

EE5175: Image Signal Processing

Lab-12

Non-local Means Filtering

In this experiment, we will implement non-local means (NLM) filtering algorithm for the application of denoising.

You are given a noisy image, \mathbf{g} (`krishna_0.001.png`), corresponding to a latent image, \mathbf{f} (`krishna.png`), corrupted with additive Gaussian noise of mean 0 and variance 0.001. Your task is to apply NLM filtering on \mathbf{g} following the steps in the given pseudocode to arrive at the denoised image, $\hat{\mathbf{f}}$.

The parameters of the algorithm are the search neighbourhood radius W , the similarity neighbourhood radius W_{sim} and the filter parameter σ_{NLM} . A radius of W at a pixel denotes a window size of $(2W + 1) \times (2W + 1)$ around that pixel. The same applies to W_{sim} .

Q1. Show plots between the PSNR between \mathbf{f} and $\hat{\mathbf{f}}$ (y-axis) for different NLM filter parameter values $\sigma_{NLM} = 0.1$ to 0.5 in steps of 0.1 (x-axis) for the following search radius and similarity radius settings:

- (a) $W = 3, W_{sim} = 3$,
- (b) $W = 5, W_{sim} = 3$.

Show two plots in the same window with two different colours corresponding to (a) and (b). Compare the PSNR plots with the baseline PSNR between the noisy image \mathbf{g} and the latent image \mathbf{f} .

Q2. We will now compare NLM filtering with the traditional Gaussian filtering. Denoise \mathbf{g} using space-invariant Gaussian filter with $\sigma_g = 0.1$ to 0.5 in steps of 0.1 having a kernel window size of 7×7 for all σ_g values. Calculate the PSNR between the denoised images and \mathbf{f} . Add this plot to the plot window in **Q1**.

For the following filtering settings: (a) $W = 5, W_{sim} = 3, \sigma_{NLM} = 0.5$ for the NLM filtering, and (b) $\sigma_g = 1.0$ for Gaussian filtering, and at the following pixel locations \mathbf{p} : (i) row = 31, column = 46, and (ii) row = 38, column = 58, (total four combinations), do **Q3** and **Q4**.

Q3. Show the 11×11 filter (kernel) as an image.

Q4. Show the 11×11 image patch from the noisy image and the denoised images.

Pseudocode:

Read the noisy image \mathbf{g} and the latent image \mathbf{f} in the intensity range $[0, 1]$

for every pixel position \mathbf{p} **do**

// Obtain similarity neighbourhood around \mathbf{p}

Take the RGB patch \mathcal{N}_p around \mathbf{p} of radius W_{sim} in the image \mathbf{g}

Vectorize the patch \mathcal{N}_p as a column vector \mathbf{V}_p

// Form the filter \mathbf{w}_p at pixel \mathbf{p} .

// It can be formed as a 1D vector and visualized as a 2D matrix.

// We form a single filter for all three colour components.

for every pixel position \mathbf{q} around \mathbf{p} within radius W **do**

// Obtain similarity neighbourhood around \mathbf{q}

Take the RGB patch \mathcal{N}_q around \mathbf{q} of radius W_{sim} in the image \mathbf{g}

Vectorize the patch \mathcal{N}_q as a column vector \mathbf{V}_q

The value of the filter \mathbf{w}_p for the position \mathbf{q} is given by

$$\mathbf{w}_p(q) = \exp \left(\frac{-(\mathbf{V}_p - \mathbf{V}_q)^T (\mathbf{V}_p - \mathbf{V}_q)}{\sigma_{NLM}^2} \right)$$

end for

Normalize $\mathbf{w}_p \leftarrow \mathbf{w}_p / \sum \mathbf{w}_p$

// Obtain search neighbourhood patch around \mathbf{p}

Take the RGB patches $\mathcal{N}_p^W(\mathbf{R})$, $\mathcal{N}_p^W(\mathbf{G})$, $\mathcal{N}_p^W(\mathbf{B})$ around \mathbf{p} of radius W in the image \mathbf{g} separately

Vectorize them as column vectors $\mathbf{V}_p^W(\mathbf{R})$, $\mathbf{V}_p^W(\mathbf{G})$, $\mathbf{V}_p^W(\mathbf{B})$

// Calculate the filtered output at pixel \mathbf{p}

// Use the same filter for all colour channels

The intensity at the output pixel \mathbf{p} for each colour channel is given by

$$\hat{\mathbf{f}}(\mathbf{p}, \mathbf{R}) = \mathbf{V}_p^W(\mathbf{R})^T \mathbf{w}_p$$

$$\hat{\mathbf{f}}(\mathbf{p}, \mathbf{G}) = \mathbf{V}_p^W(\mathbf{G})^T \mathbf{w}_p$$

$$\hat{\mathbf{f}}(\mathbf{p}, \mathbf{B}) = \mathbf{V}_p^W(\mathbf{B})^T \mathbf{w}_p$$

// Calculate the PSNR

// MSE : Mean Squared Error

// PSNR : Peak Signal-to-Noise Ratio

// The operation here assumes \mathbf{f} and $\hat{\mathbf{f}}$ are column vectors.

MSE = $(\mathbf{f} - \hat{\mathbf{f}})^T (\mathbf{f} - \hat{\mathbf{f}})$ / (total number of pixels including all colour channels)

$$\text{PSNR} = 10 \log_{10} \left(\frac{1}{MSE} \right)$$

end for

Note:

The general formula for PSNR is $10 \log_{10} \left(\frac{\text{MAX} * \text{MAX}}{\text{MSE}} \right)$, where MAX is the maximum image intensity value. We use MAX=1 in this experiment.