Problem 1. Choose the top leader by running a random walk on the graph with teleportation.

Solution.

1 Introduction

PageRank is an algorithm used to measure the importance of nodes in a network, particularly in the context of web pages on the internet. Originally developed by Larry Page and Sergey Brin at Google, PageRank assigns a numerical weight to each node in a network based on the structure of links between them. The fundamental idea behind PageRank is that important nodes are likely to be linked to by other important nodes.

In this report, I have discussed how PageRank is calculated, and the Top Leader is found using a random walk with teleportation approach, implemented in Python using the NetworkX library.

2 Random Walk with Teleportation

Random walk with teleportation is a method to simulate the movement of a particle through a network, where at each step, the particle either moves to a neighbouring node or teleports to a random node with a certain probability. This approach is used in PageRank to model the behavior of a user navigating through web pages, where they may follow links or randomly jump to a different page.

3 Implementation

The provided Python code implements the random walk with teleportation algorithm to calculate PageRank for nodes in a given directed graph and then provide the Leader. Let's break down the implementation:

```
import pandas as pd
import networkx as nx
import random
import numpy as np

#Reading the csv file
data = pd.read_csv('modified_impression_network.csv')

#Creating directed graph from the csv file data
G = nx.DiGraph()
for index, row in data.iterrows():
```

```
node = row.iloc[0]
                          # Assuming the first column contains the
12
         node
      neighbors = row.iloc[1:].dropna().tolist() # Assuming the rest
13
          columns are neighbors
      G.add_node(node) # Adding nodes to the graph
14
      for neighbor in neighbors: # Adding neighbors to the graph
           G.add_edge(node, neighbor)
  0.00
      Performing a random walk with teleportation on the given graph.
19
      Parameters used:
           G (networkx.DiGraph): Directed graph to perform random walk
           teleport_prob : Probability of teleportation (default is
              0.15).
           num_steps : Number of steps in the random walk (default is
              1000000).
      Returns:
26
           tuple: A tuple containing two lists - nodes and their random
               walk points.
  def random_walk_with_teleportation(G, teleport_prob=0.15, num_steps
     =1000000):
      nodes = list(G.nodes())# Extracting all nodes from the graph
30
      rw_points = {node: 0 for node in nodes}# Initializing random
31
          walk points for each node
      current_node = random.choice(nodes)# Choosing a random starting
32
         node
      for _ in range(num_steps):
34
           # Perform teleportation with a certain probability
35
           if random.random() <= teleport_prob:</pre>
36
               current_node = random.choice(nodes)# Teleporting to a
                  random node
           else:
               neighbors = list(G.neighbors(current_node))# Getting
                  neighbors of the current node
               if neighbors: # If neighbors exist
40
                   current_node = random.choice(neighbors)# Moving to a
41
                       random neighbor
               else:
42
                   current_node = random.choice(nodes)# Teleporting if
43
                      no neighbors exist
           rw_points[current_node] += 1# Incrementing random walk
              points for the current node
```

```
return nodes, rw_points
46
47
  #Sorting nodes based on their random walk points in descending order
48
  def nodes_sorting(nodes, points):
49
       points_array = np.array(list(points.values())) # Extract values
           from the dictionary
       sorted_indices = np.argsort(-points_array)# Sorting indices in
          descending order of points
       sorted_nodes = [nodes[i] for i in sorted_indices] # Sorting
          nodes based on sorted indices
       return sorted_nodes
53
  #Performing the functions defined above
  nodes, rw_points = random_walk_with_teleportation(G, teleport_prob
     =0.15, num_steps=1000000)
  sorted_nodes = nodes_sorting(nodes, rw_points)
57
58
  # Printing the top 10 nodes with their random walk points
59
  print("Node_\t\t_Random_Walk_Points")
60
  for node in sorted_nodes[:10]:
61
       print(f"{node}_\\t_\{rw_points[node]}")
62
  #Printing the leader with max random walk points
64
  leader=sorted_nodes[0]
65
  print ("The Top Leader=", leader)
```

- 1. **Reading Data**: The code reads data from a CSV file containing information about nodes and their neighbours.
- 2. Creating the Directed Graph: Using NetworkX, a directed graph is constructed from the data where each node represents a student, and edges represent links between students.
- 3. Random Walk with Teleportation Function: The random_walk_with_teleportation function performs the random walk simulation on the graph. At each step, the algorithm either moves to a neighbouring node or teleports to a random node with a specified teleportation probability.
- 4. Sorting Nodes by Random Walk Points: After simulating the random walk, nodes are sorted based on their accumulated random walk points in descending order. This sorting identifies the nodes with higher random walk points.
- 5. **Printing Results**: The code prints the top 10 nodes along with their random walk points, providing insights into the most important nodes in the network, it identifies the node with the highest PageRank (random walk points) score as the top leader.

