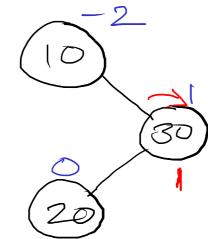
RR Imbalance

Keys: 10, 20, 30 -tout

bf < 1 fb value > trav. right data

RL Imbalance

Keys: 10, 30, 20

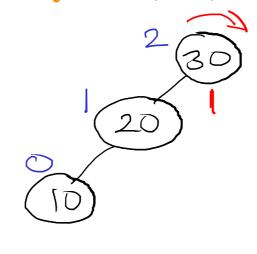


bf<-1 8-8

value < trav. right. data

LL Imbalance

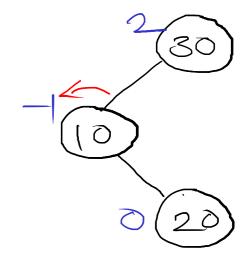
Keys: 30, 20, 10

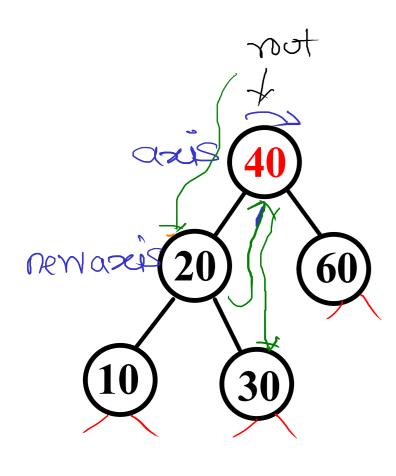


bf>1 ff value < trav-left.data

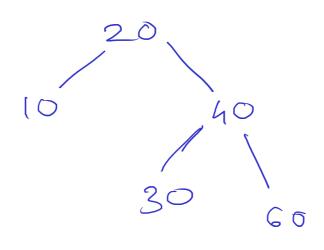
LR Imbalance

Keys: 30, 10, 20





Right Rotation



right rotation (anis, perrent);

new anis = anis. left

anis. left = newanis. right

newaris. right = anis

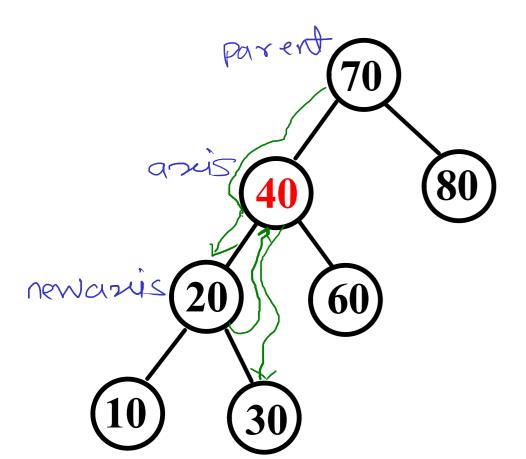
if (anis == not)

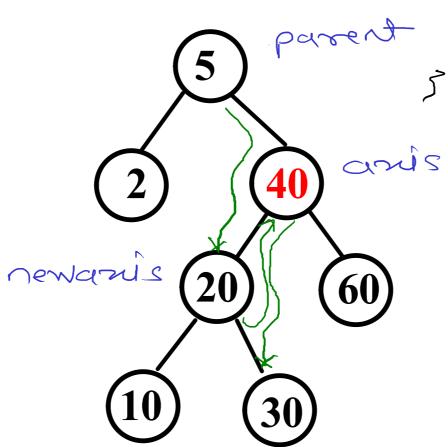
not = newaris;

else if (anis == parent. left)

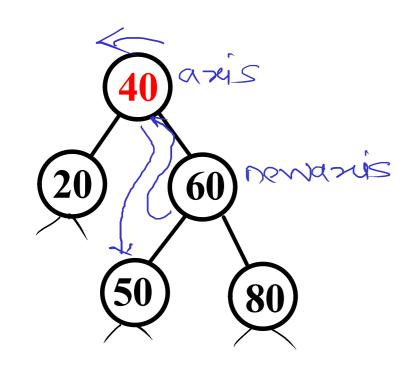
parent. left = newaris;

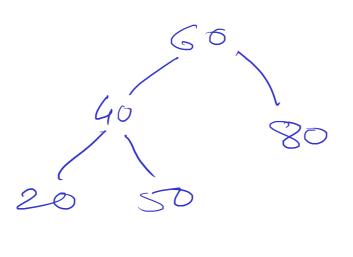
else parent. right = newaris;

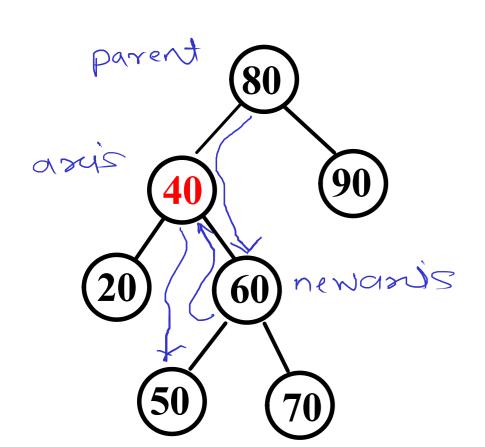


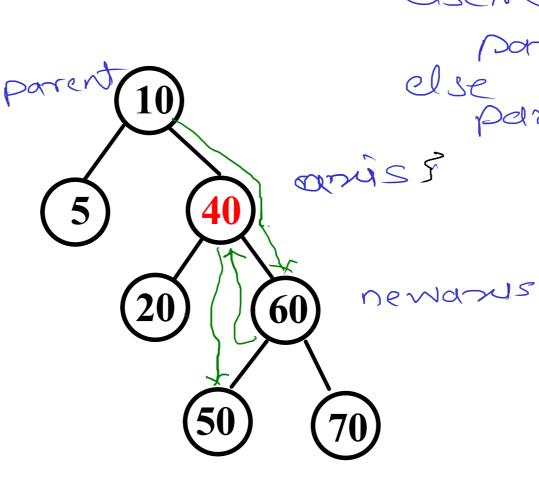


Left Rotation









left_notation (axis, parent) {
newanis = axis.right
anis.right = newaxis.left;
newaxis.left=axis;
if (axis = = root)
root = newaxis;

elseif (axis = = parent. left)

parent. left = newaxis;
else
parent. right = newaxis;

AVL Tree

- Self balancing binary Search Tree
- on every insertion and deletion of node, tree is balanced
- All operation on AVL tree are perfromed in O(log n) time
- Balance factor of all nodes is either -1, 0 or +1

Keys: 40, 20, 10, 25, 30, 22, 50

