5. Syllabus content

It is expected that any course in physics will be based on experimental work. Teachers are encouraged to develop appropriate practical work for candidates to facilitate a greater understanding of the subject. Candidates should be aware of the appropriate safety precautions to follow when carrying out practical work.

Certain learning outcomes of the syllabus have been marked with an asterisk (*) to indicate the possibility of the application of IT.

Section I: General Physics

1. Physical Quantities, Units and Measurement

Content

- 1.1 Scalars and vectors
- 1.2 Measurement techniques
- 1.3 Units and symbols

Learning outcomes

- (a) define the terms scalar and vector.
- (b) determine the resultant of two vectors by a graphical method.
- (c) list the vectors and scalars from distance, displacement, length, speed, velocity, time, acceleration, mass and force.
- (d) describe how to measure a variety of lengths with appropriate accuracy using tapes, rules, micrometers and calipers. (The use of a vernier scale is **not** required.)
- (e) describe how to measure a variety of time intervals using clocks and stopwatches.
- (f) recognise and use the conventions and symbols contained in 'Signs, Symbols and Systematics', Association for Science Education, 2000.

Section II: Newtonian Mechanics

2. Kinematics

Content

- 2.1 Speed, velocity and acceleration
- 2.2 Graphical analysis of motion
- 2.3 Free-fall

Learning outcomes

- (a) state what is meant by speed and velocity.
- (b) recall and use average speed = distance travelled/time taken.
- (c) state what is meant by uniform acceleration and recall and use acceleration = change in velocity/time taken.
- (d) discuss non-uniform acceleration.
- (e) recall that deceleration is a negative acceleration.
- (f) *plot and *interpret speed-time and distance-time graphs.
- (g) *recognise from the shape of a speed-time graph when a body is
 - (1) at rest,
 - (2) moving with uniform speed,
 - (3) moving with uniform acceleration,
 - (4) moving with non-uniform acceleration.
- (h) calculate the area under a speed–time graph to determine the distance travelled for motion with uniform speed or uniform acceleration.
- (i) state that the acceleration of free-fall for a body near to the Earth is constant and is approximately 10 m/s^2 .
- (j) describe qualitatively the motion of bodies with constant weight falling with and without air resistance (including reference to terminal velocity).

3. Dynamics

Content

- 3.1 Balanced and unbalanced forces
- 3.2 Friction
- 3.3 Circular motion

Learning outcomes

Candidates should be able to:

- (a) state Newton's third law.
- (b) describe the effect of balanced and unbalanced forces on a body.
- (c) describe the ways in which a force may change the motion of a body.
- (d) recall and use the equation force = $mass \times acceleration$.
- (e) explain that friction is a force that impedes motion and produces heating.
- (f) discuss the effect of friction on the motion of a vehicle in the context of tyre surface, road conditions (including skidding), braking force, braking distance, thinking distance and stopping distance.
- (g) describe qualitatively motion in a circular path due to a constant perpendicular force, including electrostatic forces on an electron in an atom and gravitational forces on a satellite. ($F = mv^2/r$ is **not** required.)
- (h) discuss how ideas of circular motion are related to the motion of planets in the solar system.

4. Mass, Weight and Density

Content

- 4.1 Mass and weight
- 4.2 Gravitational fields
- 4.3 Density

Learning outcomes

- (a) state that mass is a measure of the amount of substance in a body.
- (b) state that the mass of a body resists change from its state of rest or motion.
- (c) state that a gravitational field is a region in which a mass experiences a force due to gravitational attraction.
- (d) recall and use the equation $weight = mass \times gravitational$ field strength.
- (e) explain that weights, and therefore masses, may be compared using a balance.
- (f) describe how to measure mass and weight by using appropriate balances.
- (g) describe how to use a measuring cylinder to measure the volume of a liquid or solid.
- (h) describe how to determine the density of a liquid, of a regularly shaped solid and of an irregularly shaped solid which sinks in water (volume by displacement).
- (i) define density and recall and use the formula density = mass/volume.

5. Turning Effect of Forces

Content

- 5.1 Moments
- 5.2 Centre of mass
- 5.3 Stability

Learning outcomes

Candidates should be able to:

- (a) describe the moment of a force in terms of its turning effect and relate this to everyday examples.
- (b) state the principle of moments for a body in equilibrium.
- (c) define moment of a force and recall and use the formula moment = force × perpendicular distance from the pivot and the principle of moments.
- (d) describe how to verify the principle of moments.
- (e) describe how to determine the position of the centre of mass of a plane lamina.
- (f) describe qualitatively the effect of the position of the centre of mass on the stability of simple objects.

6. Deformation

Content

6.1 Elastic deformation

Learning outcomes

- (a) state that a force may produce a change in size and shape of a body.
- (b) *plot, draw and interpret extension—load graphs for an elastic solid and describe the associated experimental procedure.
- (c) *recognise the significance of the term "limit of proportionality" for an elastic solid (an understanding of the elastic limit is **not** required).
- (d) calculate extensions for an elastic solid using proportionality.

7. Pressure

Content

- 7.1 Pressure
- 7.2 Pressure changes

Learning outcomes

- (a) define the term *pressure* in terms of force and area, and do calculations using the equation *pressure* = *force*/*area*.
- (b) explain how pressure varies with force and area in the context of everyday examples.
- (c) describe how the height of a liquid column may be used to measure the atmospheric pressure.
- (d) explain quantitatively how the pressure beneath a liquid surface changes with depth and density of the liquid in appropriate examples.
- (e) recall and use the equation for hydrostatic pressure $p = \rho gh$.
- (f) describe the use of a manometer in the measurement of pressure difference.
- (g) describe and explain the transmission of pressure in hydraulic systems with particular reference to the hydraulic press and hydraulic brakes on vehicles.
- (h) describe how a change in volume of a fixed mass of gas at constant temperature is caused by a change in pressure applied to the gas.
- (i) recall and use $p_1V_1 = p_2V_2$.

