

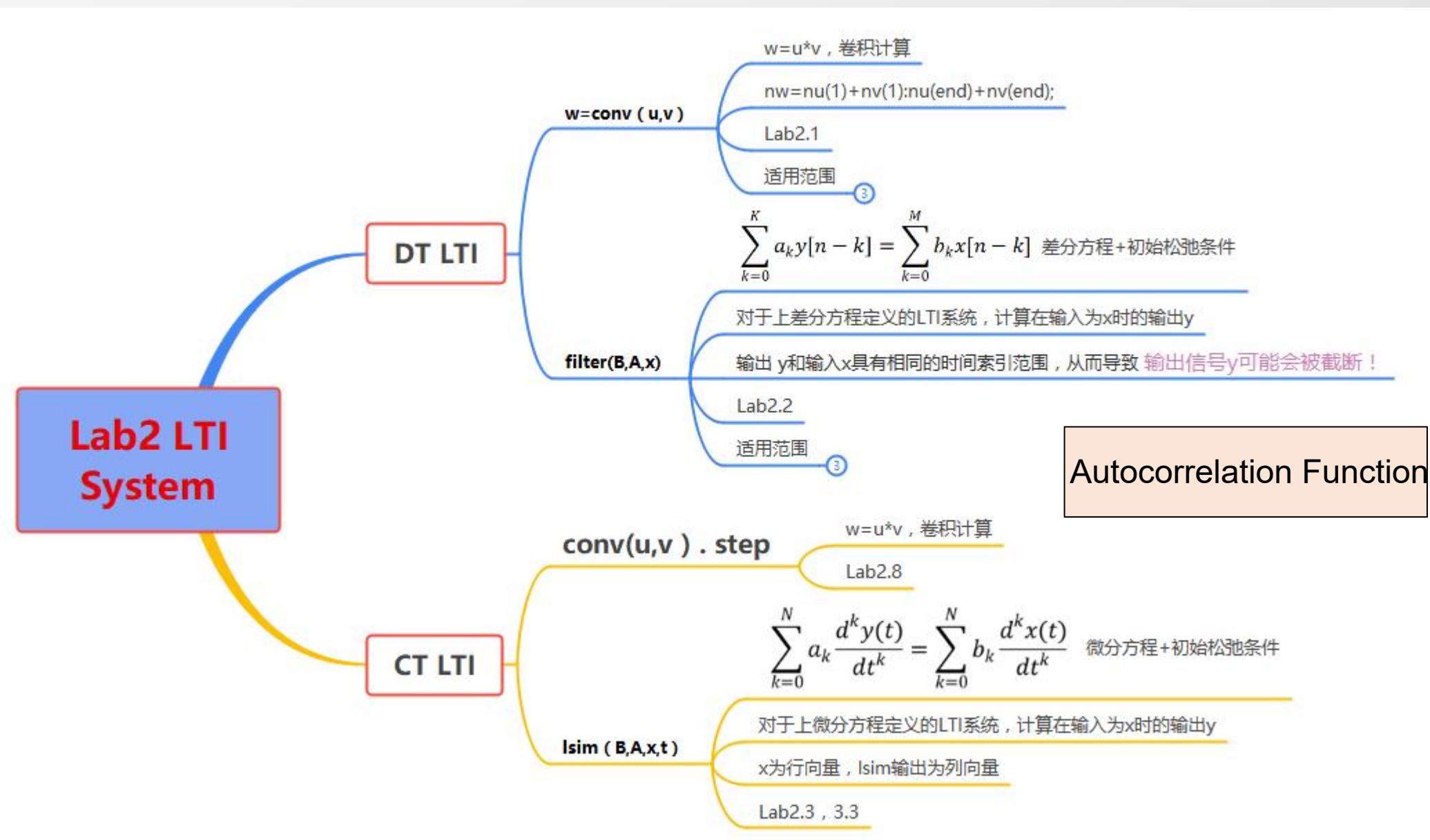
Lab3 Fourier Series Representation of Periodic Signals

周期信号的傅里叶级数表示

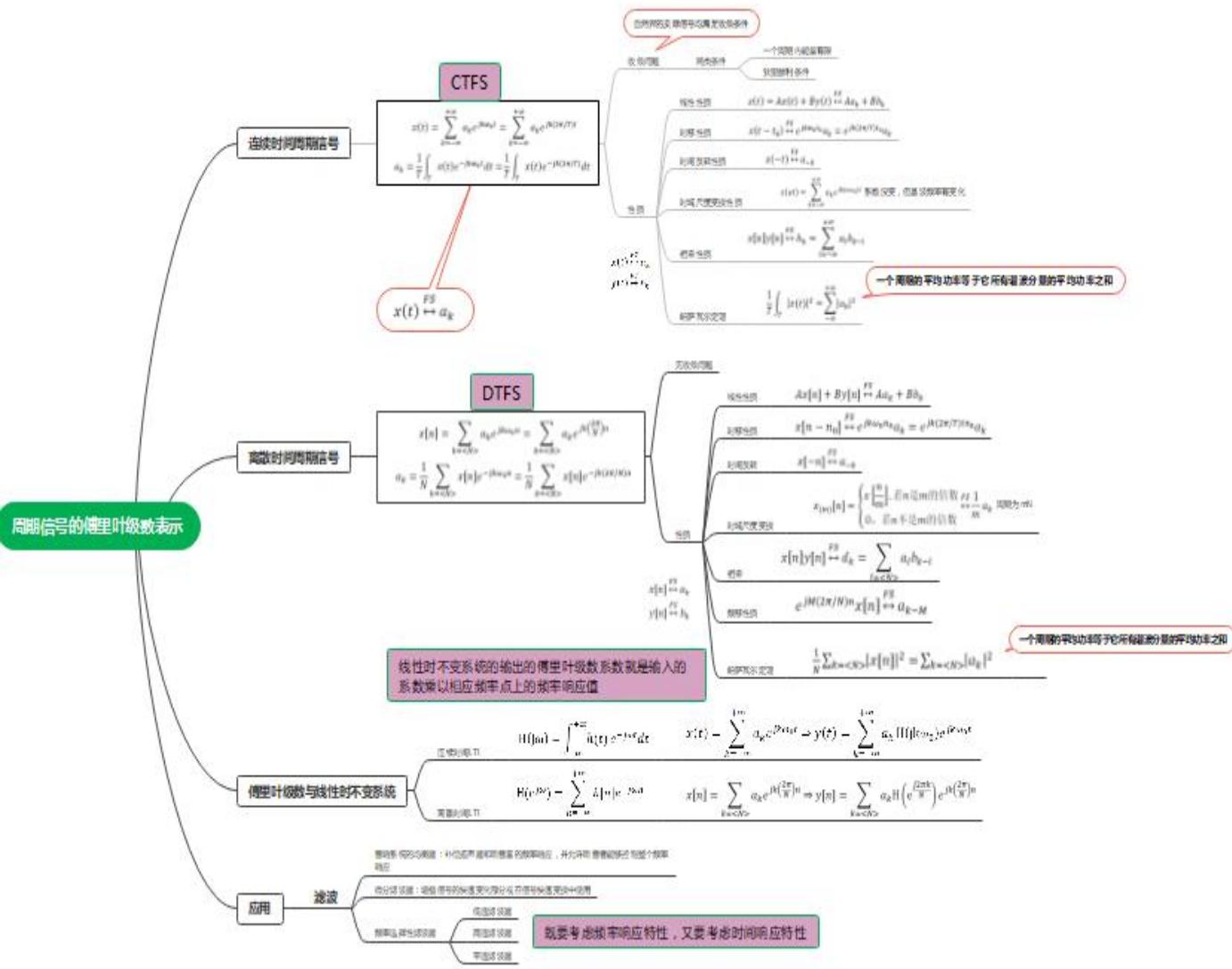


主讲老师：王小静
办公地点：一教131

Review



Objectives



➤ Fourier Series Representation of Periodic Signals

➤ Properties of Fourier Series

➤ Frequency Response of a LTI System

Contents



- 1** DTFS (Fourier Series Representation of DT Periodic Signals)
- 2** Frequency Response of LTI Systems
- 3** Output of a CT LTI System

Overview

chapter

2

$$x(t) = \int_{-\infty}^{+\infty} x(\tau) \delta(t - \tau) d\tau$$

$$x[n] = \sum_{k=-\infty}^{+\infty} x[k] \delta[n - k]$$

LTI Systems

($h(t)/h[n]$)

$$y(t) = \int_{-\infty}^{+\infty} x(\tau) h(t - \tau) d\tau$$

$$y[n] = \sum_{k=-\infty}^{+\infty} x[k] h[n - k]$$

chapter

3~5

$$x(t) = \sum_k a_k e^{st}$$

$$x[n] = \sum_k a_k z_k^n$$

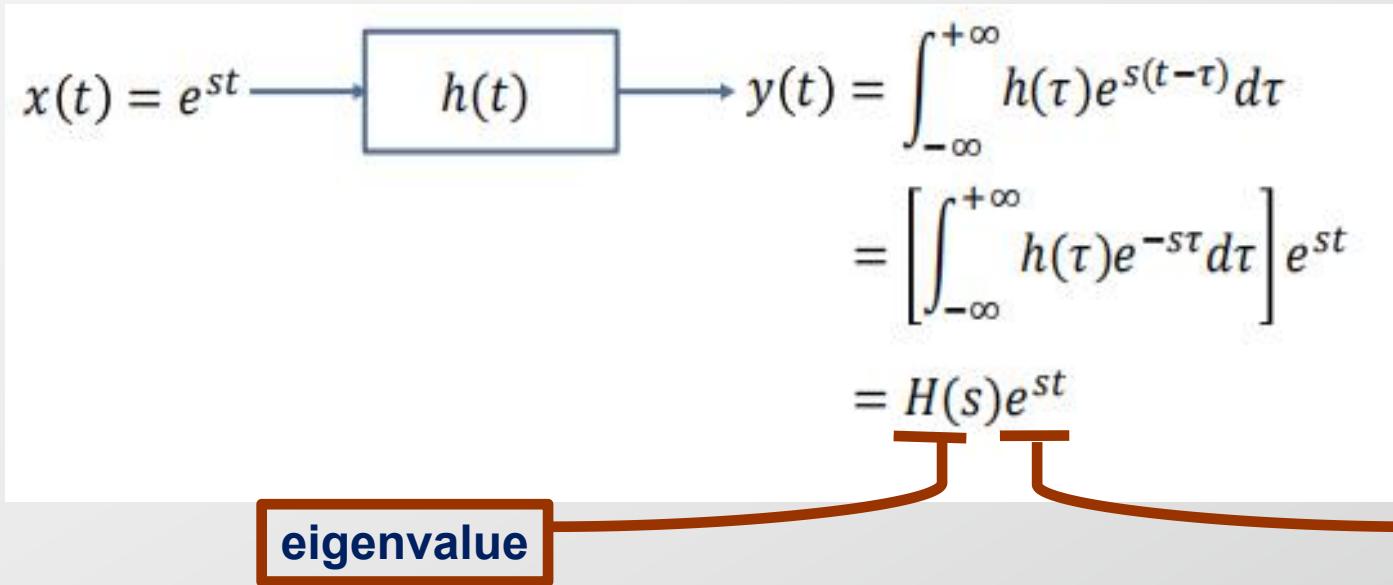
LTI Systems

($h(t)/h[n]$)

