

# PHYSICALY BASED RENDERING

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## 1. RADIOMETRY & LIGHT ATTENUATION

### 1.1. Radiometry Recap. What to measure in a simulation?

**Definition 1.1** (Radiant flux). Total amount of energy passing through surface (measured per second).  $\Phi [W]$ .

This is not sufficient to measure, because it is the energy per surface area, then consider a large radiant flux that could either be

- (1) a lot of energy over a small surface.
- (2) a little energy over a large surface.

Thus this metric is too ambiguous, and not good enough for us.

**Definition 1.2** (Irradiance). Total amount of energy passing through a unit area.  $E [W/m^2]$ .

This is still ambiguous, we haven't fixed the angle which the light arrives to the surface. So

- (1) a lot of energy in a huge angle
- (2) a little energy in a small angle

will measure the same irradiance.

**Definition 1.3** (Radiance). Total energy passing through a unit area with unit angle  $I [W/(m^2 \cdot sr)]$ <sup>1</sup>.

This is the measurement that we will be using.

### 1.2. The most fundamental question. How much light exits a surface point in a given direction?

The complete answer is given by Maxwell equations! In practice, we don't do this, it would require simulations on the size of wavelengths of light, and that is overly complex.

The real solution is the rendering equation!

### 1.3. The scalar product.

$$\vec{a} \cdot \vec{b} \equiv \|\vec{a}\| \cdot \|\vec{b}\| \cos \theta.$$

For this work we will always assume that the vectors are normalized, and so this becomes

**1.4. Terminology.** The key components in the terminology are depicted in figure 1.1<sup>2</sup>.

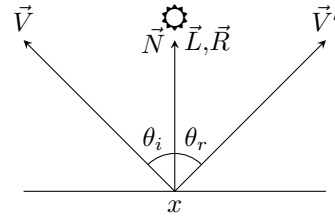


FIGURE 1.1. Basic terminology

$\vec{V}$  direction towards the viewer (eye, camera)

$\vec{N}$  surface normal

$\vec{L}$  vector point towards the light source

$\vec{R}$  reflected ray direction  $\vec{R} = \vec{L} - 2\vec{N}\vec{L} \cdot \vec{N}$ .

$\theta_i, \theta_r$  incident and reflected angles.

**1.5. Light Attenuation.** When the sun is directly above as in figure 1.1, then

$$(\vec{L} \cdot \vec{N}) \Phi = \cos \alpha|_{\alpha \approx 0} \Phi = \Phi.$$

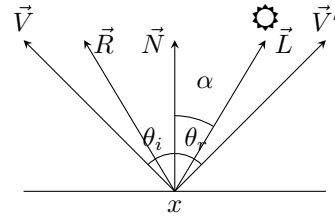


FIGURE 1.2. Light attenuation with sun at  $45^\circ$ .

When the sun is at an angle as in figure 1.2, then

$$(\vec{L} \cdot \vec{N}) \Phi = \cos \alpha|_{\alpha \approx 45^\circ} \Phi = 0.7\Phi.$$

<sup>1</sup>Angle in more dimensions is called solid angle, for which the unit is steradians(sr)

<sup>2</sup>Vectors are always pointing away from the point of interest  $x$

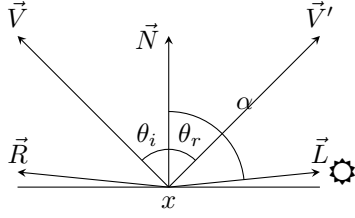


FIGURE 1.3. Light attenuation with sun at  $90^\circ$ .

When the sun is at an angle as in figure 1.3, then

$$(\vec{L} \cdot \vec{N}) \Phi = \cos \alpha |_{\alpha \approx 90^\circ} \Phi = 0.$$

Thus we can model this light attenuation using this dot product.

## 2. BRDF MODELS & THE RENDERING EQUATION

### 2.1. Materials. What makes the difference between materials?

Different materials reflect incoming light to different directions and absorb different amounts of it.

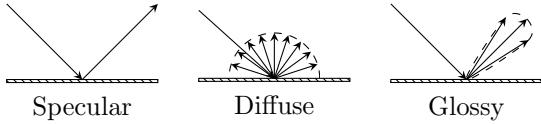


FIGURE 2.4. Specula, diffuse, and spread reflections from a surface

**Specular:** For one incoming direction there is only one outgoing direction, this is what a mirror would be.

**Diffuse:** For one incoming direction on there are many possible outcomes.

**Glossy/Spread:** This is a mixture of specular and diffuse.

**2.2. BRDF.** We will create a probability density function that takes

- (1) an incoming light direction
- (2) a point on the surface

as parameters, and outputs the probability of a given outward direction. We define this function as

**Definition 2.1** (Bidirectional reflectance distribution function(BRDF)).

$$f_r(\vec{\omega}, x, \vec{\omega}').$$

What about materials that don't reflect all incoming light, some things that could transmit the light. There are some examples in figure 2.5.

