```
import torch
import torch.nn as nn
import torch.optim as optim
from torchvision import datasets, transforms
from torch.utils.data import DataLoader
import numpy as np
import matplotlib.pyplot as plt
class MNISTWithBoundingBoxes:
          def __init__(self, train=True):
                    self.dataset = datasets.MNIST(
                              root='./data',
                              train=train.
                              download=True,
                              transform=transforms.ToTensor()
                    )
          def __getitem__(self, idx):
                    img, label = self.dataset[idx]
                    img_np = img.squeeze(0).numpy() # Convert to numpy for bbox calculation
                    # Calculate the bounding box for the digit
                    rows, cols = np.where(img_np > 0)
                    y_min, x_min = rows.min(), cols.min()
                    y_max, x_max = rows.max(), cols.max()
                    # Normalize the bounding box coordinates
                    bbox = torch.tensor([x_min / 28, y_min / 28, x_max / 28, y_max / 28], dtype=torch.float32)
                    return img, label, bbox
          def __len__(self):
                    return len(self.dataset)
  # Initialize DataLoaders
train_dataset = MNISTWithBoundingBoxes(train=True)
test_dataset = MNISTWithBoundingBoxes(train=False)
train_loader = DataLoader(train_dataset, batch_size=32, shuffle=True)
test_loader = DataLoader(test_dataset, batch_size=32, shuffle=False)
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class LocalizationModel(nn.Module):
    def __init__(self):
        super(LocalizationModel, self).__init__()
        self.backbone = nn.Sequential(
            nn.Conv2d(1, 16, kernel_size=3, stride=1, padding=1),
            nn.ReLU(),
            nn.MaxPool2d(2, 2),
           nn.Conv2d(16, 32, kernel_size=3, stride=1, padding=1),
           nn.ReLU(),
           nn.MaxPool2d(2, 2)
        self.fc = nn.Sequential(
           nn.Flatten(),
           nn.Linear(32 * 7 * 7, 128),
           nn.ReLU(),
           nn.Linear(128, 4) # 4 outputs: [x_min, y_min, x_max, y_max]
    def forward(self, x):
        features = self.backbone(x)
        bbox = self.fc(features)
        return bbox
# Initialize model
device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
model = LocalizationModel().to(device)
criterion = nn.MSELoss() # Mean Squared Error for bounding box regression
optimizer = optim.Adam(model.parameters(), lr=0.001)
epochs = 5
for epoch in range(epochs):
 model.train()
 total_loss = 0
 for imgs, _, bboxes in train_loader:
      imgs, bboxes = imgs.to(device), bboxes.to(device)
      optimizer.zero_grad()
      pred_bboxes = model(imgs)
      loss = criterion(pred_bboxes, bboxes)
      loss.backward()
      optimizer.step()
      total_loss += loss.item()
      print(f"Epoch [{epoch+1}/{epochs}], Loss: {total_loss / len(train_loader):.4f}")
₹ Epoch [5/5], Loss: 0.0001
model.eval()
with torch.no_grad():
 for imgs, _, bboxes in test_loader:
      imgs, bboxes = imgs.to(device), bboxes.to(device)
      pred_bboxes = model(imgs)
      print("Predicted BBox:", pred_bboxes[0].cpu().numpy())
      print("Ground Truth BBox:", bboxes[0].cpu().numpy())
      break
Predicted BBox: [0.20574346 0.25867143 0.7338158 0.93095803]
     Ground Truth BBox: [0.21428572 0.25
                                             0.75
```