Section III: Energy and Thermal Physics

8. Energy Sources and Transfer of Energy

Content

- 8.1 Energy forms
- 8.2 Major sources of energy
- 8.3 Work
- 8.4 Efficiency
- 8.5 Power

Learning outcomes

- (a) list the different forms of energy with examples in which each form occurs.
- (b) state the principle of the conservation of energy and apply this principle to the conversion of energy from one form to another.
- (c) state that kinetic energy is given by $E_{\rm k} = \frac{1}{2}mv^2$ and that gravitational potential energy is given by $E_{\rm p} = mgh$, and use these equations in calculations.
- (d) list renewable and non-renewable energy sources.
- (e) describe the processes by which energy is converted from one form to another, including reference to
 - (1) chemical/fuel energy (a re-grouping of atoms),
 - (2) hydroelectric generation (emphasising the mechanical energies involved),
 - (3) solar energy (nuclei of atoms in the Sun),
 - (4) nuclear energy,
 - (5) geothermal energy,
 - (6) wind energy.
- (f) explain nuclear fusion and fission in terms of energy-releasing processes.
- (g) describe the process of electricity generation and draw a block diagram of the process from fuel input to electricity output.
- (h) discuss the environmental issues associated with power generation.
- (i) define work done and use the formula $work = force \times distance moved in the line of action of the force.$
- (j) recall and use the formula efficiency = energy converted to the required form/total energy input for an energy conversion.
- (k) discuss the efficiency of energy conversions in common use, particularly those giving electrical output.
- (I) discuss the usefulness of energy output from a number of energy conversions.
- (m) define power and recall and use the formula power = work done/time taken.

9. Transfer of Thermal Energy

Content

- 9.1 Conduction
- 9.2 Convection
- 9.3 Radiation

Learning outcomes

Candidates should be able to:

- (a) describe how to distinguish between good and bad conductors of heat.
- (b) describe, in terms of the movement of molecules or free electrons, how heat transfer occurs in solids.
- (c) describe convection in fluids in terms of density changes.
- (d) describe the process of heat transfer by radiation.
- (e) describe the effect of surface colour (black or white) and texture (dull or shiny) on the emission, absorption and reflection of radiation.
- (f) describe how to distinguish between good and bad emitters and good and bad absorbers of infrared radiation.
- (g) describe how heat is transferred to or from buildings and to or from a room.
- (h) state and explain the use of the important practical methods of thermal insulation for buildings.

10. Temperature

Content

- 10.1 Principles of thermometry
- 10.2 Practical thermometers

Learning outcomes

- (a) explain how a physical property which varies with temperature may be used for the measurement of temperature and state examples of such properties.
- (b) explain the need for fixed points and state what is meant by the ice point and steam point.
- (c) discuss sensitivity, range and linearity of thermometers.
- (d) describe the structure and action of liquid-in-glass thermometers (including clinical) and of a thermocouple thermometer, showing an appreciation of its use for measuring high temperatures and those which vary rapidly.
- (e) describe and explain how the structure of a liquid-in-glass thermometer affects its sensitivity, range and linearity.

11. Thermal Properties of Matter

Content

- 11.1 Specific heat capacity
- 11.2 Melting and boiling
- 11.3 Thermal expansion of solids, liquids and gases

Learning outcomes

Candidates should be able to:

- (a) describe a rise in temperature of a body in terms of an increase in its internal energy (random thermal energy).
- (b) define the terms heat capacity and specific heat capacity.
- (c) recall and use the formula thermal energy = $mass \times specific$ heat capacity \times change in temperature.
- (d) describe melting/solidification and boiling/condensation in terms of energy transfer without a change in temperature.
- (e) state the meaning of melting point and boiling point.
- (f) explain the difference between boiling and evaporation.
- (g) define the terms latent heat and specific latent heat.
- (h) explain latent heat in terms of molecular behaviour.
- (i) calculate heat transferred in a change of state using the formula thermal energy = mass × specific latent heat.
- (j) describe qualitatively the thermal expansion of solids, liquids and gases.
- (k) describe the relative order of magnitude of the expansion of solids, liquids and gases.
- (1) list and explain some of the everyday applications and consequences of thermal expansion.
- (m) describe qualitatively the effect of a change of temperature on the volume of a gas at constant pressure.

12. Kinetic Model of Matter

Content

- 12.1 States of matter
- 12.2 Molecular model
- 12.3 Evaporation

Learning outcomes

- (a) state the distinguishing properties of solids, liquids and gases.
- (b) describe qualitatively the molecular structure of solids, liquids and gases, relating their properties to the forces and distances between molecules and to the motion of the molecules.
- (c) describe the relationship between the motion of molecules and temperature.
- (d) explain the pressure of a gas in terms of the motion of its molecules.
- (e) describe evaporation in terms of the escape of more energetic molecules from the surface of a liquid.
- (f) describe how temperature, surface area and draught over a surface influence evaporation.
- (g) explain that evaporation causes cooling.

Section IV: Waves

13. General Wave Properties

Content

- 13.1 Describing wave motion
- 13.2 Wave terms
- 13.3 Wave behaviour

Learning outcomes

- (a) describe what is meant by wave motion as illustrated by vibrations in ropes and springs and by experiments using a ripple tank.
- (b) state what is meant by the term wavefront.
- (c) define the terms speed, frequency, wavelength and amplitude and recall and use the formula $velocity = frequency \times wavelength$.
- (d) describe transverse and longitudinal waves in such a way as to illustrate the differences between them.
- (e) describe the use of a ripple tank to show
 - (1) reflection at a plane surface,
 - (2) refraction due to a change of speed at constant frequency.
- (f) describe simple experiments to show the reflection of sound waves.

14. Light

Content

- 14.1 Reflection of light
- 14.2 Refraction of light
- 14.3 Thin converging and diverging lenses

Learning outcomes

- (a) define the terms used in reflection including normal, angle of incidence and angle of reflection.
- (b) describe an experiment to illustrate the law of reflection.
- (c) describe an experiment to find the position and characteristics of an optical image formed by a plane mirror.
- (d) state that for reflection, the angle of incidence is equal to the angle of reflection and use this in constructions, measurements and calculations.
- (e) define the terms used in refraction including angle of incidence, angle of refraction and refractive index.
- (f) describe experiments to show refraction of light through glass blocks.
- (g) recall and use the equation $\sin i/\sin r = n$.
- (h) define the terms critical angle and total internal reflection and recall and use the formula $\sin c = 1/n$.
- (i) describe experiments to show total internal reflection.
- (j) describe the use of optical fibres in telecommunications and state the advantages of their use.
- (k) describe the action of thin lenses (both converging and diverging) on a beam of light.
- (1) define the term focal length.
- (m) *draw ray diagrams to illustrate the formation of real and virtual images of an object by a converging lens, and the formation of a virtual image by a diverging lens.
- (n) define the term *linear magnification* and *draw scale diagrams to determine the focal length needed for particular values of magnification (converging lens only).
- (o) describe the use of a single lens as a magnifying glass and in a camera, projector and photographic enlarger and draw ray diagrams to show how each forms an image.
- (p) draw ray diagrams to show the formation of images in the normal eye, a short-sighted eye and a long-sighted eye.
- (q) describe the correction of short-sight and long-sight.

