



CS786: Computational Cognitive Science Assignment 1

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ANN for Boolean function

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0.1 (a) Taking any three variable Boolean function as input and generating the truth table

```
In [2]: import numpy as np
        truth_table=[]
        for p in False, True:
            for q in False, True:
                for r in False, True:
                    truth_table.append([int(p),int(q), int(r)])
```

0.2 b)Generating five boolean function

```
In [3]: l=len(truth_table)
        y_or=[]
        y_and=[]
        y_xor=[]
        y_nand=[]
        y_nor=[]
        y_list=[]
        for i in range(l):
            yt1=truth_table[i][0] or truth_table[i][1] or truth_table[i][2]
            yt2=truth_table[i][0] and truth_table[i][1] and truth_table[i][2]
            yt3=truth_table[i][0] ^ truth_table[i][1] ^ truth_table[i][2]
            yt4=not yt2
            yt5=not yt1
            y_or.append(yt1)
            y_and.append(yt2)
            y_xor.append(yt3)
            y_nand.append(yt4)
            y_nor.append(yt5)
        y_or=np.array(y_or)
        y_and=np.array(y_and)
        y_xor=np.array(y_xor)
        y_nand=np.array(y_nand)
        y_nor=np.array(y_nor)
        y_list.append(y_or)
        y_list.append(y_and)
        y_list.append(y_xor)
```

```

y_list.append(y_nand)
y_list.append(y_nor)
fn_list=["OR", "AND", "XOR", "NAND", "NOR"]

```

0.3 Different Activation Function

```

In [6]: def sigmoid(x):
        return 1.0/(1.0 + np.exp(-x))

        def sigmoid_prime(x):
            return sigmoid(x)*(1.0-sigmoid(x))

        def tanh(x):
            return np.tanh(x)

        def tanh_prime(x):
            return 1.0 - x**2

```

Neural Network Implementation

```

In [9]: class NeuralNetwork:

        def __init__(self, layers, activation='tanh'):
            if activation == 'sigmoid':
                self.activation = sigmoid
                self.activation_prime = sigmoid_prime
            elif activation == 'tanh':
                self.activation = tanh
                self.activation_prime = tanh_prime

            self.weights = []
            for i in range(1, len(layers) - 1):
                r = 2*np.random.random((layers[i-1] + 1, layers[i] + 1)) - 1
                self.weights.append(r)
            r = 2*np.random.random((layers[i] + 1, layers[i+1])) - 1
            self.weights.append(r)

        def fit(self, X, y, learning_rate=0.2, epochs=100000):
            ones = np.atleast_2d(np.ones(X.shape[0]))
            X = np.concatenate((ones.T, X), axis=1)

            for k in range(epochs):
                #if k % 10000 == 0: print('epochs:', k)

                i = np.random.randint(X.shape[0])
                a = [X[i]]

                for l in range(len(self.weights)):

```

```

        dot_value = np.dot(a[l], self.weights[l])
        activation = self.activation(dot_value)
        a.append(activation)
# output layer
        error = y[i] - a[-1]
        deltas = [error * self.activation_prime(a[-1])]

        for l in range(len(a) - 2, 0, -1):
            deltas.append(deltas[-1].dot(self.weights[l].T)*self.activation_prime(a[l]))

        deltas.reverse()
        for i in range(len(self.weights)):
            layer = np.atleast_2d(a[i])
            delta = np.atleast_2d(deltas[i])
            self.weights[i] += learning_rate * layer.T.dot(delta)

    def predict(self, x):
        a = np.concatenate((np.ones(1).T, np.array(x)))
        for l in range(0, len(self.weights)):
            a = self.activation(np.dot(a, self.weights[l]))
        return a

```

0.4 c)d) Training and Verifying five boolean function

```

In [10]: X=np.array(truth_table)
nn = NeuralNetwork([3,3,1])
for i in range(len(y_list)):
    nn.fit(X, y_list[i])
    print("Function Name",fn_list[i])
    for e in X:
        p=nn.predict(e)
        if p > 0.50:
            print(e,p,1)
        else:
            print(e,p,0)

```

```

Function Name OR
[0 0 0] [7.09817703e-06] 0
[0 0 1] [0.99733063] 1
[0 1 0] [0.996947] 1
[0 1 1] [0.99951977] 1
[1 0 0] [0.99711943] 1

```

```

[1 0 1] [0.99962003] 1
[1 1 0] [0.99955787] 1
[1 1 1] [0.99972434] 1
Function Name AND
[0 0 0] [0.0001482] 0
[0 0 1] [0.00015319] 0
[0 1 0] [7.24907019e-05] 0
[0 1 1] [0.00047451] 0
[1 0 0] [0.00017896] 0
[1 0 1] [0.00064648] 0
[1 1 0] [0.00035616] 0
[1 1 1] [0.99313259] 1
Function Name XOR
[0 0 0] [0.02054847] 0
[0 0 1] [0.99561807] 1
[0 1 0] [0.99535562] 1
[0 1 1] [0.00284612] 0
[1 0 0] [0.99554909] 1
[1 0 1] [0.00238422] 0
[1 1 0] [-0.00134827] 0
[1 1 1] [0.99163479] 1
Function Name NAND
[0 0 0] [0.99921373] 1
[0 0 1] [0.99996664] 1
[0 1 0] [0.9999641] 1
[0 1 1] [0.99909302] 1
[1 0 0] [0.9999661] 1
[1 0 1] [0.99896553] 1
[1 1 0] [0.9990262] 1
[1 1 1] [1.34080823e-05] 0
Function Name NOR
[0 0 0] [0.99578573] 1
[0 0 1] [-0.00042567] 0
[0 1 0] [0.00035315] 0
[0 1 1] [4.27031609e-05] 0
[1 0 0] [0.00027225] 0
[1 0 1] [0.00023193] 0
[1 1 0] [-0.00045874] 0
[1 1 1] [0.00467176] 0

```

In []:

In []:

