

2.1.5 Group Work Imagine you are cooking some soup on a stovetop. At steady state, the temperature distribution T inside the metal volume of the pot Ω can be found by solving the equation

$$-\Delta T = 0 \quad \text{in } \Omega.$$

On the surface of the pot, the temperature is fixed as follows:

- $T = 200^\circ\text{C}$ on the bottom surface Γ_1 that is in contact with the element
- $T = 93^\circ\text{C}$ on the inner surface Γ_2 that is in contact with the hot soup
- $T = 32^\circ\text{C}$ on the surface of the handle Γ_3 that is in contact with your hand
- $T = 22^\circ\text{C}$ everywhere else on the pot surface $\partial\Omega \setminus (\Gamma_1 \cup \Gamma_2 \cup \Gamma_3)$ that is in contact with the surrounding air.

- (a) What is the best lower bound and the best upper bound you can derive from the elliptic maximum principle for the temperature distribution T in the metal volume of the pot?

Both the max & the min principle apply.

$$\left. \begin{array}{l} \text{Max principle} \Rightarrow T(x) \leq \max_{\partial\Omega} T = 200^\circ\text{C} \\ \text{Min principle} \Rightarrow T(x) \geq \min_{\partial\Omega} T = 22^\circ\text{C} \end{array} \right\} \text{ for all } x \in \overline{\Omega}$$

- (b) What changes in your answer to part (a) if you switch on an infrared lamp above the stove, as a consequence of which the PDE model now reads $-\Delta T = f$ with $f > 0$?

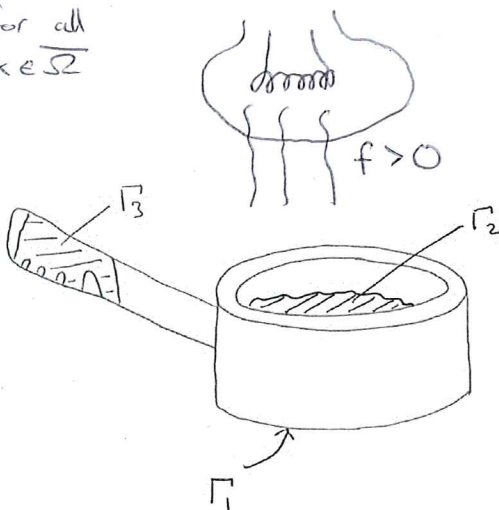
Only the min principle applies.

$$T(x) \geq 22^\circ\text{C} \quad \text{for all } x \in \overline{\Omega}, \text{ but}$$

temperatures $> 200^\circ\text{C}$ could arise now

due to the positive source term

→ extra heating



2.1.6 Group Work (Outlook: Discrete Maximum Principle) Assume that we want to solve the PDE problem

$$\begin{array}{ll} Lu = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{array}$$

numerically, with an elliptic operator L that satisfies the assumptions of the maximum principle. This could e.g. be a temperature problem like above or steady advection-diffusion-reaction problem. After discretisation e.g. with finite differences or finite elements, we obtain a linear system

$$Ax = b. \quad \text{Hint: } x = A^{-1}b$$

In analogy to the continuous maximum / minimum principle, whenever the the right hand side vector b does not go below zero, nor should the numerical solution vector x . Can you derive a condition on the matrix A that guarantees just that, i.e. $x \geq 0$ whenever $b \geq 0$? (NB: This \geq notation for vectors should be understood componentwise. $x \geq 0$ means that all entries of the vector x should be non-negative.)

If $A^{-1} \geq 0$ (componentwise), then all entries of x satisfy

$$x_i = \sum_j \underbrace{(A^{-1})_{ij}}_{\geq 0} \underbrace{b_j}_{\geq 0} \geq 0$$

We'll soon learn about more practical

criteria that are easier to check than the signs in A^{-1} !