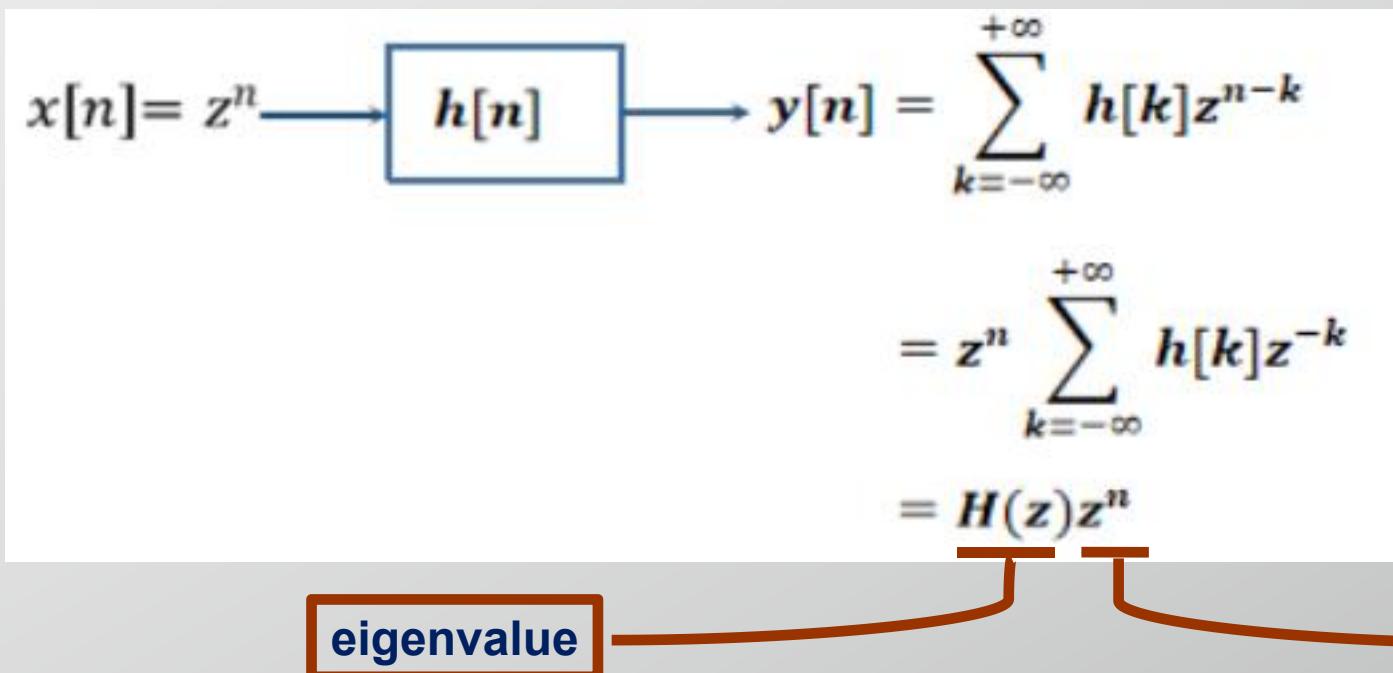
$$y(t) = \sum_k a_k H(s_k) e^{st}$$

$$y[n] = \sum_k a_k H(z_k) z_k^n$$

CT LTI



DT LTI



Complex exponentials are eigenfunctions of LTI systems, i.e., when the input sequence is a complex exponential, the output is the same complex exponential only scaled in amplitude by a complex constant. This constant can be computed from the impulse response $h[n]$. When the input to a discrete-time LTI system is $x[n] = z^n$, the output is $y[n] = H(z)z^n$, where

$$H(z) = \sum_{k=-\infty}^{+\infty} h[k]z^{-k}$$

The Response of LTI systems to Complex Exponentials

$$\begin{array}{ccc} \frac{x(t) = e^{st}}{x[n] = z^n} & \xrightarrow{\text{LTI Systems}} & \frac{y(t) = H(s)e^{st}}{y[n] = H(z)z^n} \end{array}$$

The response of LTI Systems to Complex Exponentials is the Complex Exponentials multiply a complex constant.

For CT LTI System: Complex Exponentials e^{st} is its eigenfunction. The constant $H(s)$ for a specific value of s is then the eigenvalue

$$H(s) = \int_{-\infty}^{+\infty} h(\tau) e^{-s\tau} d\tau$$

For DT LTI System: Complex Exponentials z^n is its eigenfunction, The constant $H(z)$ for a specific value of z is then the eigenvalue

$$H(z) = \sum_{-\infty}^{+\infty} h[k] z^{-k}$$

$$\frac{x(t) = e^{st}}{x[n] = z^n} \rightarrow \text{LTI Systems } (h(t)/h[n]) \rightarrow \frac{y(t) = H(s)e^{st}}{y[n] = H(z)z^n}$$

↓ Superposition

$$x(t) = \sum_k a_k e^{s_k t} \rightarrow \text{CT LTI Systems } (h(t)) \rightarrow y(t) = \sum_k a_k H(s_k) e^{s_k t}$$

$$x[n] = \sum_k a_k z_k^n \rightarrow \text{DT LTI Systems } (h[n]) \rightarrow y[n] = \sum_k a_k H(z_k) z_k^n$$

we consider only when $s=jw$ $z=e^{jw}$

$$x(t) = \sum_k a_k e^{jw_k t} \longrightarrow \text{CT LTI Systems } (h(t)) \longrightarrow y(t) = \sum_k a_k H(jw_k) e^{jw_k t}$$

$$x[n] = \sum_k a_k e^{jw_k n} \longrightarrow \text{DT LTI Systems } (h[n]) \longrightarrow y[n] = \sum_k a_k H(e^{jw_k}) e^{jw_k n}$$

$$x(t) = e^{st} \rightarrow \boxed{h(t)} \rightarrow y(t) = \int_{-\infty}^{+\infty} h(\tau) e^{s(t-\tau)} d\tau$$

$$= \left[\int_{-\infty}^{+\infty} h(\tau) e^{-s\tau} d\tau \right] e^{st}$$

$$= H(s) e^{st}$$

$$H(s) = \int_{-\infty}^{+\infty} h(\tau) e^{-s\tau} d\tau$$

when s is arbitrary complex number, $H(s)$ is System Function.
 when $s=jw$, $H(s)$ is $H(jw)$, that we named Frequency Response.

$$x[n] = z^n \rightarrow \boxed{h[n]} \rightarrow y[n] = \sum_{k=-\infty}^{+\infty} h[k] z^{n-k}$$

$$= z^n \sum_{k=-\infty}^{+\infty} h[k] z^{-k}$$

$$= H(z) z^n$$

$$H(z) = \sum_{-\infty}^{+\infty} h[k] z^{-k}$$

when z is arbitrary complex number, $H(z)$ is System Function.
 when $z=ejw$, $H(z)$ is $H(ejw)$, that we named Frequency Response.

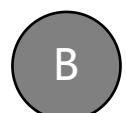
$$x(t) = \sum_k a_k e^{jw_k t} \longrightarrow \text{CT LTI Systems } (h(t)) \longrightarrow y(t) = \sum_k a_k H(jw_k) e^{jw_k t}$$

$$x[n] = \sum_k a_k e^{jw_k n} \longrightarrow \text{DT LTI Systems } (h[n]) \longrightarrow y[n] = \sum_k a_k H(e^{jw_k}) e^{jw_k n}$$

Let $x(t)$ or $x[n]$ correspond to a linear combination of some complex exponentials, and we also know the frequency response $H(jw)$ or $H(e^{jw})$ of the LTI system, then we can easily calculate the response of the LTI system to $x(t)$ or $x[n]$.



Yes



No

提交



$$e^{j\omega n}$$

*DT LTI Systems
($h(n)$)*

$$H(e^{j\omega})e^{j\omega n}$$

$$x[n] \left[\begin{array}{l} a_0 e^{j0(\frac{2\pi}{N})n} \\ a_1 e^{j1(\frac{2\pi}{N})n} \\ a_2 e^{j2(\frac{2\pi}{N})n} \\ \dots \\ a_{N-1} e^{j(N-1)(\frac{2\pi}{N})n} \end{array} \right]$$

$$y[n] \left[\begin{array}{l} a_0 H(e^{j0(\frac{2\pi}{N})}) e^{j0(\frac{2\pi}{N})n} \\ a_1 H(e^{j1(\frac{2\pi}{N})}) e^{j1(\frac{2\pi}{N})n} \\ a_2 H(e^{j2(\frac{2\pi}{N})}) e^{j2(\frac{2\pi}{N})n} \\ \dots \\ a_{N-1} H(e^{j(N-1)(\frac{2\pi}{N})}) e^{j(N-1)(\frac{2\pi}{N})n} \end{array} \right]$$

$e^{j\omega t} \rightarrow CT LTI Systems$
 $(h(t)) \rightarrow H(j\omega)e^{j\omega t}$

$$\begin{array}{ll}
 a_{-\infty} e^{j - \infty (\frac{2\pi}{T})t} & a_{-\infty} H(j - \infty (\frac{2\pi}{T})) e^{j - \infty (\frac{2\pi}{T})t} \\
 \cdot \quad \cdot \quad \cdot & \cdot \quad \cdot \quad \cdot \\
 a_{-2} e^{j - 2(\frac{2\pi}{T})t} & a_{-2} H(j - 2(\frac{2\pi}{T})) e^{j - 2(\frac{2\pi}{T})t} \\
 a_{-1} e^{j - 1(\frac{2\pi}{T})t} & a_{-1} H(j - 1(\frac{2\pi}{T})) e^{j - 1(\frac{2\pi}{T})t} \\
 a_0 e^{j 0(\frac{2\pi}{T})t} & a_0 H(j 0(\frac{2\pi}{T})) e^{j 0(\frac{2\pi}{T})t} \\
 a_1 e^{j 1(\frac{2\pi}{T})t} & a_1 H(j 1(\frac{2\pi}{T})) e^{j 1(\frac{2\pi}{T})t} \\
 a_2 e^{j 2(\frac{2\pi}{T})t} & a_2 H(j 2(\frac{2\pi}{T})) e^{j 2(\frac{2\pi}{T})t} \\
 \cdot \quad \cdot \quad \cdot & \cdot \quad \cdot \quad \cdot \\
 a_\infty e^{j \infty (\frac{2\pi}{T})t} & a_\infty H(j \infty (\frac{2\pi}{T})) e^{j \infty (\frac{2\pi}{T})t}
 \end{array}$$

$x(t)$ $y(t)$

Then,
to analyze the LTI Systems, we only need to do **two things**:

1: Let $x(t)$ or $x[n]$ correspond to a linear combination of some complex exponentials

$$x(t) = \sum_k a_k e^{jw_k t}$$

$$x[n] = \sum_k a_k e^{jw_k n}$$

2: figure out the System Function of the LTI systems

$$H(s) = \int_{-\infty}^{+\infty} h(\tau) e^{-s\tau} d\tau$$

$$H(z) = \sum_{-\infty}^{+\infty} h[k] z^{-k}$$

When $s=j\omega$ $z=e^{j\omega}$

$$H(j\omega) = \int_{-\infty}^{+\infty} h(t) e^{-j\omega t} dt$$

$$H(e^{j\omega}) = \sum_{n=-\infty}^{+\infty} h[n] e^{-j\omega n}$$

In the lab, we focus on DT Signals、DT LTI Systems more

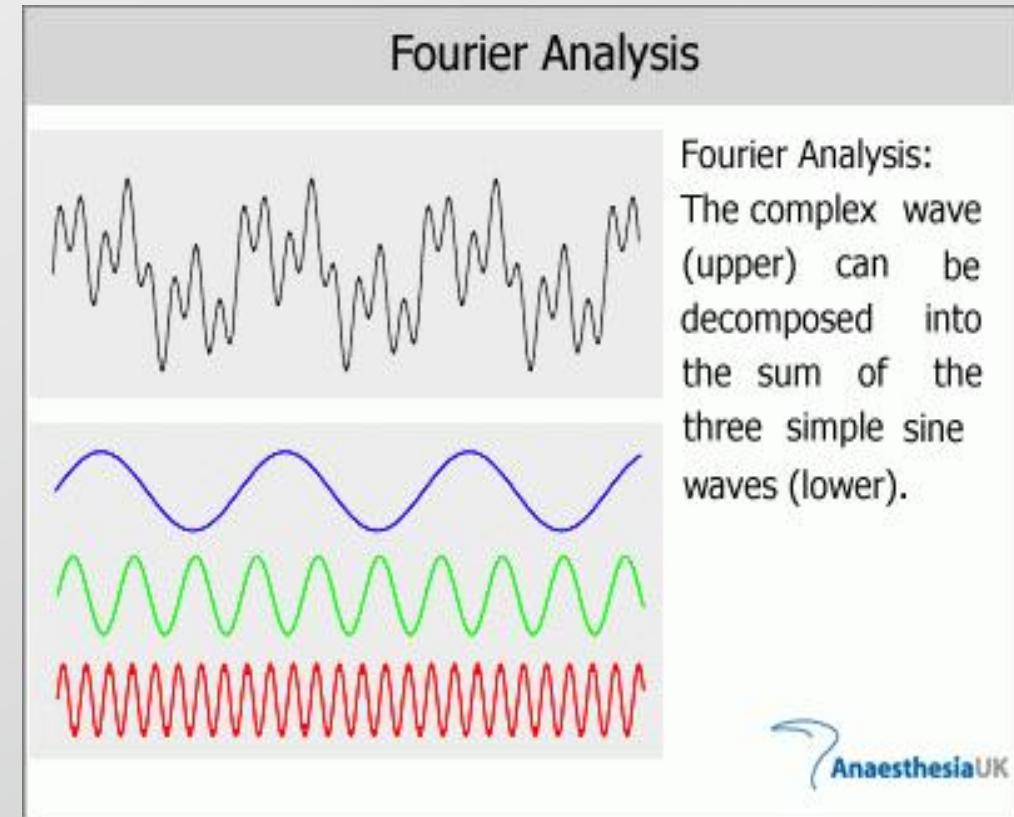


Part I: Fourier Series Representation of DT Periodic Signals

Joseph Fourier



SCIENCEPHOTOLIBRARY



DTFS

$$x[n] = \sum_{k=-N}^{N-1} a_k e^{jk\omega_0 n} = \sum_{k=-N}^{N-1} a_k e^{jk(2\pi/N)n}$$
$$a_k = \frac{1}{N} \sum_{n=-N}^{N-1} x[n] e^{-jk\omega_0 n} = \frac{1}{N} \sum_{n=-N}^{N-1} x[n] e^{-jk(2\pi/N)n}$$