Qlearning

January 28, 2019

0.1 ****(a) Generated a random instance of the frozen lake scenario given two inputs - the size of the lake (N)=4 assuming its square, and the number of holes (M)=4****

```
In [2]: import numpy as np
import random
import matplotlib.pyplot as plt

In [3]: def generate_Reward_table(n,m):
    #n=4
    #m=4
    R=np.zeros((n,n))
    #print(R)
    i=np.random.choice(n, m,replace=False)
    j=np.random.choice(n, m,replace=False)
    #print(i,j)

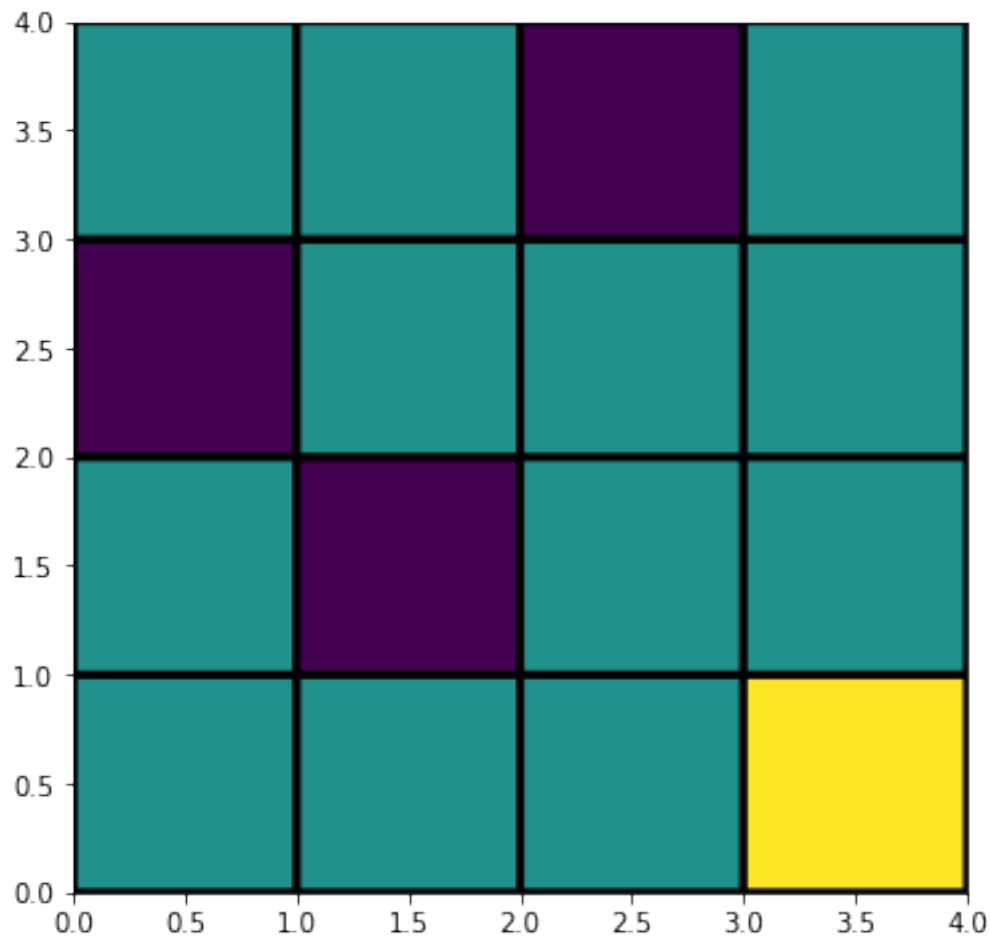
    for k in range(len(i)):
        i1=i[k]
        i2=j[k]
        R[i1][i2]=-100

    R[n-1][n-1]=100
    R[0][0]=0
    #print(R)
    F_R=R.flatten()
    #print(F_R)
    q_learning_table = np.zeros([n*n+1,4])
    return R,F_R,q_learning_table

In [4]: R,F_R,q_learning_table=generate_Reward_table(4,4)
print(R)
plt.figure(figsize=(6,6))
plt.pcolor(R[:,:-1],edgecolors='k', linewidths=3)
plt.show()

[[ 0.   0. -100.   0.]
 [-100.  0.   0.   0.]
```

```
[ 0. -100.  0.  0.]
[ 0.   0.  0. 100.]]
```



0.2 ****Function to define available action****

```
In [5]: def available_action(curr,n):
        moves=[]
        if (curr%n)!=1:
            #moves.append(curr-1)
            moves.append(0)
        if (curr%n)!=0:
            #moves.append(curr+1)
            moves.append(1)
        if curr-n>0:
            #moves.append(curr-n)
            moves.append(2)
        if curr+n<=(n**2):
```

```

        #moves.append(curr+n)
        moves.append(3)
    return moves

```

0.3 Calculate Next State and reward

```

In [6]: def next_state_and_reward(curr_state,action,F_R):
        #print("inside next state",curr_state,action)
        if action==0:
            next_st=curr_state-1
        if action==1:
            next_st=curr_state+1
        if action==2:
            next_st=curr_state-n
        if action==3:
            next_st=curr_state+n

        reward=F_R[next_st-1]
        #print(i,j,reward)
        return next_st,reward

```

0.4 Get Sample Action

```

In [7]: def sample_next_action(available_state_range):
        next_action=int(np.random.choice(available_state_range,1))
        return next_action

```

0.5 b) Qlearning Function

```

In [53]: def QLearning(n,F_R,gamma,alpha,epsilon,q_learning_table,ran):
        state=1
        rlist = []

        for i in range(ran):
            rAll=0
            state=1
            while state <n*n:
                a=0
                available_act=available_action(state,n)
                if random.uniform(0,1) > epsilon:
                    max_v=0
                    for x in available_act:
                        #print(x)
                        if q_learning_table[state][x] >=max_v:
                            max_v=q_learning_table[state][x]
                            a=x
                else:

```



```

        a=sample_next_action(available_act)

        next_st,reward=next_state_and_reward(state,a,F_R)
        q_learning_table[state,a] = (1-alpha)*q_learning_table[state,a] + (alpha
        state=next_st
        rAll += reward
        #print(state)
        epsilon = min_epsilon + (max_epsilon - min_epsilon)*np.exp(-decay_rate*i)
#         if i%200 == 0:
#             print('Trial {0}; reward : {1}'.format(i, rAll))
        rlist.append(rAll)
        #print(q_learning_table)
    return q_learning_table,rlist

