

# Computer Architecture – Notes

## **Unit 1: Introduction to Computer Architecture**

### **1. Computer Architecture**

**Detailed Definition:** Computer architecture refers to the design and organization of the various components of a computer system and how they work together to execute instructions. It's like the "blueprint" of a computer that defines what it can do and how it performs tasks.

#### **Key Components:**

- **CPU (Central Processing Unit):** The brain of the computer
- **Memory:** Where data and instructions are stored
- **Input/Output Devices:** Keyboard, mouse, monitor, etc.
- **Storage:** Hard drives, SSDs for long-term data storage

### **2. Functional Units of a Computer**

#### **Input Unit**

- Receives data and instructions from external devices
- Examples: Keyboard, mouse, scanner
- Converts human-readable data to computer-readable format

#### **Output Unit**

- Sends processed data to external devices
- Examples: Monitor, printer, speakers
- Converts computer data to human-readable format

#### **Memory Unit**

- Stores data and instructions
- **Primary Memory:** RAM (temporary), ROM (permanent)
- **Secondary Memory:** Hard disk, SSD (long-term)

#### **Arithmetic Logic Unit (ALU)**

- Performs mathematical calculations (+, -, ×, ÷)
- Performs logical operations (AND, OR, NOT)
- The "calculator" of the computer

#### **Control Unit (CU)**

- Coordinates all computer operations
- Manages data flow between components
- The "traffic controller" of the computer

## **Central Processing Unit (CPU)**

- Combination of ALU and Control Unit
- Executes program instructions
- The "brain" of the computer

## **3. Von Neumann Architecture**

**Detailed Definition:** A computer design model where both data and programs are stored in the same memory. This is the foundation of most modern computers.

### **Key Features:**

- Single memory for both data and instructions
- Sequential instruction processing
- Stored-program concept
- Four main components: Memory, ALU, Control Unit, Input/Output

### **How it Works:**

1. Fetch instruction from memory
2. Decode the instruction
3. Execute the instruction
4. Store results

## **4. Generations of Computers**

### **First Generation (1940-1956)**

- Used vacuum tubes
- Very large and expensive
- Example: ENIAC

### **Second Generation (1956-1963)**

- Used transistors
- Smaller and more reliable
- Example: IBM 1401

### **Third Generation (1964-1971)**

- Used integrated circuits (ICs)
- Even smaller and faster
- Example: IBM System/360

### **Fourth Generation (1971-Present)**

- Used microprocessors
- Personal computers emerged

- Example: Modern PCs, laptops

### **Fifth Generation (Present and Beyond)**

- Artificial Intelligence
- Parallel processing
- Quantum computing

## **5. Performance Factors**

### **Clock Speed**

- Measured in Hertz (Hz)
- How many cycles per second
- Higher clock speed = faster processing

### **Word Size**

- Number of bits processed at once
- 32-bit vs 64-bit processors
- Larger word size = better performance

### **Cache Memory**

- Small, fast memory near CPU
- Stores frequently used data
- Reduces time to access main memory

### **Number of Cores**

- Multiple processors on one chip
- Dual-core, quad-core, octa-core
- More cores = better multitasking

### **Video Links:**

- **English:** [Computer Architecture Basics](#)
- **Hindi:** [Computer Architecture in Hindi](#)

## **Unit 2: Digital Logic and Circuits**

### **1. Logic Gates**

**Detailed Definition:** Basic building blocks of digital circuits that perform logical operations on binary inputs (0 and 1) to produce a single binary output.

### **Basic Gates:**

- **AND Gate:** Output 1 only if all inputs are 1
- **OR Gate:** Output 1 if at least one input is 1

- **NOT Gate:** Output is opposite of input (inverter)

#### **Universal Gates:**

- **NAND Gate:** AND followed by NOT
- **NOR Gate:** OR followed by NOT

#### **Other Gates:**

- **XOR Gate:** Output 1 if inputs are different
- **XNOR Gate:** Output 1 if inputs are same

## **2. Boolean Algebra**

**Detailed Definition:** A mathematical system for logical operations using binary variables (TRUE/FALSE, 1/0) and logical operators (AND, OR, NOT).

