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# Temperature Control Lab 2 (TCL 2)

Institute for Automation Engineering  
Chair for Automation/Modeling

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## 1 Objectives

The identified systems transfer function from TCL 1 will be used in this lab to determine controller parameters of a PI-controller. The PI-controller should be implemented with MATLAB/Simulink and tested via simulation and the TCL. The objectives for this lab are:

- Gaining experience with standard controllers.
- Application of simple standard methods to design controllers in the frequency domain.
- Determination and validation of controller design strategies without prior model identification.

## 2 Controller Design

### 2.1 Preparation

1. Use the transfer function obtained in TCL 1 to design the PI controller in the frequency domain:
  - a) Gain adjustment with phase margin  $\phi_M = 30^\circ$  and  $\phi_M = 70^\circ$ .
  - b) Try to improve the results of (a) by increasing the crossover frequency while keeping the phase margin constant (Loop shaping).

2. Use the transfer function obtained in TCL 1 to design the PI controller using
  - a) Ziegler tuning rules,
  - b)  $T_{\Sigma}$  rules,
  - c) Opelt tuning rules.
3. Implement the PI controllers identified above in the Matlab/SIMULINK file with the transfer function from TCL 1 and test their performance.

## 2.2 Practical part

The following tasks refer to the same Heater-Sensor-System which was used in TCL 1:

1. Use the methods from Preparation/2a-c to design a PI controller with experimental data from the TCL.
2. Implement and test the controller for the Heater-Sensor-System by
  - a) disturbing the system via the other heater,
  - b) changing the set point of the heater-sensor-system.
3. Interpret the experimental results and compare the performance of the controllers to each other.

## 3 Deadline

Please upload your final report including answers to the questions from the preparation section and your solution of the practical part as pdf file in the e-learning platform:

<https://elearning.ovgu.de/course/view.php?id=11281>

Submission deadline: 16th December 2021