→ *Synthesis Equation*

→ *Analysis Equation*

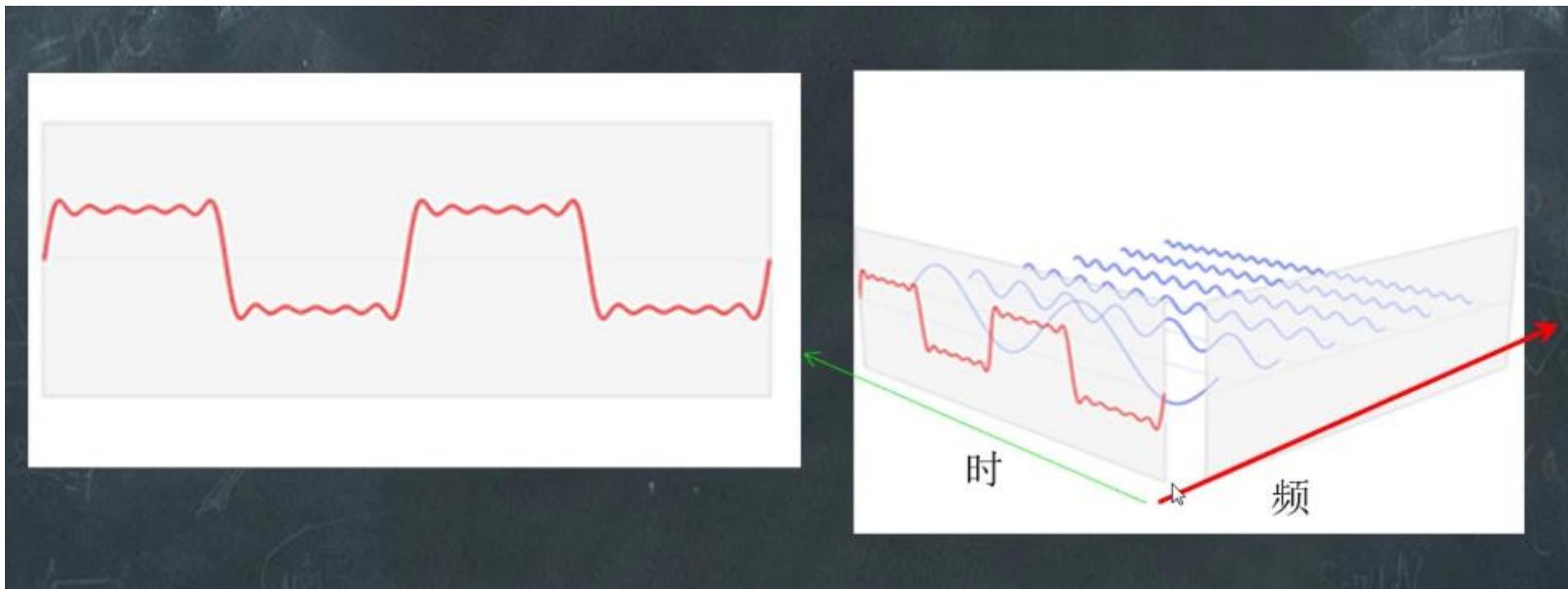
{ a_k } are often called the Fourier series coefficients or the **spectral coefficients**.

There is N values of k, that is a_k repeat periodically with period N.

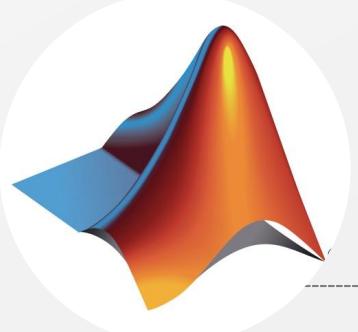
Linearity, Time shifting,
Frequency Shifting, Time
Reversal, Time Scaling,
Periodic Convolution,
Multiplication, Conjugate
Symmetry for Real Signals,
Parseval's Relation for
Periodic Signals

$$a_0 = \frac{1}{N} \sum_{n=-N}^{N-1} x[n]$$

$$\frac{1}{N} \sum_{k=-N}^{N-1} |x[n]|^2 = \sum_{k=-N}^{N-1} |a_k|^2$$



$$x[n] = \sum_{k=0}^{N-1} a_k e^{j k \omega_0 n} = \sum_{k=0}^{N-1} a_k e^{j k (2\pi/N) n}$$
$$a_k = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-j k \omega_0 n} = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-j k (2\pi/N) n}$$



Calculate DTFS

according to the Synthesis and Analysis Equations

```
clear,close all
```

```
x=[0,1]; N=2;
```

```
%dtfs
```

```
x0=x(1); x1=x(2);
```

```
a0=1/N*(x0+x1); a1=1/N*(x0+x1*exp(-j*1*2*pi/N*1));
```

```
a=[a0,a1];
```

```
%Synthesize x
```

$$x[n] = \begin{cases} 1, & n = 1 \\ 0, & n = 0 \end{cases}, \text{ preiod is } 2$$

$$a_k = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-jk(2\pi/N)n} = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-jk(2\pi/N)n}$$

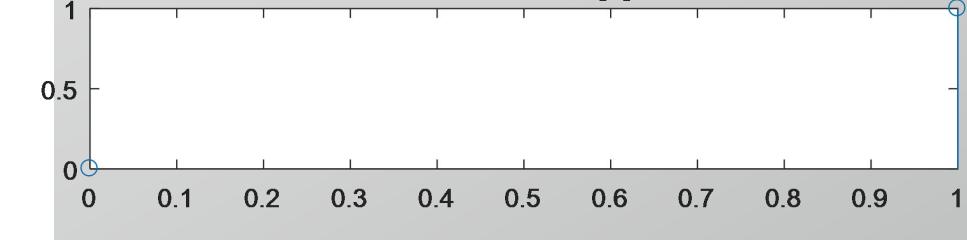
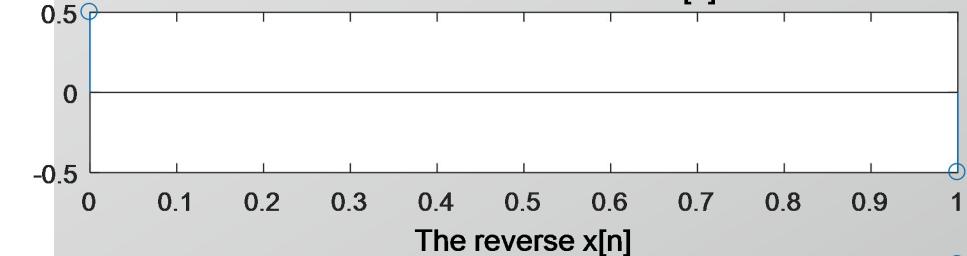
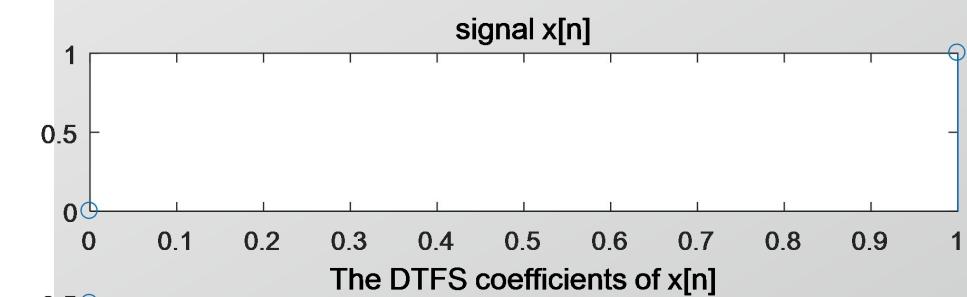
```
x_revers(1)=a(1)+a(2);
```

```
x_revers(2)=a(1)+a(2)*exp(-j*1*2*pi/N*1);
```

```
subplot(3,1,1),stem([0:N-1],x),title('signal x[n]')
```

```
subplot(3,1,2),stem([0:N-1],a),title('The DTFS coefficients of x[n]');
```

```
subplot(3,1,3),stem([0:N-1],x_revers),title('The reverse x[n]');
```



Complexity Analysis of DTFS

$$a_k = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-jk\omega_0 n} = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-jk(2\pi/N)n}$$

Suppose we know the matrix $E(n, k) = e^{-jk(2\pi/N)n}$

- ? How many multiplications & additions are needed to calculate Fourier series $[a_0, a_1, \dots, a_{N-1}]$

$$a_k = \frac{1}{N} \sum_{n=<N>} x[n] e^{-jk\omega_0 n} = \frac{1}{N} \sum_{n=<N>} x[n] e^{-jk(2\pi/N)n}$$

$$E(n, k) = e^{-jk(2\pi/N)n}$$

$$a_0 = \frac{1}{N} \sum_{n=<N>} x[n] e^{-j0(2\pi/N)n} = \frac{1}{N} \sum_{n=<N>} x[n] E(n, 0)$$

$$a_1 = \frac{1}{N} \sum_{n=<N>} x[n] e^{-j1(2\pi/N)n} = \frac{1}{N} \sum_{n=<N>} x[n] E(n, 1)$$

•
•
•

Each: $N + 1 \times; N - 1 +$
 Total: $N(N + 1) \times; N(N - 1) +$

Fast Fourier Transform (FFT)

$$E(n, k) = e^{-jk(2\pi/N)n}$$

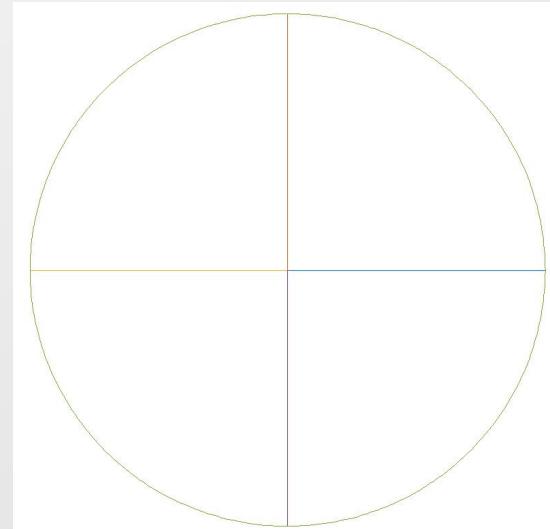
N=4

$$a_0 = (x[0]E(0,0) + x[1]E(1,0) + x[2]E(2,0) + x[3]E(3,0))/N$$

$$a_2 = (x[0]E(0,2) + x[1]E(1,2) + x[2]E(2,2) + x[3]E(3,2))/N$$

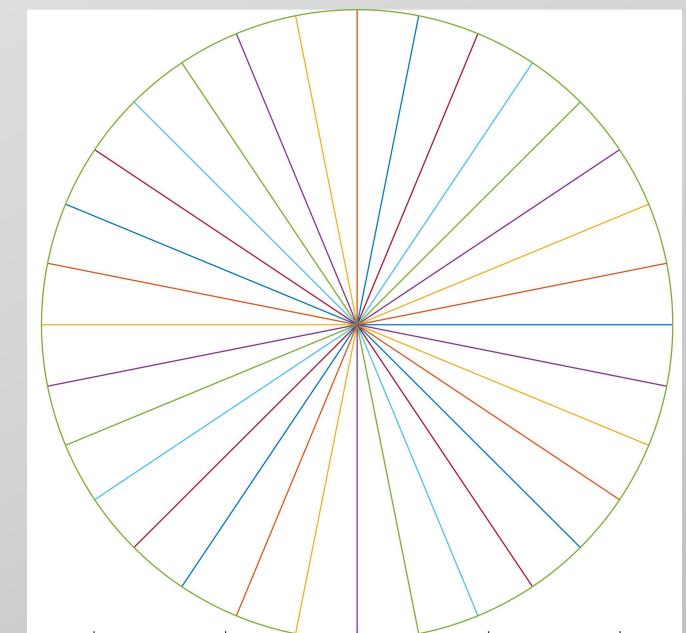
$$a_1 = (x[0]E(0,1) + x[1]E(1,1) + x[2]E(2,1) + x[3]E(3,1))/N$$

$$a_3 = (x[0]E(0,3) + x[1]E(1,3) + x[2]E(2,3) + x[3]E(3,3))/N$$



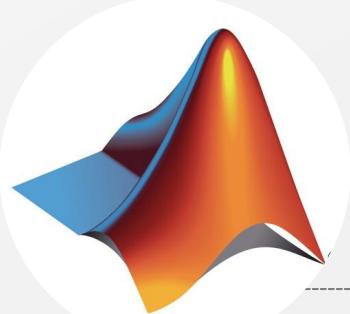
$E(n, k)$

*2 π is divided into 4 parts;
Although there are 16 elements, only four values are different from each other, and there is a symmetric relationship between them.*