4 Conclusion

The provided code demonstrates how PageRank can be calculated using the random walk with teleportation algorithm. By simulating the movement of a particle through the network, the algorithm assigns importance scores to each node, helping to identify the most influential nodes in the graph. This approach is fundamental to various applications such as web search, recommendation systems, and network analysis.

Problem 2. Recommend missing links using the matrix method explained in the class.

Solution.

Introduction

Social network analysis is a critical tool in understanding relationships and interactions within a network. One common task in social network analysis is to predict missing links between nodes, which can provide insights into potential connections that have not yet been established. In this report, I present a method for predicting missing links in a social network graph using linear algebra techniques (Matrix method) and least squares regression.

Method

The method used in this report involves the following steps:

- 1. **Data Preparation**: The input data is assumed to be in the form of a CSV file containing information about the network, with each row representing a node and its associated neighbors.
- 2. **Graph Construction**: A directed graph (DiGraph) is created using the NetworkX library in Python. Nodes represent individuals, and edges represent relationships between them. The graph is constructed based on the information provided in the CSV file.
- 3. Adjacency Matrix Generation: An adjacency matrix is generated from the constructed graph using the nx.adjacency_matrix function. This matrix represents the relationships between nodes in the graph.
- 4. **Prediction of Missing Links**: The predict_zero_values function is employed to predict missing links in the graph. This function iterates through the adjacency matrix, identifies zero elements (indicating missing links), and predicts their values using linear algebra techniques.
- 5. Linear Least Squares Regression: Within the predict_zero_values function, linear least squares regression is performed to predict the value of each missing link. This involves expressing the row containing the zero element as a linear combination of the

- remaining rows in the adjacency matrix. The coefficients obtained from the regression are then used to predict the value of the missing link based on the corresponding column values.
- 6. Thresholding: Predicted values exceeding a certain threshold (in this case, 0.6 as if the predicted value is less than or equal to zero then there is no edge between that nodes but as by this method the values approximately range from some -0.9 to 3 so for more accuracy I took 0.6 as the threshold) are considered significant and are added as edges to the graph.

Implementation

The provided Python code implements the aforementioned method as follows:

```
import numpy as np
  import networkx as nx
  import pandas as pd
  def predict_zero_values(adj_matrix):
      zero_indices = np.argwhere(adj_matrix == 0) # Finding indices
6
         of zeroes in the matrix
      if len(zero_indices) == 0:
          print("Nouzeroufounduinutheuadjacencyumatrix.")
          return None
      predicted_values = [] #List for storing the predicted values
      for zero_index in zero_indices:
13
          row, col = zero_index #Rows and columns corresponding to
             zeroes in the matrix
          deleted_row = adj_matrix[row]# Extracting the row containing
              the zero
          deleted_row = np.delete(deleted_row, col, axis=0)# Deleting
             the zero element from the row
          deleted_col = adj_matrix[:, col]# Extracting the column
             containing the zero
          deleted_col = np.delete(deleted_col, row, axis=0) # Deleting
18
              the zero element from the column
          # Deleting row and column
          adj_matrix_temp = np.delete(adj_matrix, row, axis=0)#
21
             Deleting the row from the adjacency matrix
          adj_matrix_temp = np.delete(adj_matrix_temp, col, axis=1)#
             Deleting the column from the adjacency matrix
23
          # Expressing deleted row as linear combination of remaining
             rows using numpy built in function (matrix method)
```

```
'', working of the built in function used here:
          np.linalg.lstsq: This function computes the least-squares
              solution to a linear matrix equation. It is commonly used
              when you have an overdetermined system of linear
              equations, meaning there are more equations than unknowns
           adj_matrix_temp.T: This is the matrix of independent
              variables , it represents the remaining rows of the
              adjacency matrix after deleting the row corresponding to
              the zero element.
30
           deleted_row: This is the dependent variable vector,
              representing the row containing the zero element that we
              want to express as a linear combination of the remaining
              rows.
32
          rcond=None: This argument specifies the cutoff for small
33
              singular values. When roond is set to None, NumPy
              internally determines the threshold for determining rank
              of the coefficient matrix, which is used to solve the
              least squares problem. It essentially controls the
              numerical stability of the solution.
34
           [0]: The result of np.linalg.lstsq is a tuple containing
35
              several elements, including the solution to the least
              squares problem. By accessing element [0], we're
              extracting the solution coefficients from the tuple.
                   , , ,
36
           coefficients = np.linalg.lstsq(adj_matrix_temp.T,
              deleted_row, rcond=None)[0]
38
           # Predicting the value of the zero in the deleted row/column
          predicted_value = np.dot(coefficients, deleted_col)
40
41
           # Storing the predicted value along with its index
           predicted_values.append((zero_index, predicted_value))
44
      return predicted_values
45
46
47
  #Reading the csv file
48
  data = pd.read_csv('modified_impression_network.csv')
49
  #Creating directed graph from the csv file data
  G = nx.DiGraph()
```

```
for index, row in data.iterrows():
      node = row.iloc[0] # Assuming the first column contains the
      neighbors = row.iloc[1:].dropna().tolist() # Assuming the rest
          columns are neighbors
      G.add_node(node) # Adding nodes to the graph
56
      for neighbor in neighbors: # Adding neighbors to the graph
           G.add_edge(node, neighbor)
  adj_matrix = nx.adjacency_matrix(G).todense()# Generating the
60
     adjacency matrix from the graph
61
  predicted_values = predict_zero_values(adj_matrix)# Predicting zero
62
     values in the adjacency matrix
  missing_links = [] # List to store missing links
  persons = list(G.nodes())# List of persons in the graph so that i
     can get the entry no. of the students corresponding to its index
     in adjacency matrix
  for zero_index, predicted_value in predicted_values:
65
66
      if predicted_value > 0.6:# Checking if predicted value exceeds a
          threshold
           i,j = zero_index# Extracting row and column indices
           missing_links.append((persons[i], persons[j]))# Storing
69
              missing links in the form of entry no. of the students
          G.add_edge(persons[i], persons[j])# Adding missing links to
              the graph
  # Printing missing links
  print("missing_links")
  for m in missing_links:
      print(m)
```