```

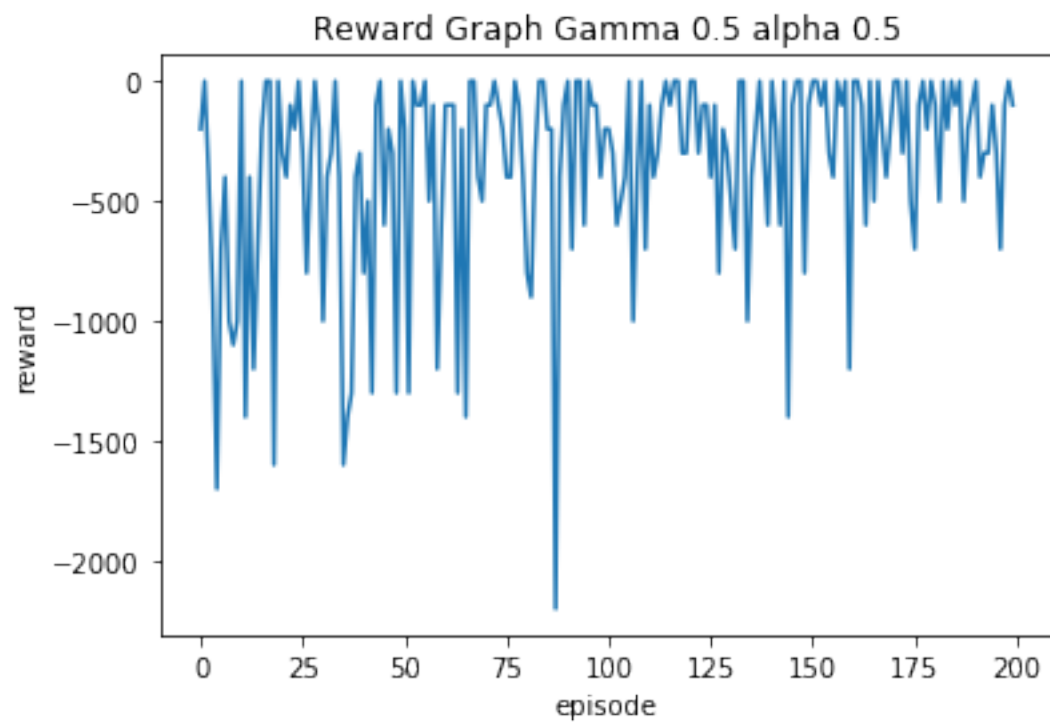
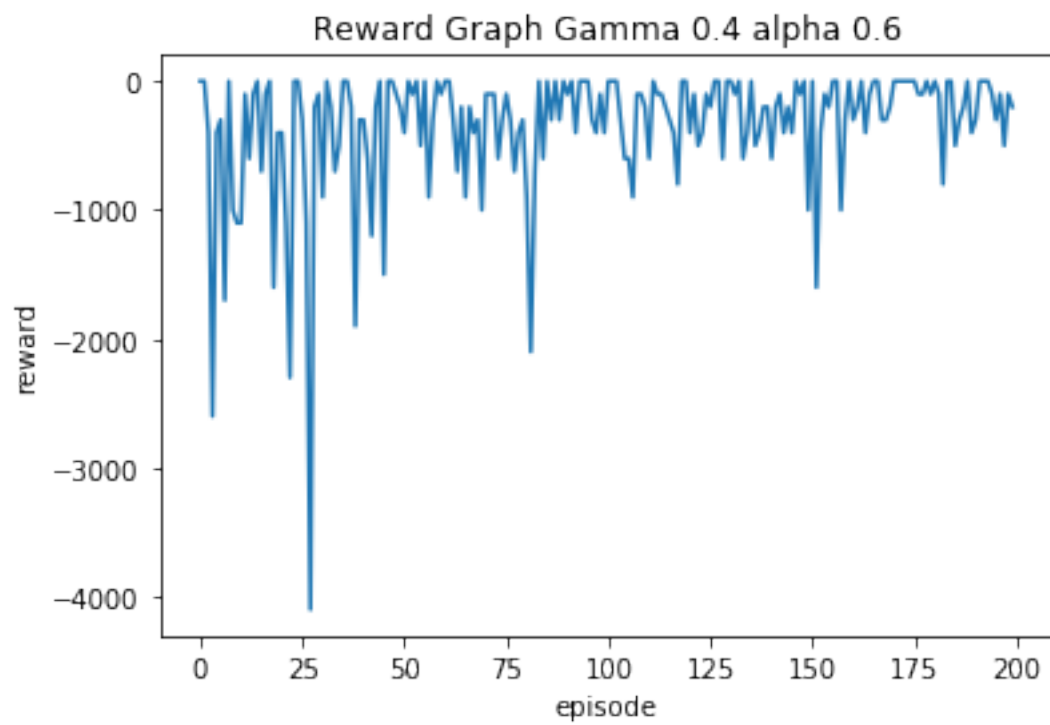
0.6 Plotting Reward with respect to episode for different parameter

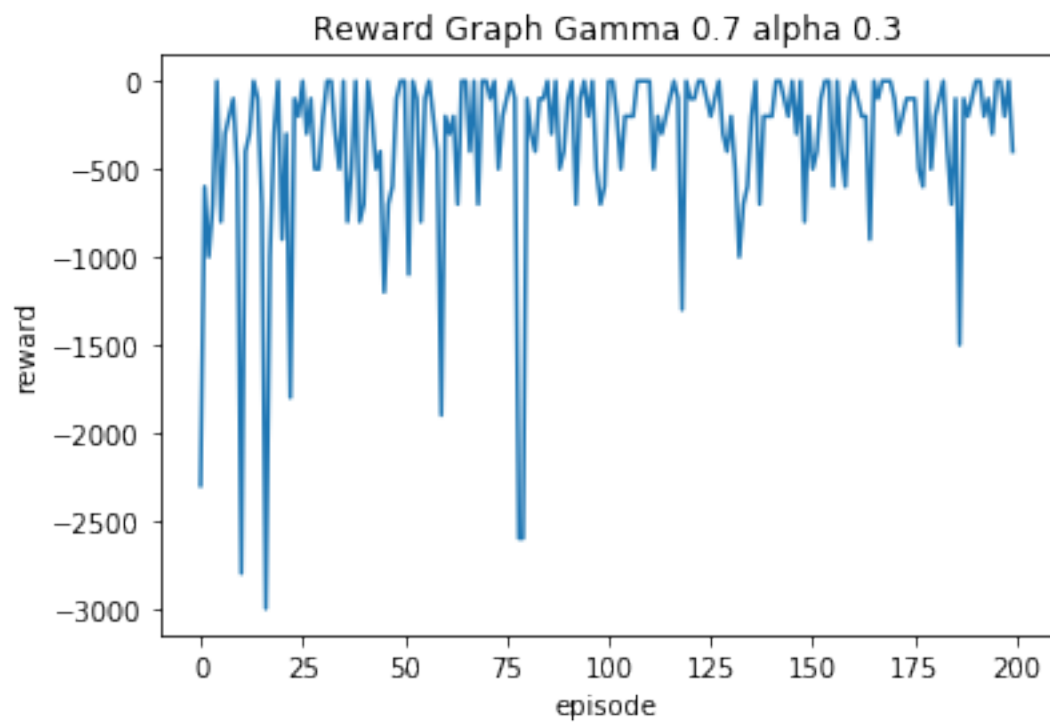
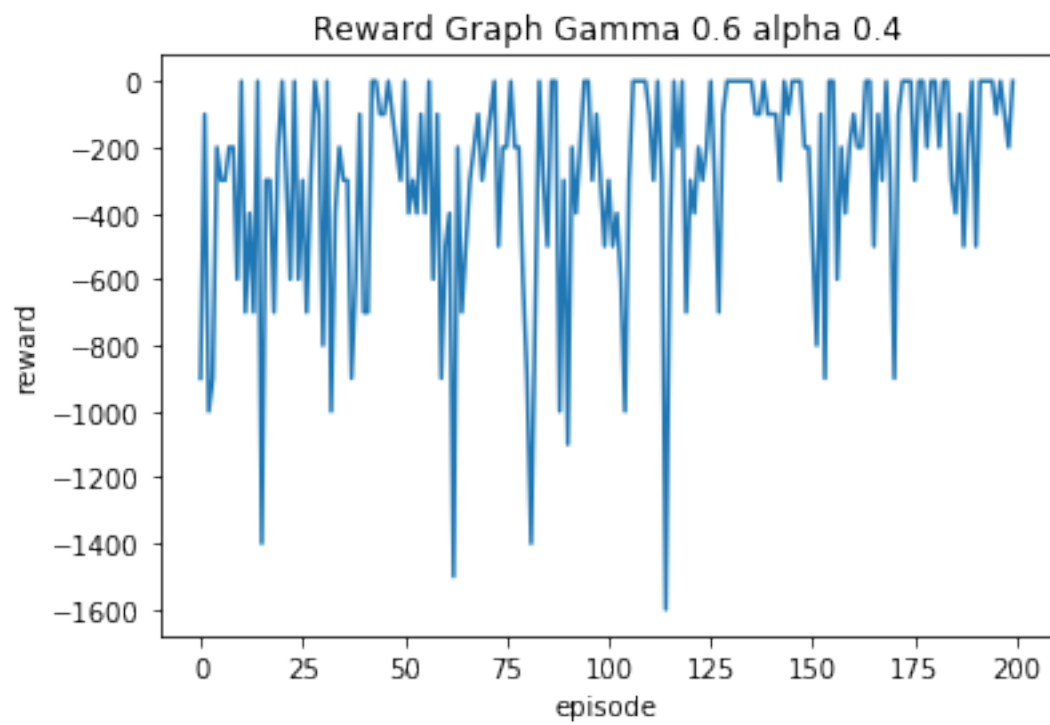
we Can see below the effect of changing alpha value and gamma.alpha value represent learing rate so small alpha it will take more time to converge. Gamma is the value of future reward. If it is equal to one, the agent values future reward as current reward. when it is reduced it will give discount to the future reward.