15. Electromagnetic Spectrum

Content

- 15.1 Dispersion of light
- 15.2 Properties of electromagnetic waves
- 15.3 Applications of electromagnetic waves

Learning outcomes

- (a) describe the dispersion of light as illustrated by the action on light of a glass prism.
- (b) state the colours of the spectrum and explain how the colours are related to frequency/wavelength.
- (c) state that all electromagnetic waves travel with the same high speed in air and state the magnitude of that speed.
- (d) describe the main components of the electromagnetic spectrum.
- (e) discuss the role of the following components in the stated applications:
 - (1) radio waves radio and television communications,
 - (2) microwaves satellite television and telephone,
 - (3) infrared household electrical appliances, television controllers and intruder alarms,
 - (4) light optical fibres in medical uses and telephone,
 - (5) ultraviolet sunbeds, fluorescent tubes and sterilisation,
 - (6) X-rays hospital use in medical imaging and killing cancerous cells, and engineering applications such as detecting cracks in metal,
 - (7) gamma rays medical treatment in killing cancerous cells, and engineering applications such as detecting cracks in metal.

16. Sound

Content

- 16.1 Sound waves
- 16.2 Speed of sound
- 16.3 Ultrasound

Learning outcomes

- (a) describe the production of sound by vibrating sources.
- (b) describe the longitudinal nature of sound waves and describe compression and rarefaction.
- (c) state the approximate range of audible frequencies for the healthy human ear as 20 Hz to 20000 Hz.
- (d) explain why a medium is required in order to transmit sound waves and describe an experiment to demonstrate this.
- (e) describe a direct method for the determination of the speed of sound in air and make the necessary calculation.
- (f) state the order of magnitude of the speeds of sound in air, liquids and solids.
- (g) explain how the loudness and pitch of sound waves relate to amplitude and frequency.
- (h) describe how the reflection of sound may produce an echo.
- (i) describe how the shape of a sound wave as demonstrated by an oscilloscope is affected by the quality (timbre) of the sound wave.
- (i) define ultrasound.
- (k) describe the uses of ultrasound in cleaning, quality control and pre-natal scanning.

19. Current Electricity

Content

- 19.1 Current
- 19.2 Electromotive force
- 19.3 Potential difference
- 19.4 Resistance

Learning outcomes

- (a) state that a current is a flow of charge and that current is measured in amperes.
- (b) recall and use the equation charge = current \times time.
- (c) describe the use of an ammeter with different ranges.
- (d) explain that electromotive force (e.m.f.) is measured by the energy dissipated by a source in driving a unit charge around a complete circuit.
- (e) state that e.m.f. is work done/charge.
- (f) state that the volt is given by J/C.
- (g) calculate the total e.m.f. where several sources are arranged in series and discuss how this is used in the design of batteries.
- (h) discuss the advantage of making a battery from several equal voltage sources of e.m.f. arranged in parallel.
- (i) state that the potential difference (p.d.) across a circuit component is measured in volts.
- **stat**e that the p.d. across a component in a circuit is given by the work done in the component/charge passed through the component.
- (k) describe the use of a voltmeter with different ranges.
- state that resistance = p.d./current and use the equation resistance = voltage/current in calculations.
- (m) describe an experiment to measure the resistance of a metallic conductor using a voltmeter and an ammeter and make the necessary calculations.
- (n) state Ohm's Law and discuss the temperature limitation on Ohm's Law.
- (o) *use quantitatively the proportionality between resistance and the length and the cross-sectional area of a wire.
- (p) calculate the net effect of a number of resistors in series and in parallel.
- (q) describe the effect of temperature increase on the resistance of a resistor and a filament lamp and draw the respective sketch graphs of current/voltage.
- (r) describe the operation of a light-dependent resistor.

D.C. Circuits 20.

Content

- 20.1 Current and potential difference in circuits
- 20.2 Series and parallel circuits

Learning outcomes

Candidates should be able to:

- (a) *draw circuit diagrams with power sources (cell, battery or a.c. mains), switches (closed and open), resistors (fixed and variable), light-dependent resistors, thermistors, lamps, ammeters, voltmeters, magnetising coils, bells, fuses, relays, diodes and light-emitting diodes.
- (b) state that the current at every point in a series circuit is the same, and use this in calculations.
- (c) state that the sum of the potential differences in a series circuit is equal to the potential difference across the whole circuit and use this in calculations.
- (d) state that the current from the source is the sum of the currents in the separate branches of a parallel circuit.
- (e) do calculations on the whole circuit, recalling and using formulae including R = V/I and those for potential differences in series, resistors in series and resistors in parallel.

21. Practical Electricity

Content

- 21.1 Uses of electricity
- 21.2 Dangers of electricity
- 21.3 Safe use of electricity in the home

Learning outcomes

- (a) describe the use of electricity in heating, lighting and motors.
- (b) recall and use the equations power = voltage \times current, and energy = voltage \times current \times time.
- (c) define the kilowatt-hour (kWh) and calculate the cost of using electrical appliances where the energy unit is the kWh.
- (d) state the hazards of damaged insulation, overheating of cables and damp conditions.
- (e) explain the use of fuses and circuit breakers, and fuse ratings and circuit breaker settings.
- (f) explain the need for earthing metal cases and for double insulation.
- (g) state the meaning of the terms live, neutral and earth.
- (h) describe how to wire a mains plug safely. (Candidates will **not** be expected to show knowledge of the colours of the wires used in a mains supply.)
- (i) explain why switches, fuses and circuit breakers are wired into the live conductor.

22. Electromagnetism

Content

- 22.1 Force on a current-carrying conductor
- 22.2 The d.c. motor

Learning outcomes

Candidates should be able to:

- (a) describe experiments to show the force on a current-carrying conductor, and on a beam of charged particles, in a magnetic field, including the effect of reversing (1) the current, (2) the direction of the field.
- (b) state the relative directions of force, field and current.
- (c) describe the field patterns between currents in parallel conductors and relate these to the forces which exist between the conductors (excluding the Earth's field).
- (d) explain how a current-carrying coil in a magnetic field experiences a turning effect and that the effect is increased by increasing (1) the number of turns on the coil, (2) the current.
- (e) discuss how this turning effect is used in the action of an electric motor.
- (f) describe the action of a split-ring commutator in a two-pole, single-coil motor and the effect of winding the coil onto a soft-iron cylinder.