- It imports necessary libraries such as NumPy for numerical operations, NetworkX for graph manipulation, and Pandas for data handling.
- The predict_zero_values function is defined to predict missing links in the adjacency matrix.
- The CSV file containing network data is read using Pandas, and a directed graph is constructed based on the information in the file.
- The adjacency matrix of the graph is generated.
- Missing links are predicted using the predict_zero_values function, and significant predictions are added as edges to the graph.
- Finally, the missing links are printed for analysis.

Conclusion

The method described provides a systematic approach for predicting missing links in a social network graph. By leveraging linear algebra techniques and least squares regression, it offers insights into potential connections that can enhance our understanding of network dynamics. Further experimentation and validation on real-world datasets can validate the effectiveness of this approach in practical scenarios.

Problem 3. Propose a brand new problem based on this dataset and provide a solution for the same. Be as creative as possible.

Solution.

1 Problem: Find the Strongly Connected Components (SCC) in the Graph

The Question is to identify the strongly connected components in a given directed graph. This involves partitioning the graph into subsets of nodes where each subset forms an SCC, meaning that every node in an SCC can reach every other node within the same SCC.

2 Introduction

Strongly Connected Components (SCCs) are fundamental concepts in graph theory, particularly in the analysis of directed graphs. An SCC is a subset of nodes in a directed graph where every node is reachable from every other node within the subset. SCCs play a crucial role in understanding the structure and connectivity of directed graphs.

3 What are SCCs and How are They Used in Examining the Graph

Strongly Connected Components provide valuable insights into the structure and connectivity of directed graphs. They help in identifying clusters or communities within the graph where nodes have strong interactions or dependencies. SCCs are used in various graph analysis tasks, including:

- 1. Graph Visualization: SCCs can be visualized as distinct clusters within a directed graph, providing a clear representation of the graph's connectivity patterns.
- 2. Network Analysis: Identifying SCCs allows for the examination of interconnected subgraphs, revealing important structures and relationships within the larger graph.
- 3. Algorithm Design: SCCs are utilized in algorithms for tasks such as finding shortest paths, detecting cycles, and identifying central nodes in a graph.

4 Algorithm Used for Finding SCCs

The algorithm that I have used for finding strongly connected components in a directed graph is Kosaraju's algorithm. Kosaraju's algorithm is a two-pass algorithm that efficiently identifies SCCs in linear time complexity.

- 1. First Pass (Forward DFS): Perform a depth-first search (DFS) traversal of the graph to compute the finishing times for each node. This step assigns a finishing time to each node, with nodes finishing later having higher finishing times.
- 2. Second Pass (Backward DFS): Reverse the direction of all edges in the graph. Perform another DFS traversal, this time starting from nodes with the highest finishing times computed in the first pass. This step identifies the SCCs by exploring nodes in the reverse topological order of the original graph.