To calculate the DFT and FFT of a 1024*1024 image:

CPU	Clock Frequency	DFT	FFT
1941	60 Hz	152.3 y	271.4 d
1971 (4004)	108KHz	30.8 d	3.6 h
1978 (8086)	10MHz	8.0 h	2.3 min
1982 (80286)	20MHz	4.0 h	1.2min
1985 (80386)	33MHz	2.4h	42.6s
1989 (80486)	100MHz	48.0min	14.1s
1995 (Pentium)	200MHz	24.0min	7.0s
1999 (Pentium III)	450MHz	10.7min	3.1s
2000 (Pentium 4)	1.4GHz	3.4min	1.0s
2001 (Pentium 4)	2GHz	2.4min	0.7s



Calculate DTFS by Matlab

$Y = \text{fft}(X)$ computes the discrete Fourier transform (DFT) of X using a fast Fourier transform (FFT) algorithm.

```
>> help fft
```

$$X(k) = \sum_{n=1}^N x(n) \exp(-j \cdot 2 \cdot \pi \cdot (k-1) \cdot (n-1) / N), \quad 1 \leq k \leq N.$$



- Compare with DTFS's Definition: $a_k = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-jk(2\pi/N)n} = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-jk(2\pi/N)n}$
- Calculate the DTFS of vector x whose period is N : $a = (1/N) * \text{fft}(x)$

```
clc,clear,close all
```

```
x=[zeros(1,20) ones(1,20)];
```

```
stem(0:39, x); xlim([0 39]); ylim([0 1.2]);
```

```
%DTFS by equations
```

```
N=length(x);
```

```
a=zeros(1,N);
```

```
for k=0:1:N-1
```

```
    for n=0:1:N-1
```

```
        a(k+1)=a(k+1)+x(n+1)*exp(-j*k*(2*pi/N)*n);
```

```
    end
```

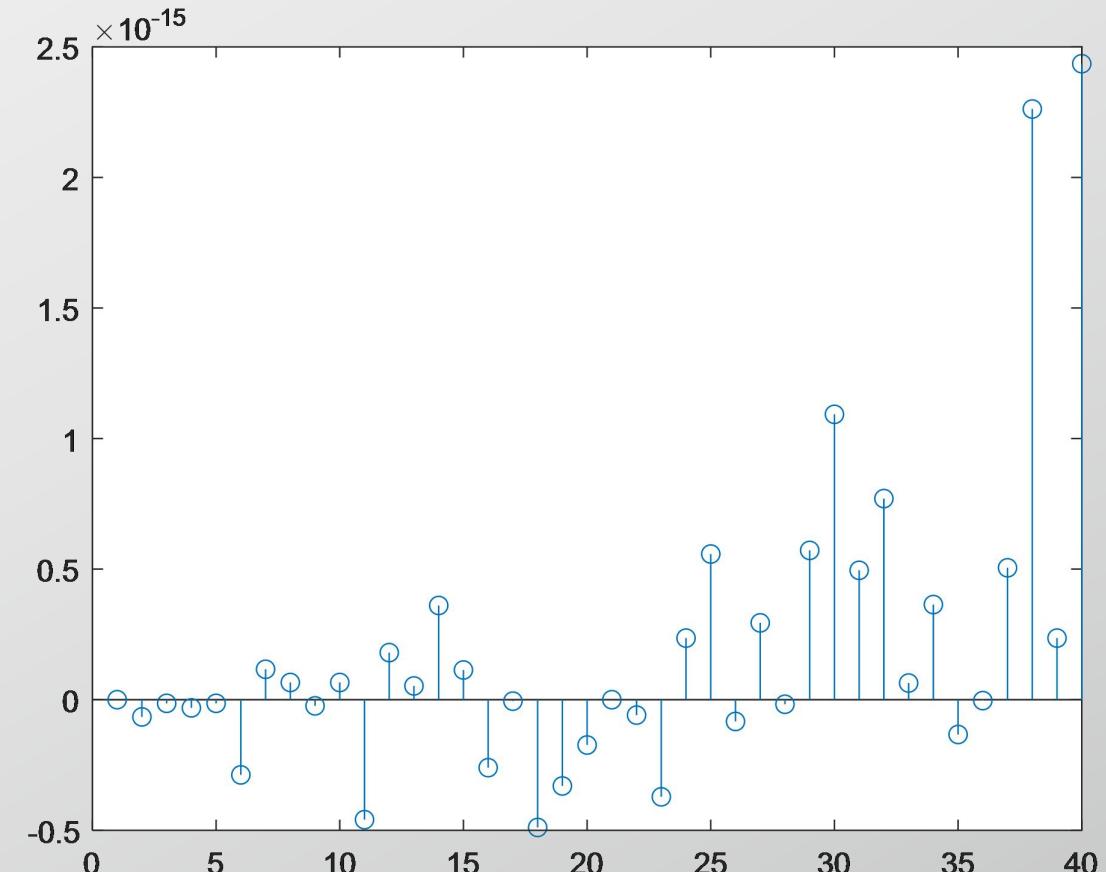
```
end
```

```
a=a./N;
```

```
%DTFS by fft
```

```
b=fft(x)/N;
```

```
stem(a-b)
```



X = ifft(Y), computes the inverse discrete Fourier transform of Y using a fast Fourier transform algorithm.

Reconstruct signals from DTFS coefficients

```
>> help fft
```

The inverse DFT (computed by IFFT) is given by
N

$$x(n) = \frac{1}{N} \sum_{k=1}^N X(k) * \exp(j * 2 * \pi * (k-1) * (n-1) / N), \quad 1 \leq n \leq N.$$



- Compare with our definition:

$$x[n] = \sum_{k=0}^{N-1} a_k e^{j k \omega_0 n} = \sum_{k=0}^{N-1} a_k e^{j k (2\pi/N) n}$$

- Reconstruct signal x from DTFS coefficients a: **x=N*ifft(a)**



$$a=1/N*fft(x), \quad x=N*ifft(a)$$

```
clear,close all
```

```
x=[0,1];
```

```
N=2;
```

```
%dtfs
```

```
a=1/N*fft(x);
```

```
%Synthesize x
```

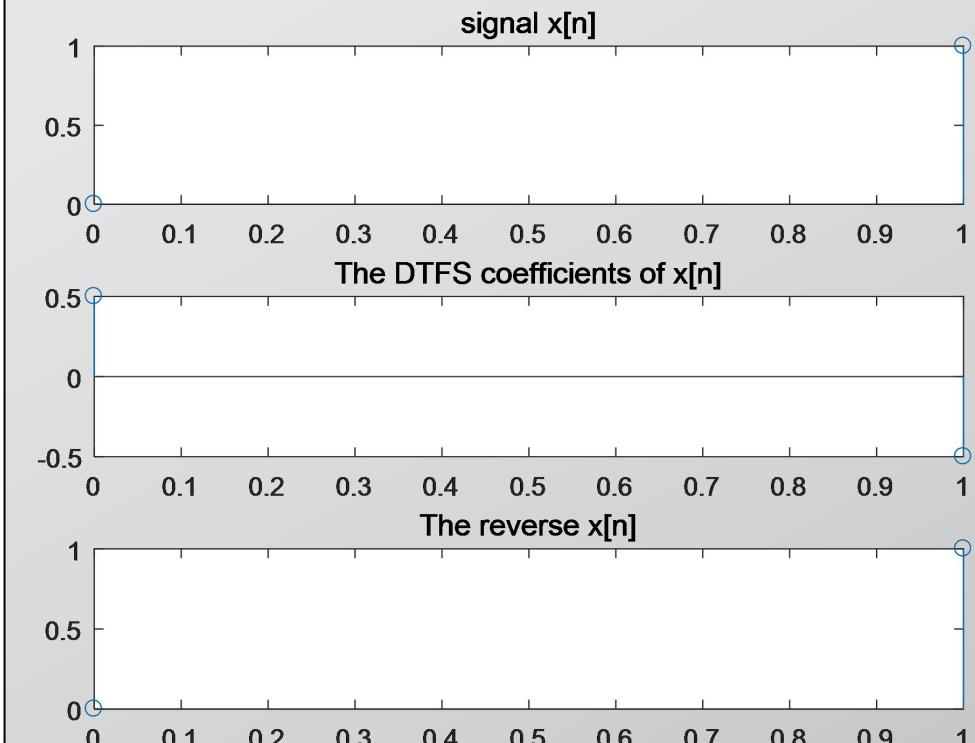
```
x_revers=N*ifft(a);
```

```
subplot(3,1,1),stem([0:N-1],x),title('signal x[n]')
```

```
subplot(3,1,2),stem([0:N-1],a),title('The DTFS coefficients of x[n]');
```

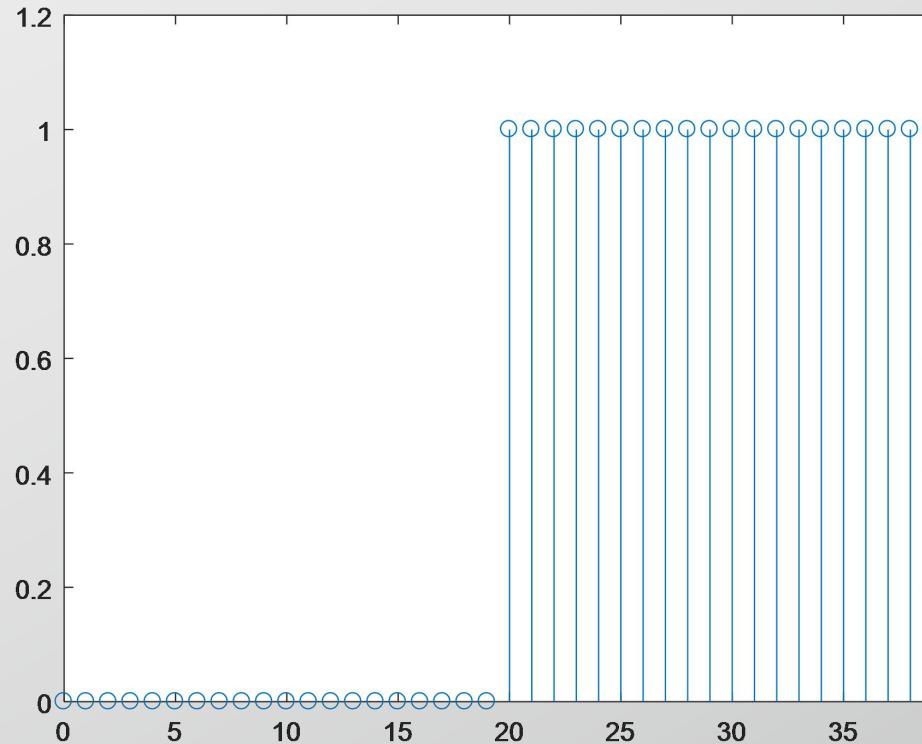
```
subplot(3,1,3),stem([0:N-1],x_revers),title('The reverse x[n]')
```

$$x[n] = \begin{cases} 1, & n = 1 \\ 0, & n = 0 \end{cases}, \text{ Period is 2}$$



Practice: Periodic Signal $x=[\text{zeros}(1,20) \text{ ones}(1,20)]; nx=0:1:39$; $N=40$. Calculate its Fourier Series coefficients by Matlab function fft;

```
x=[zeros(1,20) ones(1,20)];
stem(0:39, x);
xlim([0 39]);
ylim([0 1.2]);
```



```

N=length(x);
A =1/N* fft(x);
figure
subplot(2,1,1), stem(0: N-1,real(A),'*-' );
title('the real part of x[n] DTFS')
subplot(2,1,2), stem(0: N-1,imag(A),'*-' );
title('the imagginary part of x[n] DTFS')