#### **Basic Laws:**

- **Commutative Law:**  $A+B = B+A$ ,  $A \cdot B = B \cdot A$
- **Associative Law:**  $(A+B)+C = A+(B+C)$
- **Distributive Law:**  $A \cdot (B+C) = A \cdot B + A \cdot C$
- **Identity Law:**  $A+0 = A$ ,  $A \cdot 1 = A$

## **3. Combinational Logic Circuits**

**Detailed Definition:** Digital circuits where output depends only on current inputs (no memory).

#### **Examples:**

- **Adders:** Half adder, Full adder
- **Multiplexers:** Selects one of many inputs
- **Decoders:** Converts coded inputs to outputs

## **4. Sequential Logic Circuits**

**Detailed Definition:** Digital circuits where output depends on both current inputs and previous states (have memory).

#### **Examples:**

- **Flip-flops:** Basic memory elements
- **Registers:** Store multiple bits
- **Counters:** Count clock pulses

## **5. Flip-Flops**

**Detailed Definition:** Basic memory elements that can store one bit of information.

#### **Types:**

- **SR Flip-flop:** Set-Reset

- **JK Flip-flop:** Improved version of SR
- **D Flip-flop:** Delay (stores input value)
- **T Flip-flop:** Toggle

## 6. Registers

**Detailed Definition:** Groups of flip-flops that can store multiple bits of data.

**Types:**

- **Shift Register:** Shifts bits left or right
- **Parallel Register:** Loads all bits at once

## 7. Karnaugh Maps (K-Maps)

**Detailed Definition:** A graphical method used to simplify Boolean algebra expressions.

**Benefits:**

- Visual representation
- Easy minimization
- Reduces circuit complexity

**Video Links:**

- **English:** [Digital Logic Circuits](#)
  - **Hindi:** [Logic Gates in Hindi](#)
- 

## Unit 3: Data Representation and Arithmetic

### 1. Number Systems

#### Binary System (Base 2)

- Uses only 0 and 1
- Fundamental computer language
- Example:  $1011_2 = 11_{10}$

#### Octal System (Base 8)

- Uses digits 0-7
- Shorter representation of binary
- Example:  $75_8 = 61_{10}$

#### Decimal System (Base 10)

- Uses digits 0-9
- Everyday number system
- Example:  $123_{10}$

## Hexadecimal System (Base 16)

- Uses digits 0-9 and A-F
- Compact representation of binary
- Example:  $A5F_{16} = 2655_{10}$

## 2. Data Representation

### Integer Representation

- **Signed Magnitude:** Leftmost bit for sign
- **1's Complement:** Flip all bits
- **2's Complement:** Flip bits and add 1 (most common)

### Floating Point Representation

- For real numbers (decimals)
- **Format:** Sign + Exponent + Mantissa
- Example: IEEE 754 standard

### Character Representation

- **ASCII:** 7-bit code for English characters
- **Unicode:** Supports multiple languages

## 3. Computer Arithmetic

### Binary Addition

$$\begin{array}{r} 1011 \quad (11) \\ + 0110 \quad (6) \\ \hline 10001 \quad (17) \end{array}$$

### Binary Subtraction

- Using 2's complement method

### Binary Multiplication

- Similar to decimal multiplication
- Uses shifting and adding

### Binary Division

- Similar to decimal division
- Uses shifting and subtracting

## 4. Complements

### 1's Complement

- Flip all bits (0→1, 1→0)

- Example:  $1010 \rightarrow 0101$

## 2's Complement

- 1's complement + 1
- Used for signed numbers
- Example:  $1010 \rightarrow 0101 + 1 = 0110$

## Video Links:

- **English:** [Number Systems and Data Representation](#)
  - **Hindi:** [Data Representation in Hindi](#)
- 

## Unit 4: Basic Computer Organization and Design

### 1. Bus Organization

**Detailed Definition:** A communication system that transfers data between computer components using shared pathways.

#### Types of Buses:

- **Data Bus:** Carries data between components
- **Address Bus:** Carries memory addresses
- **Control Bus:** Carries control signals