5 Implementation

The provided Python code implements Kosaraju's algorithm to find strongly connected components in a given directed graph. It utilizes the NetworkX library to represent and traverse the graph efficiently. After identifying SCCs, the code outputs the nodes belonging to each SCC, providing valuable insights into the graph's structure and connectivity.

```
import pandas as pd
  import networkx as nx
  class Graph:
      def __init__(self):
           self.graph = {} # Initializing an empty dictionary to
              represent the graph
      def add_edge(self, u, v):
           if u not in self.graph:
               self.graph[u] = [] # Adding node 'u' to the graph if not
                  already present
           self.graph[u].append(v)# Adding edge (u, v) to the graph
11
12
      def dfs(self, v, visited, stack):
13
           visited.add(v)# Marking node 'v' as visited
14
           for neighbor in self.graph.get(v, []):
               if neighbor not in visited:
                   self.dfs(neighbor, visited, stack)# Recursively
                      performing DFS on unvisited neighbors
           stack.append(v) # Adding node 'v' to the stack after
18
              visiting all its neighbors
19
      def transpose(self):
20
           transposed = Graph()# Creating a new instance of Graph to
21
              represent the transposed graph
```

```
for u in self.graph:
               for v in self.graph[u]:
                   transposed.add_edge(v, u) #Reversing the direction
                      of each edge in the original graph
           return transposed# Returning the transposed graph
      def fill_order(self, v, visited, stack):
           visited.add(v)# Marking node 'v' as visited
           for neighbor in self.graph.get(v, []):
29
               if neighbor not in visited:
30
                   self.fill_order(neighbor, visited, stack)#
                      Recursively performing DFS on unvisited neighbors
           stack.append(v)# Adding node 'v' to the stack after visiting
32
               all its neighbors
      def get_sccs(self):
           stack = [] # Initializing a stack to store nodes in order of
               their finishing times
           visited = set()# Initializing a set to store visited nodes
36
           for node in self.graph:
37
               if node not in visited:
38
                   self.dfs(node, visited, stack)# Performing DFS on
39
                      all unvisited nodes
          # Getting the transposed graph
           transposed = self.transpose()
          # Clearing the visited set to reuse it for the next DFS
42
              traversal
          visited.clear()
43
           sccs = []# Initializing a list to store strongly connected
              components
           while stack:
46
               v = stack.pop() # Popping a node from the stack
47
               if v not in visited:
48
                   scc = [] # Initializing a list to store nodes in the
49
                       current strongly connected component
                   transposed.fill_order(v, visited, scc)# Performing
                      DFS on the transposed graph to get the SCC
                   sccs.append(scc)# Adding the SCC to the list of SCCs
          return sccs
  #Reading the csv file
  data = pd.read_csv('modified_impression_network.csv')
  #Creating directed graph from the csv file data
  G = nx.DiGraph()
```

```
for index, row in data.iterrows():
                          # Assuming the first column contains the
      node = row.iloc[0]
61
       neighbors = row.iloc[1:].dropna().tolist()
                                                   # Assuming the rest
          columns are neighbors
       G.add_node(node) # Adding nodes to the graph
63
       for neighbor in neighbors: # Adding neighbors to the graph
           G.add_edge(node, neighbor)
66
  # Converting NetworkX graph to adjacency list
67
   adjacency_list = {}
68
  for edge in G.edges:
69
       if edge[0] not in adjacency_list:
           adjacency_list[edge[0]] = [] # Adding node 'u' to the
              adjacency list if not already present
       adjacency_list[edge[0]].append(edge[1])# Adding edge (u, v) to
          the adjacency list
  # Creating a Graph object and initialize it with the adjacency list
  g = Graph() # Creating an instance of the Graph class
75
  for node, neighbors in adjacency_list.items():
      for neighbor in neighbors:
           g.add_edge(node, neighbor)# Adding edges to the graph using
              the adjacency list
  # Finding strongly connected components using Kosaraju's algorithm
80
  sccs = g.get_sccs()# Getting the strongly connected components
81
  print("Strongly Connected Components:")
82
  for scc in sccs:
83
      print(scc)
  # Getting the largest strongly connected component
86
  largest_scc = max(sccs, key=len)
87
88
  # Number of nodes in the largest strongly connected component
89
  num_nodes_in_largest_scc = len(largest_scc)
90
  print("Number_of_nodes_in_the_largest_strongly_connected_component:"
      , num_nodes_in_largest_scc)
```

6 Conclusion

Finding strongly connected components in a directed graph is a crucial task in graph analysis. SCCs help in understanding the underlying structure and connectivity patterns of directed graphs. If the biggest strongly connected component (SCC) found has a large number of nodes, approximately equal to the total number of nodes in the graph, it implies that

the graph is highly connected and lacks distinct substructures. Such a scenario suggests that the graph forms a single cohesive unit where nearly every node is reachable from every other node. This can indicate a tightly interconnected network with strong relationships and dependencies between its constituents. It suggests a homogeneous structure where information or influence can flow freely across the entire network without encountering significant barriers.