23. Electromagnetic Induction

Content

- 23.1 Principles of electromagnetic induction
- 23.2 The a.c. generator
- 23.3 The transformer

Learning outcomes

- (a) describe an experiment which shows that a changing magnetic field can induce an e.m.f. in a circuit.
- (b) state the factors affecting the magnitude of the induced e.m.f.
- (c) state that the direction of a current produced by an induced e.m.f. opposes the change producing it (Lenz's Law) and describe how this law may be demonstrated.
- (d) describe a simple form of a.c. generator (rotating coil or rotating magnet) and the use of slip rings where needed.
- (e) *sketch a graph of voltage output against time for a simple a.c. generator.
- (f) describe the structure and principle of operation of a simple iron-cored transformer.
- (g) recall and use the equation $(V_p/V_s) = (N_p/N_s)$
- (h) state the advantages of high voltage transmission.
- (i) discuss the environmental and cost implications of underground power transmission compared to overhead lines.

24. Introductory Electronics

Content

- 24.1 Thermionic emission and cathode-rays
- 24.2 Uses of an oscilloscope
- 24.3 Action and use of circuit components

Learning outcomes

- (a) state that electrons are emitted by a hot metal filament.
- (b) explain that to cause a continuous flow of emitted electrons requires (1) high positive potential and (2) very low gas pressure.
- (c) describe the deflection of an electron beam by electric fields and magnetic fields.
- (d) state that the flow of electrons (electron current) is from negative to positive and is in the opposite direction to conventional current.
- (e) describe the use of an oscilloscope to display waveforms and to measure p.d.s and short intervals of time (the structure of the oscilloscope is **not** required).
- (f) explain how the values of resistors are chosen according to a colour code and why widely different values are needed in different types of circuit.
- (g) discuss the need to choose components with suitable power ratings.
- (h) describe the action of thermistors and light-dependent resistors and explain their use as input sensors (thermistors will be assumed to be of the negative temperature coefficient type).
- (i) describe the action of a variable potential divider (potentiometer).
- (j) describe the action of a diode in passing current in one direction only.
- (k) describe the action of a light-emitting diode in passing current in one direction only and emitting light.
- (/) describe and explain the action of relays in switching circuits.
- (m) describe and explain circuits operating as light-sensitive switches and temperature-operated alarms (using a relay or other circuits).

25. Electronic Systems

Note: There is no compulsory question set on Section 25 of the syllabus. Questions set on topics within Section 25 are always set as an alternative within a question.

Content

- 25.1 Switching and logic circuits
- 25.2 Bistable and astable circuits

Learning outcomes

- (a) describe the action of a bipolar npn transistor as an electrically operated switch and explain its use in switching circuits.
- (b) state in words and in truth table form, the action of the following logic gates, AND, OR, NAND, NOR and NOT (inverter).
- (c) state the symbols for the logic gates listed above (American ANSI Y 32.14 symbols will be used).
- (d) describe the use of a bistable circuit.
- (e) discuss the fact that bistable circuits exhibit the property of memory.

Section VI: Atomic Physics

26. Radioactivity

Content

- 26.1 Detection of radioactivity
- 26.2 Characteristics of the three types of emission
- 26.3 Nuclear reactions
- 26.4 Half-life
- 26.5 Uses of radioactive isotopes including safety precautions

Learning outcomes

Candidates should be able to:

- (a) describe the detection of alpha-particles, beta-particles and gamma rays by appropriate methods.
- (b) state and explain the random emission of radioactivity in direction and time.
- (c) state, for radioactive emissions, their nature, relative ionising effects and relative penetrating powers.
- (d) describe the deflection of radioactive emissions in electric fields and magnetic fields.
- (e) explain what is meant by radioactive decay.
- (f) explain the processes of fusion and fission.
- (g) describe, with the aid of a block diagram, one type of fission reactor for use in a power station.
- (h) discuss theories of star formation and their energy production by fusion.
- (i) explain what is meant by the term half-life.
- (j) make calculations based on half-life which might involve information in tables or shown by decay curves.
- (k) describe how radioactive materials are moved, used and stored in a safe way.
- (1) discuss the way in which the type of radiation emitted and the half-life determine the use for the material.
- (m) discuss the origins and effect of background radiation.
- (n) discuss the dating of objects by the use of ¹⁴C.

27. The Nuclear Atom

Content

- 27.1 Atomic model
- 27.2 Nucleus

Learning outcomes

- (a) describe the structure of the atom in terms of nucleus and electrons.
- (b) describe how the Geiger-Marsden alpha-particle scattering experiment provides evidence for the nuclear atom.
- (c) describe the composition of the nucleus in terms of protons and neutrons.
- (d) define the terms proton number (atomic number), Z and nucleon number (mass number), A.
- (e) explain the term nuclide and use the nuclide notation ${}^{A}_{Z}X$ to construct equations where radioactive decay leads to changes in the composition of the nucleus.
- (f) define the term isotope.
- (g) explain, using nuclide notation, how one element may have a number of isotopes.

7. Appendix

7.1 Summary of key quantities, symbols and units

Candidates should be able to state the symbols for the following physical quantities and, where indicated, state the units in which they are measured.

Candidates should be familiar with the following multipliers: M mega, k kilo, c centi, m milli.

Quantity	Usual symbol	Usual unit
length	<i>l, h</i>	km, m, cm, mm
area	Α	m², cm²
volume	V	m³, cm³
weight	W	N
mass	m, M	kg, g, mg
time	t	h, min, s, ms
density	ρ	g/cm ³ , kg/m ³
speed	u, v	km/h, m/s, cm/s
acceleration	а	m/s ²
acceleration of free fall	g	m/s ²
force	F	N
gravitational field strength	g	N/kg
moment of a force		Nm
work done	W, E	J
energy	E	J, kWh
power	Р	W
pressure	р, Р	Pa, N/m ²
temperature	θ, t, T	°C
heat capacity	С	J/°C
specific heat capacity	С	J/(kg°C), J/(g°C)
latent heat	L	J
specific latent heat	1	J/kg, J/g
frequency	f	Hz
wavelength	λ	m, cm

Quantity	Usual symbol	Usual unit
focal length	f	m, cm
angle of incidence	i	degree (°)
angles of reflection, refraction	r	degree (°)
critical angle	С	degree (°)
refractive index	n	
potential difference/voltage	V	V, mV
current	I	A, mA
charge	Q	С
e.m.f.	E	V
resistance	R	Ω

