

# Argument Sum Rules From Homogeneous Linear Differential Equations Of Constant Coefficients Conjecture

<https://github.com/Nazgand/nazgandMathBook>

Mark Andrew Gerads: [Nazgand@Gmail.Com](mailto:Nazgand@Gmail.Com)

August 3, 2024

## Abstract

The goal of this paper is to conjecture a seemingly fundamental calculus fact.

## 1 Assumptions and definitions

A [homogeneous linear differential equation of constant coefficients] has the form

$$0 = \sum_{k=0}^n a_k \frac{\partial^k}{\partial z^k} f(z) = \sum_{k=0}^n a_k f^{(k)}(z) \quad (1.1)$$

where  $\forall k, a_k \in \mathbb{C}, n \in \mathbb{Z}^+, a_n \neq 0$ , and  $f : \mathbb{C} \rightarrow \mathbb{C}$  is differentiable at least  $n$  times everywhere. Let  $g_0(z), \dots, g_{n-1}(z)$  be solutions that are a basis of the vector space of solutions of the [homogeneous linear differential equation of constant coefficients]. To be clear:

$$\text{Solutions} = \left\{ h(z) \mid 0 = \sum_{k=0}^n a_k h^{(k)}(z) \right\} = \left\{ \sum_{k=0}^{n-1} b_k g_k(z) \mid b_k \in \mathbb{C} \right\} \quad (1.2)$$

Let us define a column vector and clarify its transpose (a row vector):

$$v(z_0) = \begin{pmatrix} g_0(z_0) \\ \vdots \\ g_{n-1}(z_0) \end{pmatrix}, v(z_1)^T = (g_0(z_1) \quad \dots \quad g_{n-1}(z_1)) \quad (1.3)$$

## 2 Main conjecture with 2 arguments

I conjecture there exists a complex-valued constant  $n$  by  $n$  symmetric matrix  $A$  ( $A = A^T$ ) such that

$$f(z_0 + z_1) = v(z_1)^T A v(z_0) = v(z_0)^T A v(z_1) \quad (2.1)$$

### 2.1 A reason $A$ is symmetric

Suppose instead of a symmetric matrix  $A$ , we find a matrix  $B$  such that

$$f(z_0 + z_1) = v(z_1)^T B v(z_0) \quad (2.2)$$

Then take the transpose of the equation and substitute  $z_0 \rightarrow z_1, z_1 \rightarrow z_0$ , resulting in the following equation:

$$f(z_0 + z_1) = v(z_1)^T B^T v(z_0) \quad (2.3)$$

Average both equations:

$$f(z_0 + z_1) = v(z_1)^T \frac{B + B^T}{2} v(z_0) \quad (2.4)$$

Note that we can set  $A = \frac{B+B^T}{2}$  because it is symmetric. □

## 3 Motivation

The first thing of note is

$$f(z) \in \text{Solutions} \quad (3.1)$$

The next thing of note is that offsetting the function's argument by a constant results in the same differential equation, with a solution of the same form.

$$\frac{\partial}{\partial z} z_0 = 0 \Rightarrow f(z + z_0) \in \text{Solutions} \quad (3.2)$$

One thing to note is that all constants are replaced with functions of the constant  $z_0$ . This allows us that change  $z_0$  from a constant to a variable and still have working math when we consider all possible constants  $z_0$ .

$$\left[ \frac{\partial}{\partial z} z_0 = 0 \wedge f(z + z_0) \in \text{Solutions} \right] \Rightarrow \exists b_{0,k} : \mathbb{C} \rightarrow \mathbb{C}, f(z + z_0) = \sum_{k=0}^{n-1} b_{0,k}(z_0) g_k(z) \quad (3.3)$$

Because we were careful about making all constants a function of the constant  $z_0$ , we can make  $z_0$  a variable with the conclusion

$$\exists b_{0,k} : \mathbb{C} \rightarrow \mathbb{C}, f(z + z_0) = \sum_{k=0}^{n-1} b_{0,k}(z_0) g_k(z) \quad (3.4)$$