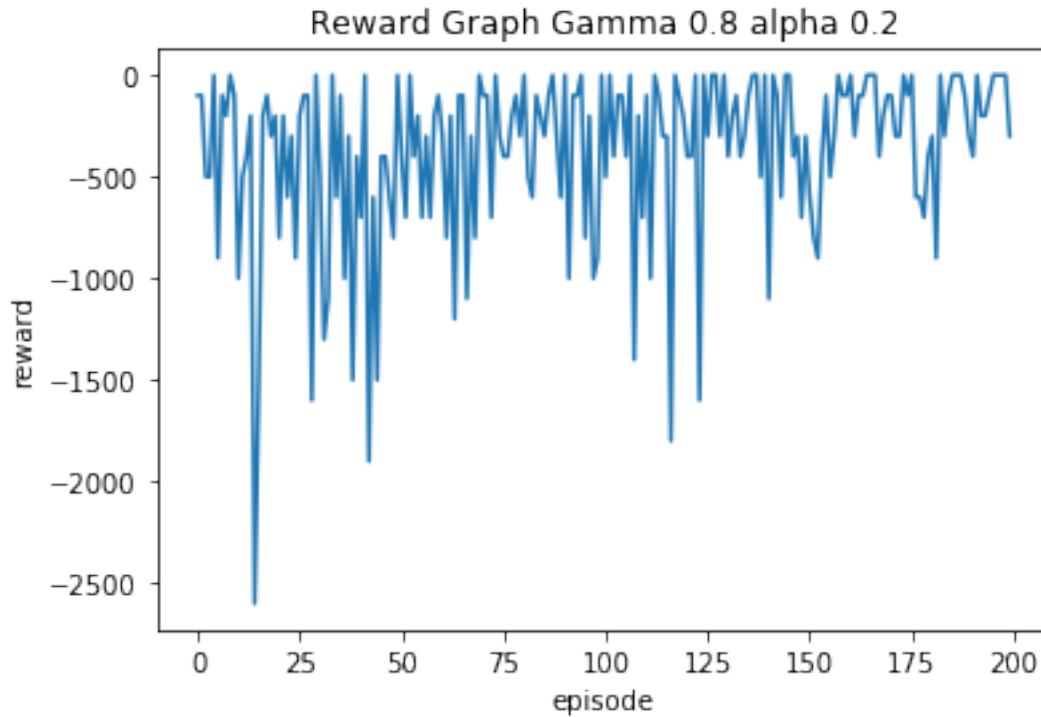
```

In [55]: gamma_l=[0.4,0.5,0.6,0.7,0.8]
        alpha_l=[0.6,0.5,0.4,0.3,0.2]
        epsilon = 1.0
        decay_rate = 0.005
        max_epsilon=1.0
        min_epsilon=0.01
        x_axis=range(200)
        n=4
        ran=200
        for i in range(5):
            gamma=gamma_l[i]
            alpha=alpha_l[i]
            q_learning_table,rlist=QLearning(n,F_R,gamma,alpha,epsilon,q_learning_table,ran)
            plt.plot(x_axis, rlist, label = "r list")
            plt.xlabel('episode')
            plt.ylabel('reward')
            plt.title('Reward Graph Gamma '+str(gamma)+ " alpha "+str(alpha))
            plt.show()
        #rlist

