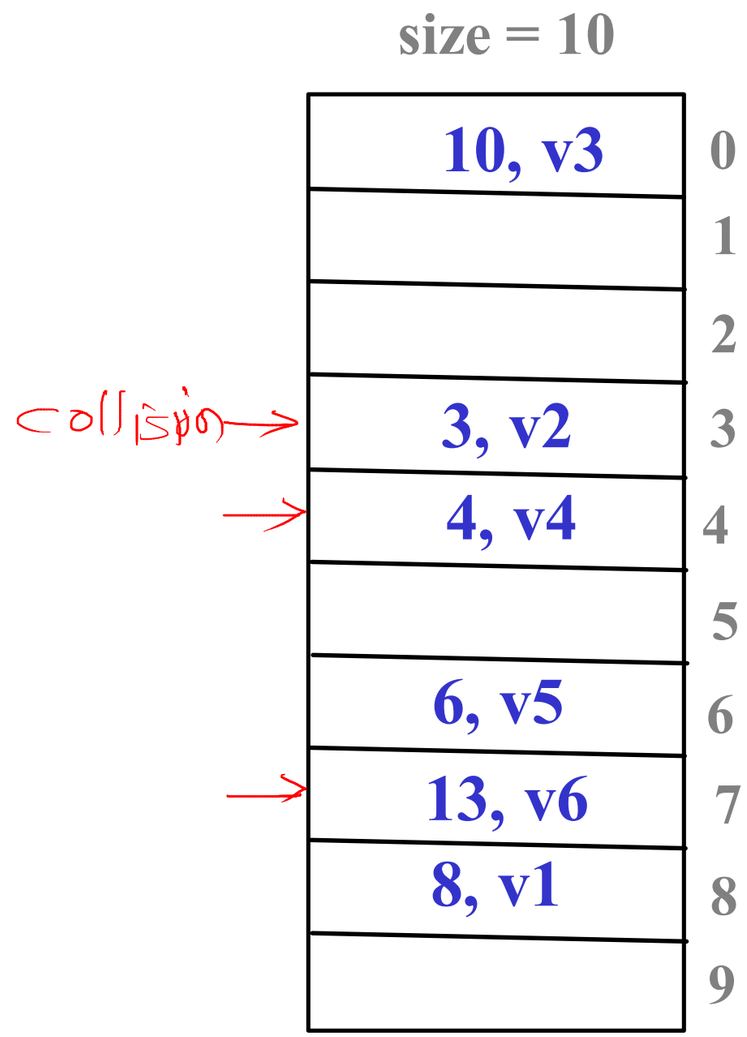
3, v2

10, v3

4, v4

6, v5

13, v6



Hash Table

h(k) = key % size

h(k, i) = [h(k) + f(i)] % size

f(i) = i^2

where i = 1, 2, 3, ...

i probe number

h(8) = 8 % 10 = 8

h(3) = 3 % 10 = 3

h(10) = 10 % 10 = 0

h(4) = 4 % 10 = 4

h(6) = 6 % 10 = 6

h(13) = 13 % 10 = 3

h(13,1) = [3+1] % 10
= 4 (1st probe) (collision)

h(13,2) = [3+4] % 10
= 7 (2nd probe)

Secondary clustering — take long runs of filled slots "away" key position

Open Addressing - Quadratic Probing

23, v7

33, v8

size = 10

10, v3	0
	1
23, v7	2
3, v2	3
4, v4	4
	5
6, v5	6
13, v6	7
8, v1	8
33, v8	9

Hash Table

h(k) = key % size

h(k, i) = [h(k) + f(i)] % size

f(i) = i^2

where i = 1, 2, 3, ...

