

# INTRODUCTION TO BAYESIAN METHODS

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SYS 6014 Decision Analysis

# BIG PICTURE: DATA-DRIVEN DECISION-MAKING

You have a set of possible actions you can take.

You have a prediction model or classification model that enables you to *differentiate* between cases, based on data.

Your decision model then enables you to discriminate — to make the “right” intervention for each different case, rather than just choosing the same action for all cases.

# PREDICTIVE MODELS

Predictive models may take many different forms.

- They may use many, many different types of data
- They may be built using different analytic techniques: statistical regression, machine learning,...

We embrace this diversity of approaches.

But: we want our predictions to include *uncertainty* information.

So: want outputs in form of *probability distributions* over decision-state variables

# PROBABILISTIC PREDICTIONS

# BAYESIAN METHODS

# BAYESIAN METHODS: INTRODUCTION VIA SIMPLE EXAMPLE

(Related readings: Hoff Ch. 1)

Suppose you want to estimate the fraction of a population that is infected with some disease.

$\theta \in [0, 1]$  : true value

Test a random sample of 20 from the population.

$Y \in \{0, 1, \dots, 20\}$  : # of positive results.

Question: What does realized value of  $Y$  tell us about the true value of  $\theta$ ?

$Y|\theta \sim \text{binomial}(20, \theta)$ : For  $y = 0, 1, \dots, 20$ ,

$$l(y|\theta) = \Pr(Y = y|\theta) = \binom{20}{y} \theta^y (1 - \theta)^{(20-y)}$$

where  $\binom{n}{k} = \frac{n!}{k!(n-k)!}$

$l(y|\theta)$  called the *likelihood function*.

Idea: For any  $0 < \theta < 1$ , all values of  $Y$  are *possible*, but some are more likely than others.

The likelihood function tells us how likely is each possible observation, for a given  $\theta$ .

If, say,  $Y = 15$ , that provides evidence that  $\theta$  is not small.

# PRIOR INFORMATION

Suppose we have some background knowledge about the likely values of  $\theta$ . Represent this knowledge by means of a *prior distribution*  $\pi(\theta)$  over  $[0, 1]$ . Obviously, there are many (infinitely many) possible such distributions. For convenience, we typically choose to model priors as chosen from a parametrized family of distributions.



# THE BETA DISTRIBUTION

$$\pi(\theta) \sim \text{beta}(a, b)$$

For our case, let's suppose our prior beliefs correspond to:

$$\pi(\theta) \sim \text{beta}(2, 20)$$

# BAYES THEOREM

Let  $\pi(\theta|y)$  denote our *posterior distribution* over values of  $\theta$ .

This means: our *updated* beliefs about the likelihood that  $\theta$  takes various values, *after* we've received our test results.

Bayes Theorem says:

$$\pi(\theta|y) = \frac{I(y|\theta)\pi(\theta)}{\Pr\{Y = y\}} = \frac{I(y|\theta)\pi(\theta)}{\int_{\Theta} I(y|\tilde{\theta})\pi(\tilde{\theta})d\tilde{\theta}}$$