```







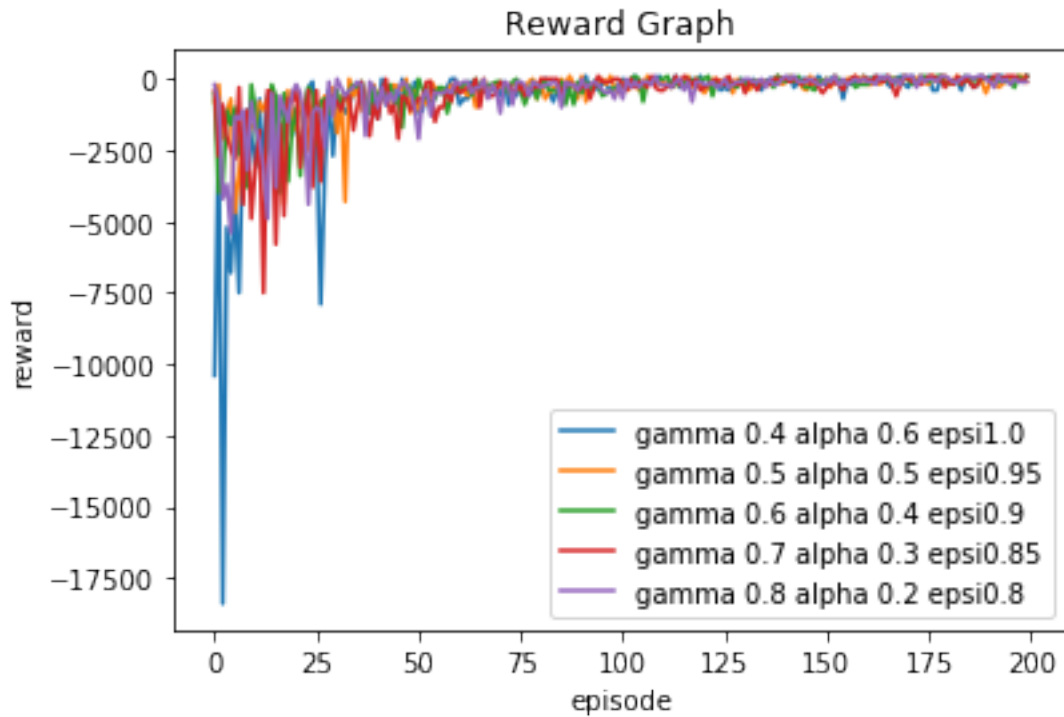
```
In [56]: def calculate_step(n,F_R,q_learning_table):
    #for episode in range(5):
    state=1
    step=0
    while state <n*n:
        available_act=available_action(state,n)
        max_v=0
        for x in available_act:
            if q_learning_table[state][x] >=max_v:
                max_v=q_learning_table[state][x]
                a=x
        next_st,reward=next_state_and_reward(state,a,F_R)
        #print(next_st)
        step+=1
        state = next_st
        #print("Steps",step)
    return step

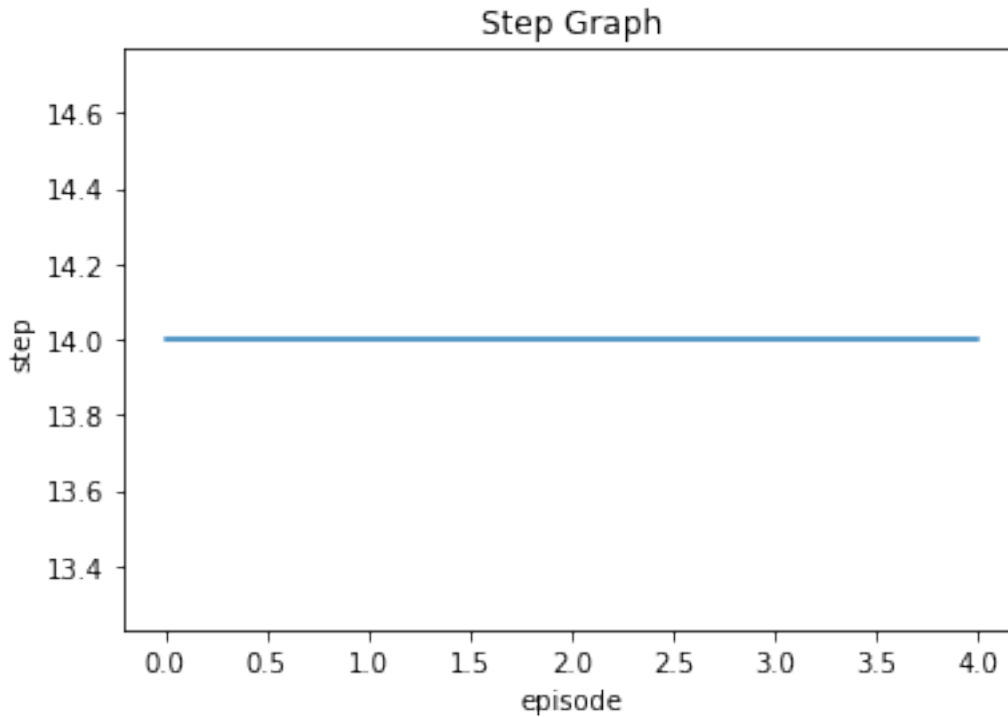
In [61]: step_l=[]
    epsilon_l=[1.0,0.95,0.9,0.85,0.8]
    x_axis1=range(200)
    ran=200
    for i in range(5):
        gamma=gamma_l[i]
```

```

alpha=alpha_l[i]
epsilon=epsilon_l[i]
q_learning_table,rlist=QLearning(n,F_R,gamma,alpha,epsilon,q_learning_table,ran)
step=calculate_step(n,F_R,q_learning_table)
step_l.append(step)
plt.plot(x_axis1, rlist, label = "gamma "+ str(gamma)+ " alpha "+str(alpha) +" epsilon "+str(epsilon))
plt.xlabel('episode')
plt.ylabel('reward')
plt.title('Reward Graph')
plt.legend()
plt.show()
x_axis=range(5)
plt.plot(x_axis, step_l, label = "step")
plt.xlabel('episode')
plt.ylabel('step')
plt.title('Step Graph')
plt.show()