### 2. Micro-operations

**Detailed Definition:** Elementary operations performed on data stored in registers.

#### Types:

- **Register Transfer:** Move data between registers
- **Arithmetic:** Add, subtract, increment
- **Logic:** AND, OR, NOT operations
- **Shift:** Shift bits left or right

### 3. Instruction Codes and Formats

**Detailed Definition:** Binary codes that tell the computer what operation to perform.

#### Instruction Parts:

- **Operation Code (Opcode):** What to do
- **Operand:** Data to operate on
- **Addressing Mode:** How to find operand

### 4. Hardwired vs Microprogrammed Control

#### Hardwired Control

- Control signals generated by logic circuits

- Fast but inflexible
- Used in RISC processors

### **Microprogrammed Control**

- Control signals stored in memory
- Slower but flexible
- Used in CISC processors

## **5. Instruction Cycle**

**Detailed Definition:** The sequence of steps a CPU follows to execute an instruction.

### **Steps:**

1. **Fetch:** Get instruction from memory
2. **Decode:** Understand what to do
3. **Execute:** Perform the operation
4. **Store:** Save the result

## **6. Pipelining**

**Detailed Definition:** A technique where multiple instructions are overlapped in execution to improve performance.

### **Stages:**

- Instruction Fetch (IF)
- Instruction Decode (ID)
- Execute (EX)
- Memory Access (MEM)
- Write Back (WB)

## **7. Interrupts**

**Detailed Definition:** Signals that temporarily halt normal program execution to handle urgent events.

### **Types:**

- **Hardware Interrupts:** From external devices
- **Software Interrupts:** From programs
- **Exceptions:** Error conditions

### **Video Links:**

- **English:** [Computer Organization](#)
- **Hindi:** [CPU Organization in Hindi](#)

## **Unit 5: Processors**

### **1. General Register Organization**

**Detailed Definition:** CPU design that uses multiple general-purpose registers for temporary data storage.

#### **Benefits:**

- Faster data access
- Reduced memory access
- Better performance

### **2. Stack Organization**

**Detailed Definition:** A LIFO (Last-In-First-Out) data structure used for temporary storage.

#### **Operations:**

- **PUSH:** Add item to stack
- **POP:** Remove item from stack

### **3. Addressing Modes**

**Detailed Definition:** Different ways of specifying the location of operands in instructions.

#### **Types:**

- **Immediate:** Operand in instruction itself
- **Direct:** Address in instruction
- **Indirect:** Address of address in instruction
- **Register:** Operand in register
- **Indexed:** Address + index register

### **4. RISC vs CISC Architectures**

#### **RISC (Reduced Instruction Set Computer)**

- Fewer, simpler instructions
- Fixed instruction length
- Hardwired control
- Example: ARM processors

#### **CISC (Complex Instruction Set Computer)**

- Many, complex instructions
- Variable instruction length
- Microprogrammed control

- Example: Intel x86 processors

## 5. Multicore Processors

**Detailed Definition:** A single computing component with two or more independent processing units (cores).

### Benefits:

- Parallel processing
- Better multitasking
- Improved performance

## 6. Graphics Processing Units (GPUs)

**Detailed Definition:** Specialized processors designed for rendering graphics and parallel computations.

### Features:

- Thousands of simple cores
- Massive parallelism
- Used in gaming, AI, scientific computing

### Video Links:

- English: [Processor Architecture](#)
  - Hindi: [RISC vs CISC in Hindi](#)
- 

## Unit 6: Memory and Input/Output Organization

### 1. Memory Hierarchy

**Detailed Definition:** The arrangement of different types of memory in levels based on speed, size, and cost.

#### Levels (Fastest to Slowest):

1. **Registers:** Inside CPU, very fast, very small
2. **Cache:** Fast, small, expensive
3. **Main Memory (RAM):** Medium speed, medium size
4. **Secondary Storage:** Slow, large, cheap (HDD, SSD)

### 2. Types of Memory

#### RAM (Random Access Memory)

- Volatile (loses data when power off)
- Read and write capability
- **Types:** SRAM (faster), DRAM (cheaper)

## **ROM (Read Only Memory)**

- Non-volatile (retains data)
- Read-only normally
- **Types:** PROM, EPROM, EEPROM

