





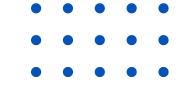
Guide -M.s Tanya Sharma

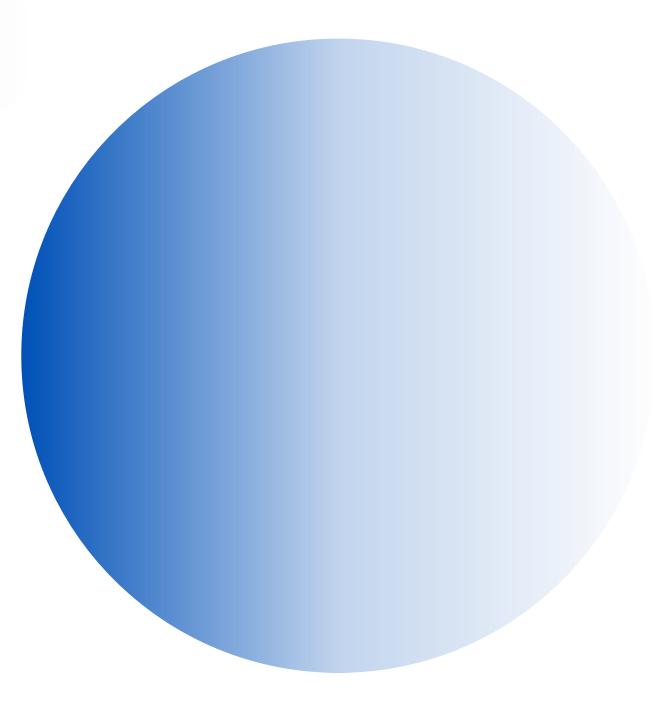
Presented by

Neeraj Upadhyay- 2100300130088 Mohit Karakoti -2100300130085

#### Problem Statement

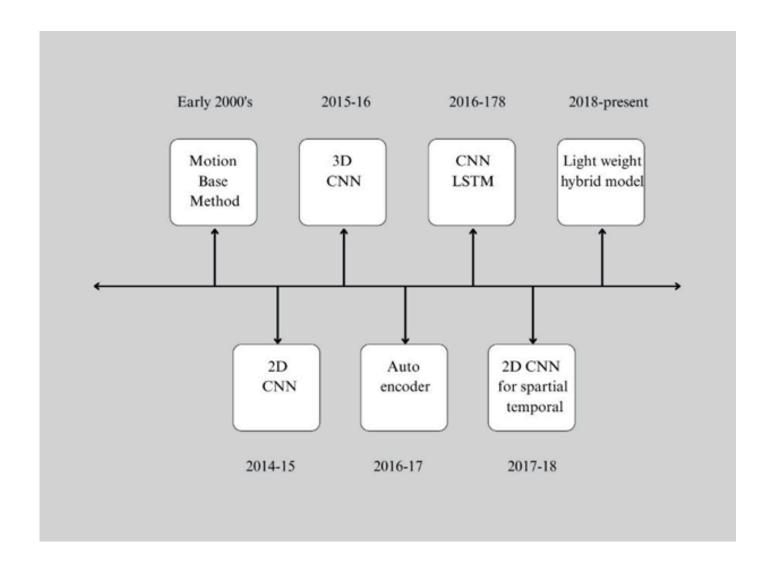
- Increasing public violence demands automated surveillance systems.
- Manual monitoring is error-prone and not scalable.
- Detecting violence in real-time from video feeds is a critical safety need.
- The challenge lies in recognizing complex, fast, and subtle violent actions accurate





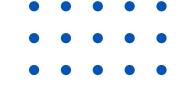
#### Related Work

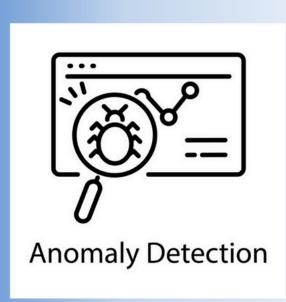
- 2D CNNs: Good for spatial features but lack temporal context.
- Autoencoders: Used for anomaly detection, but not task-specific.
- 3D CNNs: Capture temporal data, but are computationally expensive.
- CNN + LSTM: Combines spatial and sequential learning.
- Gaps: Many models struggle with real-world variability and lightweight real-time deployment.