```



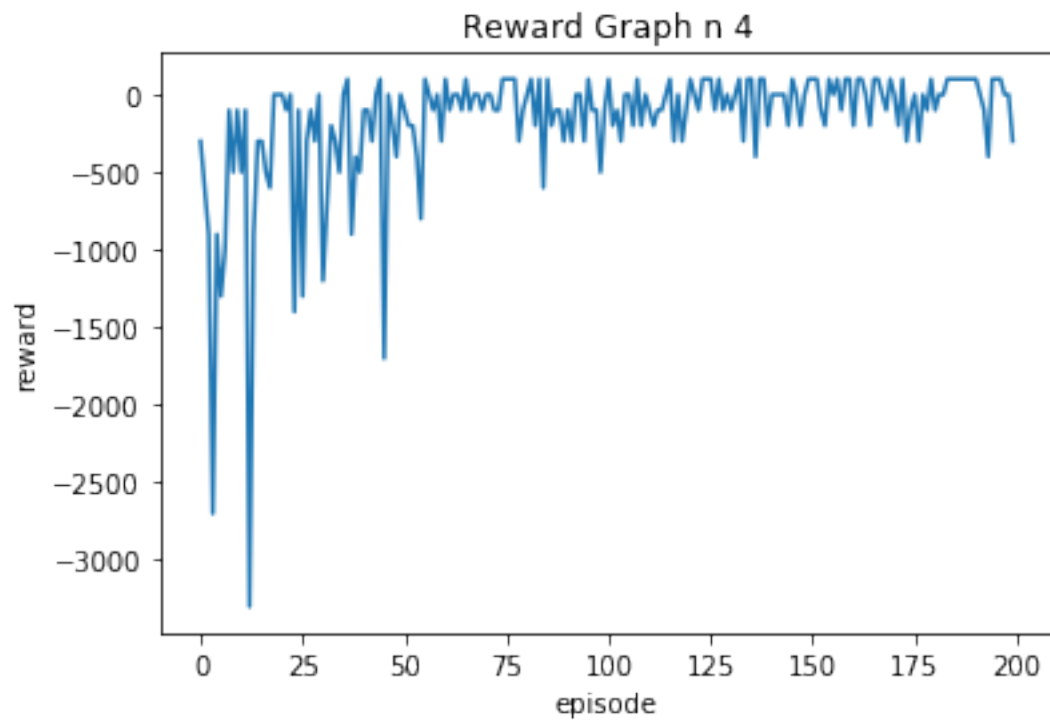


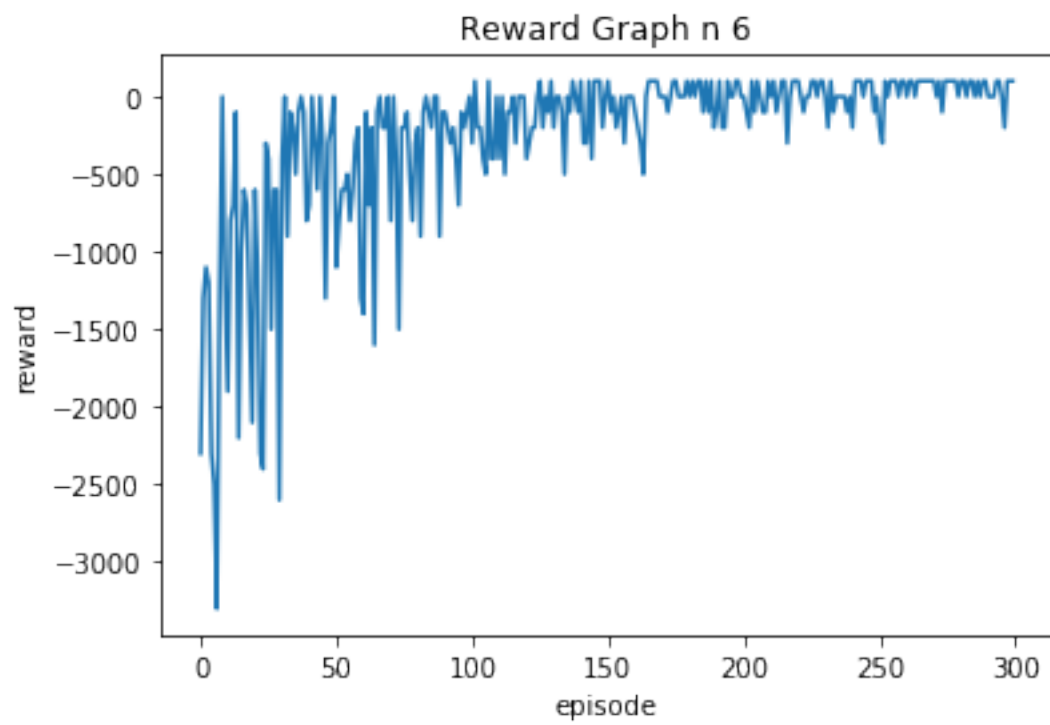
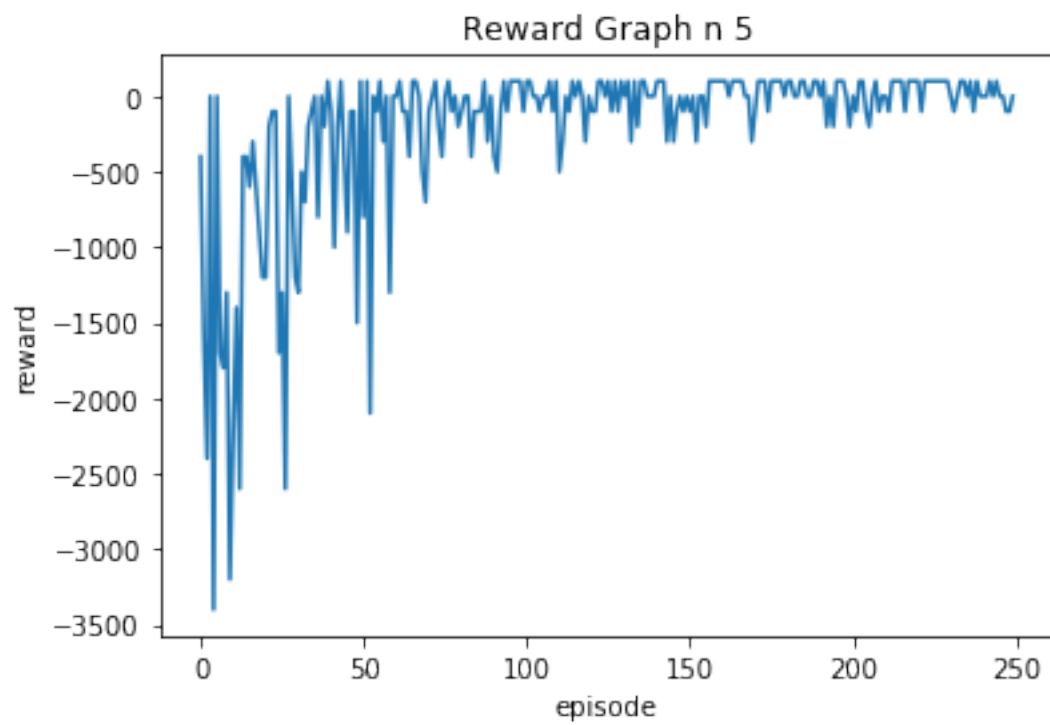
1 # Plotting Reward for different value of n