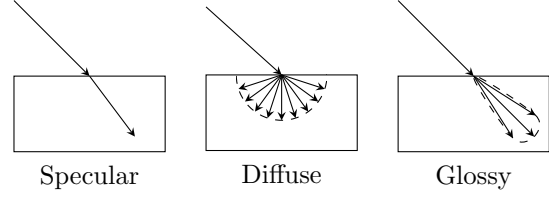


FIGURE 2.5. Transmitted models of light

Things are transparent because atom are mostly empty. Things are opaque, because the electrons are absorbing the photons. The electrons then jump to an outer orbit. Glass is transparent because the orbits of the electrons are too far apart, so that if an electron absorbs a photon it does not get enough energy to jump to the higher orbit. Note that if the light is of a higher energy (not in the visible spectrum) then it could be opaque. For instance glass is opaque to UV-light.

**2.3. BTDF.** For light that is also transmitted, we have the Bidirectional transmittance distribution function.

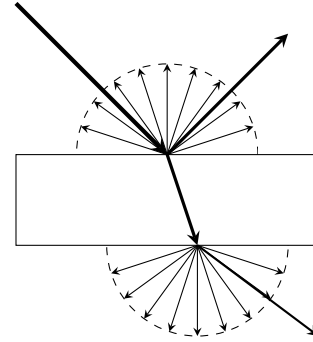


FIGURE 2.6. Light that is both reflected and transmitted

**2.4. BSDF.** To generalize the BRDF and BTDF, we use the BSDF (S is for scattering).

### 2.5. BRDF Properties.

- (1) Helmholtz-reciprocity: The direction of the ray of light can be reversed

$$\forall \vec{\omega}, \vec{\omega}' : f_r(\vec{\omega}, x, \vec{\omega}') = f_r(\vec{\omega}', x, \vec{\omega})$$

- (2) Positivity: It is an impossibility for an exit direction to have a negative probability.

$$\forall \vec{\omega}, \vec{\omega}' : f_r(\vec{\omega}, x, \vec{\omega}') \geq 0$$

- (3) Energy conservation: An object may reflect or absorb incoming light, but no more can come out than the incoming amount.

$$\int_{\Omega} f_r(\vec{\omega}, x, \vec{\omega}') \cos \theta d\vec{\omega}' \leq 1$$

This means that we add up all the incoming energy from all possible directions, taking the light attenuation into account. If it equals 1, all light is reflected, if it is less than 1 some of the light is absorbed. More than 1 is impossible.

**2.6. The Rendering Equation.** An object can emit light itself. It also receives light from different directions, which it will either reflect or absorb, therefore

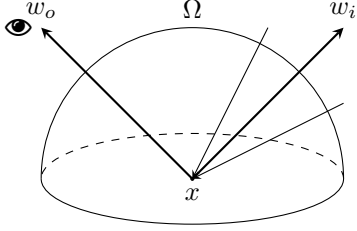


FIGURE 2.7. Rendering Equation Representation

$$L_o(x, \vec{\omega}) = \underbrace{L_e(x, \vec{\omega})}_{\text{emitted}} + \underbrace{\int_{\Omega} L_i(x, \vec{\omega}) f_r(\vec{\omega}, x, \vec{\omega}') \cos \theta d\vec{\omega}'}_{\text{reflected incoming light}}$$

Where

$L_o(x, \vec{\omega})$ : exiting radiance in point  $x$  towards direction  $\vec{\omega}$ .

$L_e(x, \vec{\omega})$ : emitted radiance in point  $x$  towards direction  $\vec{\omega}$ .

$\int_{\Omega} \dots d\vec{\omega}'$ : Sum of the incoming radiance from all  $\vec{\omega}'$  directions<sup>3</sup>.

$L_i(x, \vec{\omega}')$ : Incoming radiance from the direction  $\vec{\omega}'$  to point  $x$ .

$f_r(\vec{\omega}, x, \vec{\omega}')$ : BRDF.

$\cos \theta$ : light attenuation.

Difficulties

- (1) The exitant radiance of a point  $x$  depends on the incoming radiance of every other point, which also depend on  $x$ . Thus every point depends on every other point, and so would be infinitely recursive.
- (2) It is absolutely hopeless to compute this integral in closed form.
- (3) The integral is also infinite-dimensional. We need to compute an infinite number of bounces of light.
- (4) It is often singular.

As of now, we have insufficient knowledge to even give an approximate solution to this equation.

The solution is to compute the entirety of the light path, then move the last bounce point, and compute the contribution of each individual light source to the sensor. This is not what we will be using. But here it is

$$L_o(p' \rightarrow p) = L_e(p' \rightarrow p) + \int_A L_i(p^n \rightarrow p') f_r(p^n \rightarrow p' \rightarrow p) \cdot G(p^n \leftrightarrow p') dA(p^n)$$

$L_o(p' \rightarrow p)$ : outgoing radiance from point  $p'$  to  $p$ .

$L_e(p' \rightarrow p)$ : emitted radiance from  $p'$  to  $p$ .

$\int_{\Omega} \dots dA(p^n)'$ : sum for all possible  $p^n$  surface points.

$L_i(p^n \rightarrow p')$ : incoming radiance from point  $p^n$  to  $p'$ .

$f_r(p^n \rightarrow p' \rightarrow p)$ : probability of  $p^n \rightarrow p' \rightarrow p$  transfer.

$G(p^n \leftrightarrow p')$ : geometry term.

### 3. DIFFUSE, SPECULAR, AND AMBIENT SHADING

<sup>3</sup> $\Omega$  is only the hemisphere, because the  $\cos \theta$  from below would be negative, and we don't need to deal with this light

