

# Neal Elharidy

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## EDUCATION

The University of British Columbia - SBME Systems and Signals Engineer

## PROFESSIONAL SKILLS

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| <ul style="list-style-type: none"><li>• Python</li><li>• Matlab</li><li>• C# &amp; C++</li><li>• R &amp; R-Studio</li><li>• HTML &amp; CSS</li><li>• Javascript</li><li>• MySQL</li></ul> | <ul style="list-style-type: none"><li>• Solidworks</li><li>• Fusion 360</li><li>• FDM 3D-Printing</li><li>• PCB Design, Fabrication &amp; Assembly</li><li>• K-Layout</li><li>• Lumerical Mode</li><li>• Micro-Soldering</li></ul> | <ul style="list-style-type: none"><li>• PyTorch</li><li>• ANE Transformers</li><li>• AWS Cloud Practitioner (In-Progress)</li><li>• Optical Signal Processing</li><li>• LiDar Model Scanning</li><li>• Unix / Linux Systems</li><li>• Github</li></ul> |
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## PROFESSIONAL EXPERIENCE

### Soapstand LLC. - Systems and Assembly Engineer Aug 2022 - Sep 2023

- Improved weekly production from 6 to 10 machines by streamlining the PCB fabrication and testing.
- Configured, verified, and addressed bugs in firmware (C/C++) and provided detailed reports to the development team.
- Performed, logged and automated QC testing for assembled machines following ISO 9001 standards.
- Trained new assembly technicians on processes, documented assembly instructions, and supervised QA.

### UBC's Green Joule Design Team - Executive Team Lead - July 2021 - April 2022

- Oversaw, organized wet lab research, production and finances amongst 4 subdivisions totalling 30 members.
- Programmed full monitoring and control system using C++ for controlling gas flow, PIC based temperature control, light intensity and fermentation rate.
- Coordinated with the School of Chemical and Biological Engineering, the School of Botany, and the BIOT design team on multiple collaborative projects including deploying a unified algae/brewing reactor with BIOT.

### Growth Subdivision Lead - Sept 2020 - July 2021

- Increased 2021 annual yield of biofuel synthesized by 12% via implementing a modified Folch technique for lipid extraction.
- Decreased cost per litre by 30% by utilizing local cultures growth mediums collected from UBC grounds.
- Developed a method of producing alcohol from fermentation and biofuel in a unified bioreactor that was later deployed with fellow design team BIOT to allow Carbon negative brewing.

### Hamad Hospital - Facilities Volunteer - Feb 2021 - June 2021 - Doha, Qatar

- Received vaccine thermal shippers containing 5000 vaccines each, forwarded batches to storage and medical personnel.
- Generated reports regarding medical supplies to be restocked, thermal shippers received, and daily vaccines used.
- Assisted in general administration and system IT issues by debugging SQL data base.

### Biz-Hacks - Hackathon Team Engineer - Feb 2020

- Engineered, modelled, in Fusion 360, and later 3D printed scale model of prototype interactive booth for Best Buy.
- Fabricated a prototype and modelled the booth's UI and its accompanying management and end-user apps using Python, HTML, CSS, & Javascript.

### Carnegie Mellon University - MindCraft Project Intern - April 2017 - May 2018

- Built and maintained the line tracking robots used by participants using Arduinos programmed in C++ for controllers.
- Programmed cryptography based challenges for participants in Python.
- Counselling and monitored participants throughout the program ensuring the teams maintained cohesion.

## CERTIFICATIONS

### Privacy and Information Security

Certificate ID: SRS\_PRSEC\_Oc2020idy13eal9 & SRS\_PRSEC2\_Oc2020idy13eal9

### AWS Cloud Practitioner (In Progress)

Expected completion Date: April 11, 2024

### Introduction to Laboratory Safety

Certificate ID: SRS\_ILS\_Oct2020idy14Nea57

### Workplace Hazardous Materials Information System

Certificate ID: SRS\_GWHMIS\_Oct2020idy14Nea9

## PROJECTS

**Python** - LLaMa-2 7/13B based assistant with integrated API based tools running using apple's ANE Transformers library.

**Matlab** - 3D dynamically controlled robotic arm simulation with end effector force control.

**Matlab** - Optical Computer Tomography System which processes raw OCT data and outputs manipulatable 3D volumes of imaged tissue.