

①

a) for a stationary AR(1)

$$x(t) = a_0 + a_1 x(t-1) + \varepsilon_t$$

for $L \geq 2$

$$\begin{aligned} \text{ACF}(1) &= \text{Correlation}(x(t), x(t-1)) \\ &= a_1 \end{aligned}$$

$$\begin{aligned} \text{ACF}(2) &= \text{Correlation}(x(t), x(t-2)) \\ &= a_1^2 \end{aligned}$$

$$x(t) = a_0 + a_1 x(t-1) + a_2 x(t-2)$$

$$x(t-1) = a_0 + a_1 x(t-2)$$

$$x(t) = a_0 + a_1 (a_0 + a_1 x(t-2)) + a_2 x(t-2)$$

$$x(t) = a_0 + a_1 a_0 + a_1^2 x(t-2) + a_2 x(t-2)$$

$$\begin{aligned} \text{ACF}(2) &= \text{Correlation}(x(t), x(t-2)) \\ &= a_1^2 \end{aligned}$$

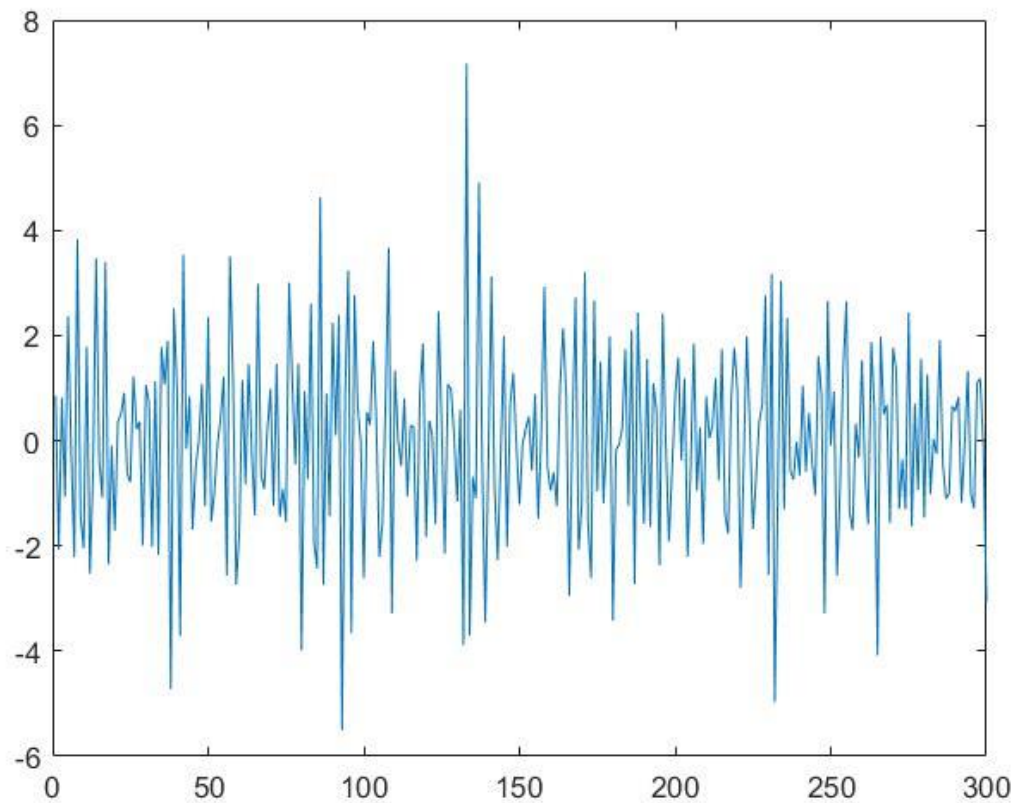
$$\text{ACF}(3) = a_1^3$$

$$\text{ACF}(4) = a_1^4$$

\therefore False, it is correlated

(b) $MA(q)$ is greater than 0 till q , after q everything becomes zero
 \therefore False, there will be no diff for $MA(1)$ after $L > 1$, $MA(1) = 1$ for $L = 1$

Q2



MATLAB Commands Used:

Time series for Q2 is imported to MATLAB. Timeseries is imported as a table, which needs to be converted into an array.