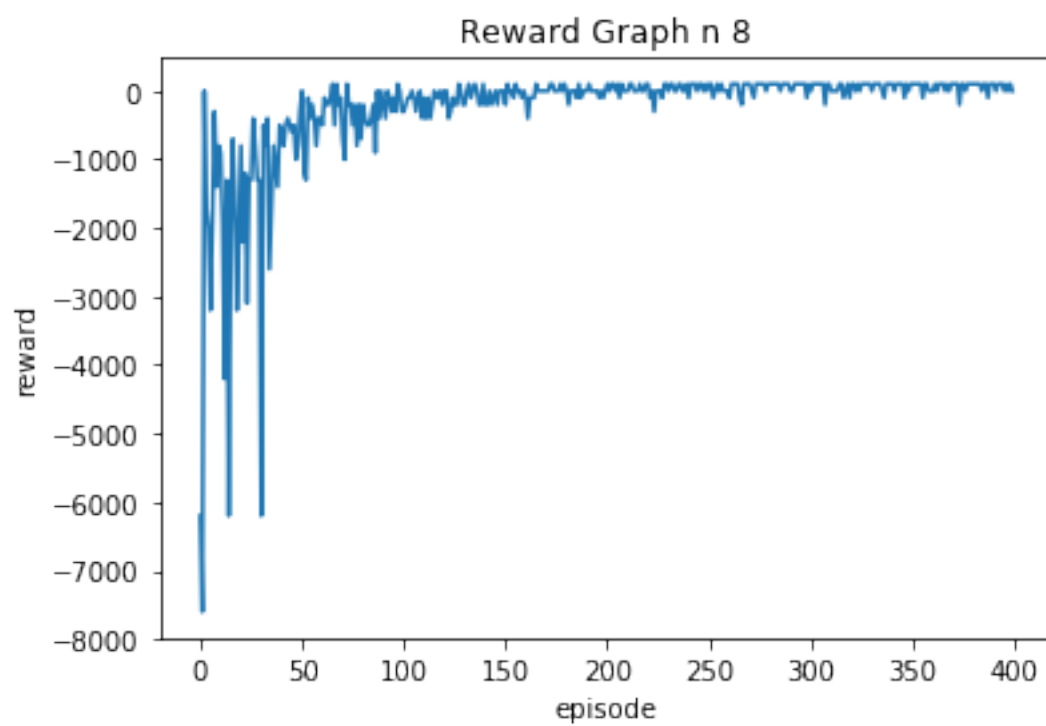
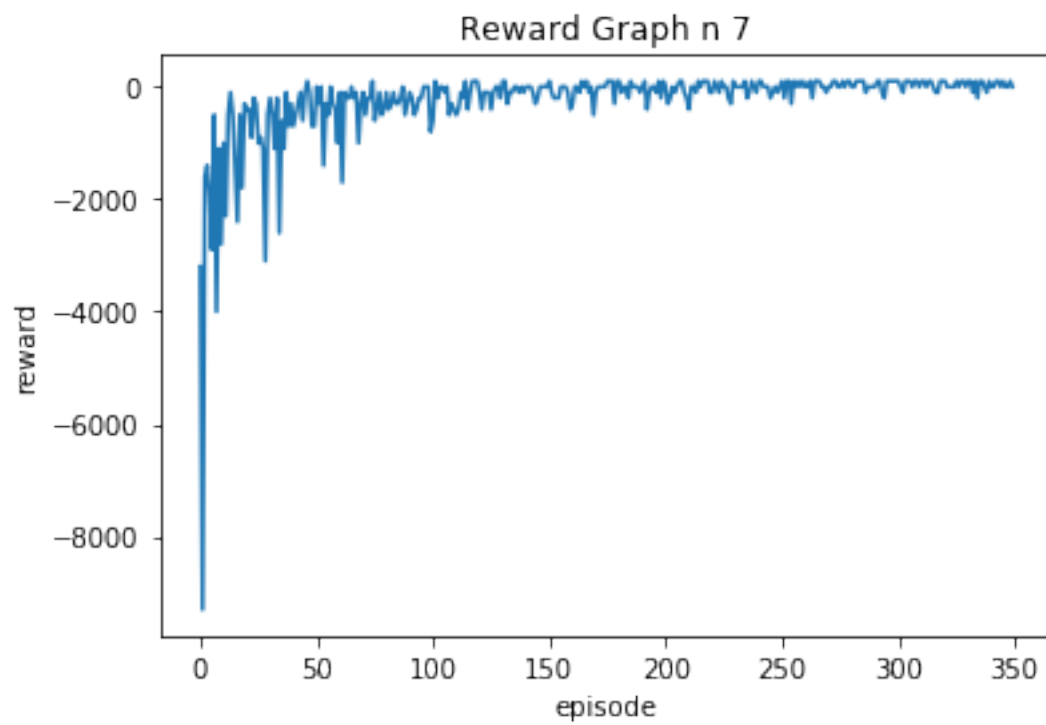
we can see the effect of differnt n and m in below graph

```
In [64]: gamma=0.5
alpha=0.5
epsilon = 1.0
decay_rate = 0.005
max_epsilon=1.0
min_epsilon=0.01
for n in range(4,9):
    R,F_R,q_learning_table=generate_Reward_table(n,n)
    # print(R)
    # plt.figure(figsize=(6,6))
    # plt.pcolor(R[:,:-1],edgecolors='k', linewidths=3)
    # plt.show()
    ran=n*50
    x_axis=range(n*50)
    q_learning_table,rlist=QLearning(n,F_R,gamma,alpha,epsilon,q_learning_table,ran)
    plt.plot(x_axis, rlist, label = "r list")
    plt.xlabel('episode')
    plt.ylabel('reward')
    plt.title('Reward Graph n '+str(n))
```

```
plt.show()
```







```
In [ ]:
```

Rulkov

January 29, 2019

0.1 Rulkov map

```
In [49]: def funX(x,y,alpha):
          x_n1=0
          if x <= 0:
              x_n1=(alpha/(1-x))+y
          elif x > 0 and x < alpha+y:
              x_n1=alpha+y
          elif x >= alpha+y:
              x_n1=-1
          return x_n1
```

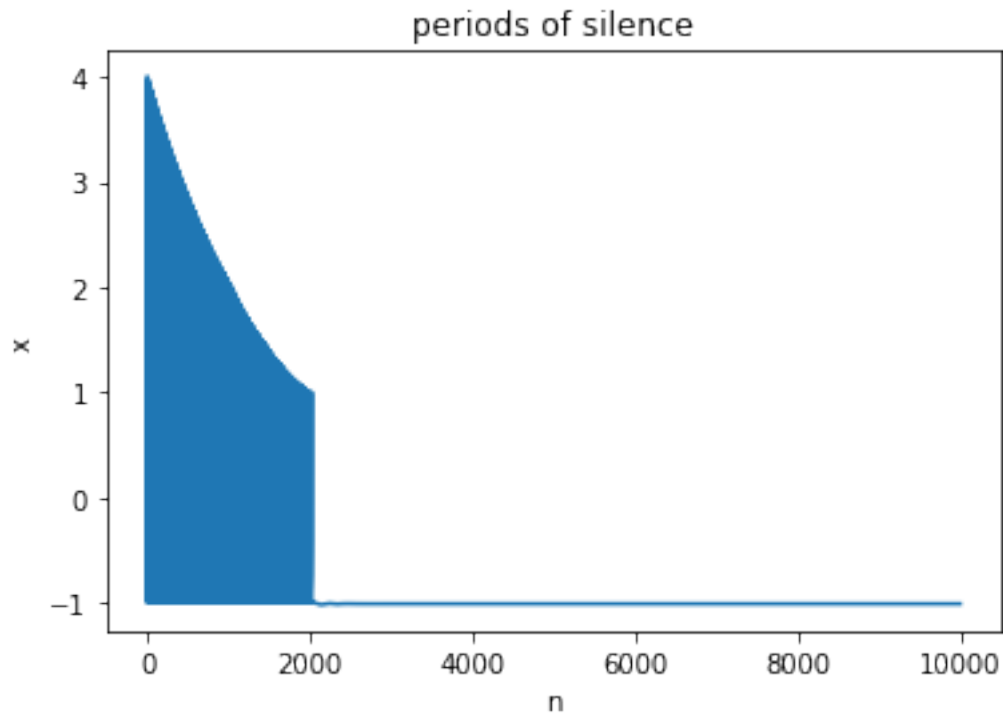
```
In [50]: def funY(x,y,mu,sigma):
          return (y-mu*(x+1)+mu*sigma)
```