```

A =

1 至 7 列

```

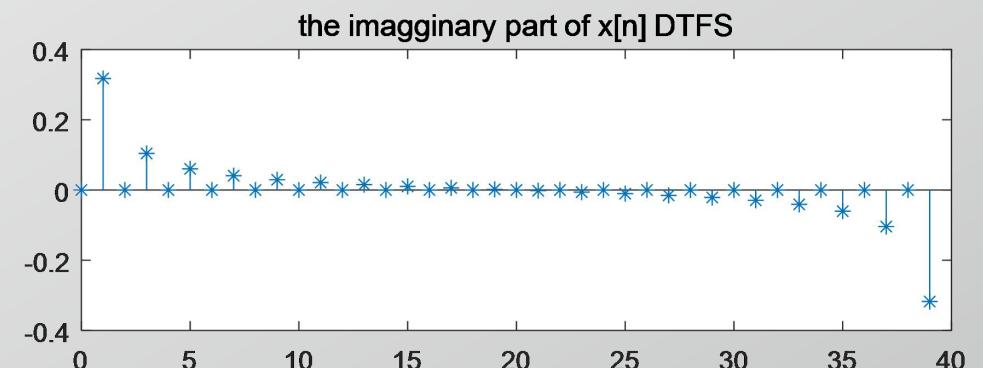
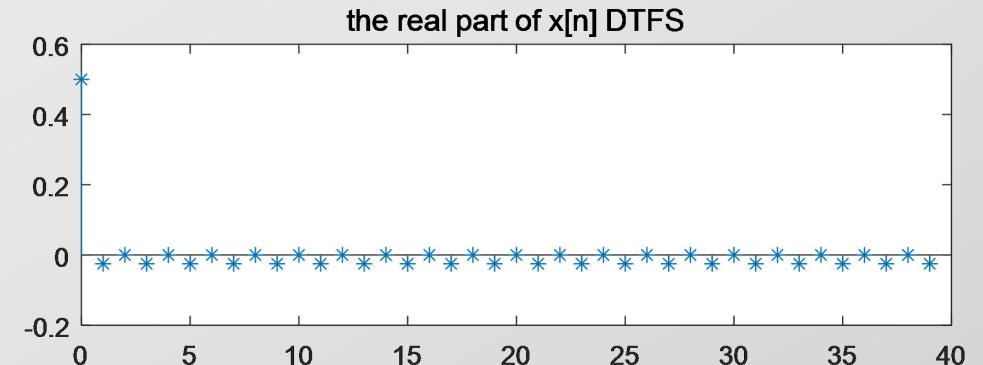
0.5000 + 0.0000i -0.0250 + 0.3177i 0.0000 + 0.0000i -0.0250 +
0.1041i 0.0000 + 0.0000i -0.0250 + 0.0604i 0.0000 + 0.0000i
.....
```

36 至 40 列

```

-0.0250 - 0.0604i 0.0000 + 0.0000i -0.0250 - 0.1041i 0.0000 +
0.0000i -0.0250 - 0.3177i
```

$$a=1/N*fft(x)$$



```
figure
```

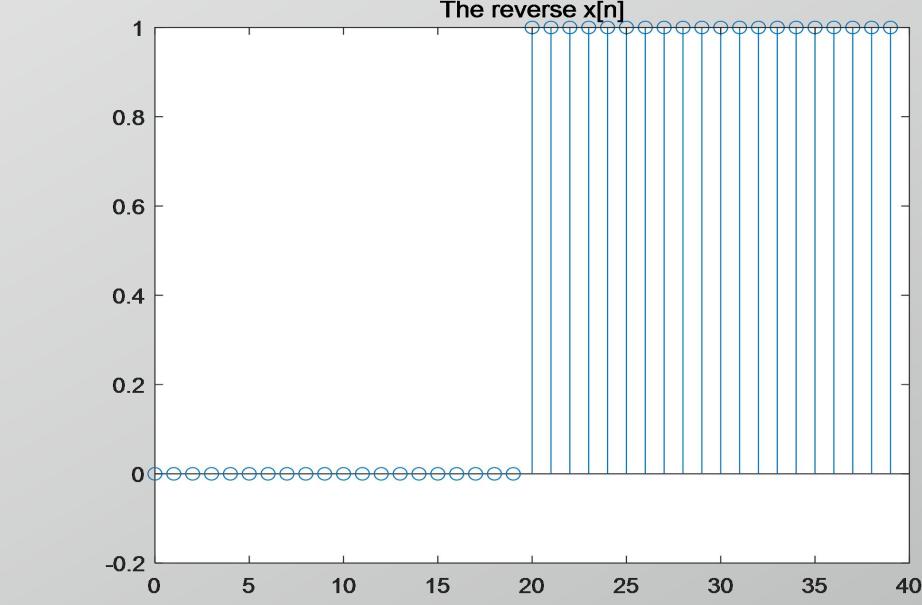
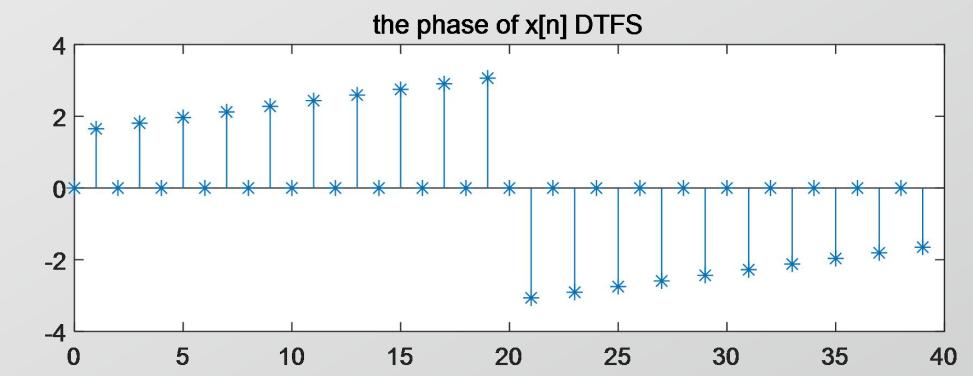
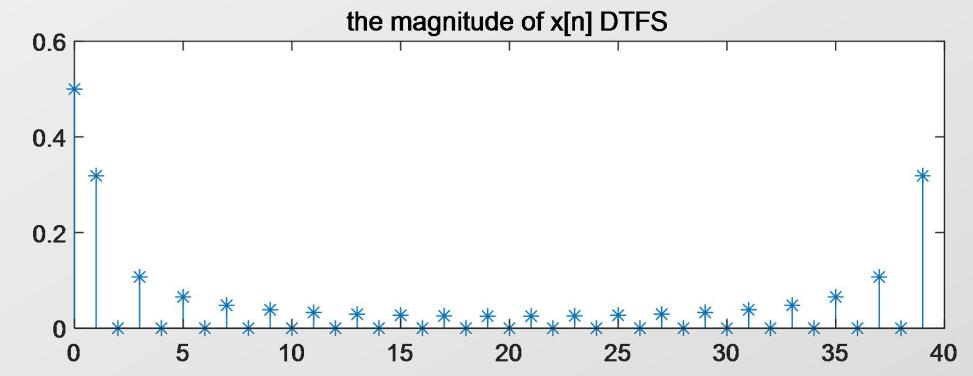
```
subplot(2,1,1),stem(0:N-1,abs(A),'*-' );  
title('the magnitude of x[n] DTFS')  
subplot(2,1,2),stem([0:N-1],angle(A),'*-' );  
title('the phase of x[n] DTFS')
```

```
%Synthesize x
```

```
x_revers=N*ifft(A)
```

```
figure
```

```
stem(0:N-1,x_revers),title('The reverse x[n]')
```

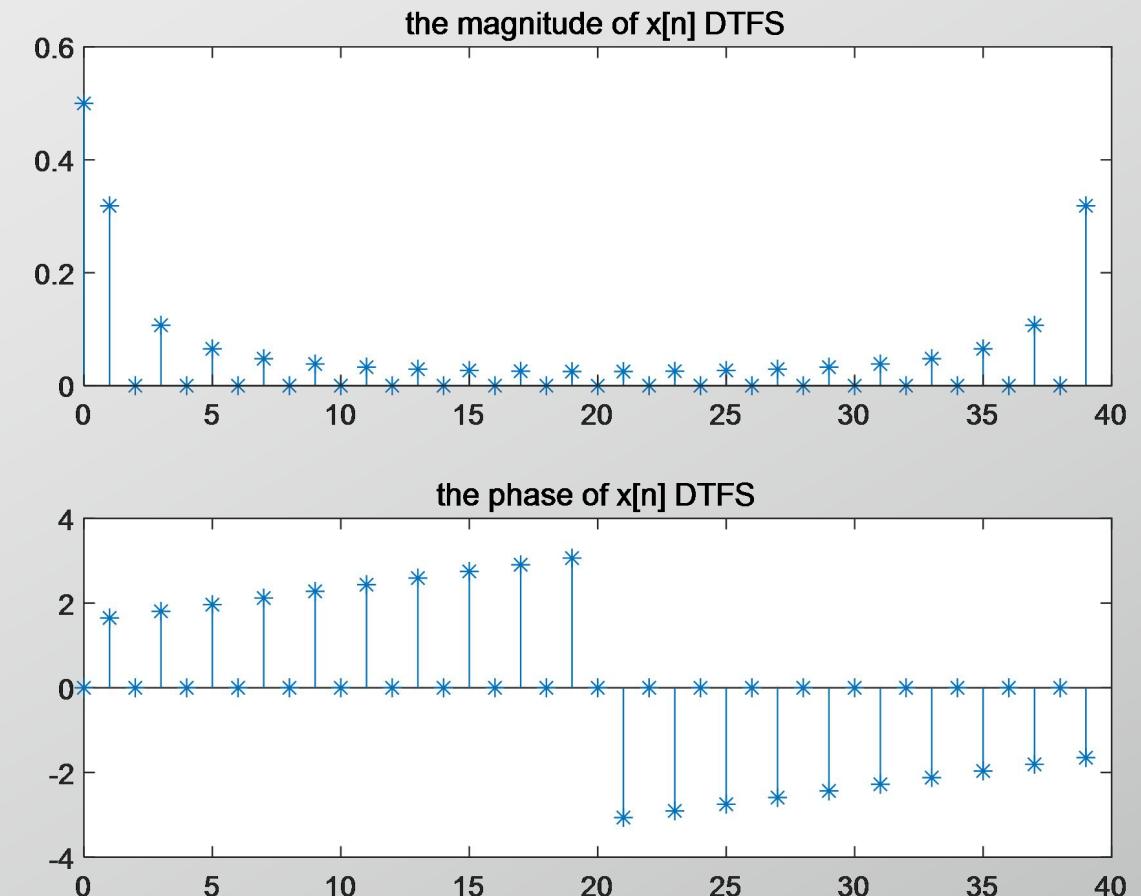


When $x(t)$ is **real**, its Fourier Series coefficients will be
Conjugate Symmetric, i.e., $a_{-k} = a_k^*$

figure

```
subplot(1,2,1),stem(0:length(x)-1,abs(A),'*-' );
title('the magnitude of x[n] DTFS')

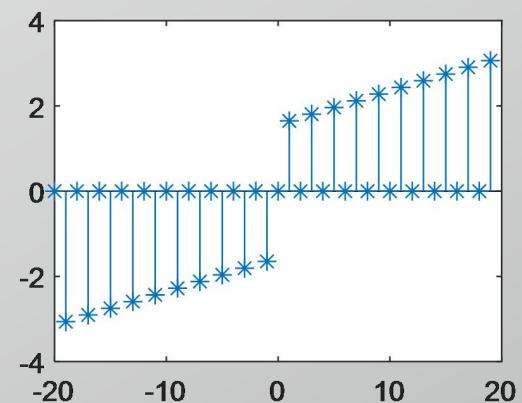
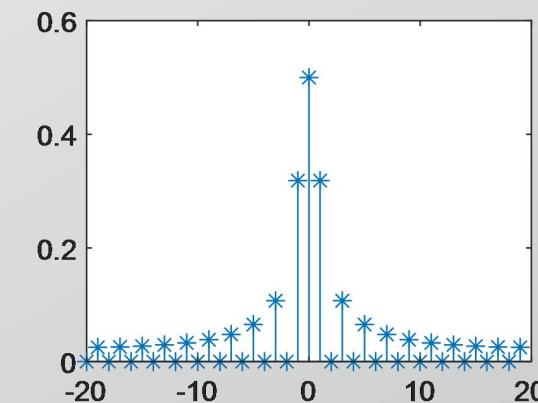
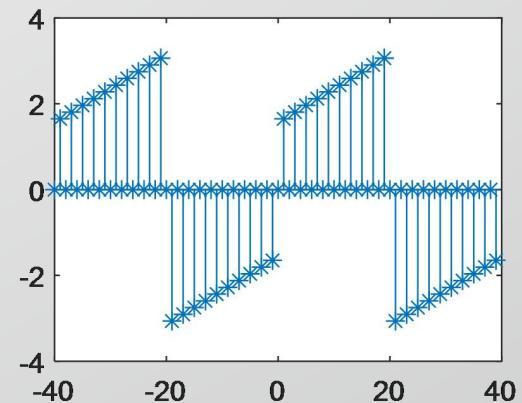
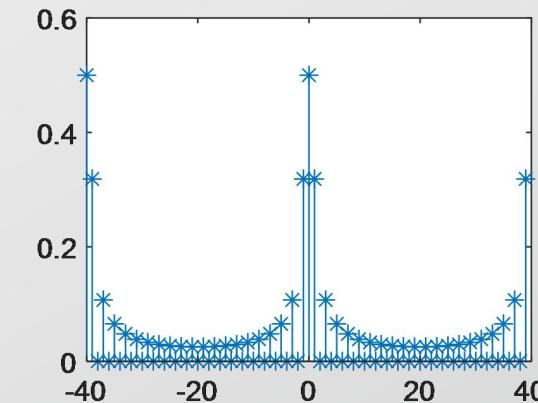
subplot(1,2,2),stem([0:length(x)-1],angle(A),'*-' );
title('the phase of x[n] DTFS')
```



When $x(t)$ is **real**, its Fourier Series coefficients will be
Conjugate Symmetric, i.e., $a_{-k} = a_k^*$

figure

```
subplot(2,2,1),stem([-N:N-1],[abs(A),abs(A)],'*-');
subplot(2,2,2),stem([-N:N-1],[angle(A),angle(A)],'*-');
subplot(2,2,3),stem([-N/2:N/2-1],abs(fftshift(A)),'*-');
subplot(2,2,4),stem([-N/2:N/2-1],angle(fftshift(A)),'*-');
```



A useful Matlab Function: **fftshift**

fftshift : Shift zero-frequency component to center of spectrum.