'O' Level Physics Formula Sheet

Measurements			
Base SI Units			
Kg	SI Unit for mass: Kilogram		
m	SI Unit for length: metre		
S	SI Unit for time: second		
A	SI Unit for current: Ampere		
K	SI Unit for Temperature: Kelvin		
mol	SI	Unit for Amount of substance: molar	
Number Prefix n (10 ⁻⁹)	no	no	
μ (10 ⁻⁶)	nano micro		
$m(10^{-3})$	micro milli		
c (10 ⁻²)	centi		
d (10 ⁻¹)	deci		
$K(10^3)$	Ki	lo	
$M(10^6)$	M	ega	
	K	inematics	
Average Speed		otal distance travelled (area under	
$\mathbf{s} = \Delta \mathbf{d} / \Delta \mathbf{t}$		time graph)	
	$\Delta x = t$	otal displacement	
Average Velocity		otal time taken	
$\mathbf{v} = \Delta \mathbf{x}/\Delta \mathbf{t}$		change in velocity	
Acceleration		ty (slope of displacement-time graph)	
$\mathbf{a} = \Delta \mathbf{v} / \Delta \mathbf{t}$		eration (slope of velocity-time graph)	
$\mathbf{v} = \mathbf{u} + \mathbf{at}$		itial velocity	
$\mathbf{x} = ut + \frac{1}{2} at^2$		nal velocity	
$\mathbf{v^2} = \mathbf{u^2} + 2\mathbf{ax}$	t = tin		
		celeration	
/ a		splacement	
$\mathbf{v}_{\mathbf{free\ fall}} = \sqrt{2gh}$	h = he		
g = gravitational constant = 9.81 m/s ²			
		Dynamics	
Newton's First L		Dynamics A hody continues to stay in its state	
Newton's First La $\Sigma \vec{F} = 0 \text{ at equilibria}$	ıw	A body continues to stay in its state	
Newton's First La $\sum \vec{F} = 0$ at equilibri	ıw	A body continues to stay in its state of rest or uniform motion in a	
→	ıw	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no	
→	ıw	A body continues to stay in its state of rest or uniform motion in a	
<u>→</u>	aw um	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the	
$\sum \vec{F} = 0$ at equilibri	aw um	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force	
$\sum \vec{F} = 0$ at equilibri	aw um	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely	
$\sum \vec{F} = 0$ at equilibri Newton's Second F = ma	um Law	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass.	
$\sum \vec{F} = 0$ at equilibri	um Law	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts	
$\sum \vec{F} = 0$ at equilibri Newton's Second F = ma	um Law	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts on object B, object B will exert an	
$\sum \vec{F} = 0$ at equilibri Newton's Second F = ma	um Law	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts on object B, object B will exert an equal and opposite	
$\sum \vec{F} = 0$ at equilibri Newton's Second F = ma	um Law	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts on object B, object B will exert an equal and opposite force on object A giving rise to	
$\sum \vec{F} = 0$ at equilibri Newton's Second F = ma Newton's Third L	um Law	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts on object B, object B will exert an equal and opposite force on object A giving rise to Reaction/Normal Forces	
$\sum \vec{F} = 0$ at equilibri Newton's Second F = ma Newton's Third L	um Law Law	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts on object B, object B will exert an equal and opposite force on object A giving rise to	
$\sum \vec{F} = 0$ at equilibriance $\vec{F} = 0$ at equilibriance	Law Output Description:	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts on object B, object B will exert an equal and opposite force on object A giving rise to Reaction/Normal Forces F _{vertical}	
$\sum \vec{F} = 0$ at equilibri Newton's Second F = ma Newton's Third I Resolving forces $F_{\text{horizontal}} = F_r \cos F_{\text{vertical}} = F_r \sin \Theta$	Law Aw Begin and the second	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts on object B, object B will exert an equal and opposite force on object A giving rise to Reaction/Normal Forces F_vertical F_F_F_F_F_F_F_F_F_F_F_F_F_F_F_F_F_F_F_	
$\sum \vec{F} = 0$ at equilibri Newton's Second F = ma Newton's Third L Resolving forces $F_{\text{horizontal}} = F_r \cos F_{\text{vertical}} = F_r \sin G$	Law Aw Begin and the second	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts on object B, object B will exert an equal and opposite force on object A giving rise to Reaction/Normal Forces F_vertical F_r F_horizontal Weight, Density	
$\sum \vec{F} = 0$ at equilibri Newton's Second F = ma Newton's Third L Resolving forces $F_{\text{horizontal}} = F_r \cos F_{\text{vertical}} = F_r \sin \Theta$ Weight	Law Aw Begin and the second	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts on object B, object B will exert an equal and opposite force on object A giving rise to Reaction/Normal Forces F_vertical F_F_F_F_F_F_F_F_F_F_F_F_F_F_F_F_F_F_F_	
$\sum \vec{F} = 0$ at equilibri Newton's Second F = ma Newton's Third L Resolving forces $F_{\text{horizontal}} = F_r \cos F_{\text{vertical}} = F_r \sin G$	Law Aw Begin and the second	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts on object B, object B will exert an equal and opposite force on object A giving rise to Reaction/Normal Forces F_vertical F_r F_r F_r F_r F_r Weight, Density w = Weight m = mass	
$\sum \vec{F} = 0$ at equilibriant $\vec{F} = 0$ at equi	Law Aw Begin and the second	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts on object B, object B will exert an equal and opposite force on object A giving rise to Reaction/Normal Forces F_vertical F_r F_horizontal Weight, Density w = Weight m = mass g = gravitational field strength	
$\sum \vec{F} = 0$ at equilibriant $\vec{F} = 0$ at equi	Law Aw Begin and the second	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts on object B, object B will exert an equal and opposite force on object A giving rise to Reaction/Normal Forces F_vertical F_r F_r F_r F_r F_r Weight, Density w = Weight m = mass	
$\sum \vec{F} = 0$ at equilibriant $\hat{F} = 0$ at equi	Law Aw Begin and the second	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts on object B, object B will exert an equal and opposite force on object A giving rise to Reaction/Normal Forces F _{vertical} F _r F _{horizontal} Weight, Density w = Weight m = mass g = gravitational field strength ρ = density	
$\sum \vec{F} = 0$ at equilibriant $\sum \vec{F} = 0$ at	Law Law Here Mass,	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts on object B, object B will exert an equal and opposite force on object A giving rise to Reaction/Normal Forces Frentical Frentier Fren	
Newton's Second F= ma Newton's Third L Resolving forces $F_{horizontal} = F_r \cos F_{vertical} = F_r \sin \Theta$ Weight $\mathbf{w} = mg$ Density $\rho = \frac{m}{V}$	Law Law Here Mass,	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts on object B, object B will exert an equal and opposite force on object A giving rise to Reaction/Normal Forces F_vertical F_r	
Newton's Second F= ma Newton's Third L Resolving forces $F_{horizontal} = F_r \cos F_{vertical} = F_r \sin \Theta$ Weight $w = mg$ Density $\rho = \frac{m}{V}$	Law Law Here Mass,	A body continues to stay in its state of rest or uniform motion in a straight line as long as there is no net force/moment acting on the body. The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass. For every force object A acts on object B, object B will exert an equal and opposite force on object A giving rise to Reaction/Normal Forces F _{vertical} Weight, Density w = Weight m = mass g = gravitational field strength ρ = density m = mass V = volume g effect of Force	

