

# Trigonometry

<https://github.com/Nazgand/nazgandMathBook>

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## Abstract

The goal of this paper is to review trigonometry.

## 1 Geometric Foundations

In [Elementary Geometry and Trigonometry.kig] by moving the angle control point to the second quadrant and comparing, we can see

$$\sin\left(\theta + \frac{\pi}{2}\right) = (\cos(\theta)), \cos\left(\theta + \frac{\pi}{2}\right) = -(\sin(\theta)) \quad (1.1)$$

Moreover, we see as  $\theta \rightarrow 0$

$$\lim_{\theta \rightarrow 0} \frac{\sin(\theta)}{\theta} = 0 \quad (1.2)$$

Comparing with [PythagoreanTheorem.png], we find

$$1 = \sin(\theta)^2 + \cos(\theta)^2 \quad (1.3)$$

From [SumOfAnglesSinCos.kig], we get

$$\sin(\alpha + \beta) = \sin(\alpha)\cos(\beta) + \cos(\alpha)\sin(\beta) \quad (1.4)$$

And

$$\cos(\alpha + \beta) = \cos(\alpha)\cos(\beta) - \sin(\alpha)\sin(\beta) \quad (1.5)$$

## 2 Derivatives

**Theorem 2.1.**

$$\frac{\partial}{\partial x} \sin(x) = \cos(x) \quad (2.1)$$

*Proof.*

$$\frac{\partial}{\partial x} \sin(x) = \lim_{h \rightarrow 0} \frac{\sin(x+h) - \sin(x)}{h} \quad (2.2)$$

Use (1.4)

$$\frac{\partial}{\partial x} \sin(x) = \lim_{h \rightarrow 0} \frac{\sin(x)\cos(h) + \cos(x)\sin(h) - \sin(x)}{h} \quad (2.3)$$

Split the limit:

$$\frac{\partial}{\partial x} \sin(x) = \lim_{h \rightarrow 0} \frac{\cos(x)\sin(h)}{h} + \lim_{h \rightarrow 0} \frac{\sin(x)(\cos(h) - 1)}{h} \quad (2.4)$$

Simplify

$$\frac{\partial}{\partial x} \sin(x) = \cos(x) \lim_{h \rightarrow 0} \frac{\sin(h)}{h} + \sin(x) \lim_{h \rightarrow 0} \frac{\cos(h) - 1}{h} \quad (2.5)$$

Use (1.2) on left limit and multiply right limit by  $\frac{\cos(h)+1}{\cos(h)+1}$

$$\frac{\partial}{\partial x} \sin(x) = \cos(x) + \sin(x) \lim_{h \rightarrow 0} \frac{\cos(h)^2 - 1}{h(\cos(h) + 1)} \quad (2.6)$$

Use (1.3)

$$\frac{\partial}{\partial x} \sin(x) = \cos(x) + \sin(x) \lim_{h \rightarrow 0} \frac{\sin(h)^2}{h(\cos(h) + 1)} \quad (2.7)$$

Split the limit:

$$\frac{\partial}{\partial x} \sin(x) = \cos(x) + \sin(x) \lim_{a \rightarrow 0} \frac{\sin(a)}{h} \lim_{b \rightarrow 0} \sin(b) \lim_{c \rightarrow 0} \frac{1}{(\cos(c) + 1)} \quad (2.8)$$

Evaluate using (1.2) again

$$\frac{\partial}{\partial x} \sin(x) = \cos(x) + 1 * 0 * \frac{1}{2} = \cos(x) \quad (2.9)$$

□

**Theorem 2.2.**

$$\frac{\partial}{\partial x} \cos (x) = -\sin (x) \tag{2.10}$$

*Proof.* Use (1.1)

$$\frac{\partial}{\partial x} \cos (x) = \frac{\partial}{\partial x} \sin \left(x + \frac{\pi}{2}\right) \tag{2.11}$$

Use the chain rule:

$$\frac{\partial}{\partial x} \cos (x) = \left(\frac{\partial}{\partial z} \sin (z) : z \rightarrow x + \frac{\pi}{2}\right) \frac{\partial}{\partial x} \left(x + \frac{\pi}{2}\right) \tag{2.12}$$

Simplify

$$\frac{\partial}{\partial x} \cos (x) = \cos \left(x + \frac{\pi}{2}\right) \tag{2.13}$$

Use Use (1.1)

$$\frac{\partial}{\partial x} \cos (x) = -\sin (x) \tag{2.14}$$

□

### 3 Taylor Series

**Theorem 3.1.**

$$\sin (x) = \sum_{k=0}^{\infty} \frac{(-1)^k x^{2k+1}}{(2k+1)!} \tag{3.1}$$

*Proof.* The multiple derivatives cycle through 4 functions. Let  $n \in \mathbb{Z}$ :

$$\frac{\partial^{4n}}{\partial x^{4n}} \sin (x) = \sin (x) \tag{3.2}$$

$$\frac{\partial^{4n+1}}{\partial x^{4n+1}} \sin (x) = \cos (x) \tag{3.3}$$

$$\frac{\partial^{4n+2}}{\partial x^{4n+2}} \sin (x) = -\sin (x) \tag{3.4}$$

$$\frac{\partial^{4n+3}}{\partial x^{4n+3}} \sin (x) = -\cos (x) \tag{3.5}$$

The derivatives at 0 thus cycle through 0, 1, 0, −1. Use [TaylorSeries(0.1)] and simplify out the zeroes. □

**Theorem 3.2.**

$$\cos (x) = \sum_{k=0}^{\infty} \frac{(-1)^k x^{2k}}{(2k)!} \tag{3.6}$$

*Proof.* The multiple derivatives cycle through 4 functions. Let  $n \in \mathbb{Z}$ :

$$\frac{\partial^{4n}}{\partial x^{4n}} \sin (x) = \cos (x) \tag{3.7}$$

$$\frac{\partial^{4n+1}}{\partial x^{4n+1}} \sin (x) = -\sin (x) \tag{3.8}$$

$$\frac{\partial^{4n+2}}{\partial x^{4n+2}} \sin (x) = -\cos (x) \tag{3.9}$$

$$\frac{\partial^{4n+3}}{\partial x^{4n+3}} \sin (x) = \sin (x) \tag{3.10}$$

The derivatives at 0 thus cycle through 1, 0, −1, 0. Use [TaylorSeries(0.1)] and simplify out the zeroes. □