Proposal CS686

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***Abstract*— Topic will be the route-finding problems for Autonomous Guided Vehicles. Includes the general path finding and collision avoidance.**

I. Introduction

An automated guided vehicle or automatic guided vehicle (AGV) is a robot that follows along marked long lines or wires on the floor, or uses radio waves, vision cameras, magnets, or lasers for navigation. AGVs are commonly used to transport raw materials in industry such as paper, steel, rubber, metal, and plastic. AGVs are also deployed within warehouses and fulfillment centers to automate material handling and package logistics.

The route-finding problem and the AGV scheduling problem is a interesting problem because it is more than a path-finding problem. It is a combination of path finding, task scheduling and collision avoidance.

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