# Argument Sum Rules From Homogeneous Linear Differential Equations Of Constant Coefficients Conjecture

## https://github.com/Nazgand/nazgandMathBook

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#### Abstract

The goal of this paper is to conjecture a seemingly fundamental calculus fact.

A [homogeneous linear differential equation of constant coefficients] has the form

$$0 = \sum_{k=0}^{n} a_k \frac{\partial^k}{\partial z^k} f(z) = \sum_{k=0}^{n} a_k f^{(k)}(z)$$
 (0.1)

where  $\forall k, a_k \in \mathbb{C}, a_n \neq 0$ , and  $f : \mathbb{C} \to \mathbb{C}$  is differentiable everywhere. Let  $g_0(z), \dots, g_{n-1}(z)$  be solutions that span the vector space of solutions of the [homogeneous linear differential equation of constant coefficients]. To be clear:

Solutions = 
$$\left\{ h(z) \mid 0 = \sum_{k=0}^{n} a_k h^{(k)}(z) \right\} = \left\{ \sum_{k=0}^{n-1} b_k g_k(z) \mid b_k \in \mathbb{C} \right\}$$
 (0.2)

Let us define a column vector and clarify its transpose (a row vector):

$$v(z_0) = \begin{pmatrix} g_0(z_0) \\ \vdots \\ g_{n-1}(z_0) \end{pmatrix}, v(z_1)^T = (g_0(z_1) \dots g_{n-1}(z_1))$$
(0.3)

I conjecture there exists a complex-valued constant n by n symmetric matrix A ( $A = A^{T}$ ) such that

$$f(z_0 + z_1) = v(z_1)^T A v(z_0) = v(z_0)^T A v(z_1)$$
(0.4)

### 1 A reason A is symmetric

Suppose instead of a symmetric matrix A, we find a matrix B such that

$$f(z_0 + z_1) = v(z_1)^T B v(z_0)$$
(1.1)

Then take the transpose of the equation and substitute  $z_0 \to z_1, z_1 \to z_0$ , resulting in the following equation:

$$f(z_0 + z_1) = v(z_1)^T B^T v(z_0)$$
(1.2)

Average both equations:

$$f(z_0 + z_1) = v(z_1)^T \frac{B + B^T}{2} v(z_0)$$
(1.3)

Note that we can set  $A = \frac{B+B^T}{2}$  because it is symmetric.

### 2 Motivation

The first thing of note is

$$f(z) \in \text{Solutions}$$
 (2.1)

The next thing of note is that offsetting the function's argument by a constant results in the same differential equation, with a solution of the same form.

$$\frac{\partial}{\partial z} z_0 = 0 \Rightarrow f(z + z_0) \in \text{Solutions}$$
 (2.2)

One thing to note is that all constants are replaced with functions of the constant  $z_0$ . This allows us that change  $z_0$  from a constant to a variable and still have working math when we consider all possible constants  $z_0$ .

$$\left[\frac{\partial}{\partial z}z_0 = 0 \land f(z+z_0) \in \text{Solutions}\right] \Rightarrow \exists b_{0,k} : \mathbb{C} \to \mathbb{C}, f(z+z_0) = \sum_{k=0}^{n-1} b_{0,k}(z_0)g_k(z)$$
 (2.3)

Because we were careful about making all constants a function of the constant  $z_0$ , we can make  $z_0$  a variable with the conclusion

$$\exists b_{0,k} : \mathbb{C} \to \mathbb{C}, f(z+z_0) = \sum_{k=0}^{n-1} b_{0,k}(z_0) g_k(z)$$
(2.4)

Follow the same logic with a constant named  $z_1$ :

$$\frac{\partial}{\partial z}z_1 = 0 \Rightarrow f(z + z_1) \in \text{Solutions}$$
 (2.5)

$$\left[\frac{\partial}{\partial z}z_1 = 0 \land f(z+z_1) \in \text{Solutions}\right] \Rightarrow \exists b_{1,k} : \mathbb{C} \to \mathbb{C}, f(z+z_1) = \sum_{k=0}^{n-1} b_{1,k}(z_1)g_k(z)$$
 (2.6)

$$\exists b_{1,k} : \mathbb{C} \to \mathbb{C}, f(z+z_1) = \sum_{k=0}^{n-1} b_{1,k}(z_1) g_k(z)$$
(2.7)

Now we substitute  $z \to z_1$  in (2.4), and we substitute  $z \to z_0$  in (2.7), and combine them.

$$\exists b_{0,k} : \mathbb{C} \to \mathbb{C}, \exists b_{1,k} : \mathbb{C} \to \mathbb{C}, f(z_0 + z_1) = \sum_{k=0}^{n-1} b_{0,k}(z_0) g_k(z_1) = \sum_{k=0}^{n-1} b_{1,k}(z_1) g_k(z_0)$$
(2.8)

We now have 2 ways of viewing  $f(z_0 + z_1)$ , and we could imagine a sum of a line from the front, a sum of a line from the right, and 'deduce' that the true form is probably the sum of a square from above, which leads to the matrix form conjectured, but this is slightly sketchy logic that needs more rigor.