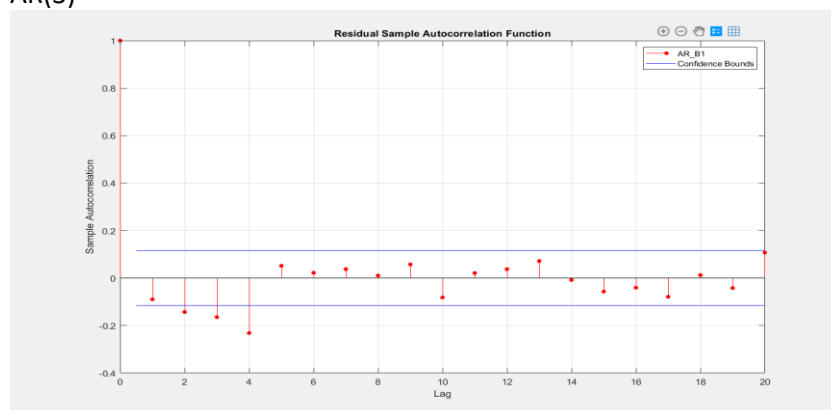
```
B = table2array(EE627AHW2Q2);  
plot(B)
```

B is imported to Econometric toolbox to plot PACF and ACF.

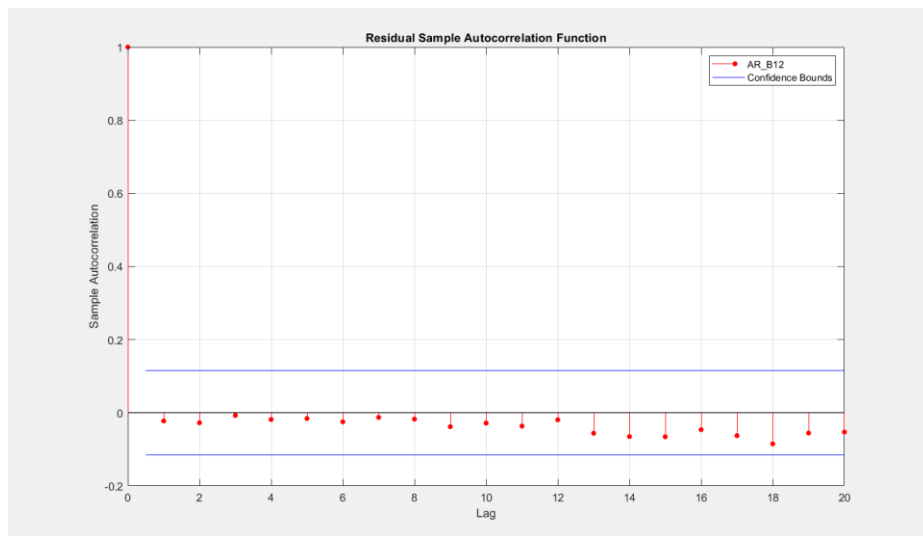
Following which a model is created.

The models I created are given below with residual auto correlation:

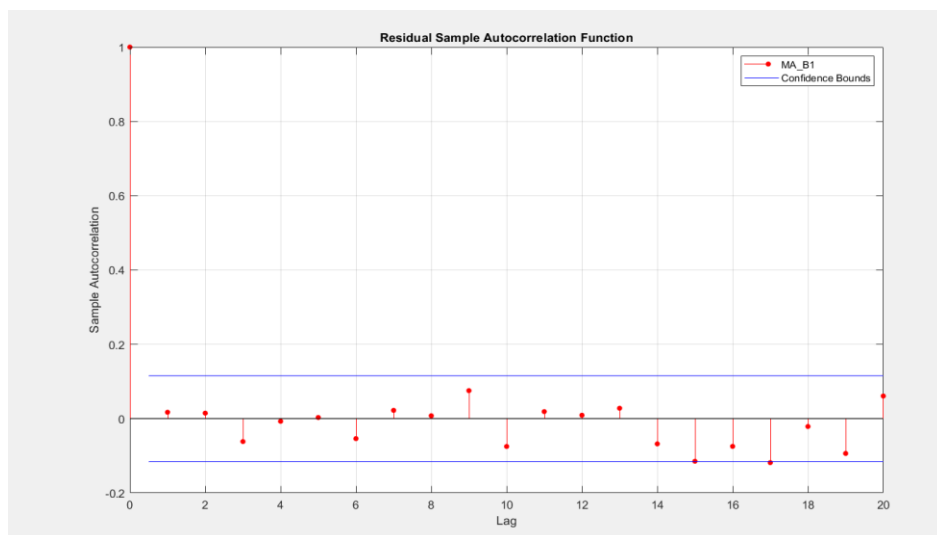
i) AR(3)



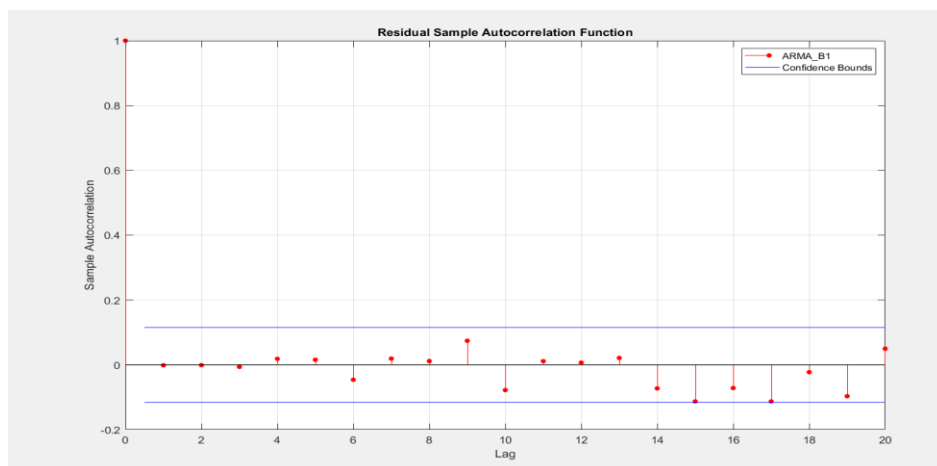
ii) AR(20)



iii) MA(3)