h(23) = 23 % 10 = 3 (c)

h(23, 1) = [3 + 1] % 10 = 4 (c) (1st)

h(23, 2) = [3 + 4] % 10 = 7 (c) (2nd)

h(23, 3) = [3 + 9] % 10 = 2 (5rd)

h(33) = 33 % 10 = 3

h(33, 1) = [3 + 1] % 10 = 4

h(33, 2) = [3 + 4] % 10 = 7

h(33, 3) = [3 + 9] % 10 = 2

h(33, 4) = [3 + 16] % 10 = 9

Hashing - Double Hashing

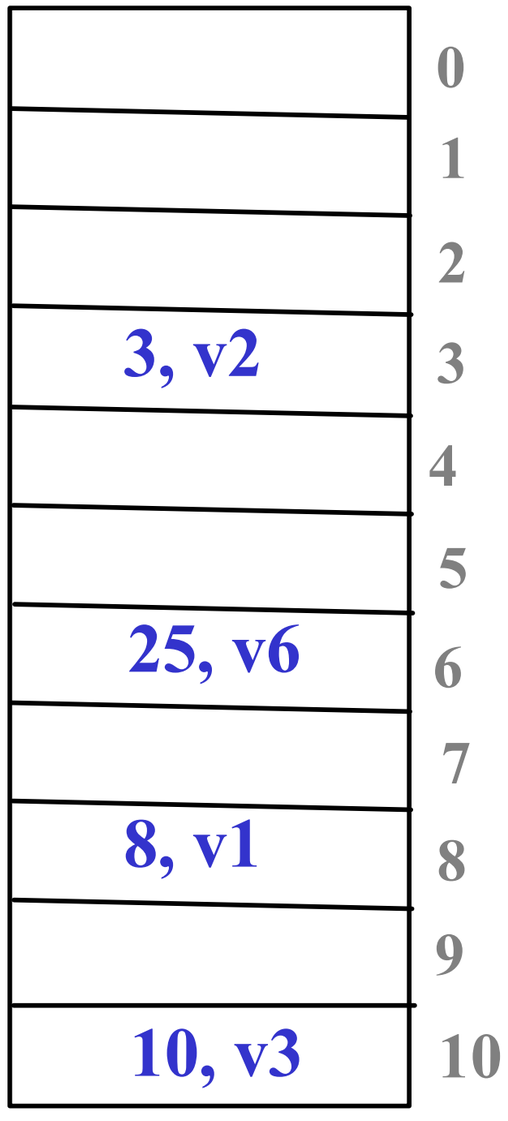
8, v1

3, v2

10, v3

25, v6

size = 11



Hash Table

h1(k) = key % size

h2(k) = 7 - (key % 7)

h(k, i) = [h1(k) + i * h2(k)] % size

h1(8) = 8 % 11 = 8

h1(3) = 3 % 11 = 3

h1(10) = 10 % 11 = 10

h1(25) = 25 % 11 = 3 ©

h2(25) = 7 - 4 = 3

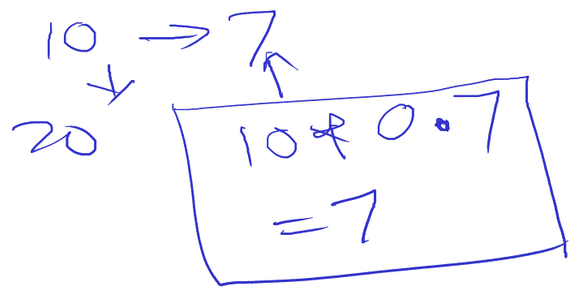
h(25,1) = [3 + 1*3] % 11

= 6 (1st probe)

Rehashing

$$\text{Load Factor } (\lambda) = \frac{n}{N}$$

(0 to 1)



n - Number of elements (key value pairs) in hash table
N - Number of slots in hash table

if n < N	**Load factor < 1**	**- free slots are available**
if n = N	**Load factor = 1**	**- no free slots**
if n > N	**Load factor > 1**	**- can not insert at all**

- Rehashing is make the hash table size twice of existing size if hash table is 70 or 75 % full

- In rehashing existing key value pairs are again mapped according to new hash table size