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EXPERIENCE

Facebook Al Research | Software Engineer Intern

C++, Python, PyTorch, Torchscript | New York, NY (Remote) | May - Sep 2020

- · Working with the AI Platform team to design and implement highperformance NLP building blocks (Tokenizer, Vector, Vocab) for PyTorch
- Training a BERT model with masked-language modeling and next-sentence tasks to improve performance on IWSLT'14 English-German translation dataset
- Supporting upcoming Pytorch releases to facilitate NLP research and demonstrate feasability of new features for internal adoption

Lyft Level 5 | Software Engineer Intern - Autonomous Driving C++, Python, TensorFlow, OpenCV, BigQuery | Palo Alto, CA | Jan - Apr 2020

- Trained new classifier with the Perception team capable of detecting traffic light bulb shapes with 90%+ accuracy on an extremely unbalanced dataset
- Designed a regression test suite which can provide a binary decision for engineers when deciding whether to release a new model to the vehicle

Facebook Al Research | Software Engineer Intern

C++, Python, OpenCV, PyTorch, Presto | Menlo Park, CA | May - Aug 2019

- Worked with the Computer Vision team to create a face detection and tracking pipeline running on all Facebook videos in real-time
- Benchmarked precision and recall of various detection models (Mask R-CNN, DFSD, Viola-Jones) and tracking algorithms on a 600k SOA video dataset
- Collaborated with leading researchers (Ross Girschick and Yufei Wang) to anonymize faces in the video dataset using detection and tracking results

Microsoft | Software Engineer Intern

C#, Redis, Kusto, Azure | Redmond, WA | Aug - Dec 2018

- Architected Ownership Enforcer (OE) service on the Azure Infrastructure team to enforce PR code reviews for compliance and security assurance
- · Improved performance of OE service by designing multi-layered a Redis caching pipeline from the ground up, reducing all API calls by 150%

Microsoft | Software Engineer Intern

C#, C++, Unity, XAML, HoloLens | Vancouver, BC | Jan - Apr 2018

• Worked on the 3D Viewer team to create a cross-platform Windows/HoloLens app for viewing 3D files used by 3 million+ monthly users

Watonomous | Path Planning Engineer - Autonomous Driving C++, ROS, RViz, CMake | Waterloo, ON | Sep 2017 - Apr 2019

• Collaborating on a student-led design team to transform a Chevrolet Bolt EV into a Level 4 autonomous vehicle for the SAE AutoDrive Challenge

PROJECTS

Flappy Goose | Game in an Embedded RTOS Environment

Recreated Flappy Bird game using a Keil MCB1700 board in a real-time OS

Study Space | PennApps XVI (Google Prize Winner)

• Created IoT device and companion app to display real-time occupancy of specific locations on campus using 'Android Nearby' communication platform

EDUCATION

University of Waterloo

2016 - 2021

BASc in Honours Mechatronics Engineering, Co-op Option in Artificial Intelligence

Charles III University of Madrid

International Exchange Semester

Relevant Courses

- CS231n Convolutional Neural Networks (Stanford)
- Practical Deep Learning for Coders (fast.ai)
- Machine Learning (Coursera)

SKILLS

Languages

Python

• C++

• C#

Java

SOL

JavaScript

Technologies/Frameworks

PyTorch

OpenCV

Pandas

NumPy

ROS

TensorFlow

Tools

• Git

Jupyter

AWS

Linux

BigQuery

Redis

ACCOMPLISHMENTS

- Recipient of \$70,000+ in scholarships
 - · Int'l Experience Award
 - Google Prize @ PennApps XVI
 - 3rd Place @ IEEE Hardware Hackathon

HOBBIES/INTERESTS

Varsity

Running

Ultimate

Mentorship

Road Cycling • Robotics