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Principle of Moment	For a body in rotational	
Σ Anticlockwise Moment	1 1	
$=\Sigma$ Clockwise Moment	Sum of ACW Moment = sum of	
	CW Moment	
Pressure		
Pressure	P = Pressure	
$\mathbf{P} = \frac{\mathbf{F}}{\mathbf{F}}$	F = Force over area, A	
1 - A	A = Area	
Pressure of liquid	P = Pressure	
column	$\rho = \text{density},$	
$\mathbf{P} = \mathbf{h} \mathbf{\rho} \mathbf{g}$	h = height of liquid column	
, ,	g = gravitational field strength.	
Energy,		
Work Done	W = work done	
$\mathbf{W} = \mathbf{Fd}$	F= force	
,, = 1 u	d= distance in direction of force	
Power	Work done per unit time, t	
$\mathbf{P} = \mathbf{W}/\mathbf{t} = \mathbf{F}\mathbf{v}$	vi ork done per dint time, t	
Kinetic Energy	$E_k = Kinetic Energy$	
	m = mass	
$\mathbf{E_k} = \frac{1}{2} \text{mv}^2$	v = velocity	
Gravitational Potential	g = gravity = 9.81 m/s	
Energy	h = height	
$\mathbf{E_p} = \mathrm{mgh}$	m = mass	
Conservation of Energy	II.	
$E_1 = E_2$	E_1 = Total Energy Before E_2 = Total Energy After	
$\mathbf{E}_1 = \mathbf{E}_2$		
	Energy cannot be created or	
	destroyed. It can only be transformed or converted into other	
	transformed of converted into other	
Kinetic	forms.	
1	forms. Model of Matter	
Ideal Gas Law	forms. Model of Matter P = pressure of fixed mass of gas	
1	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass	
Ideal Gas Law	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas	
Ideal Gas Law PV ∞ T	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas	
Ideal Gas Law	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state	
Ideal Gas Law $PV \infty T$ $P_1V_1 = P_2V_2$	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state	
Ideal Gas Law $PV \infty T$ $P_1V_1 = P_2V_2$ Thermal F	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter	
Ideal Gas Law $PV \infty T$ $P_1V_1 = P_2V_2$ Thermal I Specific Heat Capacity	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter C = Specific heat capacity (Energy	
Ideal Gas Law $PV \infty T$ $P_1V_1 = P_2V_2$ Thermal F	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter c = Specific heat capacity (Energy required to raise the temperature of	
Ideal Gas Law $PV \infty T$ $P_1V_1 = P_2V_2$ Thermal I Specific Heat Capacity	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter c = Specific heat capacity (Energy required to raise the temperature of 1kg of the object by 1 °C)	
Ideal Gas Law $PV \infty T$ $P_1V_1 = P_2V_2$ Thermal I Specific Heat Capacity	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter c = Specific heat capacity (Energy required to raise the temperature of 1kg of the object by 1 °C) m = mass	
Ideal Gas Law $PV \infty T$ $P_1V_1 = P_2V_2$ Thermal F Specific Heat Capacity $E = m c \Delta T$	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter c = Specific heat capacity (Energy required to raise the temperature of 1kg of the object by 1 °C) m = mass ΔT = change in temperature.	
Ideal Gas Law $PV \infty T$ $P_1V_1 = P_2V_2$ Thermal F Specific Heat Capacity $E = m c \Delta T$	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter C = Specific heat capacity (Energy required to raise the temperature of 1kg of the object by 1 °C) m = mass ΔT = change in temperature. L _{fusion} = latent heat of fusion (Energy)	
Ideal Gas Law $PV \infty T$ $P_1V_1 = P_2V_2$ Thermal F Specific Heat Capacity $E = m c \Delta T$ Latent Heat For melting,	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter C = Specific heat capacity (Energy required to raise the temperature of 1kg of the object by 1 °C) m = mass ΔT = change in temperature. L _{fusion} = latent heat of fusion (Energy required to change 1kg of solid to	
Ideal Gas Law $PV \infty T$ $P_1V_1 = P_2V_2$ Thermal F Specific Heat Capacity $E = m c \Delta T$	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter C = Specific heat capacity (Energy required to raise the temperature of 1kg of the object by 1 °C) m = mass ΔT = change in temperature. L _{fusion} = latent heat of fusion (Energy required to change 1kg of solid to liquid at the constant temp)	
Ideal Gas Law $PV \propto T$ $P_1V_1 = P_2V_2$ $Thermal \ I$ Specific Heat Capacity $E = m \ c \ \Delta T$ $Latent \ Heat$ For melting, $E = m \ L_{fusion}$	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter C = Specific heat capacity (Energy required to raise the temperature of 1kg of the object by 1 °C) m = mass ΔT = change in temperature. L _{fusion} = latent heat of fusion (Energy required to change 1kg of solid to liquid at the constant temp) L _{vaporization} = latent heat of L _{vap}	
Ideal Gas Law $PV \infty T$ $P_1V_1 = P_2V_2$ Thermal F Specific Heat Capacity $E = m c \Delta T$ Latent Heat For melting, $E = m L_{fusion}$ For boiling,	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter c = Specific heat capacity (Energy required to raise the temperature of 1kg of the object by 1 °C) m = mass ΔT = change in temperature. L _{fusion} = latent heat of fusion (Energy required to change 1kg of solid to liquid at the constant temp) L _{vaporization} = latent heat of vaporization (Energy required to change requ	
Ideal Gas Law $PV \propto T$ $P_1V_1 = P_2V_2$ $Thermal \ I$ Specific Heat Capacity $E = m \ c \ \Delta T$ $Latent \ Heat$ For melting, $E = m \ L_{fusion}$	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter C = Specific heat capacity (Energy required to raise the temperature of 1kg of the object by 1 °C) m = mass ΔT = change in temperature. L _{fusion} = latent heat of fusion (Energy required to change 1kg of solid to liquid at the constant temp) L _{vaporization} = latent heat of L _{vap}	
