

## Kevin Denamganai

Date of birth : 10/05/1993

Computer Science and Electronical Engineering student ( ENSEA)

Artificial Intelligence and Robotics Master student (University of Cergy-Pontoise)

Electronic and Information Systems Master student (Osaka Prefecture University)

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## Work Experience

### Keepschool

Teacher (Mathematics and English)

(since Octobre 2013 )

## Internships :

- ETIS Laboratory (Summer 2014 ) :

[Computer Vision & Robotics - Calibration & Stereovision](#) :

crafted an artificial vision system meant to autonomously control a robotic arm made up of Dynamixel AX12 servomotors.

- ETIS Laboratory ( Summer 2015) :

[Design and Evaluation of a LRF-based SLAM system](#) : following a state-of-the-art with multiple implementation of already existing LRF-based SLAM systems as ROS nodes, I implemented my own system following incremental innovations and carried on an evaluation of that system against few others.

- ETIS Laboratory (Winter 2015-2016) :

[Visual Context for a Spatial Recognition System in Wide Environments](#)

## Education

Electrical and Information Systems Master Degree

Osaka Prefecture University (OPU) – Osaka – JAPAN

2016-2017 (expected)

Artificial Intelligence and Robotics Master Degree

Université de Cergy-Pontoise (UCP) – Cergy-Pontoise

(95) – FRANCE

2015-2017 (expected)

Computer Science and Electronical Engineering

Ecole nationale supérieure de l'Electronique et de ses

Applications (ENSEA) – Cergy (95) – FRANCE

2013 – 2017 (expected)

### Languages

French (Mother tongue)  
English ( TOEIC 950 (2014) )  
Deutsch (Good working knowledge)  
Japanese (Beginner)

## Skills

C, C++, Java, ROS, Gazebo  
Python, Prolog, VHDL FreeCAD, Blender  
Matlab, Mathematica, Octave Linux

## Activities-Projects

AMFS -Vice president (July 2014-2015)

- Planning the forum “[Bouge La Science](#)”, a vulgarisation event.

ARES - Secretary (July 2014-2015)

- Designing a [controller for a differential-wheeled robot](#) meant for the 2015 Robotic French Cup. (November 2014)
- Crafting a [humanoid robot](#) with MG995 servomotors. (December 2015)

### ENSEA projects :

- [Controller for a Quadrocopter](#) (September 2014-May 2015)
- [Semi-Dense/Features-based Visual SLAM systems](#) (September 2014-May 2015)
- [Iterative/Simultaneous Impulse-based/Force-based Physics Engines for a Game development](#) (September 2015-January 2016)

### OPU projects :

- [Deep Reinforcement Learning Framework in C++](#) (May 2016)
- [Multiple Object Detection and Tracking system with OpenCV](#) (September 2016)

## Qualifications

### Machine Learning

Coursera January 2014

### Computational Neuroscience

Coursera March 2014

### Discrete Inference and Learning in Artificial Vision

Coursera March 2014

### Linear and Discrete Optimization

Coursera May 2014

### [AUTONAVx: Autonomous Navigation for Flying Robots](#)

Edx July 2014

### Automata

Coursera November 2014

### [AMRx: Autonomous Mobile Robots](#)

Edx October 2015

### 6.832x: Underactuated Robotics

Edx December 2015

Raspberry Pi  
Arduino  
STM32

Machine Learning,  
TensorFlow, Theano  
[Computer Vision, OpenCV](#)

## Interests

Mathematics	Basket-ball	Artificial Intelligence	Martial Arts :
Origami	Music : Violin	Robotics	Tai C'hi Chuan
Astronomy	Psychology		Wing Chun