1. Perform basic Image Handling and processing operations on the image. • Read an image in python

and Convert an Image to Grayscale

AIM:

To Perform Basic Operations to Read Image and Convert to Grayscale using Python

PROGRAM

import cv2

import numpy as np

kernel = np.ones((5,5),np.uint8)

print(kernel)

path = r"C:\Users\ACER\Downloads\Buagti.jpg"

img =cv2.imread(path)

imgGray = cv2.cvtColor(img,cv2.COLOR_BGR2GRAY)

cv2.imshow("GrayScale",imgGray)

cv2.waitKey(0)

INPUT





2. Perform basic Image Handling and processing operations on the image. • Read an image in python and Convert an Image to Blur using GaussianBlur.

AIM:

To Perform Basic Operations to Read Image and Convert to Blur using GaussianBlur.

PROGRAM:

import cv2

import numpy as np

kernel = np.ones((5,5),np.uint8)

print(kernel)

path = r"C:\Users\ACER\Downloads\Waterfall .jpg"

img =cv2.imread(path)

imgGray = cv2.cvtColor(img,cv2.COLOR_BGR2GRAY)

imgBlur = cv2.GaussianBlur(imgGray,(7,7),0)

cv2.imshow("Img Blur",imgBlur)

cv2.waitKey(0)

INPUT:





3. Perform basic Image Handling and processing operations on the image• Read an image in python and Convert an Image to show outline using Canny function

AIM: To Perform Basic Operations to Convert image to show outline Canny function in Python.

PROGRAM:

import cv2

import numpy as np

kernel = np.ones((5,5),np.uint8)

print(kernel)

path = r"C:\Users\ACER\Downloads\MOUNTAIN.jpg"

img =cv2.imread(path)

imgGray = cv2.cvtColor(img,cv2.COLOR_BGR2GRAY)

imgBlur = cv2.GaussianBlur(imgGray,(7,7),0)

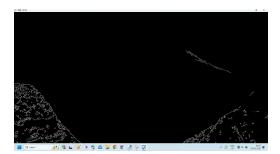
imgCanny = cv2.Canny(imgBlur,100,200)

cv2.imshow("Img Canny",imgCanny)

cv2.waitKey(0)

INPUT:





4. Perform basic Image Handling and processing operations on the image • Read an image in python and Dilate an Image using Dilate function.

AIM: To Perform Basic Operations to Read Image and Dilate an Image using Python.

PROGRAM:

import cv2

import numpy as np

kernel = np.ones((5,5),np.uint8)

print(kernel)

path = r"C:\Users\ACER\Downloads\Waterfall .jpg"

img =cv2.imread(path)

imgGray = cv2.cvtColor(img,cv2.COLOR BGR2GRAY)

imgBlur = cv2.GaussianBlur(imgGray,(7,7),0)

imgCanny = cv2.Canny(imgBlur,100,200)

imgDilation = cv2.dilate(imgCanny,kernel, iterations = 10)

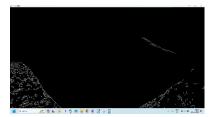
imgEroded = cv2.erode(imgDilation,kernel,iterations=2)

cv2.imshow("Img Erosion",imgEroded)

cv2.waitKey(0)

INPUT:





5. Perform basic Image Handling and processing operations on the image • Read an image in python and Erode an Image using erode function

AIM: The Aim of the experiment is to Read an image in python and Erode an Image using erode function.

PROGRAM:

import cv2

import numpy as np

kernel = np.ones((5,5),np.uint8)

print(kernel)

path = r"C:\Users\ACER\Downloads\MICKYMOUSE.JPG"

img =cv2.imread(path)

imgGray = cv2.cvtColor(img,cv2.COLOR BGR2GRAY)

imgBlur = cv2.GaussianBlur(imgGray,(7,7),0)

imgCanny = cv2.Canny(imgBlur,100,200)

imgDilation = cv2.dilate(imgCanny,kernel, iterations = 10)

imgEroded = cv2.erode(imgDilation,kernel,iterations=2)

cv2.imshow("Img Erosion",imgEroded)

cv2.waitKey(0)

INPUT:





6. Perform basic video processing operations on the captured video • Read captured video in python and display the video, in slow motion and in fast motion.