### Proposed system

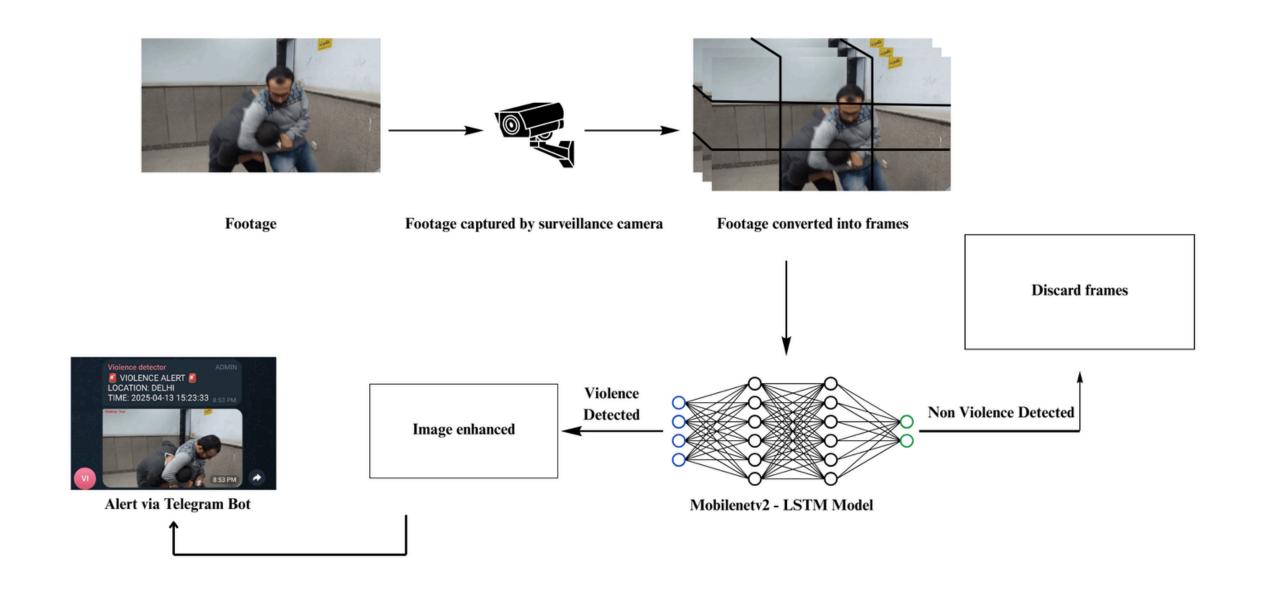
- The recommended technique is used for recognizing violent and non-violent incidents in real-time security camera footage is thoroughly examined in this section.
- In our system, we use MobileNetV2 and LSTM, along with hyperparameters that accurately identify the presence of violence in videos.
- When violence is detected, messages are sent to a telegram group via a telegram bot for real real-time