Y=fftshift(X), rearranges a Fourier transform X by shifting the zero-frequency component to the center of the array.

Tests:

```
ak1=[0 1 2 3 4 5 6 7];  
fftshift(ak1)
```

```
ak2=[0 1 2 3 4 5 6 7 8];  
fftshift(ak2)
```

Practice: $x[n]$ is a periodic signal and its Fourier Series coefficients is A. Please reconstruct signal $x[n]$

$$x = N * \text{ifft}(a)$$

```
A1 = [A(1) zeros(1,39)];
```

```
A2 = [A(1) A(2) zeros(1,37) A(40)];
```

```
A3 = [A(1) A(2:15) zeros(1,11) A(27:40)];
```

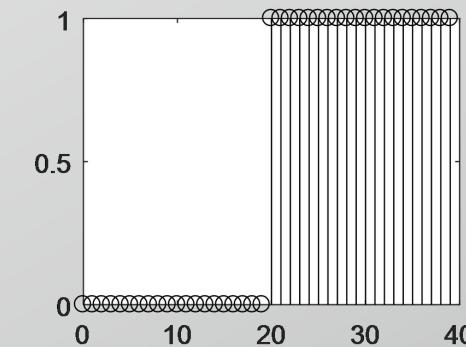
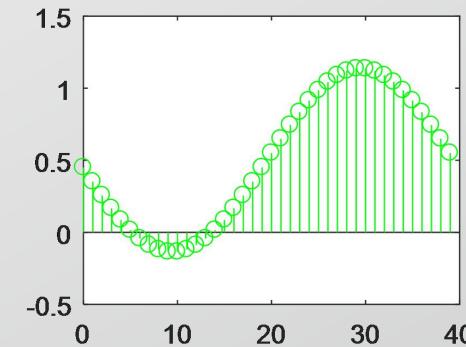
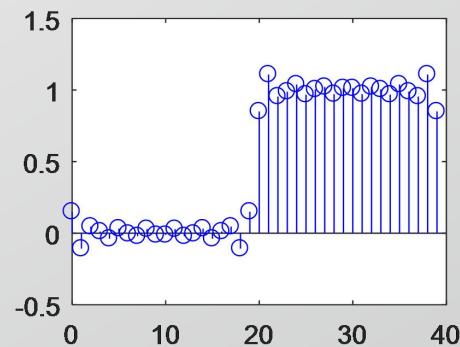
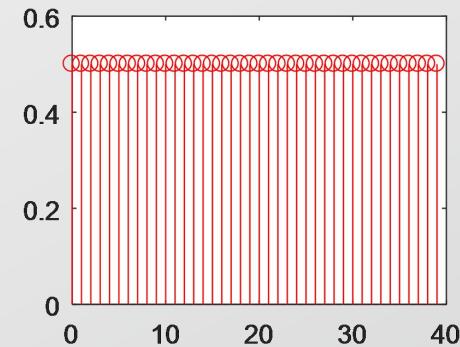
```
figure
```

```
subplot(2,2,1), stem(0:39,ifft(A1)*40, 'r');
```

```
subplot(2,2,2), stem(0:39,ifft(A2)*40, 'g');
```

```
subplot(2,2,3), stem(0:39,ifft(A3)*40, 'b');
```

```
subplot(2,2,4), stem(0:39,ifft(A)*40, 'k');
```



```
A= 0.5000 + 0.0000i -0.0250 + 0.3177i 0.0000 + 0.0000i -0.0250 + 0.1041i 0.0000 + 0.0000i  
-0.0250 + 0.0604i 0.0000 + 0.0000i -0.0250 + 0.0408i 0.0000 + 0.0000i -0.0250 + 0.0293i  
0.0000 + 0.0000i -0.0250 + 0.0214i .....
```

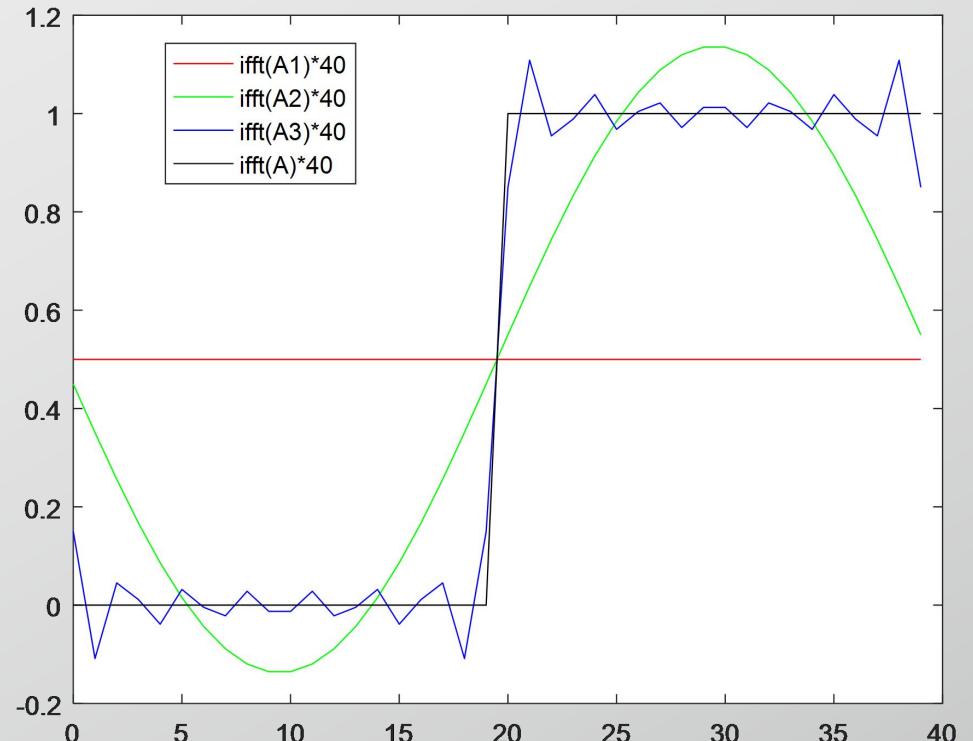


$$x = N * \text{ifft}(a)$$

figure

```
plot(0:39,ifft(A1)*40, 'r', ...  
     0:39,ifft(A2)*40, 'g', ...  
     0:39,ifft(A3)*40, 'b',...  
     0:39,ifft(A)*40, 'k');
```

```
legend('ifft(A1)*40','ifft(A2)*40','ifft(A3)*40','ifft(A)*40')
```



No Gibbs phenomenon



Fourier Series Representation of CT Periodic Signals

CTFS

$$x(t) = \sum_{k=-\infty}^{+\infty} a_k e^{jkw_0 t} = \sum_{k=-\infty}^{+\infty} a_k e^{jk(2\pi/T)t}$$

$$a_k = \frac{1}{T} \int_T x(t) e^{-jkw_0 t} dt = \frac{1}{T} \int_T x(t) e^{-jk(2\pi/T)t} dt$$

→ *Synthesis Equation*

→ *Analysis Equation*

$\{a_k\}$ are often called the Fourier series coefficients or the **spectral coefficients**.

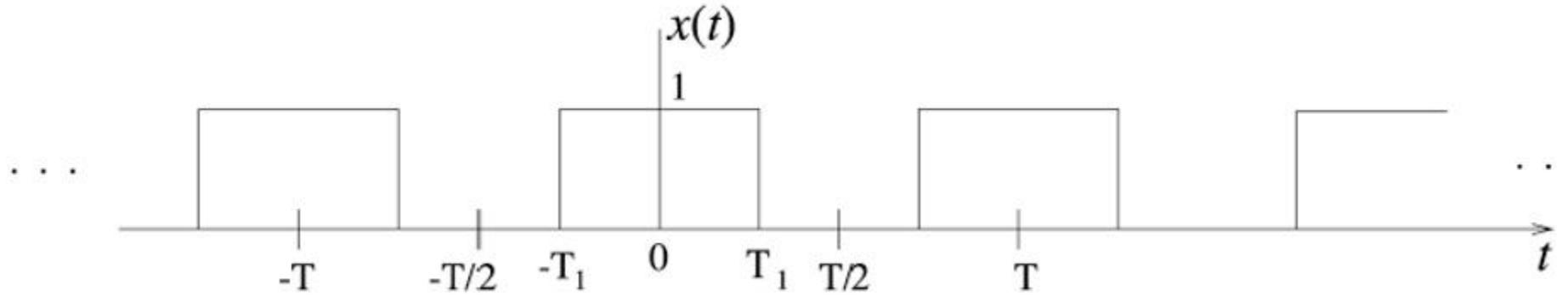
$$k \in (-\infty, +\infty)$$

$$a_0 = \frac{1}{T} \int_T x(t) dt$$

$$\frac{1}{T} \int_T |x(t)|^2 = \sum_{-\infty}^{+\infty} |a_k|^2$$

Linearity, Time shifting,
Frequency Shifting, Time
Reversal, Time Scaling,
Periodic Convolution,
Multiplication, Conjugate
Symmetry for Real Signals,
Parseval's Relation for
Periodic Signals

Lab 3.11, 3.12

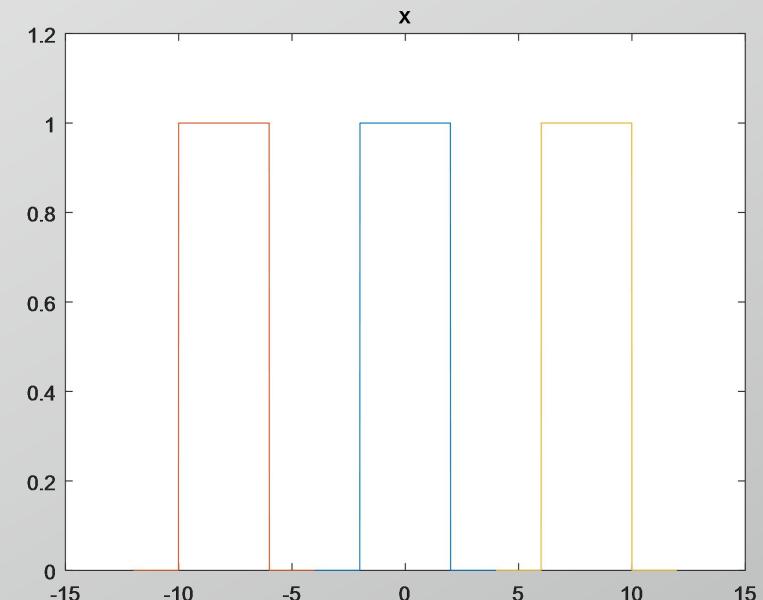


$$a_k = \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-jk\omega_0 t} dt = \frac{\sin(kw_0 T_1)}{k\pi}$$