AIM: The Aim of the Experiment is to Read captured video in python and display the video, in slow motion and in fast motion.

PROGRAM: import cv2

cap = cv2.VideoCapture(r"C:\Users\ACER\Pictures\www.5MovieRulz.gg - Tiger
Nageswara Rao (2023) Telugu DVDScr x264 MP3 750MB.mkv")

if not cap.isOpened():
 print("Error opening video file")

while cap.isOpened():
 ret, frame = cap.read()
 if ret:
 cv2.imshow('Frame', frame)
 if cv2.waitKey(250) & 0xFF == ord('q'):
 break
 else:
 break

cap.release()
cv2.destroyAllWindows()

INPUT:

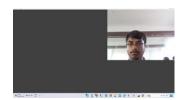




7. Capture video from web Camera and Display the video, in slow motion and in fast motion operations on the captured video

AIM: The Aim is to Capture video from web Camera and Display the video, in slow motion and in fast motion operations on the captured video.

```
PROGRAM: import cv2
cap = cv2.VideoCapture(0)
height = int(cap.get(cv2.CAP PROP FRAME HEIGHT))
width = int(cap.get(cv2.CAP_PROP_FRAME_WIDTH))
fps = cap.get(cv2.CAP_PROP_FPS)
path = "output.mp4"
fourcc = cv2.VideoWriter_fourcc(*'mp4v')
output = cv2.VideoWriter(path, fourcc, 2, (width, height))
while True:
  ret, frame = cap.read()
  cv2.imshow("frame", frame)
  output.write(frame)
  k = cv2.waitKey(24)
  if k == ord("q"):
    break
cap.release()
output.release()
cv2.destroyAllWindows()
```



8. Scaling an image to its Bigger and Smaller sizes.

AIM:

The Aim is resize the image from bigger to smaller size.

PROGRAM:

import cv2

import numpy as np

kernel = np.ones((5,5),np.uint8)

img =

 $cv2.imread (r"C:\Users\ACER\Downloads\MICKYMOUSE.JPG", cv2.IMREAD_COLOR)$

img = cv2.resize(img,(600,600))

cv2.imshow("image",img)

cv2.waitKey(0)

INPUT:





9. Perform Rotation of an image to clockwise and counter clockwise direction.

AIM:

The Aim of the Experiment is to perform Rotation of an image along 90 degree.

PROGRAM:

import cv2

path = r"C:\Users\ACER\Downloads\MOUNTAIN.jpg"

src = cv2.imread(path)

window_name = 'Image'

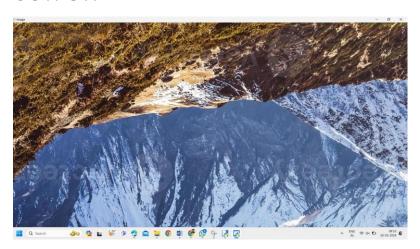
image = cv2.rotate(src, cv2.ROTATE_180)

cv2.imshow(window_name, image)

cv2.waitKey(0)

INPUT:





ROTATION ALONG 180 DEGREE

AIM:

The Aim of the Experiment is to perform Rotation of an image along 180 degree.

PROGRAM:

import cv2

path = r"C:\Users\ACER\Downloads\MOUNTAIN.jpg"

src = cv2.imread(path)

window_name = 'Image'

image = cv2.rotate(src, cv2.ROTATE_90_COUNTERCLOCKWISE)

cv2.imshow(window_name, image)

cv2.waitKey(0)



10.ROTATION ALONG 270 DEGREE

AIM:

The Aim of the Experiment is to perform Rotation of an image along 270 degree.

PROGRAM:

import cv2

path = r"C:\Users\ACER\Downloads\MICKYMOUSE.JPG"

src = cv2.imread(path)

image_rotated_270 = cv2.rotate(src, cv2.ROTATE_90_CLOCKWISE)

cv2.imshow('Rotated Image 270', image_rotated_270)

cv2.waitKey(0)

cv2.destroyAllWindows()