Follow the same logic with a constant named  $z_1$ :

$$\frac{\partial}{\partial z} z_1 = 0 \Rightarrow f(z + z_1) \in \text{Solutions} \quad (3.5)$$

$$\left[ \frac{\partial}{\partial z} z_1 = 0 \wedge f(z + z_1) \in \text{Solutions} \right] \Rightarrow \exists b_{1,k} : \mathbb{C} \rightarrow \mathbb{C}, f(z + z_1) = \sum_{k=0}^{n-1} b_{1,k}(z_1) g_k(z) \quad (3.6)$$

$$\exists b_{1,k} : \mathbb{C} \rightarrow \mathbb{C}, f(z + z_1) = \sum_{k=0}^{n-1} b_{1,k}(z_1) g_k(z) \quad (3.7)$$

Now we substitute  $z \rightarrow z_1$  in (3.4), and we substitute  $z \rightarrow z_0$  in (3.7), and combine them.

$$\exists b_{0,k} : \mathbb{C} \rightarrow \mathbb{C}, \exists b_{1,k} : \mathbb{C} \rightarrow \mathbb{C}, f(z_0 + z_1) = \sum_{k=0}^{n-1} b_{0,k}(z_0) g_k(z_1) = \sum_{k=0}^{n-1} b_{1,k}(z_1) g_k(z_0) \quad (3.8)$$

We now have 2 ways of viewing  $f(z_0 + z_1)$ , and we could imagine a sum of a line from the front, a sum of a line from the right, and 'deduce' that the true form is probably the sum of a square from above, which leads to the matrix form conjectured, but this is slightly sketchy logic that needs more rigor.

## 4 LEAN 4 code

This conjecture has been formalized in LEAN 4:

<https://github.com/Nazgand/NazgandLean4/blob/master/NazgandLean4/ArgumentSumConjecture.lean>

For a given differential equation, if the conjecture is true for 1 basis, then it is true for all bases.

## 5 Conjecture generalized to positive integer amounts of arguments in addition to 2

The following statements use the same assumptions and definitions as the main conjecture.

### 5.1 1 argument

The following statement, which I call ArgSumCon(1), is known to be true and seems to have been proved by Euler, though I have not seen a rigorous formalized proof yet.

$$\exists c(k_0) \in \mathbb{C}, f(z_0) = \sum_{k_0=0}^{n-1} c(k_0) g_{k_0}(z_0) \quad (5.1)$$

### 5.2 2 arguments

The following statement, which I call ArgSumCon(2), is equivalent to the main conjecture, minus the symmetry requirement.

$$\exists c(k_0, k_1) \in \mathbb{C}, f(z_0 + z_1) = \sum_{k_0=0}^{n-1} \sum_{k_1=0}^{n-1} c(k_0, k_1) g_{k_0}(z_0) g_{k_1}(z_1) \quad (5.2)$$

### 5.3 3 arguments

The following statement, I call ArgSumCon(3).

$$\exists c(k_0, k_1, k_2) \in \mathbb{C}, f(z_0 + z_1 + z_2) = \sum_{k_0=0}^{n-1} \sum_{k_1=0}^{n-1} \sum_{k_2=0}^{n-1} c(k_0, k_1, k_2) g_{k_0}(z_0) g_{k_1}(z_1) g_{k_2}(z_2) \quad (5.3)$$

### 5.4 m arguments for $m \in \mathbb{Z}^+$

The following statement, I call ArgSumCon(m).

$$\exists c(k_0, k_1, \dots, k_{m-1}) \in \mathbb{C}, f\left(\sum_{k=0}^{n-1} z_k\right) = \sum_{k_0=0}^{n-1} \sum_{k_1=0}^{n-1} \cdots \sum_{k_{m-1}=0}^{n-1} c(k_0, k_1, \dots, k_{m-1}) \prod_{j=0}^{m-1} g_{k_j}(z_j) \quad (5.4)$$

Note ArgSumCon( $m+1$ )  $\Rightarrow$  ArgSumCon( $m$ ), as can be seen by replacing 1 of the variables with 0.