## **3. Cache Memory**

**Detailed Definition:** Small, fast memory between CPU and main memory that stores frequently used data.

### **Levels:**

- **L1 Cache:** Inside CPU, fastest
- **L2 Cache:** Slower than L1, larger
- **L3 Cache:** Shared between cores

## **4. Input-Output Interface**

**Detailed Definition:** Hardware and software that enables communication between CPU and I/O devices.

### **Functions:**

- Data buffering
- Error detection
- Protocol conversion

## **5. Modes of Data Transfer**

### **Programmed I/O**

- CPU directly controls I/O
- Simple but inefficient
- CPU waits for I/O completion

### **Interrupt-driven I/O**

- I/O device interrupts CPU when ready
- Better CPU utilization
- Still involves CPU for data transfer

### **Direct Memory Access (DMA)**

- Special controller transfers data directly to memory
- CPU free during transfer
- Most efficient method

### **Video Links:**

- **English:** [Memory Hierarchy and I/O](#)

- **Hindi:** [Computer Memory in Hindi](#)
- 

## Unit 7: Advanced Topics in Computer Architecture

### 1. Performance Measurement

#### Clock Rate

- Cycles per second (Hz)
- Higher = faster, but not always better

#### Instructions Per Second

- MIPS (Million Instructions Per Second)
- FLOPS (Floating Point Operations Per Second)

#### Benchmarks

- Standard tests to compare performance
- Example: SPEC, Geekbench

### 2. Parallel Architectures

**Detailed Definition:** Computer systems with multiple processing elements that work simultaneously to solve problems.

#### Types:

- **SISD:** Single Instruction, Single Data
- **SIMD:** Single Instruction, Multiple Data
- **MISD:** Multiple Instruction, Single Data
- **MIMD:** Multiple Instruction, Multiple Data

### 3. Distributed Architectures

**Detailed Definition:** Multiple computers connected via network working together as a single system.

#### Examples:

- **Cluster Computing:** Group of connected computers
- **Grid Computing:** Geographically distributed resources
- **Cloud Computing:** Internet-based computing services

### 4. Modern Design Trends

#### Multi-core Processors

- Multiple processors on single chip
- Standard in modern computers

#### Quantum Computing

- Uses quantum bits (qubits)
- Can solve complex problems faster

### **Neuromorphic Computing**

- Mimics human brain structure
- Efficient for AI applications

### **3D Chip Stacking**

- Multiple layers of circuits
- Saves space, improves performance

## **5. Emerging Technologies**

- **Optical Computing:** Uses light instead of electricity
- **DNA Computing:** Uses biological molecules
- **Reversible Computing:** Reduces energy consumption

### **Video Links:**

- **English:** [Advanced Computer Architecture](#)
  - **Hindi:** [Parallel Processing in Hindi](#)
- 

## **Important Concepts Summary**

### **Memory Types Comparison:**

Type	Speed	Volatility	Cost	Use
Registers	Fastest	Volatile	Highest	CPU internal
Cache	Very Fast	Volatile	High	CPU-Memory bridge
RAM	Fast	Volatile	Medium	Main memory
ROM	Slow	Non-volatile	Low	Firmware
SSD	Medium	Non-volatile	Medium	Storage
HDD	Slowest	Non-volatile	Lowest	Mass storage

### **Processor Performance Factors:**

1. **Clock Speed:** GHz rating
2. **Cache Size:** L1, L2, L3 cache

3. **Number of Cores:** Parallel processing capability
4. **Architecture:** RISC vs CISC
5. **Instruction Set:** Complexity and efficiency

#### **Data Transfer Methods:**

1. **Programmed I/O:** Simplest, CPU-intensive
2. **Interrupt-driven I/O:** Better CPU utilization
3. **DMA:** Most efficient, uses separate controller

#### **Career Applications:**

- CPU Design Engineer
- Computer Architect
- Embedded Systems Engineer
- Hardware Developer
- Systems Analyst

**Final English Video:** [Computer Architecture Full Course](#)

**Final Hindi Video:** [Computer Architecture Complete Course](#)