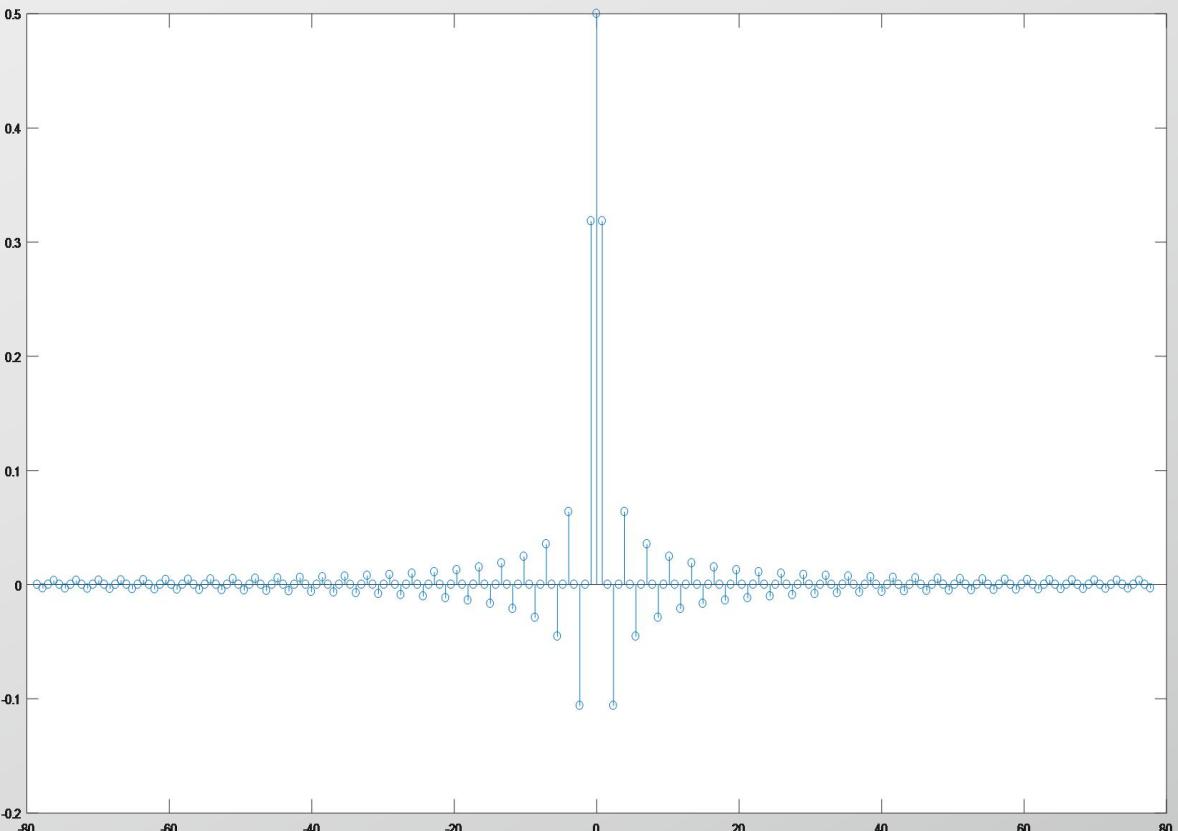
```

clear,close all
step=0.01;
t=-4:step:4-step;
x=[zeros(1,length(t)/4),ones(1,length(t)/2),zeros(1,length(t)/4)];
figure
plot(t,x),title('x'),ylim([0 1.2]),hold on
plot((t-8),x),hold on,plot((t+8),x)

```

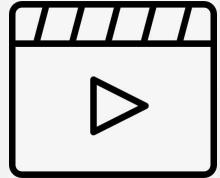


```
N=100;  
k=-N:1:N-1;  
T=8;  
T1=2;  
w0=2*pi/T;  
T1=2;  
a0=0.5;  
a=(sin(k*w0*T1)/pi)./k  
a(N+1)=0.5;  
stem(k,a)
```



Properties of DTFS

线性性质	$Ax[n] + By[n] \xrightarrow{FS} Aa_k + Bb_k$
时移性质	$x[n - n_0] \xrightarrow{FS} e^{jk\omega_0 n_0} a_k = e^{jk(2\pi/T)t n_0} a_k$
时间反转	$x[-n] \xrightarrow{FS} a_{-k}$
时域尺度变换	$x_{(m)}[n] = \begin{cases} x\left[\frac{n}{m}\right], & \text{若 } n \text{ 是 } m \text{ 的倍数} \\ 0, & \text{若 } n \text{ 不是 } m \text{ 的倍数} \end{cases} \xrightarrow{FS} \frac{1}{m} a_k \text{ 周期为 } mN$
共轭和共轭对称性质	$x^*[n] \xrightarrow{FS} a_{-k}^*$
	实信号的共轭对称 $a_k = a_k^*$ 当 $x[n]$ 为实信号
周期卷积	$\sum_{r=<N>} x[r]h[n-r] \xrightarrow{FS} N a_k b_k$
相乘	$x[n]y[n] \xrightarrow{FS} d_k = \sum_{l=<N>} a_l b_{k-l}$
频移性质	$e^{jM(2\pi/N)n} x[n] \xrightarrow{FS} a_{k-M}$
一个周期的平均功率等于它所有谐波分量的平均功率之和	
帕萨瓦尔定理	$\frac{1}{N} \sum_{k=<N>} x[n] ^2 = \sum_{k=<N>} a_k ^2$



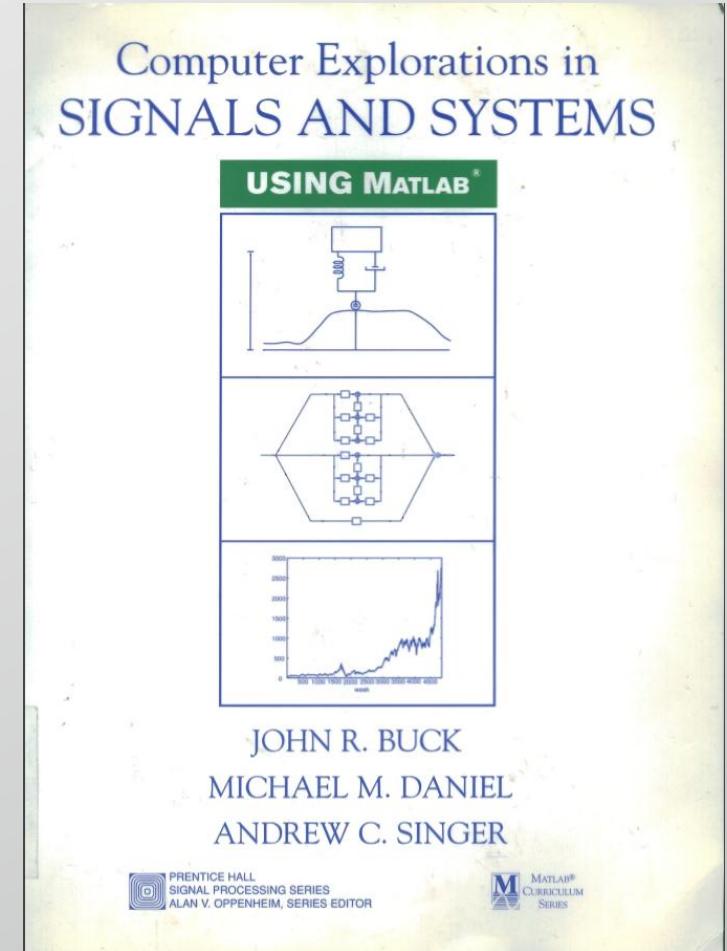
Lab3 Assignments a

- Read tutorial 3.1、3.2
- Assignments: 3.5 & 3.10

Tips :

1

Several parts of this exercise require you to generate vectors which should be purely real, but have very small imaginary parts due to numerical roundoff errors. Use **real** to remove these residual imaginary parts from these vectors.



■ 3.5 Synthesizing Signals with the Discrete-Time Fourier Series

The discrete-time Fourier series (DTFS) is a frequency-domain representation for periodic discrete-time sequences. The synthesis and analysis equations for the DTFS are given by Eqs. (3.1) and (3.2). This exercise contains three sets of problems to give you practice working with these equations. The Basic Problems allow you to synthesize a very simple periodic discrete-time signal from its DTFS coefficients. In the Intermediate Problems, you will both analyze a set of periodic discrete-time signals to obtain their DTFS coefficients, and construct one of these signals by adding in a few coefficients at a time. For the Advanced Problem, you will write a function to find the DTFS coefficients of an arbitrary periodic discrete-time signal from one period of samples.

Basic Problems

In these problems, you will synthesize a periodic discrete-time signal with period $N = 5$ and the following DTFS coefficients

$$a_0 = 1, \quad a_2 = a_{-2}^* = e^{j\pi/4}, \quad a_4 = a_{-4}^* = 2e^{j\pi/3}.$$

- (a). Based on the DTFS coefficients, do you expect $x[n]$ to be complex-valued, purely real, or purely imaginary? Why?
- (b). Using the DTFS coefficients given above, determine the values of a_0 through a_4 and specify a vector \mathbf{a} containing these values.

2

Lab 3.5

- The DTFS coefficients of a periodic discrete-time signal with period N = 5:

$$a_0 = 1, \quad a_2 = a_{-2}^* = e^{j\pi/4}, \quad a_4 = a_{-4}^* = 2e^{j\pi/3}.$$

$$a_1 \ ? \ ?$$

$$a_3 \ ? \ ?$$

$$a_k = a_{k+N}$$

3

$$x[n] = \sum_{k=<N>} a_k e^{jk\omega_0 n} = \sum_{k=<N>} a_k e^{jk(\frac{2\pi}{N})n}$$
$$a_k = \frac{1}{N} \sum_{k=<N>} x[n] e^{-jk\omega_0 n} = \frac{1}{N} \sum_{k=<N>} x[n] e^{-jk(2\pi/N)n}$$

→ *Synthesis Equation* $x[n]=\mathcal{N}^{\star}ifft(a)$

→ *Analysis Equation* $a=(1/\mathcal{N})^{\star}fft(x)$

4

Lab 3.10 (b) (c)

Suggested in the lab book: measure the number of operations by using the internal flops ‘**flops**’

This is an obsolete function

- ✓ Measure the function performance difference by comparing the time cost by functions rather than numbers of floating point operations.
- ✓ Try to keep the PC conditions unchanged while measuring the functions timecosts

To measure the elapsed time by a function, you can choose one of the followings:

etime

tic, toc

timeit



```
t0 = clock;  
X = dtfs(x,0)  
dtfstime = etime(clock,t0)  
  
t1 = clock;  
X2 = fft(x)  
ffftime = etime(clock,t1)
```

```
>> help etime  
etime Elapsed time.
```

etime(T1,T0) returns the time in seconds that has elapsed between vectors T1 and T0. The two vectors must be six elements long, in the format returned by CLOCK:

```
T = [Year Month Day Hour Minute Second]
```

```
>> help clock  
clock Current date and time as date vector.
```

C = clock returns a six element date vector containing the current time and date in decimal form:

```
[year month day hour minute seconds]
```

➤ *tic*,*toc*

```
tic  
X = dtfs(x,0);  
toc  
tic  
X2 = fft(x);  
toc
```

```
>> help tic  
tic Start a stopwatch timer.  
tic and TOC functions work together to measure  
elapsed time.  
tic, by itself, saves the current time that TOC uses later  
to measure the time elapsed between the two.
```

➤ *timeit*

```
f1 = @( ) dtfs(x,0);  
t1_timeit = timeit(f1)  
f2 = @( ) fft(x)  
t2_timeit = timeit(f2)
```

```
>> help timeit  
timeit Measures time required to run function.  
T = timeit(F) measures the typical time (in seconds)  
required to run the function specified by the function  
handle F that takes no input argument.
```

To measure performance, it is recommended to use the **timeit** or **tic** and **toc** functions

If your PC is so good that the time cost by fft is always 0,
try to increase the value of N. ☺

Or, put your codes in a for-loop,

- Periodic convolution:

Suppose x and y are two periodic signals with common period N , the periodic convolution between x and y is defined as

$$x[n] \odot y[n] = \sum_{k=0}^{N-1} x[k]y[n-k]$$

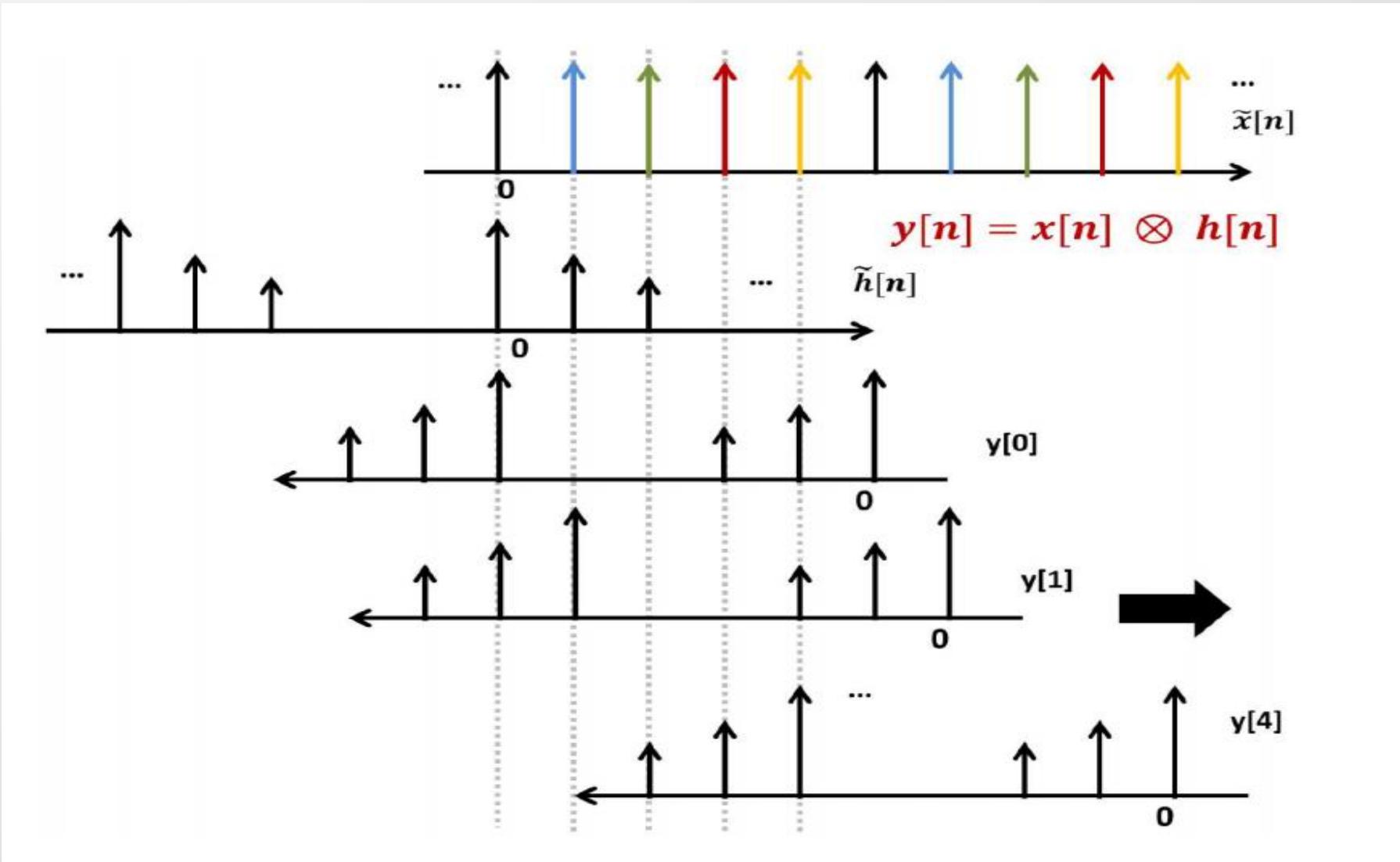
- Suppose $x[n] \rightarrow a_k$ and $y[n] \rightarrow b_k$, then