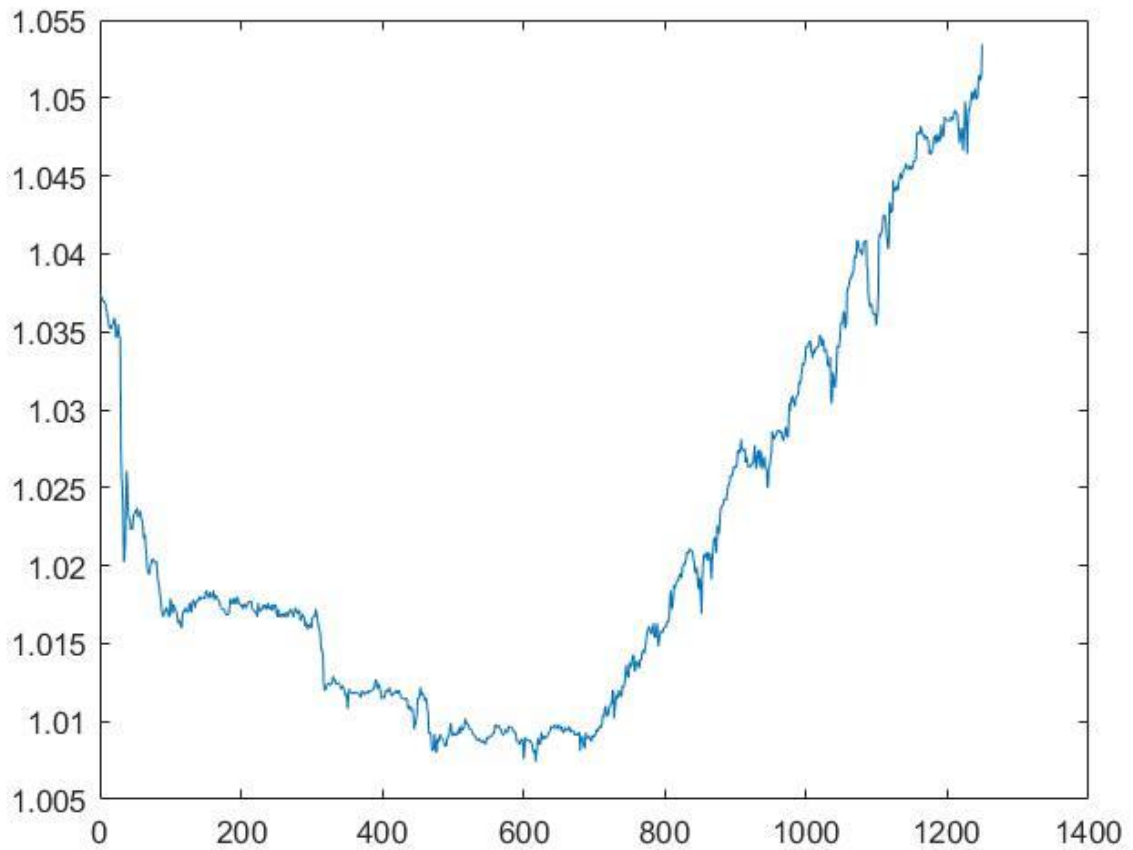


iv) ARMA(3,3)

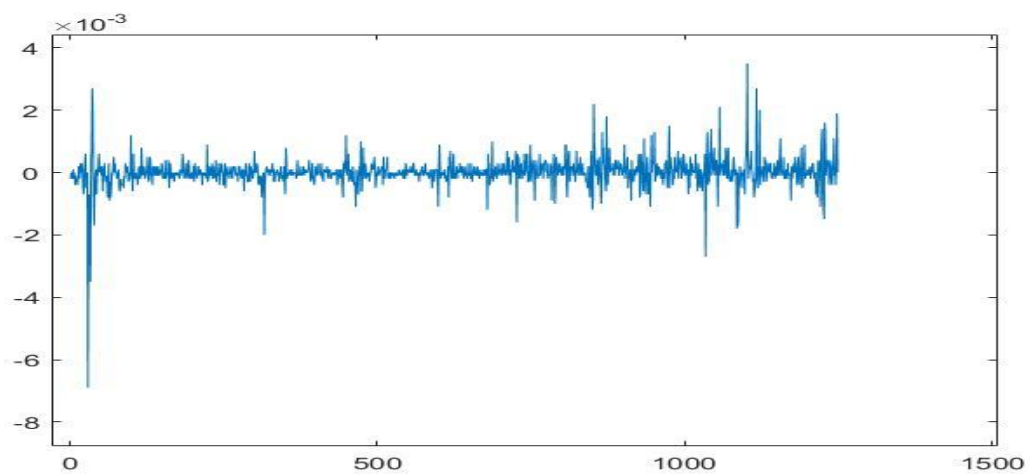


According to observation AR(20), MA(3) and ARMA(3) are best fit models. But since the one with least error terms are considered MA(3) would be a preferred model.