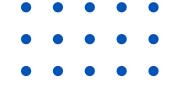




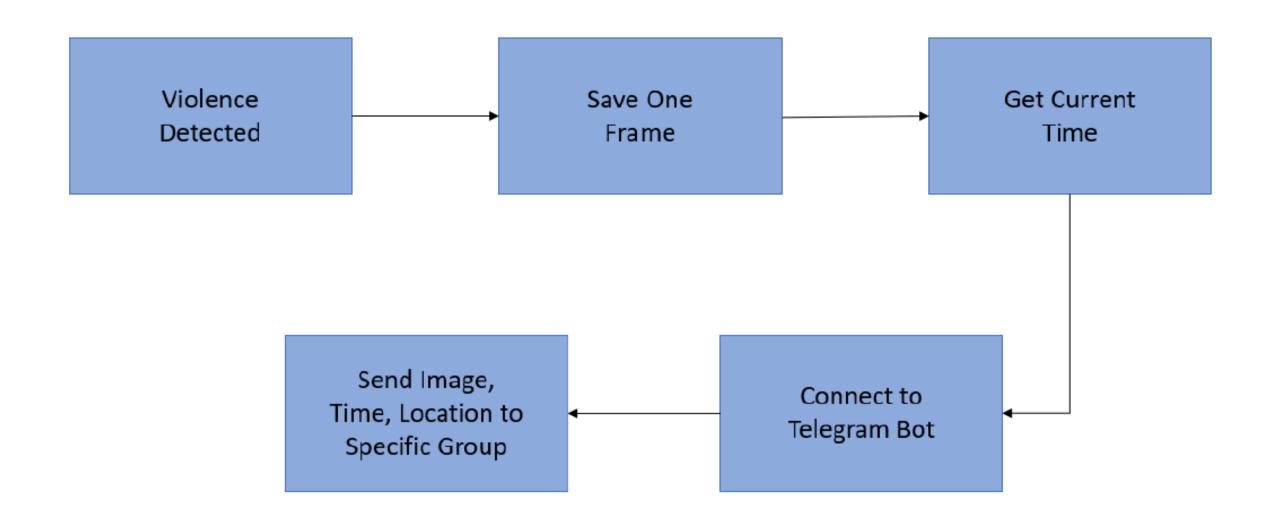


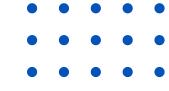
# Architectural Diagram



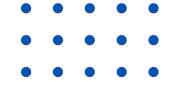


### Alert Module





- A. Dataset Collection
- B. Data Preprocessing
- C. Transfer Learning
- D. Hyperparameter initialization
- E. Performance Evaluation



#### Data collection

- To test our methodology, we work with these two datasets.
- Hockey Fight Dataset, which is standard in SOTA of violence detection, and Real Life Violence Situations Dataset, which is a relatively new dataset but has shown some promising results.







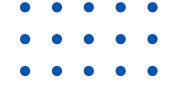






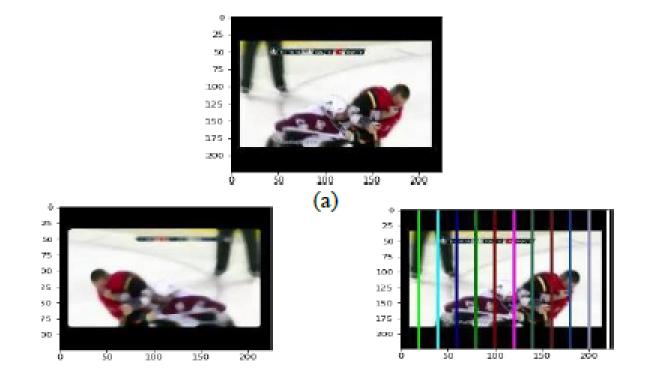


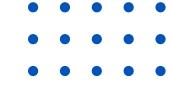




#### Preprocessing

- Video clips are converted into frames and now data augmentation is applied.
- Techniques such as cropping, random rotate, horizontal flip, motionblurr, gaussianblur, etc, are applied via Albumentations Pipeline
- Also the both datasets are splitted into training set and testing set in 80% -20% ratio where 80% clips are used to train model and rest 20% clips are used to test model
- Few frames are skipped to avoid duplication.





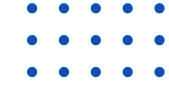
#### Tranfer Learning

- The suggested model is a binary image classification model
- MobileNetV2 act as a backbone supported by LSTM
- RelU introduces non-linearity, allowing the model to learn complex patterns also it makes training faster and avoids issues like vanishing gradients.
- Sigmoid in the final layer for binary classification output (Violent = 1, Non-Violent = 0)



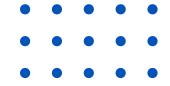
#### Hyperparameter initialization

- The initial learning rate (start\_lr) was set to 0.00001, whereas the maximum learning rate (max\_lr) used was 0.00005).
- To counteract overfitting, l2 regularization (0.005) was applied.
- ReduceLROnPlateau with an adaptive decreasing learning rate scheme if validation loss is not decreasing.
- ModelCheckpoint was used to track the weights of the best model in terms of validation accuracy.
- Batch size set to 16.
- epoch set to 50.
- Early stopping is also added to model.