$$x[n] \odot y[n] \rightarrow N a_k b_k \text{ and } x[n]y[n] \rightarrow a_k \odot b_k$$

➤ Periodic Convolution with the FFT

Periodic convolution in time domain is equivalent to multiplication in frequency domain

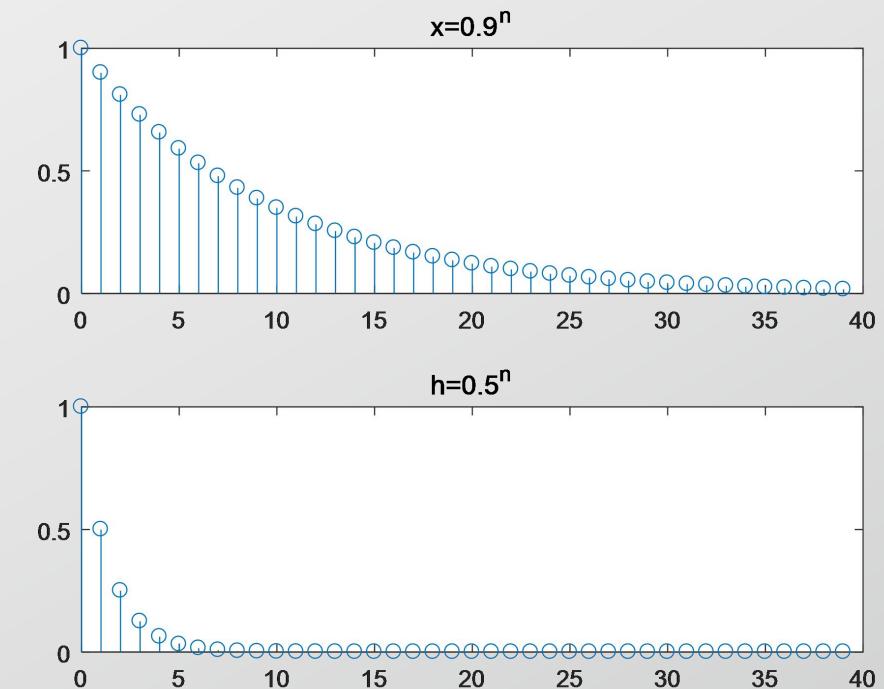
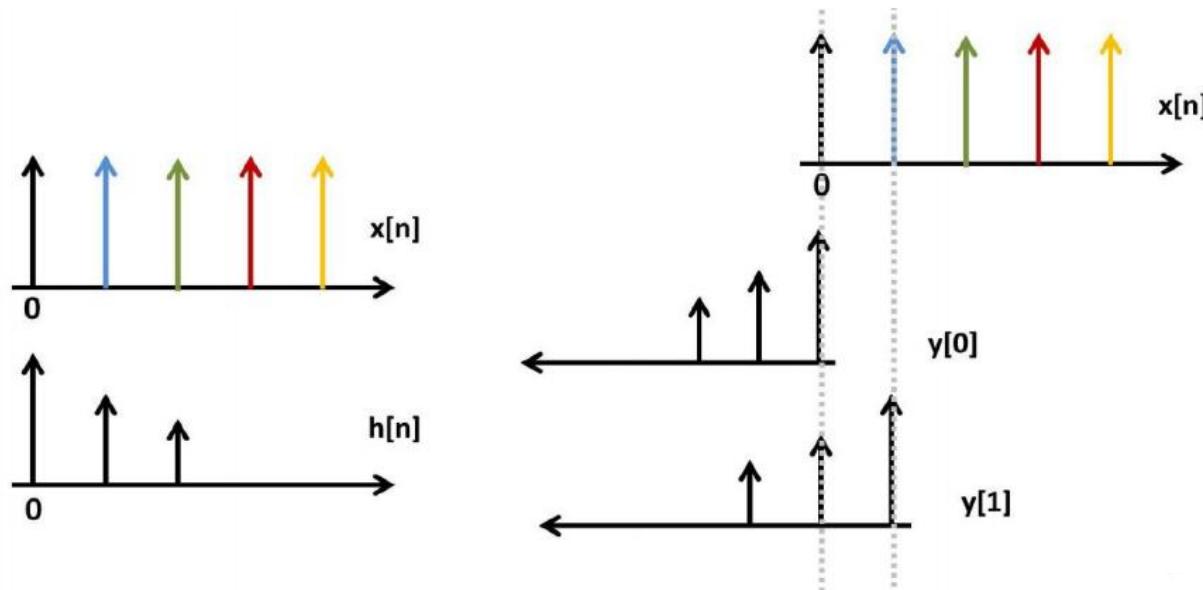
$$y[n] = \sum_{r=<N>} x[r]h[n-r] = \sum_{r=0}^{N-1} x[r]h[n-r] = x[0]h[n] + x[1]h[n-1] + \dots + x[N-1]h[n-(N-1)]$$



Lab 3.10 (g)

```

N=40;
n=0:1:N-1;
x=0.9.^n;
h=0.5.^n;
figure
subplot(2,1,1),stem(n,x),title('x=0.9^n');
subplot(2,1,2),stem(n,h),title('h=0.5^n');
    
```



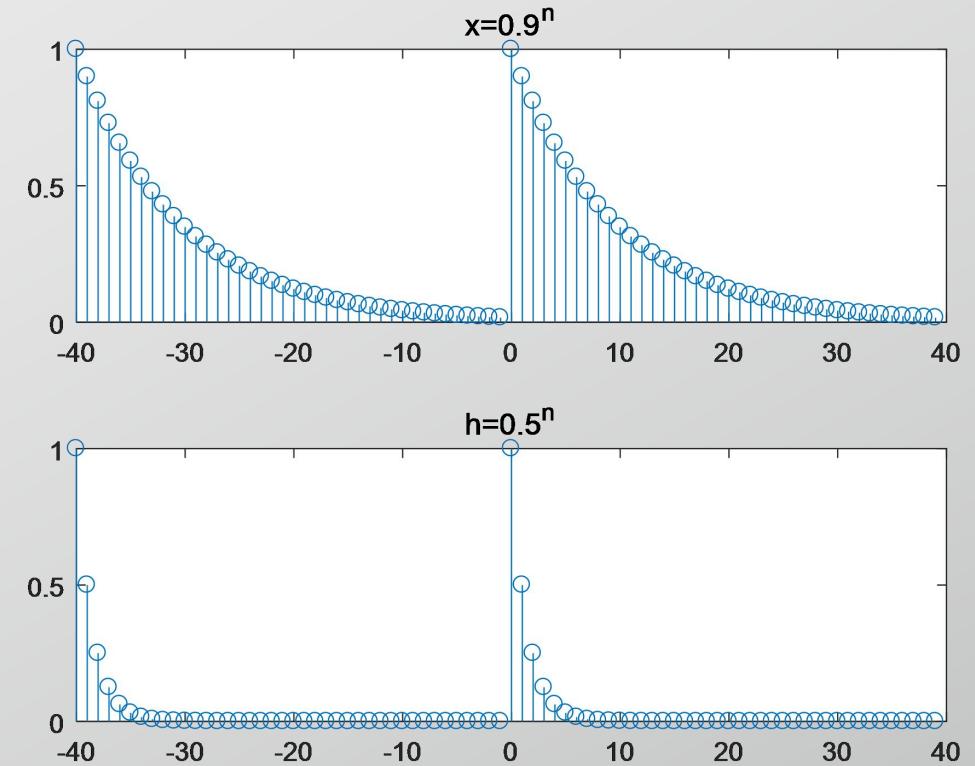
$\text{conv}(x, h)$



Lab 3.10 (g)

$$y[n] = \sum_{r=<N>} x[r]h[n-r] = \sum_{r=0}^{N-1} x[r]h[n-r] = x[0]h[n] + x[1]h[n-1] + \dots + x[N-1]h[n-(N-1)]$$

```
N=40;  
n=0:1:N-1;  
x=0.9.^n;  
h=0.5.^n;  
figure  
subplot(2,1,1),stem(-40:39,[x,x]),title('x=0.9^n');  
subplot(2,1,2),stem(-40:39,[h,h]),title('h=0.5^n');
```

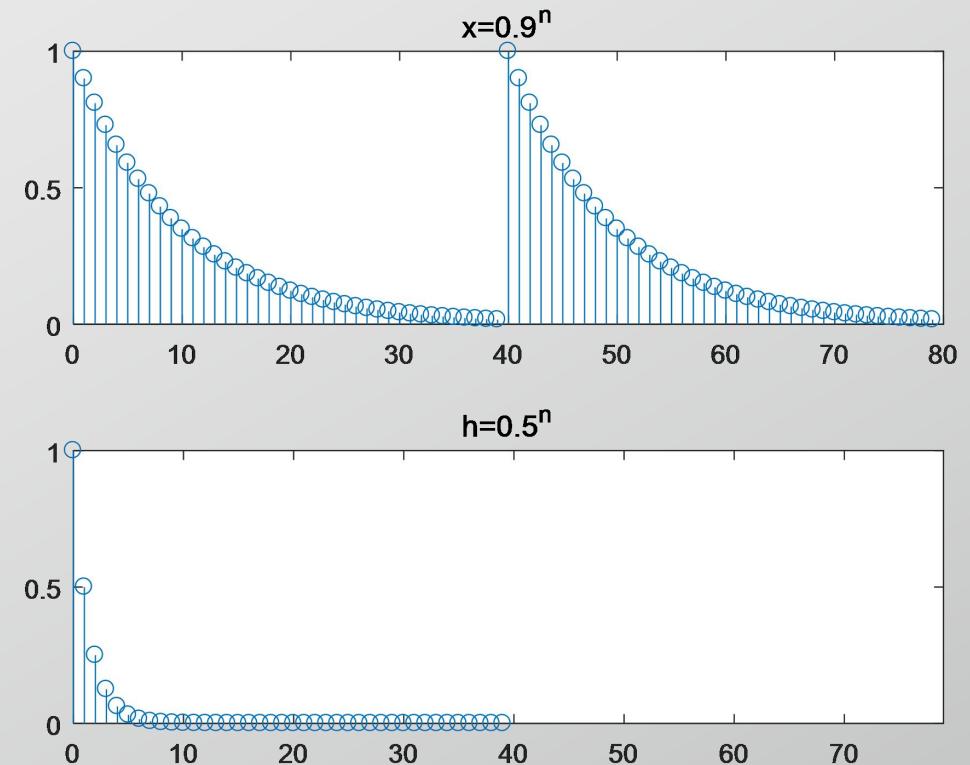


Calculate Periodic Convolutions Using Linear Convolutions

Lab 3.10 (g)

$$\text{conv}([x,x], h)$$

```
N=40;  
n=0:1:N-1;  
x=0.9.^n;  
h=0.5.^n;  
figure  
subplot(2,1,1),stem(0:79,[x,x]),title('x=0.9^n');  
subplot(2,1,2),stem(0:39,h),title('h=0.5^n'),xlim([0 79]);
```



Calculate Periodic Convolutions Using Linear Convolutions