Q3

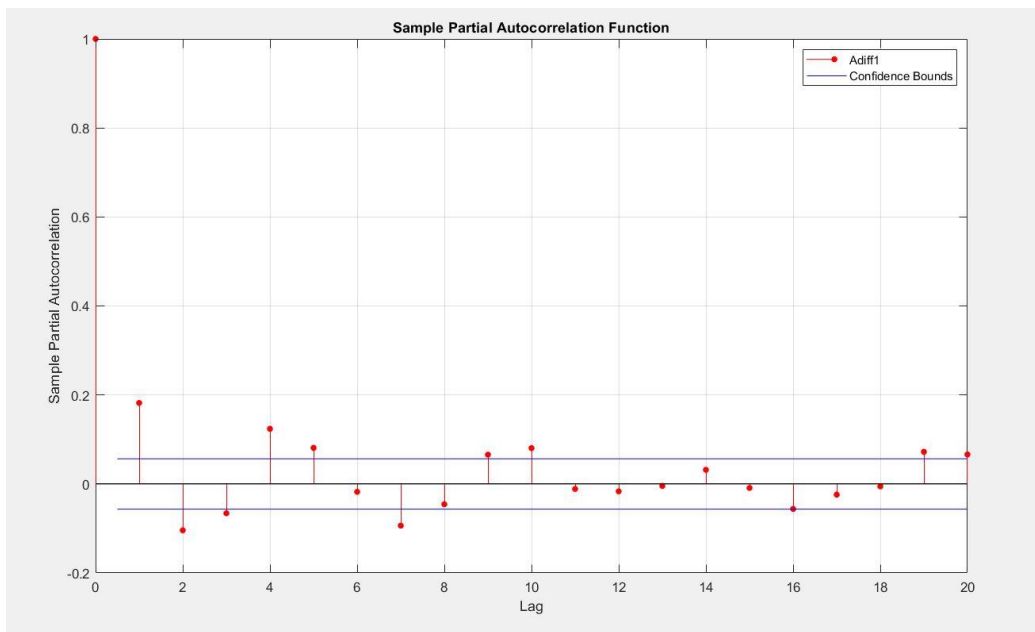


The time series is non – stationary thus, convert into stationary by taking difference. Using **diff(xt)** in MATLAB.

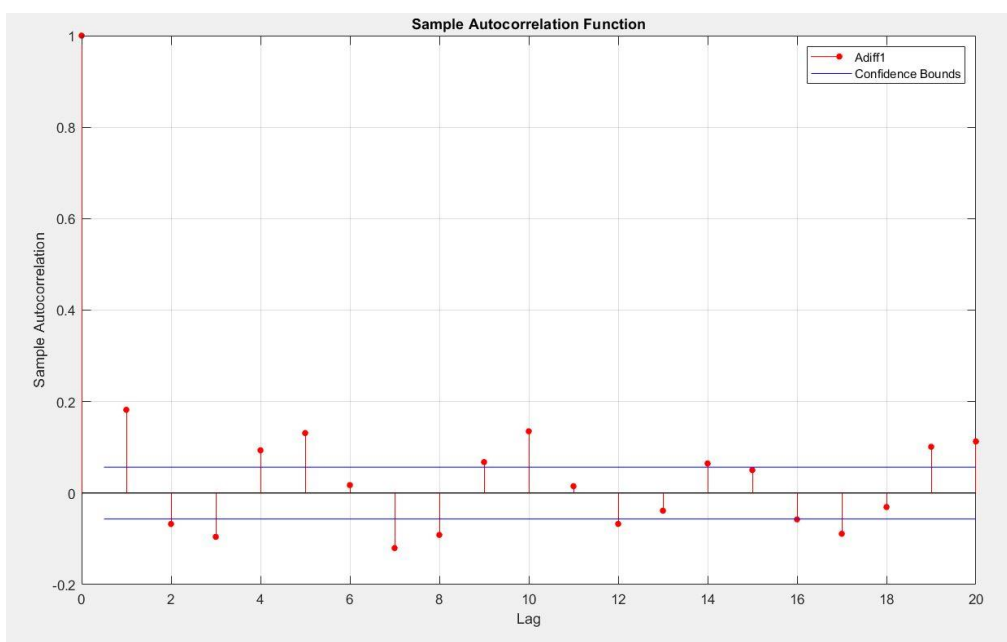


The Un-stationary signal is converted to Stationary Signal.