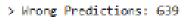


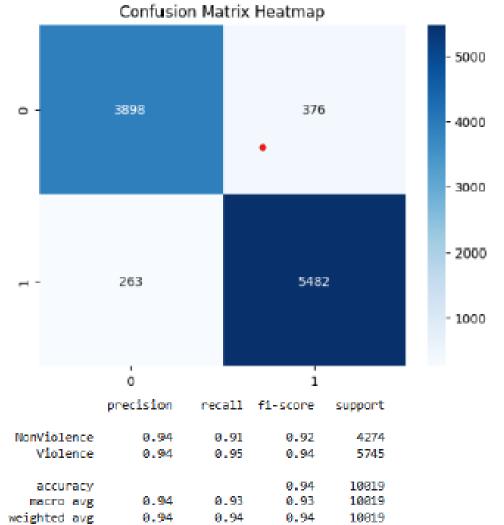
#### Performance Evaluation

- For performance evaluation, the system uses
- confusion matrix
- accuracy
- precision
- recall
- Loss

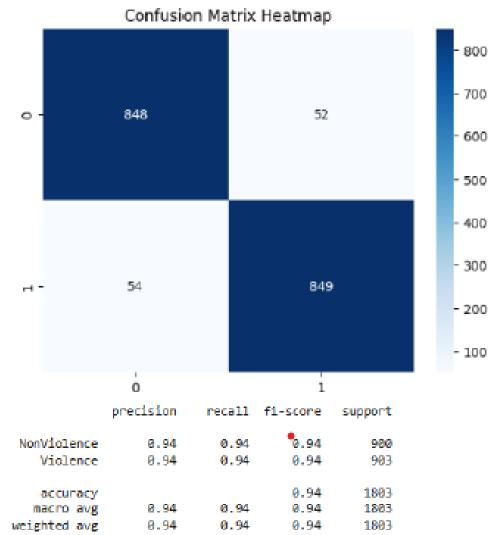


> Correct Predictions: 9380



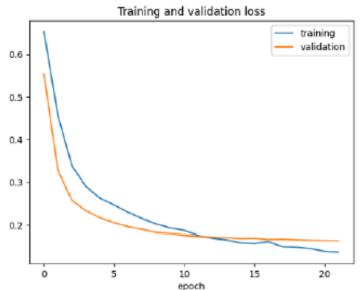


- > Correct Predictions: 1697
- > Wrong Predictions: 106





Accuracy on train: 0.9526641368865967 Loss on train: 0.14642678201198578 Accuracy on test: 0.941209077835083 Loss on test: 0.16338203847408295



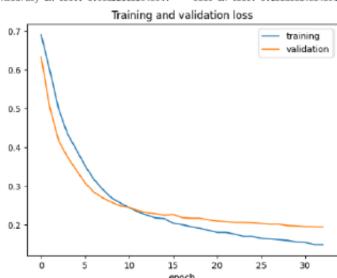
<Figure size 640x480 with 0 Axes>



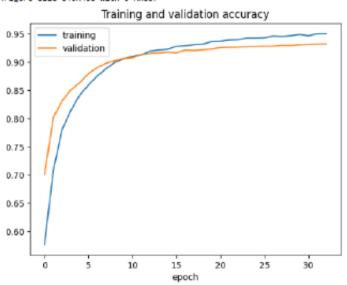
Best Epochs: 33

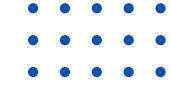
Accuracy on train: 0.9511913657188416 Loss on train: 0.14584754407405853

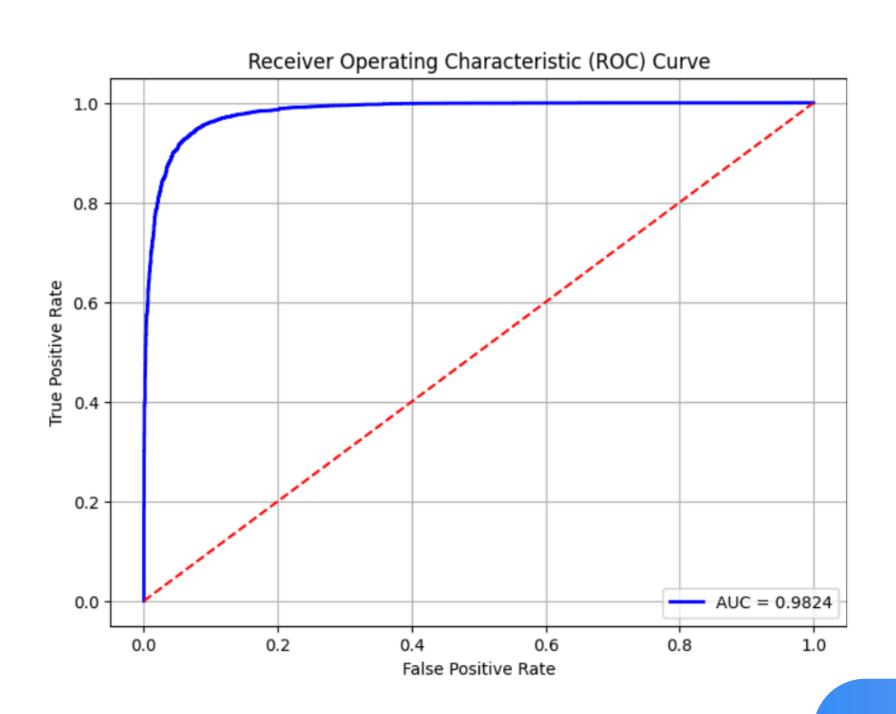
Accuracy on test: 0.936221182346344 Loss on test: 0.18665364384651184