Ideal Gas Law $PV \infty T$ $P_1V_1 = P_2V_2$ Thermal F Specific Heat Capacity $E = m c \Delta T$ Latent Heat For melting, $E = m L_{fusion}$ For boiling,	Forms. Model of Matter	
Ideal Gas Law $PV \propto T$ $P_1V_1 = P_2V_2$ $Thermal \ I$ $Specific \ Heat \ Capacity$ $E = m \ c \ \Delta T$ $Latent \ Heat$ $For \ melting,$ $E = m \ L_{fusion}$ $For \ boiling,$ $E = m \ L_{vaporization}$	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter C = Specific heat capacity (Energy required to raise the temperature of 1kg of the object by 1 °C) m = mass ΔT = change in temperature. L _{fusion} = latent heat of fusion (Energy required to change 1kg of solid to liquid at the constant temp) L _{vaporization} = latent heat of vaporization (Energy required to change 1kg of liquid to gas at the constant temp) m = mass	
Ideal Gas Law $PV \propto T$ $P_1V_1 = P_2V_2$ $Thermal \ I$ $Specific \ Heat \ Capacity$ $E = m \ c \ \Delta T$ $Latent \ Heat$ $For \ melting,$ $E = m \ L_{fusion}$ $For \ boiling,$ $E = m \ L_{vaporization}$	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter c = Specific heat capacity (Energy required to raise the temperature of 1kg of the object by 1 °C) m = mass ΔT = change in temperature. L _{fusion} = latent heat of fusion (Energy required to change 1kg of solid to liquid at the constant temp) L _{vaporization} = latent heat of vaporization (Energy required to change 1kg of liquid to gas at the constant temp) m = mass Wave Properties	
Ideal Gas Law $PV \propto T$ $P_1V_1 = P_2V_2$ $Thermal \ P$ Specific Heat Capacity $E = m \ c \ \Delta T$ $Latent \ Heat$ For melting, $E = m \ L_{fusion}$ For boiling, $E = m \ L_{vaporization}$ $General$	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter c = Specific heat capacity (Energy required to raise the temperature of 1kg of the object by 1 °C) m = mass ΔT = change in temperature. L _{fusion} = latent heat of fusion (Energy required to change 1kg of solid to liquid at the constant temp) L _{vaporization} = latent heat of vaporization (Energy required to change 1kg of liquid to gas at the constant temp) m = mass Wave Properties v = velocity of a wave	
Ideal Gas Law $PV \infty T$ $P_1V_1 = P_2V_2$ $Thermal \ F$ Specific Heat Capacity $E = m c \Delta T$ $Latent Heat For melting, E = m L_{fusion}$ For boiling, $E = m L_{vaporization}$ $General$ Wave Velocity	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter C = Specific heat capacity (Energy required to raise the temperature of 1kg of the object by 1 °C) m = mass ΔT = change in temperature. L _{fusion} = latent heat of fusion (Energy required to change 1kg of solid to liquid at the constant temp) L _{vaporization} = latent heat of vaporization (Energy required to change 1kg of liquid to gas at the constant temp) m = mass Wave Properties v = velocity of a wave f = frequency	
Ideal Gas Law $PV \infty T$ $P_1V_1 = P_2V_2$ $Thermal \ F$ $Specific \ Heat \ Capacity \ E = m \ c \ \Delta T$ $Latent \ Heat \ For \ melting, \ E = m \ L_{fusion}$ $For \ boiling, \ E = m \ L_{vaporization}$ $Wave \ Velocity \ v = f \ \lambda$	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter c = Specific heat capacity (Energy required to raise the temperature of 1kg of the object by 1 °C) m = mass ΔT = change in temperature. L _{fusion} = latent heat of fusion (Energy required to change 1kg of solid to liquid at the constant temp) L _{vaporization} = latent heat of vaporization (Energy required to change 1kg of liquid to gas at the constant temp) m = mass Wave Properties v = velocity of a wave	
Ideal Gas Law $PV \infty T$ $P_1V_1 = P_2V_2$ $Thermal \ F$ Specific Heat Capacity $E = m c \Delta T$ $Latent Heat$ For melting, $E = m L_{fusion}$ For boiling, $E = m L_{vaporization}$ $General$ Wave Velocity $\mathbf{v} = f \lambda$ $Wave frequency$	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter C = Specific heat capacity (Energy required to raise the temperature of 1kg of the object by 1 °C) m = mass ΔT = change in temperature. L _{fusion} = latent heat of fusion (Energy required to change 1kg of solid to liquid at the constant temp) L _{vaporization} = latent heat of vaporization (Energy required to change 1kg of liquid to gas at the constant temp) m = mass Wave Properties v = velocity of a wave f = frequency	
Ideal Gas Law $PV \infty T$ $P_1V_1 = P_2V_2$ $Thermal \ F$ $Specific \ Heat \ Capacity \ E = m \ c \ \Delta T$ $Latent \ Heat \ For \ melting, \ E = m \ L_{fusion}$ $For \ boiling, \ E = m \ L_{vaporization}$ $Wave \ Velocity \ v = f \ \lambda$	forms. Model of Matter P = pressure of fixed mass of gas V = volume occupies by fixed mass of gas T = Temperature of gas Subscript 1 = initial state Subscript 2 = final state Properties of Matter C = Specific heat capacity (Energy required to raise the temperature of 1kg of the object by 1 °C) m = mass ΔT = change in temperature. L _{fusion} = latent heat of fusion (Energy required to change 1kg of solid to liquid at the constant temp) L _{vaporization} = latent heat of vaporization (Energy required to change 1kg of liquid to gas at the constant temp) m = mass Wave Properties v = velocity of a wave f = frequency λ = wavelength	