i) PACF

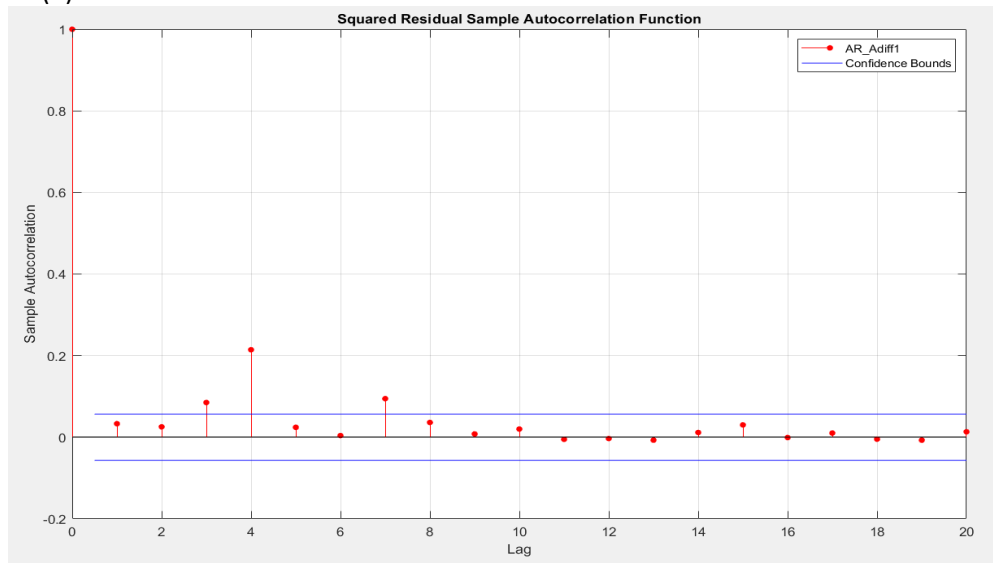


ii) ACF

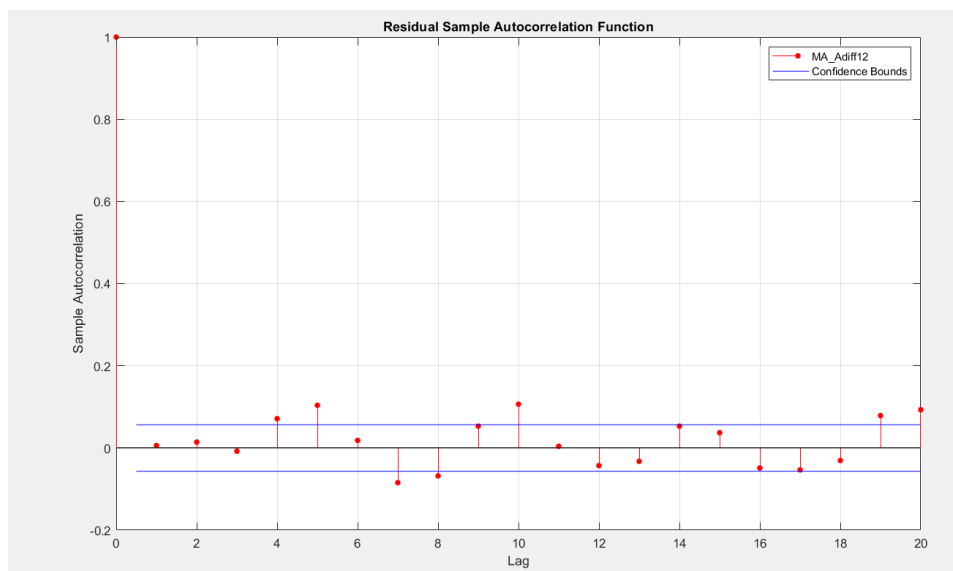


Models:

i) AR(3)



ii) MA(3)



iii) ARMA(3,3)