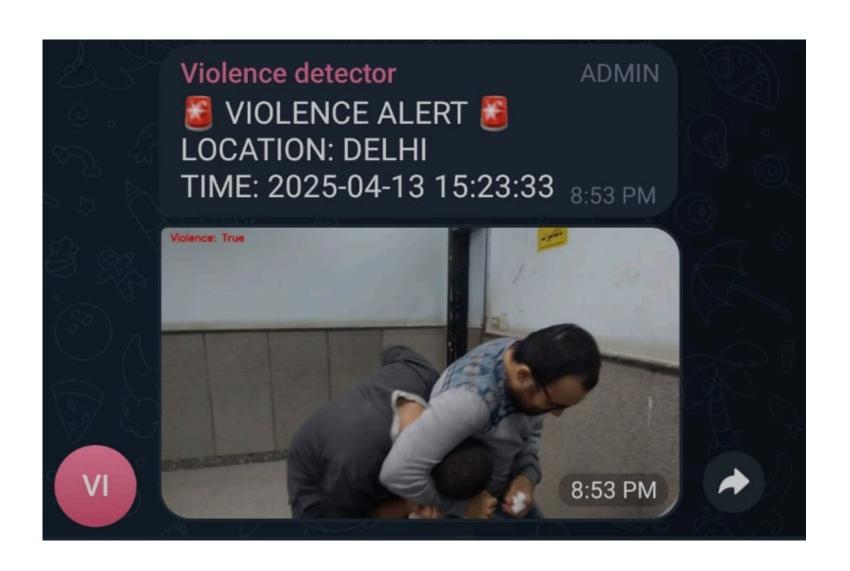
<Figure size 640x480 with 0 Axes>







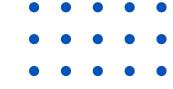






#### Refrences

- [1] https://keras.io/
- [2] https://www.tensorflow.org/
- [3]https://opencv.org/
- [4] https://matplotlib.org/
- [5] Khan SU, Haq IU, Rho S, Baik SW, Lee MY. Cover the Violence: A Novel Deep-Learning-Based Approach Towards Violence-Detection in Movies. Applied Sciences. 2019;9(22):4963. https://doi.org/10.3390/app9224963J



#### Refrences

6] R. Parlika and A. Pratama, "The Online Test Application Uses Telegram Bots Version 1.0," Journal of Physics: Conference Series, vol. 1569, p. 022042, 2020. doi: 10.1088/1742-6596/1569/2/022042.

[7] M. -S. Kang, R. -H. Park and H. -M. Park, "Efficient Spatio-Temporal Modeling Methods for Real-Time ViolenceRecognition," in IEEE Access, vol. 9, pp. 76270-76285,2021, doi: 10.1109/ACCESS.2021.3083273.

[8] Ullah FUM, Ullah A, Muhammad K, Haq IU, Baik SW.Violence Detection Using Spatiotemporal Features with 3DConvolutional Neural Network. Sensors (Basel). 2019 May30;19(11):2472. doi: 10.3390/s19112472.

[9] A. -M. R. Abdali and R. F. Al-Tuma, "Robust Real-TimeViolence Detection in Video Using CNN And LSTM," 20192nd Scientific Conference of Computer Sciences (SCCS),2019, pp. 104-108, doi: 10.1109/SCCS.2019.8852616.

#### THANK YOU