'O' Level Physics Formula Sheet

Light		
Law of Reflection	Normal .	
$\Theta_i = \Theta_r$		
	$\Theta_{i} \mid \Theta_{r}$	
Θ_i = angle of incidence		
Θ_i = angle of incidence Θ_r = angle of reflection		
Snell's Law (refraction)	Normal	
$n_1 Sin \Theta_i = n2 Sin \Theta_r$	Θ_i $n_1 = \text{refractive index 1}$	
Θ_i = angle of incidence	Θ_r	
$\Theta_{\rm r}$ = angle of refraction	$n_2 = \text{refractive index } 2$	
~	i li ₂ – refractive fildex 2	
Critical angle	Normal	
n _o	\ \ !	
$\sin \Theta_{\mathbf{c}} = \frac{\mathbf{n}_2}{\mathbf{n}_1}$	Θ_{c} $n_1 = \text{refractive index 1}$	
111		
(special case of Snell's		
law where $\Theta_r = 90^\circ$)	n = refrective index 2	
1 Where o _f = 70)	n_2 = refractive index 2	
Refractive Index	c = speed of light in vacuum.	
$\mathbf{n} = \frac{\mathbf{c}}{\mathbf{c}}$	v = speed of light in medium	
$\mathbf{n} = \frac{1}{\mathbf{v}}$	Higher reflective index of a	
	medium means light travel slower	
(n of air ≈ 1)	in the medium	
Magnification	M = magnification	
$\mathbf{M} = \frac{\mathbf{h_i}}{\mathbf{h_c}} = \frac{\mathbf{d_i}}{\mathbf{d_c}}$	h = height	
$h_o - d_o$	d = distance from lens	
	Subscript i = image	
Subscript o = object		
Current of Electricity		
Current	Current = rate of flow of charges	
$\mathbf{I} = \mathbf{Q} / \Delta \mathbf{t}$	Q = Charge	
Ob and a Large	t=time	
Ohm's Law Resistance	V = voltage,	
	R = resistance	
$\mathbf{R} = \mathbf{V} / \mathbf{I}$	I = current	
R = V / I Resistance of a wire	I = current ρ = resistivity	
$\mathbf{R} = \mathbf{V} / \mathbf{I}$	$I = current$ $\rho = resistivity$ $L = length of wire$	
R = V / I Resistance of a wire R = ρL/A	$I = current$ $\rho = resistivity$ $L = length of wire$ $A = cross sectional area$	
$R = V / I$ Resistance of a wire $R = \rho L / A$	$I = current$ $\rho = resistivity$ $L = length of wire$ $A = cross sectional area$ $C. Circuits$	
R = V / I Resistance of a wire R = ρL/A	$I = current$ $\rho = resistivity$ $L = length of wire$ $A = cross sectional area$ $C. Circuits$ $Conservation of charges.$	
R = V / I Resistance of a wire R = ρL/A D. Kirchoff's 1 st Law	$\begin{split} &I = current \\ &\rho = resistivity \\ &L = length of wire \\ &A = cross sectional area \\ \hline \textit{\textbf{C. Circuits}} \\ &Conservation of charges. \\ &\sum I_{in} = Sum of current going into a \end{split}$	
$R = V / I$ Resistance of a wire $R = \rho L / A$	$\begin{split} & I = current \\ & \rho = resistivity \\ & L = length of wire \\ & A = cross sectional area \\ \hline \textit{\textbf{C. Circuits}} \\ & Conservation of charges. \\ & \sum I_{in} = Sum of current going into a junction \end{split}$	
$\begin{aligned} \mathbf{R} &= \mathbf{V} / \mathbf{I} \\ \mathbf{Resistance of a wire} \\ \mathbf{R} &= \rho \mathbf{L} / \mathbf{A} \\ \hline \qquad \qquad$	$\begin{split} &I = current \\ &\rho = resistivity \\ &L = length of wire \\ &A = cross sectional area \\ \hline \textit{\textbf{C. Circuits}} \\ &Conservation of charges. \\ &\sum I_{in} = Sum of current going into a junction \\ &\sum I_{out} = Sum of current going out \end{split}$	
R = V / I Resistance of a wire R = ρL/A D. Kirchoff's 1 st Law	$\begin{split} & I = current \\ & \rho = resistivity \\ & L = length of wire \\ & A = cross sectional area \\ \hline \textit{\textbf{C. Circuits}} \\ & Conservation of charges. \\ & \sum I_{in} = Sum of current going into a junction \end{split}$	
$\begin{aligned} \mathbf{R} &= \mathbf{V} / \mathbf{I} \\ \mathbf{Resistance of a wire} \\ \mathbf{R} &= \rho \mathbf{L} / \mathbf{A} \\ \hline \qquad \qquad$	$\begin{split} & I = current \\ & \rho = resistivity \\ & L = length of wire \\ & A = cross sectional area \\ \hline & \textbf{\textit{C. Circuits}} \\ & Conservation of charges. \\ & \sum I_{in} = Sum \ of \ current \ going \ into \ a \\ & junction \\ & \sum I_{out} = Sum \ of \ current \ going \ out \\ & of \ a \ junction \\ \end{split}$	
$R = V / I$ $Resistance of a wire$ $R = \rho L / A$ $D.$ $Kirchoff's 1st Law$ $\sum I_{in} = \sum I_{out}$ $Kirchoff's 2nd Law$	$\begin{split} &I = current \\ &\rho = resistivity \\ &L = length of wire \\ &A = cross sectional area \\ \hline &\textbf{\textit{C. Circuits}} \\ &Conservation of charges. \\ &\sum I_{in} = Sum of current going into a junction \\ &\sum I_{out} = Sum of current going out of a junction \\ &\sum V = Sum of potential difference V across all components in a circuit \\ &E.M.F = Voltage supplied by the \\ \end{split}$	
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Practical Electricity		
Electric Power	P = Power	
	V = voltage	
$\mathbf{P} = \mathbf{V}\mathbf{I} = \mathbf{V}^2/\mathbf{R} = \mathbf{I}^2\mathbf{R}$	R = resistance	
	I = current	
Electrical Energy	E = energy output	
$\mathbf{E} = Pt = (VI)t$	P = power	
	t = time	
	V = voltage	
	I = current	
Electromagnetism		
Transformer	V = voltage	
$\frac{V_p}{V_p} = \frac{N_p}{V_p}$	N = number of coils	
$\frac{1}{V_s} = \frac{1}{N_s}$	I = current	
(ideal transformer)	Subscript p = primary coil	
	Subscript s = secondary coil	
$\begin{aligned} & V_P I_P = V_s I_s \\ \hline & \textbf{Right hand grip} \end{aligned}$		
	current direction	
Fleming's Right Hand Rule	motion or lorce F magnetic field B induced current I	
Fleming's Left Hand Rule	torce F magnetic field B current /	