0.2 Function to generate spike

```
In [65]: import matplotlib.pyplot as plt
          def generate_spike(alpha,mu,sigma,title):
              x_axis=range(10000)
              l=[]
              x=0
              y=0
              for i in range(10000):
                  x_t=funX(x,y,alpha)
                  x=x_t
                  l.append(x)
                  y_t=funY(x,y,mu,sigma)
                  y=y_t
              plt.plot(x_axis, l, label = "spike")
              plt.xlabel('n')
              plt.ylabel('x')
              plt.title(title)
              plt.show()
```

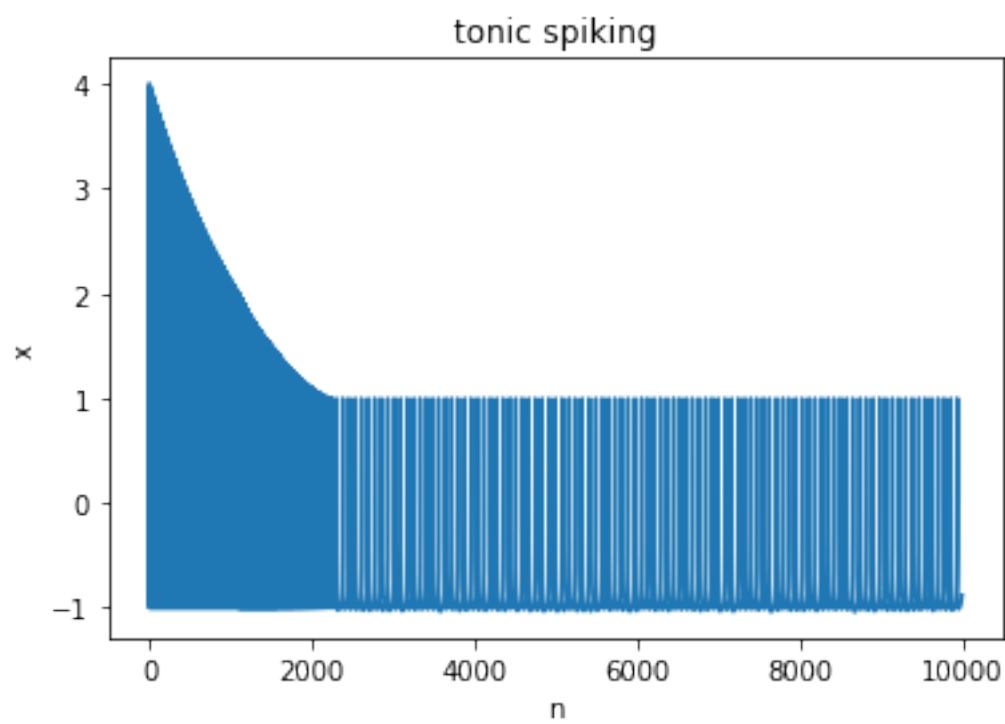
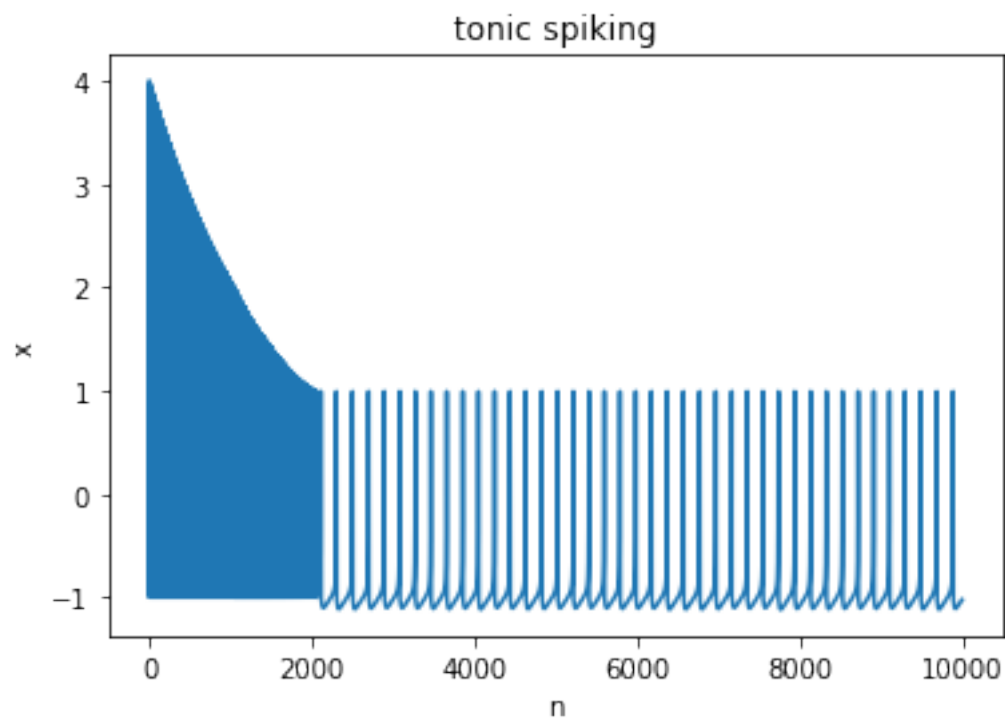
0.3 a) Periods of Silence Plot

```
In [67]: title="periods of silence"
alpha=4
mu=0.001
sigma=-0.01
generate_spike(alpha,mu,sigma,title)
```



0.4 b) Tonic spiking plot

```
In [71]: title="tonic spiking"
alpha=4
mu=0.001
sigma=0.01
generate_spike(alpha,mu,sigma,title)
sigma=0.1
generate_spike(alpha,mu,sigma,title)
```



0.5 c) Bursts of spikes plot

```
In [70]: title="bursts of spikes"
alpha=6
mu=0.001
sigma=-0.01
generate_spike(alpha,mu,sigma,title)
sigma=0.386
generate_spike(alpha,mu,sigma,title)
```

